

Project3

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7
8
9   int player;
10  const int SIZE = 8;
11
12  std::array<std::array<int, SIZE>, SIZE> value = {{{200,-100,100,75,75,100,-100,200},
13  {-100,-150,100,50,50,100,-150,-100},
14  {100,100,100,60,60,100,100,100},
15  {75,50,60,60,60,60,50,75},
16  {75,50,60,60,60,60,50,75},
17  {100,100,100,60,60,100,100,100},
18  {-100,-150,100,50,50,100,-150,-100},
19  {200,-100,100,75,75,100,-100,200}}};
20
21  struct Point {
22      int x, y;
23      Point() : Point(0, 0) {}
24      Point(float x, float y) : x(x), y(y) {}
25      bool operator==(const Point& rhs) const {
26          return x == rhs.x && y == rhs.y;
27      }
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64      }
65
66      State(State& s) {
67          for (int i = 0; i < 8; i++)
68              for (int j = 0; j < 8; j++)
69                  cur_board[i][j] = s.cur_board[i][j];
70          heuristic = s.heuristic;
71          get_valid_spots();
72      }
73
74      void update(int newx, int newy) {
75          this->cur_board[newx][newy] = this->state_player;
76          get_valid_spots();
77          set_heuristic(newx, newy);
78          this->prevx = newx;
79          this->prevy = newy;
80      }
81      void set_heuristic(int x, int y) {
82          this->heuristic = value[x][y];
83      }
84      int get next player(int player) const {
```

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127     };
128
129     int minimax(State cur_state, int depth, int a, int b, int cur_player) {
130         int value;
131         if (depth == 3 || cur_state.next_valid_nodes.size() == 0) {
132             return cur_state.heuristic;
133         }
134         if (cur_player == player) {
135             int value = -200;
136             for (auto child : cur_state.next_valid_nodes) {
137                 State next_state = cur_state;
138                 next_state.update(child.x, child.y);
139                 if (next_state.heuristic > value) {
140                     value = next_state.heuristic;
141                 }
142                 minimax(next_state, depth + 1, a, b, 3 - player);
143                 a = a > value ? a : value;
144                 if (a >= b)
145                     break;
146             }
147             return value;

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145         break;
146     }
147     return value;
148 }
149 else {
150     int value = 250;
151     for (int i = 0; i < cur_state.next_valid_nodes.size(); i++) {
152         Point child = cur_state.next_valid_nodes[i];
153         State next_state = cur_state;
154         next_state.update(child.x, child.y);
155         if (next_state.heuristic < value) {
156             value = next_state.heuristic;
157         }
158         minimax(next_state, depth + 1, a, b, 3 - cur_player);
159         if (b <= a)
160             break;
161     }
162     return value;
163 }
164 }
165

```

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184 }
185
186 void write_valid_spot(std::ofstream& fout) {
187     int n_valid_spots = next_valid_spots.size();
188     // Keep updating the output until getting killed.
189     while (true) {
190         State cur_state(board);
191         Point p;
192         int value = minimax(cur_state, 0, 250, -200, cur_state.state_player);
193         for(int i = 0; i < n_valid_spots; i++) {
194             if(next_valid_spots[i].set_value() == value)
195                 p = next_valid_spots[i];
196         }
197         // Remember to flush the output to ensure the last action is written to file.
198         fout << p.x << " " << p.y << std::endl;
199         fout.flush();
200     }
201 }
202
203
```

github.com/YouSheng-Do/project3/commits/master/107062209_project3.cpp

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YouSheng-Do committed 11 seconds ago			
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