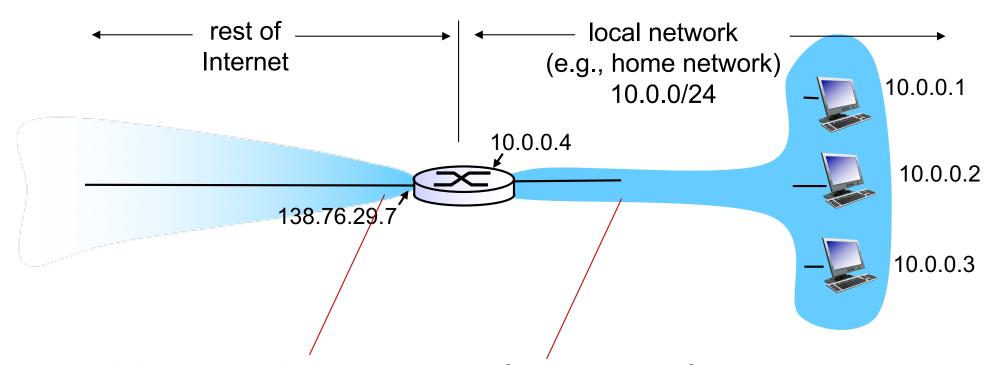
Logistics

- Reading and HW4
 - Extended: Due Sunat 10pm
- * Today:
 - Network layer

Review: NAT



all datagrams leaving local network have same single source NAT IP address: 138.76.29.7, different source port numbers datagrams with source or destination in this network have 10.0.0/24 address for source, destination (as usual)

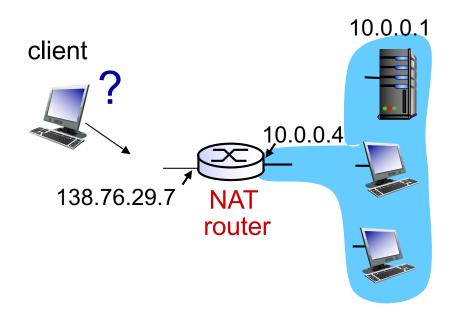
Review: NAT

implementation: NAT router must:

- outgoing datagrams: replace (source IP address, port #) of every outgoing datagram to (NAT IP address, new port #)
 . . . remote clients/servers will respond using (NAT IP address, new port #) as destination addr
- remember (in NAT translation table) every (source IP address, port #) to (NAT IP address, new port #) translation pair
- incoming datagrams: replace (NAT IP address, new port #) in dest fields of every incoming datagram with corresponding (source IP address, port #) stored in NAT table

Review: NAT traversal problem

- client wants to connect to server with address 10.0.0.1
 - server address 10.0.0.1 local to LAN (client can't use it as destination addr)
 - only one externally visible NATed address: 138.76.29.7
- solution I: statically configure NAT to forward incoming connection requests at given port to server
 - e.g., (123.76.29.7, port 2500)
 always forwarded to 10.0.0.1 port 25000



Review: IPv6 datagram format

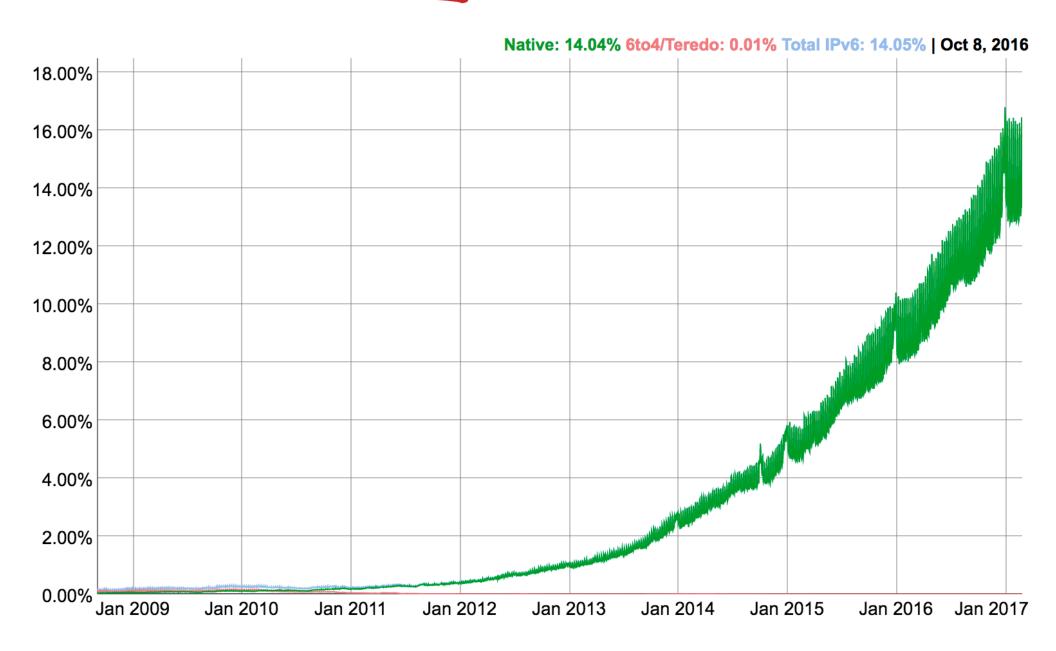
priority: identify priority among datagrams in flow flow Label: identify datagrams in same "flow." (concept of flow not well defined). next header: identify upper layer protocol for data

ver	pri	flow label		
payload len			next hdr	hop limit
source address (128 bits)				
destination address (128 bits)				
data				

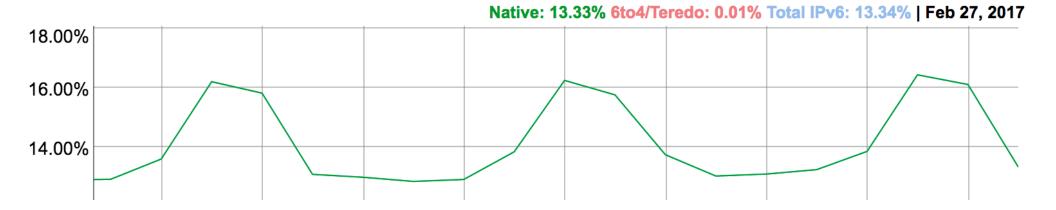
Review: Tunneling

IPv4 tunnel Α В connecting IPv6 routers logical view: IPv6 IPv6 IPv6 IPv6 Α В physical view: IPv6 IPv6 IPv6 IPv6 IPv4 IPv4

IPv6: adoption (Google)



IPv6: adoption (Google)



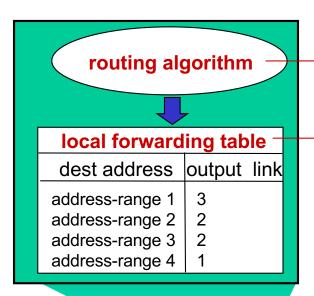
Chapter 4: outline

- 4.1 introduction
- 4.2 virtual circuit and datagram networks
- 4.3 what's inside a router
- 4.4 IP: Internet Protocol
 - datagram format
 - IPv4 addressing
 - ICMP
 - IPv6

4.5 routing algorithms

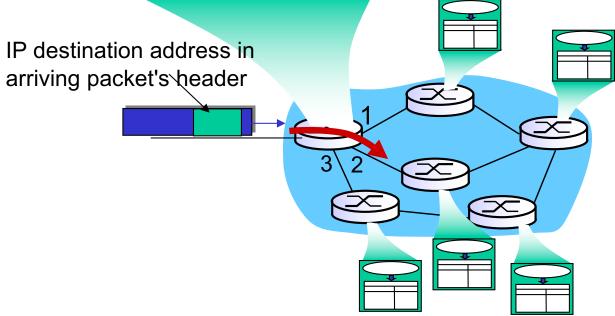
- link state
- distance vector
- hierarchical routing
- 4.6 routing in the Internet
 - RIP
 - OSPF
 - BGP
- 4.7 broadcast and multicast routing

Interplay between routing, forwarding

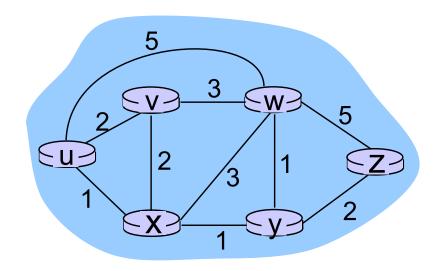


<u>rou</u>ting algorithm determines end-end-path through network

forwarding table determines local forwarding at this router



Graph abstraction



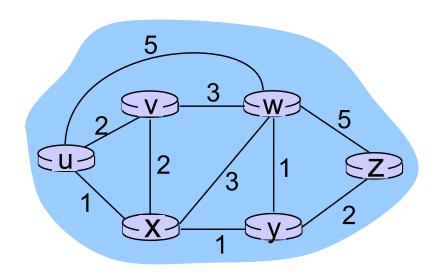
graph: G = (N,E)

 $N = set of routers = \{ u, v, w, x, y, z \}$

 $E = \text{set of links} = \{ (u,v), (u,x), (v,x), (v,w), (x,w), (x,y), (w,y), (w,z), (y,z) \}$

aside: graph abstraction is useful in other network contexts, e.g., P2P, where N is set of peers and E is set of TCP connections

Graph abstraction: costs



$$c(x,x') = cost of link (x,x')$$

e.g., $c(w,z) = 5$

cost could always be I, or inversely related to bandwidth, or inversely related to congestion

cost of path
$$(x_1, x_2, x_3, ..., x_p) = c(x_1, x_2) + c(x_2, x_3) + ... + c(x_{p-1}, x_p)$$

key question: what is the least-cost path between u and z? routing algorithm: algorithm that finds that least cost path

Routing algorithm classification

Q: global or decentralized information?

global:

- all routers have complete topology, link cost info
- "link state" algorithms decentralized:
- router knows physicallyconnected neighbors, link costs to neighbors
- iterative process of computation, exchange of info with neighbors
- "distance vector" algorithms

Q: static or dynamic?

static:

routes change slowly over time

dynamic:

- routes change more quickly
 - periodic update
 - in response to link cost changes

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A Link-State Routing Algorithm

Dijkstra's algorithm

- net topology, link costs known to all nodes
 - accomplished via "link state broadcast"
 - all nodes have same info
- computes least cost paths from one node ('source") to all other nodes
 - gives forwarding table for that node
- iterative: after k
 iterations, know least cost
 path to k dest.'s

notation:

- **\star** C(X,Y): link cost from node x to y; = ∞ if not direct neighbors
- D(V): current value of cost of path from source to dest. v
- p(V): predecessor node along path from source to
- N': set of nodes whose least cost path definitively known

Dijsktra's Algorithm

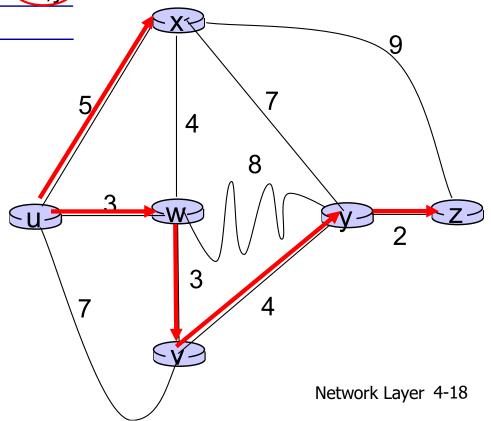
```
Initialization:
   N' = \{u\}
3 for all nodes v
    if v adjacent to u
       then D(v) = c(u,v)
     else D(v) = \infty
   Loop
    find w not in N' such that D(w) is a minimum
   add w to N'
   update D(v) for all v adjacent to w and not in N':
12
       D(v) = \min(D(v), D(w) + c(w,v))
13 /* new cost to v is either old cost to v or known
14
     shortest path cost to w plus cost from w to v */
15 until all nodes in N'
```

Dijkstra's algorithm: example

		D(v)	$D(\mathbf{w})$	D(x)	$D(\mathbf{y})$	D(z)
Ste	o N'	p(v)	p(w)	p(x)	p(y)	p(z)
0	u	7,u	(3,u)	5,u	∞	∞
1	uw	6,w		5,u) 11,W	∞
2 3	uwx	6,w			11,W	14,X
3	uwxv				10,V	14,x
4	uwxvy					12,y
5	uwxvyz					

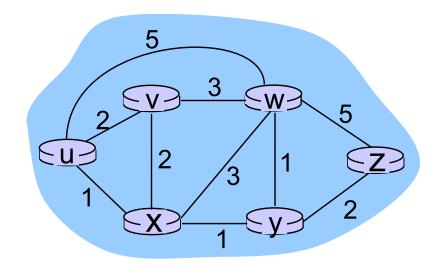
notes:

- construct shortest path tree by tracing predecessor nodes
- ties can exist (can be broken arbitrarily)



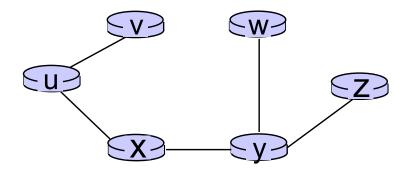
Dijkstra's algorithm: another example

Step	N'	D(v),p(v)	D(w),p(w)	D(x),p(x)	D(y),p(y)	D(z),p(z)
0	U	2,u	5,u	1,u	∞	∞
1	ux ←	2,u	4,x		2,x	∞
2	uxy <mark>←</mark>	2, u	3,y			4,y
3	uxyv		3,y			4,y
4	uxyvw 🗲					4,y
5	uxyvwz 🕶					



Dijkstra's algorithm: example (2)

resulting shortest-path tree from u:



resulting forwarding table in u:

destination	link
V	(u,v)
X	(u,x)
У	(u,x)
W	(u,x)
Z	(u,x)

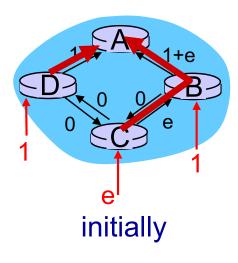
Dijkstra's algorithm, discussion

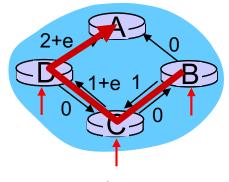
algorithm complexity: n nodes

- * each iteration: need to check all nodes, w, not in N
- \bullet n(n+1)/2 comparisons: O(n²)
- more efficient implementations possible: O(nlogn)

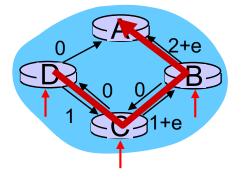
oscillations possible:

e.g., support link cost equals amount of carried traffic:

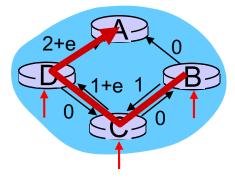




given these costs, find new routing.... resulting in new costs



given these costs, find new routing.... resulting in new costs



given these costs, find new routing.... resulting in new costs

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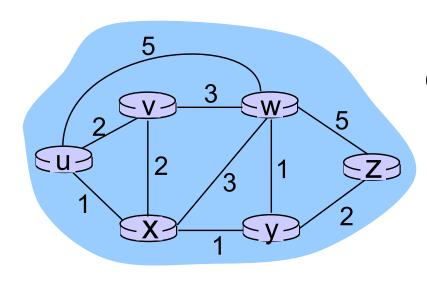
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Bellman-Ford equation (dynamic programming)

```
let d_x(y) := \text{cost of least-cost path from } x \text{ to } y then d_x(y) = \min_{v} \{c(x,v) + d_v(y)\} cost from neighbor v to destination v cost to neighbor v
```

Bellman-Ford example



clearly,
$$d_v(z) = 5$$
, $d_x(z) = 3$, $d_w(z) = 3$

B-F equation says:

$$d_{u}(z) = \min \{ c(u,v) + d_{v}(z), \\ c(u,x) + d_{x}(z), \\ c(u,w) + d_{w}(z) \}$$

$$= \min \{ 2 + 5, \\ 1 + 3, \\ 5 + 3 \} = 4$$

node achieving minimum is next hop in shortest path, used in forwarding table

- $D_{x}(y) = estimate of least cost from x to y$
 - x maintains distance vector $\mathbf{D}_{x} = [\mathbf{D}_{x}(y): y \in \mathbb{N}]$
- node x:
 - knows cost to each neighbor v: c(x,v)
 - maintains its neighbors' distance vectors. For each neighbor v, x maintains

$$\mathbf{D}_{\mathsf{v}} = [\mathsf{D}_{\mathsf{v}}(\mathsf{y}): \mathsf{y} \in \mathsf{N}]$$

key idea:

- from time-to-time, each node sends its own distance vector estimate to neighbors
- when x receives new DV estimate from neighbor, it updates its own DV using B-F equation:

$$D_x(y) \leftarrow \min_{v} \{c(x,v) + D_v(y)\}$$
 for each node $y \in N$

* under minor, natural conditions, the estimate $D_x(y)$ converge to the actual least cost $d_x(y)$

iterative, asynchronous:

- each local iteration caused by:
- local link cost change
- DV update message from neighbor

distributed:

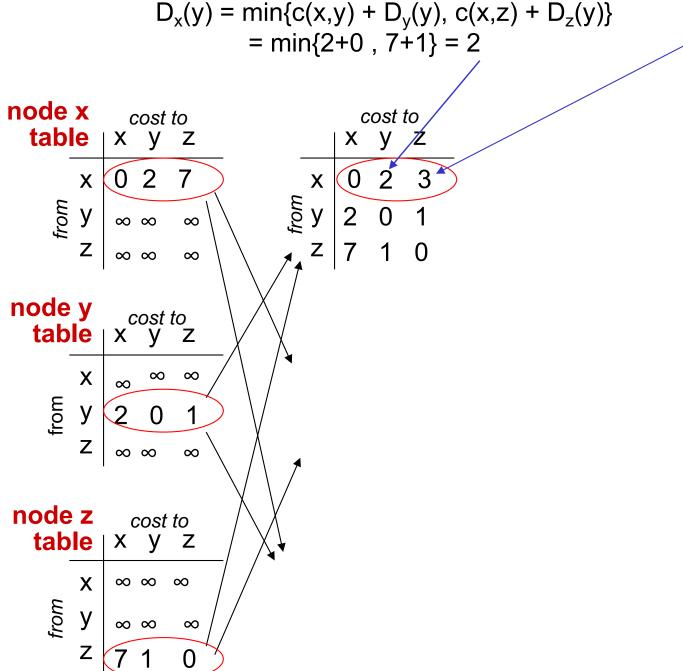
- each node notifies neighbors only when its DV changes
 - neighbors then notify their neighbors if necessary

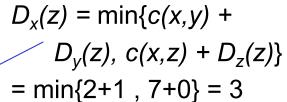
each node:

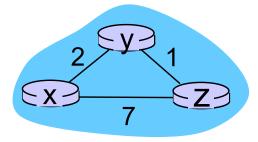
wait for (change in local link cost or msg from neighbor)

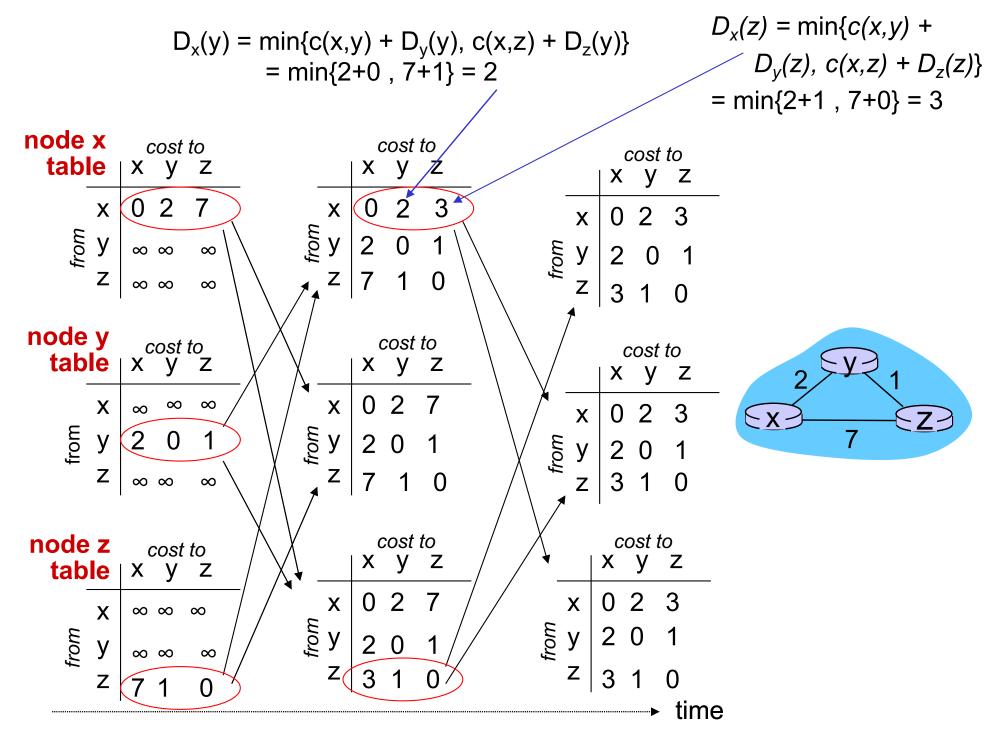
recompute estimates

if DV to any dest has changed, notify neighbors





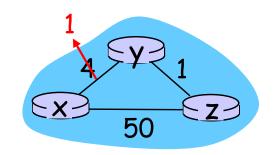




Distance vector: link cost changes

link cost changes:

- node detects local link cost change
- updates routing info, recalculates distance vector
- if DV changes, notify neighbors



"good news travels fast"

 t_0 : y detects link-cost change, updates its DV, informs its neighbors.

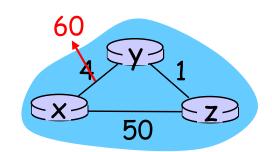
 t_1 : z receives update from y, updates its table, computes new least cost to x, sends its neighbors its DV.

 t_2 : y receives z's update, updates its distance table. y's least costs do not change, so y does not send a message to z.

Distance vector: link cost changes

link cost changes:

- node detects local link cost change
- bad news travels slow "count to infinity" problem!
- 44 iterations before algorithm stabilizes: see text



poisoned reverse:

- If Z routes through Y to get to X:
 - Z tells Y its (Z's) distance to X is infinite (so Y won't route to X via Z)
- will this completely solve count to infinity problem?

Comparison of LS and DV algorithms

message complexity

- LS: with n nodes, E links, O(nE) msgs sent
- DV: exchange between neighbors only
 - convergence time varies

speed of convergence

- LS: O(n²) algorithm requires
 O(nE) msgs
 - may have oscillations
- DV: convergence time varies
 - may be routing loops
 - count-to-infinity problem

robustness: what happens if router malfunctions?

LS:

- node can advertise incorrect link cost
- each node computes only its own table

DV:

- DV node can advertise incorrect path cost
- each node's table used by others
 - error propagate thru network