Introduction to Modern OpenGL Programming

Adapted from SIGGRAPH 2012 slides by

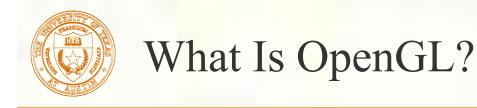
Ed Angel University of New Mexico

and

Dave Shreiner ARM, Inc



- Evolution of the OpenGL Pipeline
- A Prototype Application in OpenGL
- OpenGL Shading Language (GLSL)
- Vertex Shaders
- Fragment Shaders
- Examples



- OpenGL is a computer graphics rendering API
 - With it, you can generate high-quality color images by rendering with geometric and image primitives
 - It forms the basis of many interactive applications that include 3D graphics
 - By using OpenGL, the graphics part of your application can be
 - operating system independent
 - window system independent

This is the "new" OpenGL

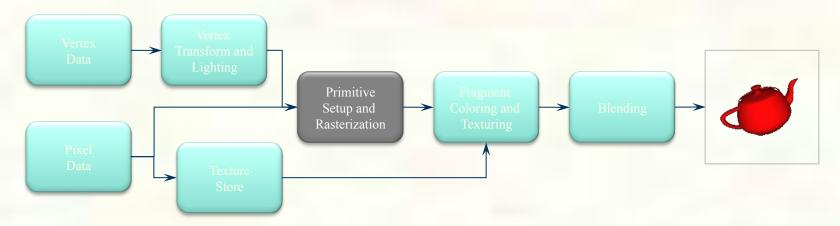
- We'll concentrate on the latest versions of OpenGL
- They enforce a new way to program with OpenGL
 - Allows more efficient use of GPU resources
- If you're familiar with "classic" graphics pipelines, modern OpenGL doesn't support
 - Fixed-function graphics operations
 - lighting
 - transformations
- All applications must use shaders for their graphics processing

The Evolution of the OpenGL Pipeline



In the Beginning ...

- OpenGL 1.0 was released on July 1st, 1994
- Its pipeline was entirely fixed-function
 - the only operations available were fixed by the implementation

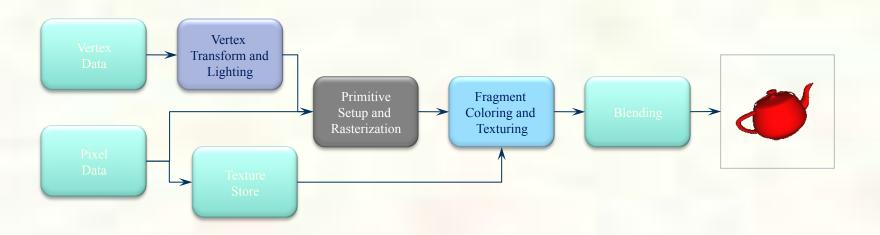


■ The pipeline evolved, but remained fixed-function through OpenGL versions 1.1 through 2.0 (Sept. 2004)



The Start of the Programmable Pipeline

- OpenGL 2.0 (officially) added programmable shaders
 - vertex shading augmented the fixed-function transform and lighting stage
 - fragment shading augmented the fragment coloring stage
- However, the fixed-function pipeline was still available





An Evolutionary Change

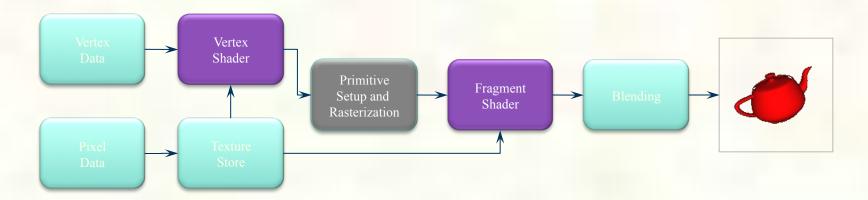
- OpenGL 3.0 introduced the deprecation model
 - the method used to remove features from OpenGL
- The pipeline remained the same until OpenGL 3.1 (released March 24th, 2009)
- Introduced a change in how OpenGL contexts are used

Context Type	Description	
Full	Includes all features (including those marked deprecated) available in the current version of OpenGL	
Forward Compatible	Includes all non-deprecated features (i.e., creates a context that would be similar to the next version of OpenGL)	



The Exclusively Programmable Pipeline

- OpenGL 3.1 removed the fixed-function pipeline
 - programs were required to use only shaders

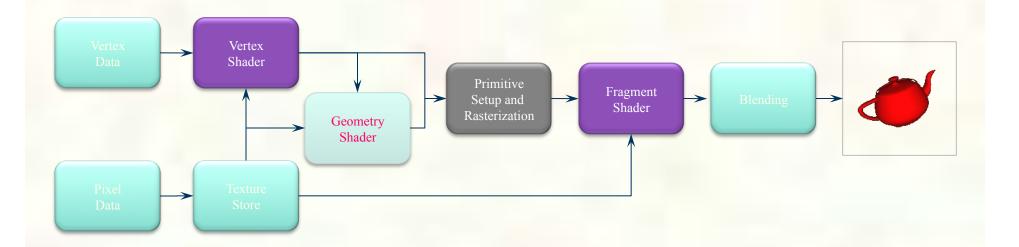


- Additionally, almost all data is GPU-resident
 - all vertex data sent using buffer objects



More Programmability

OpenGL 3.2 (released August 3rd, 2009) added an additional shading stage – geometry shaders





More Evolution – Context Profiles

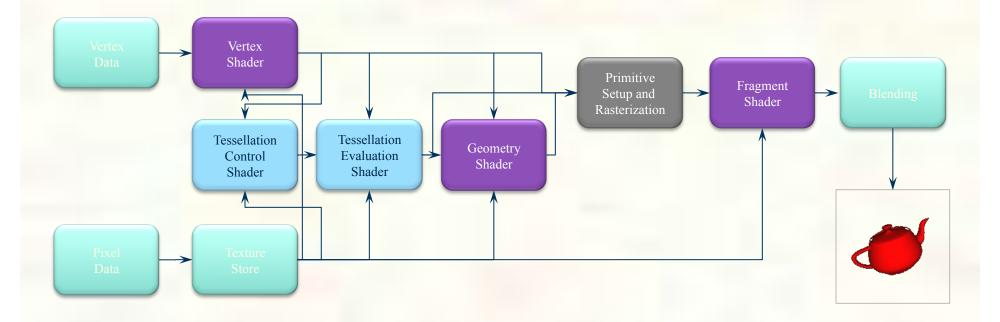
- OpenGL 3.2 also introduced context profiles
 - profiles control which features are exposed
 - currently two types of profiles: core and compatible

Context Type	Profile	Description
Full	core	All features of the current release
	compatible	All features ever in OpenGL
Forward Compatible	core	All non-deprecated features
	compatible	Not supported



The Latest Pipelines

- OpenGL 4.1 (released July 25th, 2010) included additional shading stages – tessellation-control and tessellation-evaluation shaders
- Latest version is 4.3



OpenGL ES 2.0

- Designed for embedded and hand-held devices such as cell phones
- Based on OpenGL 3.1
- Shader based

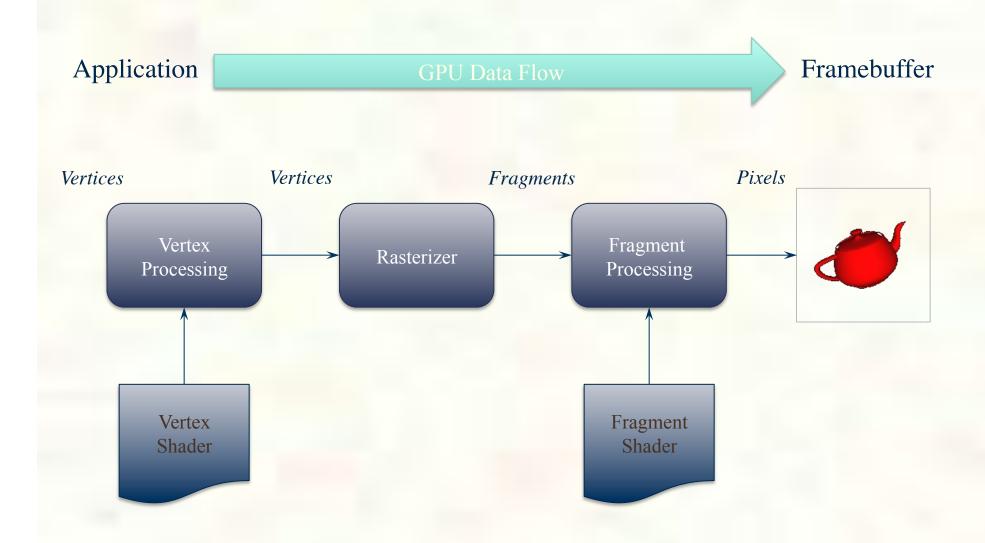
WebGL

- JavaScript implementation of ES 2.0
- Runs on most recent browsers

OpenGL Application Development



A Simplified Pipeline Model





OpenGL Programming in a Nutshell

- Modern OpenGL programs essentially do the following steps:
 - 1. Create shader programs
 - 2. Create buffer objects and load data into them
 - 3. "Connect" data locations with shader variables
 - 4. Render



Application Framework Requirements

- OpenGL applications need a place to render into
 - usually an on-screen window
- Need to communicate with native windowing system
- Each windowing system interface is different
- We use GLUT (more specifically, freeglut)
 - simple, open-source library that works everywhere
 - handles all windowing operations:
 - opening windows
 - input processing



Simplifying Working with OpenGL

- Operating systems deal with library functions differently
 - compiler linkage and runtime libraries may expose different functions
- Additionally, OpenGL has many versions and profiles which expose different sets of functions
 - managing function access is cumbersome, and window-system dependent
- We use another open-source library, GLEW, to hide those details



Representing Geometric Objects

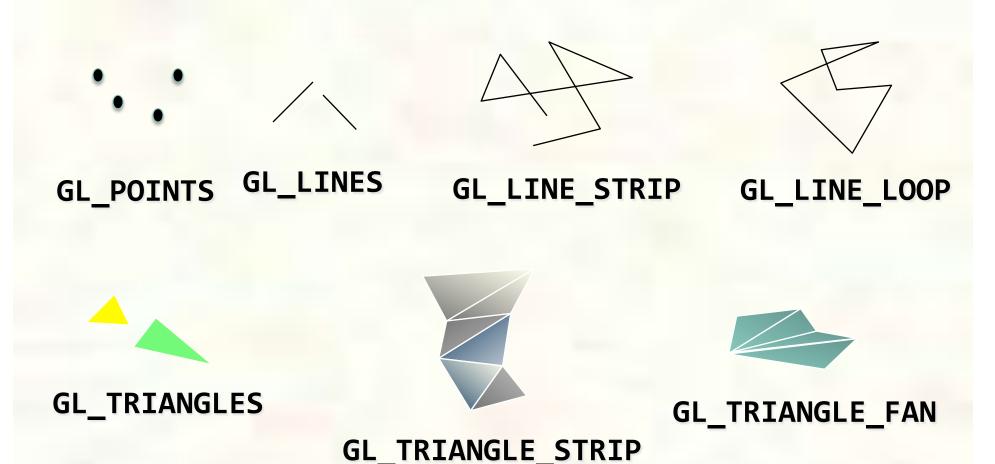
 \mathcal{V}

- Geometric objects are represented using vertices
- A vertex is a collection of generic attributes
 - positional coordinates
 - colors
 - texture coordinates
 - any other data associated with that point in space
- Position stored in 4 dimensional homogeneous coordinates
- Vertex data must be stored in vertex buffer objects (VBOs)
- VBOs must be stored in vertex array objects (VAOs)



OpenGL's Geometric Primitives

All primitives are specified by vertices



A First Program



- We'll render a cube with colors at each vertex
- Our example demonstrates:
 - initializing vertex data
 - organizing data for rendering
 - simple object modeling
 - building up 3D objects from geometric primitives
 - building geometric primitives from vertices

Initializing the Cube's Data

- We'll build each cube face from individual triangles
- Need to determine how much storage is required
 - (6 faces)(2 triangles/face)(3 vertices/triangle)
 const int NumVertices = 36;
- To simplify communicating with GLSL, we'll use a vec4 class (implemented in C++) similar to GLSL's vec4 type
 - we'll also typedef it to add logical meaning

```
typedef vec4 point4;
typedef vec4 color4;
```

Initializing the Cube's Data (cont'd)

- Before we can initialize our VBO, we need to stage the data
- Our cube has two attributes per vertex
 - position
 - color
- We create two arrays to hold the VBO data

```
point4 points[NumVertices];
color4 colors[NumVertices];
```

```
// Vertices of a unit cube centered at origin, sides aligned
  with axes
point4 vertex_positions[8] = {
   point4( -0.5, -0.5, 0.5, 1.0 ),
   point4( -0.5, 0.5, 0.5, 1.0 ),
   point4( 0.5, 0.5, 0.5, 1.0),
   point4( 0.5, -0.5, 0.5, 1.0),
   point4( -0.5, -0.5, -0.5, 1.0 ),
   point4( -0.5, 0.5, -0.5, 1.0 ),
   point4( 0.5, 0.5, -0.5, 1.0 ),
   point4( 0.5, -0.5, -0.5, 1.0 )
};
```

Generating a Cube Face from Vertices

```
// quad() generates two triangles for each face and assigns
  colors to the vertices
int Index = 0; // global variable indexing into VBO arrays
void quad(int a, int b, int c, int d) {
    colors[Index] = vertex colors[a]; points[Index] =
  vertex positions[a]; Index++;
    colors[Index] = vertex colors[b]; points[Index] =
  vertex positions[b]; Index++;
    colors[Index] = vertex colors[c]; points[Index] =
  vertex positions[c]; Index++;
    colors[Index] = vertex colors[a]; points[Index] =
  vertex positions[a]; Index++;
    colors[Index] = vertex colors[c]; points[Index] =
  vertex positions[c]; Index++;
    colors[Index] = vertex colors[d]; points[Index] =
  vertex positions[d]; Index++;
```

Generating the Cube from Faces

```
// generate 12 triangles: 36 vertices and 36
 colors
void
colorcube() {
   quad(1,0,3,2);
   quad(2,3,7,6);
   quad(3,0,4,7);
   quad(6,5,1,2);
   quad(4,5,6,7);
   quad(5, 4, 0, 1);
```

Vertex Array Objects (VAOs)

- VAOs store the data of a geometric object
- Steps in using a VAO
 - generate VAO names by calling glGenVertexArrays()
 - bind a specific VAO for initialization by calling glBindVertexArray()
 - update VBOs associated with this VAO
 - bind VAO for use in rendering
- This approach allows a single function call to specify all the data for an objects
 - previously, you might have needed to make many calls to make all the data current

```
// Create a vertex array object
GLuint vao;
glGenVertexArrays(1, &vao);
glBindVertexArray(vao);
```

Storing Vertex Attributes

- Vertex data must be stored in a VBO, and associated with a VAO
- The code-flow is similar to configuring a VAO
 - generate VBO names by calling glGenBuffers()
 - bind a specific VBO for initialization by calling glBindBuffer(GL_ARRAY_BUFFER, ...)
 - load data into VBO using glBufferData(GL_ARRAY_BUFFER, ...)
 - bind VAO for use in rendering glBindVertexArray()

```
// Create and initialize a buffer object
GLuint buffer;
glGenBuffers(1, &buffer);
glBindBuffer(GL_ARRAY_BUFFER, buffer);
glBufferData(GL_ARRAY_BUFFER, sizeof(points) +
             sizeof(colors), NULL,
  GL STATIC DRAW);
glBufferSubData(GL_ARRAY_BUFFER, 0,
                 sizeof(points), points);
glBufferSubData(GL ARRAY BUFFER, sizeof(points),
  sizeof(colors), colors);
```



Connecting Vertex Shaders with Geometry

- Application vertex data enters the OpenGL pipeline through the vertex shader
- Need to connect vertex data to shader variables
 - requires knowing the attribute location
- Attribute location can either be queried by calling glGetVertexAttribLocation()

Vertex Array Code

```
// set up vertex arrays (after shaders are loaded)
GLuint vPosition = glGetAttribLocation(program,
  "vPosition");
glEnableVertexAttribArray(vPosition);
glVertexAttribPointer(vPosition, 4, GL FLOAT,
  GL_FALSE, 0, BUFFER_OFFSET(0));
GLuint vColor = glGetAttribLocation(program,
  "vColor");
glEnableVertexAttribArray(vColor);
glVertexAttribPointer(vColor, 4, GL FLOAT,
  GL FALSE, 0, BUFFER OFFSET(sizeof(points)));
```

Drawing Geometric Primitives

- For contiguous groups of vertices glDrawArrays(GL_TRIANGLES, 0, NumVertices);
- Usually invoked in display callback
- Initiates vertex shader

Shaders and GLSL

Scalar types: float, int, bool

Vector types: vec2, vec3, vec4

ivec2, ivec3, ivec4

bvec2, bvec3, bvec4

Matrix types: mat2, mat3, mat4

Texture sampling: sampler1D, sampler2D, sampler3D, samplerCube

C++ style constructors: vec3 a = vec3(1.0, 2.0, 3.0);

- Standard C/C++ arithmetic and logic operators
- Operators overloaded for matrix and vector operations

```
mat4 m;
vec4 a, b, c;
b = a*m;
c = m*a;
```

Components and Swizzling

```
For vectors can use [], xyzw, rgba or stpq

Example:

vec3 v;

v[1], v.y, v.g, v.t all refer to the same element

Swizzling:

vec3 a, b;

a.xy = b.yx;
```

- in, out
 - Copy vertex attributes and other variables to/from shaders
 - in vec2 tex_coord;
 - out vec4 color;
- Uniform: variable from application
 - uniform float time;
 - uniform vec4 rotation;

Flow Control

- if
- if else
- expression ? true-expression : false-expression
- while, do while
- for



- Built in
 - Arithmetic: sqrt, power, abs
 - Trigonometric: sin, asin
 - Graphical: length, reflect
- User defined

Built-in Variables

- gl_Position: output position from vertex shader
- gl_FragColor: output color from fragment shader
 - Only for ES, WebGL and older versions of GLSL
 - Present version use an out variable

Simple Vertex Shader for Cube

```
in vec4 vPosition;
in vec4 vColor;
out vec4 color;

void main() {
    color = vColor;
    gl_Position = vPosition;
}
```

The Simplest Fragment Shader

```
in vec4 color;
out vec4 FragColor;

void main() {
    FragColor = color;
}
```



Getting Shaders into OpenGL

- Shaders need to be compiled and linked to form an executable shader program
- OpenGL provides the compiler and linker
- A program must contain
 - vertex and fragment shaders
 - other shaders are optional

Create Program

glCreateProgram()

Create Shader

glCreateShader()

Load Shader Source

glShaderSource()

Compile Shader

glCompileShader()

Attach Shader to Program

glAttachShader()

Link Program

glLinkProgram()

Use Program

glUseProgram()

These steps need to be repeated for each type of shader in the shader

program

- We've created a routine for this course to make it easier to load your shaders
 - available at course website

- InitShaders takes two filenames
 - vFile for the vertex shader
 - fFile for the fragment shader
- Fails if shaders don't compile, or program doesn't link



Associating Shader Variables and Data

- Need to associate a shader variable with an OpenGL data source
 - vertex shader attributes → app vertex attributes
 - shader uniforms → app provided uniform values
- OpenGL relates shader variables to indices for the app to set
- Two methods for determining variable/index association
 - specify association before program linkage
 - query association after program linkage

Determining Locations After Linking

Assumes you already know the variables' name

```
GLint idx =
  glGetAttribLocation(program, "name");

GLint idx =
  glGetUniformLocation(program, "name");
```

Initializing Uniform Variable Values

```
Uniform Variables
  glUniform4f(index, x, y, z, w);

Glboolean transpose = GL_TRUE;
  // Since we're C programmers
Glfloat mat[3][4][4] = { ... };

glUniformMatrix4fv(index, 3, transpose, mat);
```

Finishing the Cube Program

```
int main(int argc, char **argv) {
glutInit(&argc, argv);
glutInitDisplayMode(GLUT_RGBA | GLUT_DOUBLE |
  GLUT DEPTH);
  glutInitWindowSize(512, 512);
 glutCreateWindow("Color Cube");
  glewInit();
  init();
  glutDisplayFunc(display);
  glutKeyboardFunc(keyboard);
  glutMainLoop();
  return 0;
```

Cube Program GLUT Callbacks

```
void display(void) {
   glClear(GL_COLOR_BUFFER_BIT | GL_DEPTH_BUFFER_BIT);
   glDrawArrays(GL_TRIANGLES, 0, NumVertices);
   glutSwapBuffers();
void keyboard(unsigned char key, int x, int y) {
    switch( key ) {
        case 033: case 'q': case 'Q':
            exit( EXIT_SUCCESS );
            break;
```



Vertex Shader Examples

- A vertex shader is initiated by each vertex output by glDrawArrays()
- A vertex shader must output a position in clip coordinates to the rasterizer
- Basic uses of vertex shaders
 - Transformations
 - Lighting
 - Moving vertex positions

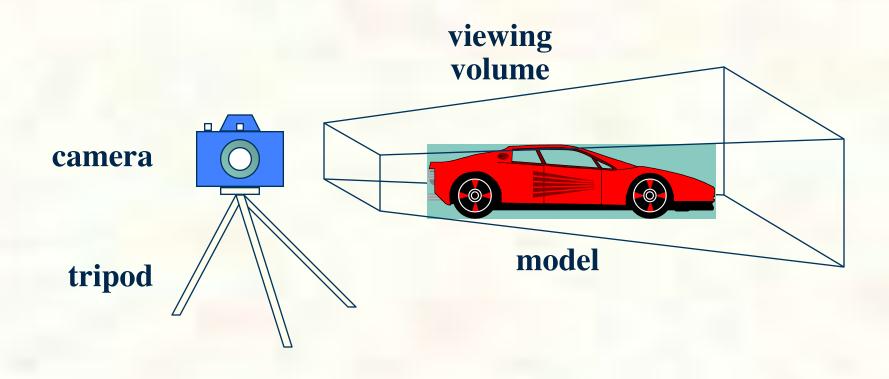


Transformations



Camera Analogy

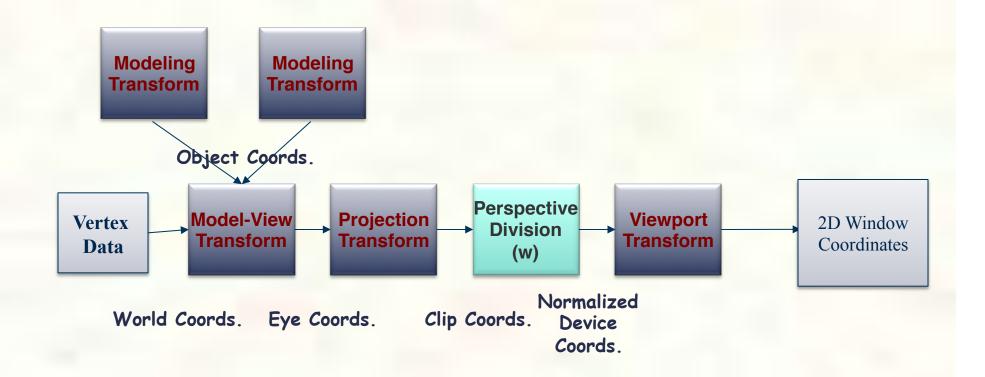
3D is just like taking a photograph (lots of photographs!)





Transformations

- Transformations take us from one "space" to another
 - All of our transforms are 4×4 matrices





Camera Analogy Transform Sequence

- Modeling transformations
 - assemble the world and move the objects
- Viewing transformations
 - define position and orientation of the viewing volume in the world
- Projection transformations
 - adjust the lens of the camera
- Viewport transformations
 - enlarge or reduce the physical photograph



3D Homogeneous Transformations

- A vertex is transformed by 4×4 matrices
 - all affine operations are matrix multiplications
 - all matrices are stored column-major in OpenGL
 - this is opposite of what "C" programmers expect

- matrices are always post-multiplied
- product of matrix and vector is

 $M\bar{v}$

$$\mathbf{M} = \begin{bmatrix} m_0 & m_4 & m_8 & m_{12} \\ m_1 & m_5 & m_9 & m_{13} \\ m_2 & m_6 & m_{10} & m_{14} \\ m_3 & m_7 & m_{11} & m_{15} \end{bmatrix}$$



- Set up a viewing frustum to specify how much of the world we can see
- Done in two steps
 - specify the size of the frustum (projection transform)
 - specify its location in space (model-view transform)
- Anything outside of the viewing frustum is clipped
 - primitive is either modified or discarded (if entirely outside frustum)



View Specification (cont'd)

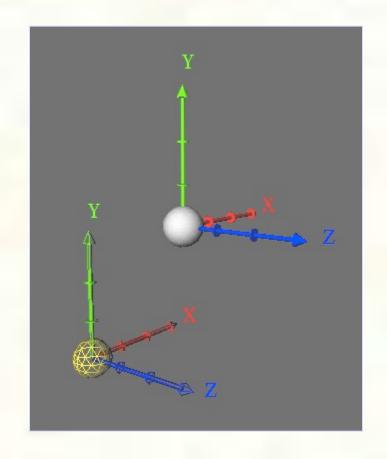
- OpenGL projection model uses eye coordinates
 - the "eye" is located at the origin
 - looking down the -z axis
- Projection matrices use a six-plane model:
 - near (image) plane and far (infinite) plane
 - both are distances from the eye (positive values)
 - enclosing planes
 - top & bottom, left & right

Viewing Transformations

- Position the camera/eye in the scene
- To "fly through" a scene
 - change viewing transformation and redraw scene
- LookAt(eye_x, eye_y, eye_z, look_x, look_y, look_z, up_x, up_y, up_z)
 - up vector determines unique orientation
 - careful of degenerate positions

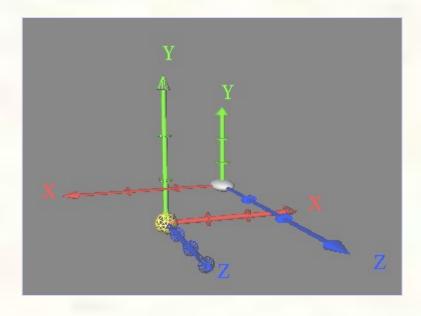
Move object or change frame origin

$$T(t_x, t_y, t_z) = \begin{pmatrix} 1 & 0 & 0 & t_x \\ 0 & 1 & 0 & t_y \\ 0 & 0 & 1 & t_z \\ 0 & 0 & 0 & 1 \end{pmatrix}$$



Stretch, mirror or decimate a coordinate direction

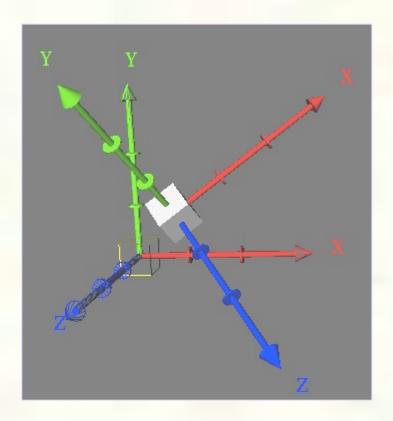
$$S(s_x, s_y, s_z) = \begin{pmatrix} s_x & 0 & 0 & 0 \\ 0 & s_y & 0 & 0 \\ 0 & 0 & s_z & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$



Note, there's a translation applied here to make things easier to see



Rotate coordinate system about an axis in space



Note, there's a translation applied here to make things easier to see

Vertex Shader for Cube Rotation

```
in vec4 vPosition;
in vec4 vColor;
out vec4 color;
uniform vec3 theta;
void main() {
    // Compute the sines and cosines of theta for
    // each of the three axes in one computation.
    vec3 angles = radians(theta);
    vec3 c = cos(angles);
    vec3 s = sin(angles);
```

Vertex Shader for Cube Rotation

```
// Remember: these matrices are column-major
mat4 rx = mat4(1.0, 0.0, 0.0, 0.0,
               0.0, c.x, s.x, 0.0,
               0.0, -s.x, c.x, 0.0,
               0.0, 0.0, 0.0, 1.0);
mat4 ry = mat4(c.y, 0.0, -s.y, 0.0,
               0.0, 1.0, 0.0, 0.0,
               s.y, 0.0, c.y, 0.0,
               0.0, 0.0, 0.0, 1.0);
```

Vertex Shader for Cube Rotation

Sending Angles from Application

```
// compute angles using mouse and idle callbacks
GLuint theta; // theta uniform location
vec3 Theta; // Axis angles

void display(void) {
   glClear(GL_COLOR_BUFFER_BIT | GL_DEPTH_BUFFER_BIT);
   glUniform3fv(theta, 1, Theta);
   glDrawArrays(GL_TRIANGLES, 0, NumVertices);

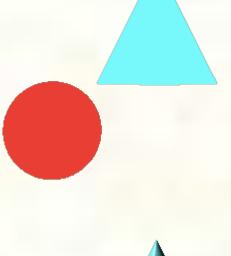
   glutSwapBuffers();
}
```

Vertex Lighting



Lighting Principles

- Lighting simulates how objects reflect light
 - material composition of object
 - light's color and position
 - global lighting parameters
- Lighting functions deprecated in 3.1
- Can implement in
 - Application (per vertex)
 - Vertex or fragment shaders



Modified Phong Model

- Computes a color or shade for each vertex using a lighting model (the modified Phong model) that takes into account
 - Diffuse reflections
 - Specular reflections
 - Ambient light
 - Emission
- Vertex shades are interpolated across polygons by the rasterizer

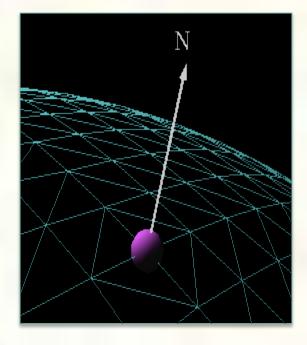
- The model is a balance between simple computation and physical realism
- The model uses
 - Light positions and intensities
 - Surface orientation (normals)
 - Material properties (reflectivity)
 - Viewer location
- Computed for each source and each color component



- Modified Phong lighting model
 - Computed at vertices
- Lighting contributors
 - Surface material properties
 - Light properties
 - Lighting model properties



- Normals define how a surface reflects light
 - Application usually provides normals as a vertex atttribute
 - Current normal is used to compute vertex's color
 - Use unit normals for proper lighting
 - scaling affects a normal's length



Define the surface properties of a primitive

Property	Description
Diffuse	Base object color
Specular	Highlight color
Ambient	Low-light color
Emission	Glow color
Shininess	Surface smoothness

you can have separate materials for front and back

```
// vertex shader
in vec4 vPosition;
in vec3 vNormal;
out vec4 color;

uniform vec4 AmbientProduct, DiffuseProduct,
    SpecularProduct;
uniform mat4 ModelView;
uniform mat4 Projection;
uniform vec4 LightPosition;
uniform float Shininess;
```

Adding Lighting to Cube

```
void main() {
    // Transform vertex position into eye coordinates
    vec3 pos = (ModelView * vPosition).xyz;

    vec3 L = normalize(LightPosition.xyz - pos);
    vec3 E = normalize(-pos);
    vec3 H = normalize(L + E);

    // Transform vertex normal into eye coordinates
    vec3 N = normalize(ModelView * vec4(vNormal, 0.0)).xyz;
```

Adding Lighting to Cube

```
// Compute terms in the illumination equation
   vec4 ambient = AmbientProduct;
   float Kd = max(dot(L, N), 0.0);
   vec4 diffuse = Kd*DiffuseProduct;
   float Ks = pow(max(dot(N, H), 0.0), Shininess);
   vec4 specular = Ks * SpecularProduct;
    if(dot(L, N) < 0.0)
        specular = vec4(0.0, 0.0, 0.0, 1.0)
   gl Position = Projection * ModelView * vPosition;
   color = ambient + diffuse + specular;
   color.a = 1.0;
```

Shader Examples



- A shader that's executed for each "potential" pixel
 - fragments still need to pass several tests before making it to the framebuffer
- There are lots of effects we can do in fragment shaders
 - Per-fragment lighting
 - Bump Mapping
 - Environment (Reflection) Maps



Per Fragment Lighting

- Compute lighting using same model as for per vertex lighting but for each fragment
- Normals and other attributes are sent to vertex shader and output to rasterizer
- Rasterizer interpolates and provides inputs for fragment shader



- Vertex Shaders
 - Moving vertices: height fields
 - Per vertex lighting: height fields
 - Per vertex lighting: cartoon shading
- Fragment Shaders
 - Per vertex vs. per fragment lighting: cartoon shader
 - Samplers: reflection Map
 - Bump mapping

Height Fields

- A height field is a function y = f(x, z) where the y value represents a quantity such as the height above a point in the x-z plane.
- Heights fields are usually rendered by sampling the function to form a rectangular mesh of triangles or rectangles from the samples $y_{ij} = f(x_i, z_j)$

Displaying a Height Field

Form a quadrilateral mesh

```
for(i=0;i<N;i++) for(j=0;j<N;j++) data[i][j]=f(i, j, time);

vertex[Index++] = vec3((float)i/N, data[i][j], (float)j/N);

vertex[Index++] = vec3((float)i/N, data[i][j], (float)(j+1)/N);

vertex[Index++] = vec3((float)(i+1)/N, data[i][j], (float)(j+1)/N);

vertex[Index++] = vec3((float)(i+1)/N, data[i][j], (float)(j)/N);</pre>
```

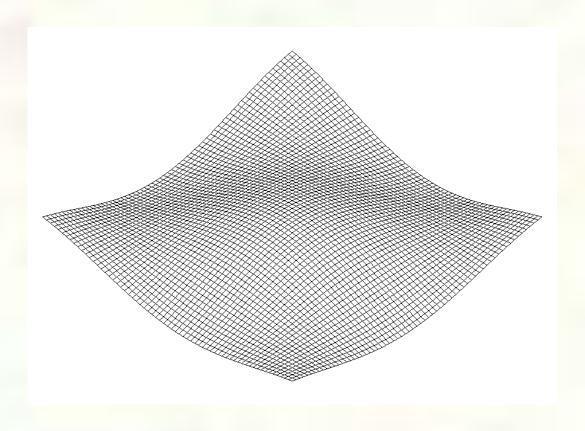
Display each quad using

```
for(i=0;i<NumVertices ;i+=4) glDrawArrays(GL_LINE_LOOP, 4*i, 4);</pre>
```

Time Varying Vertex Shader

```
in vec4 vPosition;
in vec4 vColor;
uniform float time; /* in milliseconds */
uniform mat4 ModelView, ProjectionMatrix;
void main() {
   vec4 v = vPosition;
   vec4 t = sin(0.001*time + 5.0*v);
   v.y = 0.1*t.x*t.z;
   gl Position = ModelViewProjectionMatrix * t;
```





- Solid Mesh: create two triangles for each quad
- Display with glDrawArrays(GL_TRIANGLES, 0, NumVertices);
- For better looking results, we'll add lighting
- We'll do per-vertex lighting
 - leverage the vertex shader since we'll also use it to vary the mesh in a time-varying way

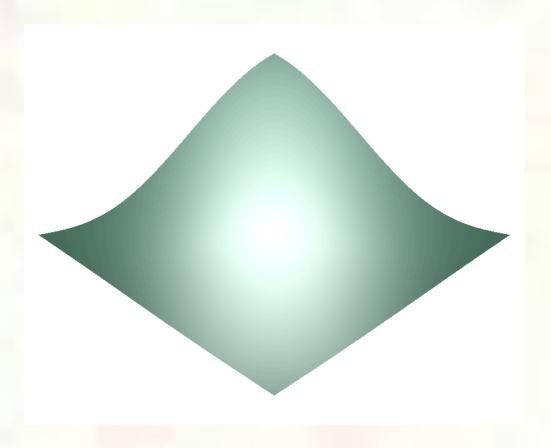
```
uniform float time, shininess;
uniform vec4 vPosition, light_position diffuse_light,
specular_light;
uniform mat4 ModelViewMatrix, ModelViewProjectionMatrix,
    NormalMatrix;
void main() {
  vec4 v = vPosition;
  vec4 t = sin(0.001*time + 5.0*v);
  v.y = 0.1*t.x*t.z;
   gl_Position = ModelViewProjectionMatrix * v;
  vec4 diffuse, specular;
   vec4 eyePosition = ModelViewMatrix * vPosition;
   vec4 eyeLightPos = light_position;
```

Mesh Shader (cont'd)

```
vec3 N = normalize(NormalMatrix * Normal);
vec3 L = normalize(eyeLightPos.xyz - eyePosition.xyz);
vec3 E = -normalize(eyePosition.xyz);
vec3 H = normalize(L + E);

float Kd = max(dot(L, N), 0.0);
float Ks = pow(max(dot(N, H), 0.0), shininess);
diffuse = Kd*diffuse_light;
specular = Ks*specular_light;
color = diffuse + specular;
}
```

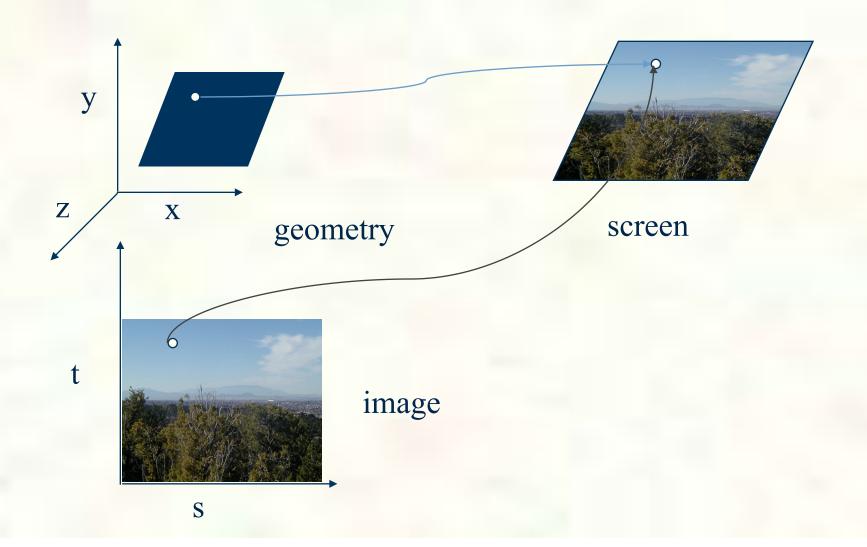




Texture Mapping



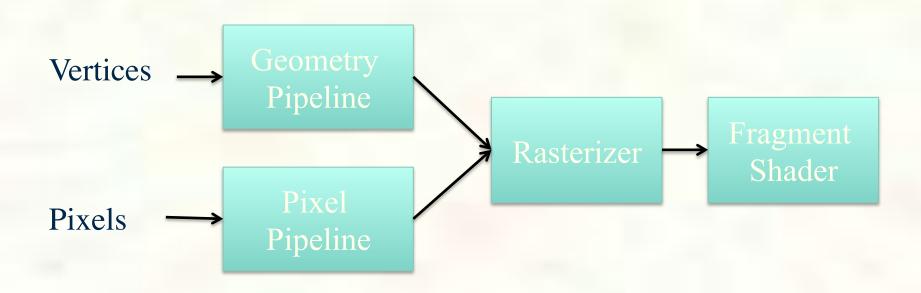
Texture Mapping





Texture Mapping in OpenGL

- Images and geometry flow through separate pipelines that join at the rasterizer
 - "complex" textures do not affect geometric complexity





Applying Textures

- Three basic steps to applying a texture
 - 1. specify the texture
 - read or generate image
 - assign to texture
 - enable texturing
 - 2. assign texture coordinates to vertices
 - 3. specify texture parameters
 - wrapping, filtering

Applying Textures

- 1. specify textures in texture objects
- 2. set texture filter
- 3. set texture function
- 4. set texture wrap mode
- 5. set optional perspective correction hint
- 6. bind texture object
- 7. enable texturing
- 8. supply texture coordinates for vertex



- Have OpenGL store your images
 - one image per texture object
 - may be shared by several graphics contexts
- Generate texture names

```
glGenTextures(n, *texIds);
```

- Create texture objects with texture data and state
 - glBindTexture(target, id);
- Bind textures before using
 - glBindTexture(target, id);

Specifying a Texture Image

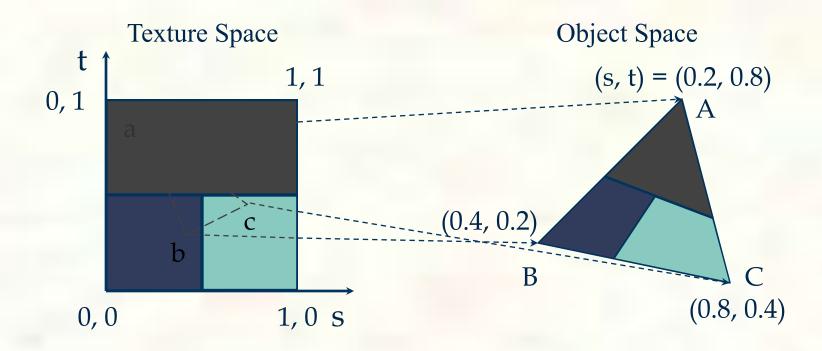
 Define a texture image from an array of texels in CPU memory

```
glTexImage2D(target, level, components,
    w, h, border, format, type, *texels);
```

- Texel colors are processed by pixel pipeline
 - pixel scales, biases and lookups can be done

Mapping a Texture

- Based on parametric texture coordinates
- Coordinates need to be specified at each vertex



Applying the Texture in the Shader

```
// Declare the sampler
uniform sampler2D diffuse_mat;
// GLSL 3.30 has overloaded texture();
// Apply the material color
vec3 diffuse = intensity *
   texture2D(diffuse_mat, coord).rgb;
```

Texturing the Cube

```
// add texture coordinate attribute to quad
function

quad(int a, int b, int c, int d) {
    quad_colors[Index] = vertex_colors[a];
    points[Index] = vertex_positions[a];
    tex_coords[Index] = vec2(0.0, 0.0);
    Index++;
    ... // rest of vertices
}
```

Creating a Texture Image

```
// Create a checkerboard pattern
for (int i = 0; i < 64; i++) {
    for (int j = 0; j < 64; j++) {
        GLubyte c;
        c = (((i \& 0x8) == 0) ^ ((j \& 0x8) == 0)) * 255;
        image[i][j][0] = c;
        image[i][j][1] = c;
        image[i][j][2] = c;
        image2[i][j][0] = c;
        image2[i][j][1] = 0;
        image2[i][j][2] = c;
```

```
in vec4 vPosition;
in vec4 vColor;
in vec2 vTexCoord;
out vec4 color;
out vec2 texCoord;
void main() {
    color = vColor;
    texCoord = vTexCoord;
   gl_Position = vPosition;
```

```
in vec4 color;
in vec2 texCoord;
out vec4 FragColor;
uniform sampler texture;

void main() {
   FragColor = color * texture(texture, texCoord);
}
```



Next class: Visual Perception

■ Topic:

How does the human visual system?
How do humans perceive color?
How do we represent color in computations?

■ Read:

- Glassner, Principles of Digital Image Synthesis, pp. 5-32. [Course reader pp.1-28]
- Watt, Chapter 15.
- Brian Wandell. Foundations of Vision. Sinauer Associates, Sunderland, MA, pp. 45-50 and 69-97, 1995.

[Course reader pp. 29-34 and pp. 35-63]