Plow States Chart

START

xx/0

x0/1

Init

always on
Sim_Start

xx/1

Plow
Open

01/0

10/1

Plow
Closed

0x/0

Legend

input: front sensor
        back sensor

output: plow motor
        (high->open
        low->closed)

(backsensor)(frontsensor)/(plow motor)