Практическая работа №9

Density-Based Clustering

Теоретические сведения

Most of the traditional clustering techniques, such as k-means, hierarchical and fuzzy clustering, can be used to group data without supervision.

However, when applied to tasks with arbitrary shape clusters, or clusters within cluster, the traditional techniques might be unable to achieve good results. That is, elements in the same cluster might not share enough similarity or the performance may be poor. Additionally, Density-based Clustering locates regions of high density that are separated from one another by regions of low density. Density, in this context, is defined as the number of points within a specified radius.

In this section, the main focus will be manipulating the data and properties of DBSCAN and observing the resulting clustering.

Большинство традиционных методов кластеризации, таких как метод k-средних, иерархическая и нечеткая кластеризация, можно использовать для группировки данных без контроля.

Однако, при применении к задачам с кластерами произвольной формы или кластерами внутри кластера традиционные методы могут не дать хороших результатов. То есть элементы в одном кластере могут иметь недостаточное сходство или производительность может быть низкой.

Кроме того, кластеризация на основе плотности находит области с высокой плотностью, которые отделены друг от друга областями с низкой плотностью. Плотность в данном контексте определяется как количество точек в пределах заданного радиуса.

В этом разделе основное внимание будет уделено управлению данными и свойствами DBSCAN и наблюдению за результирующей кластеризацией.

Программа работы

Import the following libraries:

- **numpy as np**
- **DBSCAN** from **sklearn.cluster**
- **make_blobs** from **sklearn.datasets.samples_generator**
- **StandardScaler** from **sklearn.preprocessing**
- **matplotlib.pyplot as plt**

Remember **%matplotlib inline** to display plots

In [1]:
```
# Notice: For visualization of map, you need basemap package.
# if you dont have basemap install on your machine,
# you can use the following line to install it
!pip -q install basemap --user
# from Anaconda Prompt
# !conda install -c conda-forge basemap-data-hires
# Notice: you maight have to refresh your page and re-run
# the notebook after installation
```

In [2]:
```
import numpy as np
from sklearn.cluster import DBSCAN
# https://stackoverflow.com/questions/65898399/no-module-named-sklearn-datasets-samples-
from sklearn.datasets import make_blobs
from sklearn.preprocessing import StandardScaler
import matplotlib.pyplot as plt
%matplotlib inline
import warnings
warnings.filterwarnings('ignore')
```

Data generation

The function below will generate the data points and requires these inputs:

- **centroidLocation**: Coordinates of the centroids that will generate the random data.
  - Example: input: [[4,3], [2,-1], [-1,4]]
- **numSamples**: The number of data points we want generated, split over the number of centroids (# of centroids defined in centroidLocation)
  - Example: 1500
- **clusterDeviation**: The standard deviation between the clusters. The larger the number, the further the spacing.
  - Example: 0.5

In [3]:
```
def createDataPoints(centroidLocation, numSamples, clusterDeviation):
    # Create random data and store in feature matrix X and response vector y.
    X, y = make_blobs(n_samples=numSamples, centers=centroidLocation,
```

```
                                cluster_std=clusterDeviation)

    # Standardize features by removing the mean and scaling to unit variance
    X = StandardScaler().fit_transform(X)
    return X, y
```

Use **createDataPoints** with the **3 inputs** and store the output into variables **X** and **y**.

In [4]:
```
X, y = createDataPoints([[4,3], [2,-1], [-1,4]] , 1500, 0.5)
```

Basis Idea

DBSCAN stands for Density-Based Spatial Clustering of Applications with Noise. This technique is one of the most common clustering algorithms which works based on density of object. The whole idea is that if a particular point belongs to a cluster, it should be near to lots of other points in that cluster.

It works based on two parameters: Epsilon and Minimum Points
Epsilon determine a specified radius that if includes enough number of points within, we call it dense area
minimumSamples determine the minimum number of data points we want in a neighborhood to define a cluster.

DBSCAN означает: основанная на оценке плотности пространственная кластеризация для применения в задачах с шумом. Этот метод является одним из наиболее распространенных алгоритмов кластеризации, который работает на основе оценки плотности распределения объектов. Вся идея заключается в том, что если определенная точка принадлежит кластеру, она должна находиться рядом со многими другими точками в этом кластере. Он работает на основе двух параметров: Эпсилон и Минимальное количество точек. Эпсилон определяет указанный радиус, который, если он включает в себя достаточное количество точек, мы называем его плотной областью. minimumSamples определяет минимальное количество точек данных, которые мы учитываем в окрестности некоторой базовой точки, чтобы считать это кластером.

In [5]:
```
epsilon = 0.3
minimumSamples = 7
db = DBSCAN(eps=epsilon, min_samples=minimumSamples).fit(X)
labels = db.labels_
labels
```

Out[5]:
```
array([0, 1, 2, ..., 1, 1, 0])
```

Distinguishing Outliers

Lets Replace all elements with 'True' in core_samples_mask that are in the cluster, 'False' if the points are outliers.

In [6]:
```
# First, create an array of booleans using the labels from db.
core_samples_mask = np.zeros_like(db.labels_, dtype=bool)
core_samples_mask[db.core_sample_indices_] = True
core_samples_mask
```

Out[6]:
```
array([ True,  True,  True, ...,  True,  True,  True])
```

In [7]:
```python
# Number of clusters in labels, ignoring noise if present.
n_clusters_ = len(set(labels)) - (1 if -1 in labels else 0)
n_clusters_
```

Out[7]:
```
3
```

In [8]:
```python
# Remove repetition in labels by turning it into a set.
unique_labels = set(labels)
unique_labels
```

Out[8]:
```
{-1, 0, 1, 2}
```

Data visualization

In [9]:
```python
# Create colors for the clusters.
colors = plt.cm.Spectral(np.linspace(0, 1, len(unique_labels)))
colors
```

Out[9]:
```
array([[0.61960784, 0.00392157, 0.25882353, 1.        ],
       [0.99346405, 0.74771242, 0.43529412, 1.        ],
       [0.74771242, 0.89803922, 0.62745098, 1.        ],
       [0.36862745, 0.30980392, 0.63529412, 1.        ]])
```

In [10]:
```python
# Plot the points with colors
for k, col in zip(unique_labels, colors):
    if k == -1:
        # Black used for noise.
        col = 'k'

    class_member_mask = (labels == k)

    # Plot the datapoints that are clustered
    xy = X[class_member_mask & core_samples_mask]
    plt.scatter(xy[:, 0], xy[:, 1],s=50, c=col, marker=u'o', alpha=0.5)

    # Plot the outliers
    xy = X[class_member_mask & ~core_samples_mask]
    plt.scatter(xy[:, 0], xy[:, 1],s=50, c=col, marker=u'o', alpha=0.5)
```

```
*c* argument looks like a single numeric RGB or RGBA sequence, which should be avoided a
s value-mapping will have precedence in case its length matches with *x* & *y*.  Please
use the *color* keyword-argument or provide a 2D array with a single row if you intend t
o specify the same RGB or RGBA value for all points.
*c* argument looks like a single numeric RGB or RGBA sequence, which should be avoided a
s value-mapping will have precedence in case its length matches with *x* & *y*.  Please
use the *color* keyword-argument or provide a 2D array with a single row if you intend t
o specify the same RGB or RGBA value for all points.
*c* argument looks like a single numeric RGB or RGBA sequence, which should be avoided a
s value-mapping will have precedence in case its length matches with *x* & *y*.  Please
use the *color* keyword-argument or provide a 2D array with a single row if you intend t
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use the *color* keyword-argument or provide a 2D array with a single row if you intend t
o specify the same RGB or RGBA value for all points.
*c* argument looks like a single numeric RGB or RGBA sequence, which should be avoided a
s value-mapping will have precedence in case its length matches with *x* & *y*.  Please
use the *color* keyword-argument or provide a 2D array with a single row if you intend t
o specify the same RGB or RGBA value for all points.
*c* argument looks like a single numeric RGB or RGBA sequence, which should be avoided a
s value-mapping will have precedence in case its length matches with *x* & *y*.  Please
use the *color* keyword-argument or provide a 2D array with a single row if you intend t
o specify the same RGB or RGBA value for all points.
```
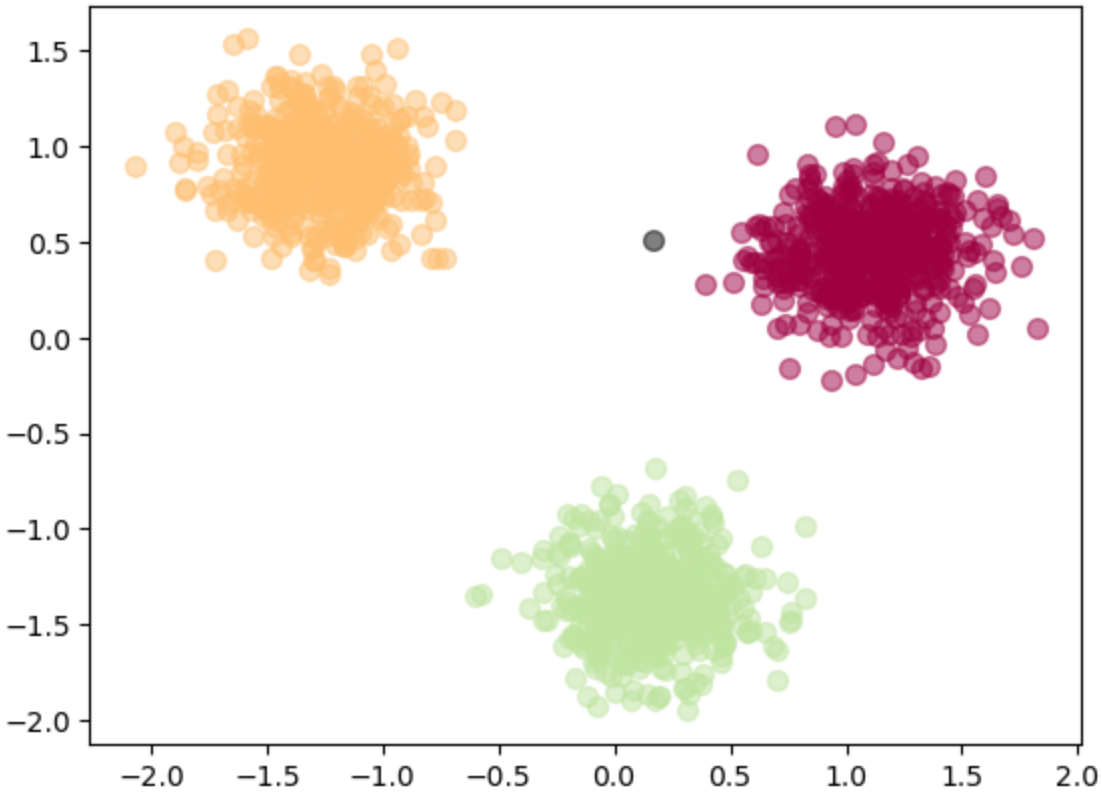



Practice

To better underestand differences between partitional and density-based clusteitng, try to cluster the above dataset into 3 clusters using k-Means.
Notice: do not generate data again, use the same dataset as above.

In [11]:
```
# write your code here
```

Double-click **here** for the solution.

Weather Station Clustering using DBSCAN & scikit-learn

DBSCAN is specially very good for tasks like class identification on a spatial context. The wonderful attribute of DBSCAN algorithm is that it can find out any arbitrary shape cluster without getting affected by noise. For example, this following example cluster the location of weather stations in Canada. DBSCAN can be used here, for instance, to find the group of stations which show the same weather condition. As you can see, it not only finds different arbitrary shaped clusters, can find the denser part of data-centered samples by ignoring less-dense areas or noises.

let's start playing with the data. We will be working according to the following workflow:

About the dataset

Environment Canada Monthly Values for July - 2015

Name in the table	Meaning
Stn_Name	**Station Name**
Lat	**Latitude (North+, degrees)**
Long	**Longitude (West - , degrees)**
Prov	Province
Tm	Mean Temperature (°C)
DwTm	Days without Valid Mean Temperature
D	Mean Temperature difference from Normal (1981-2010) (°C)
Tx	Highest Monthly Maximum Temperature (°C)
DwTx	Days without Valid Maximum Temperature
Tn	Lowest Monthly Minimum Temperature (°C)
DwTn	Days without Valid Minimum Temperature
S	Snowfall (cm)
DwS	Days without Valid Snowfall
S%N	Percent of Normal (1981-2010) Snowfall
P	**Total Precipitation (mm)**
DwP	Days without Valid Precipitation
P%N	Percent of Normal (1981-2010) Precipitation
S_G	Snow on the ground at the end of the month (cm)
Pd	Number of days with Precipitation 1.0 mm or more
BS	Bright Sunshine (hours)
DwBS	Days without Valid Bright Sunshine
BS%	Percent of Normal (1981-2010) Bright Sunshine
HDD	Degree Days below 18 °C
CDD	Degree Days above 18 °C
Stn_No	Climate station identifier (first 3 digits indicate drainage basin, last 4 characters are for sorting alphabetically).
NA	Not Available

1-Download data

To download the data, we will use **!wget** to download it from IBM Object Storage.
Did you know? When it comes to Machine Learning, you will likely be working with large datasets. As a business, where can you host your data? IBM is offering a unique opportunity for businesses, with 10 Tb of IBM Cloud Object Storage: Sign up now for free

In [12]:
```
#!wget -O weather-stations20140101-20141231.csv https://s3-api.us-geo.objectstorage.soft
```

2- Load the dataset

We will import the .csv then we creates the columns for year, month and day.

In [13]:
```
import csv
import pandas as pd
```

```
import numpy as np

filename='weather-stations20140101-20141231.csv'

#Read csv
pdf = pd.read_csv(filename)
pdf.head(5)
```

Out[13]:

	Stn_Name	Lat	Long	Prov	Tm	DwTm	D	Tx	DwTx	Tn	...	DwP	P%N	S_G	Pd	BS	DwBS	BS%	HDD	CDD	Stn_No
0	CHEMAINUS	48.935	123.742	BC	8.2	0.0	NaN	13.5	0.0	1.0	...	0.0	NaN	0.0	12.0	NaN	NaN	NaN	273.3	0.0	1011500
1	COWICHAN LAKE FORESTRY	48.824	124.133	BC	7.0	0.0	3.0	15.0	0.0	-3.0	...	0.0	104.0	0.0	12.0	NaN	NaN	NaN	307.0	0.0	1012040
2	LAKE COWICHAN	48.829	124.052	BC	6.8	13.0	2.8	16.0	9.0	-2.5	...	9.0	NaN	NaN	11.0	NaN	NaN	NaN	168.1	0.0	1012055
3	DISCOVERY ISLAND	48.425	123.226	BC	NaN	NaN	NaN	12.5	0.0	NaN	...	NaN	NaN	NaN	NaN	NaN	NaN	NaN	NaN	NaN	1012475
4	DUNCAN KELVIN CREEK	48.735	123.728	BC	7.7	2.0	3.4	14.5	2.0	-1.0	...	2.0	NaN	NaN	11.0	NaN	NaN	NaN	267.7	0.0	1012573

5 rows × 25 columns

3-Cleaning

Lets remove rows that don't have any value in the **Tm** field.

In [14]:
```
pdf = pdf[pd.notnull(pdf["Tm"])]
pdf = pdf.reset_index(drop=True)
pdf.head(5)
```

Out[14]:

	Stn_Name	Lat	Long	Prov	Tm	DwTm	D	Tx	DwTx	Tn	...	DwP	P%N	S_G	Pd	BS	DwBS	BS%	HDD	CDD	Stn_No
0	CHEMAINUS	48.935	123.742	BC	8.2	0.0	NaN	13.5	0.0	1.0	...	0.0	NaN	0.0	12.0	NaN	NaN	NaN	273.3	0.0	1011500
1	COWICHAN LAKE FORESTRY	48.824	124.133	BC	7.0	0.0	3.0	15.0	0.0	-3.0	...	0.0	104.0	0.0	12.0	NaN	NaN	NaN	307.0	0.0	1012040
2	LAKE COWICHAN	48.829	124.052	BC	6.8	13.0	2.8	16.0	9.0	-2.5	...	9.0	NaN	NaN	11.0	NaN	NaN	NaN	168.1	0.0	1012055
3	DUNCAN KELVIN CREEK	48.735	123.728	BC	7.7	2.0	3.4	14.5	2.0	-1.0	...	2.0	NaN	NaN	11.0	NaN	NaN	NaN	267.7	0.0	1012573
4	ESQUIMALT HARBOUR	48.432	123.439	BC	8.8	0.0	NaN	13.1	0.0	1.9	...	8.0	NaN	NaN	12.0	NaN	NaN	NaN	258.6	0.0	1012710

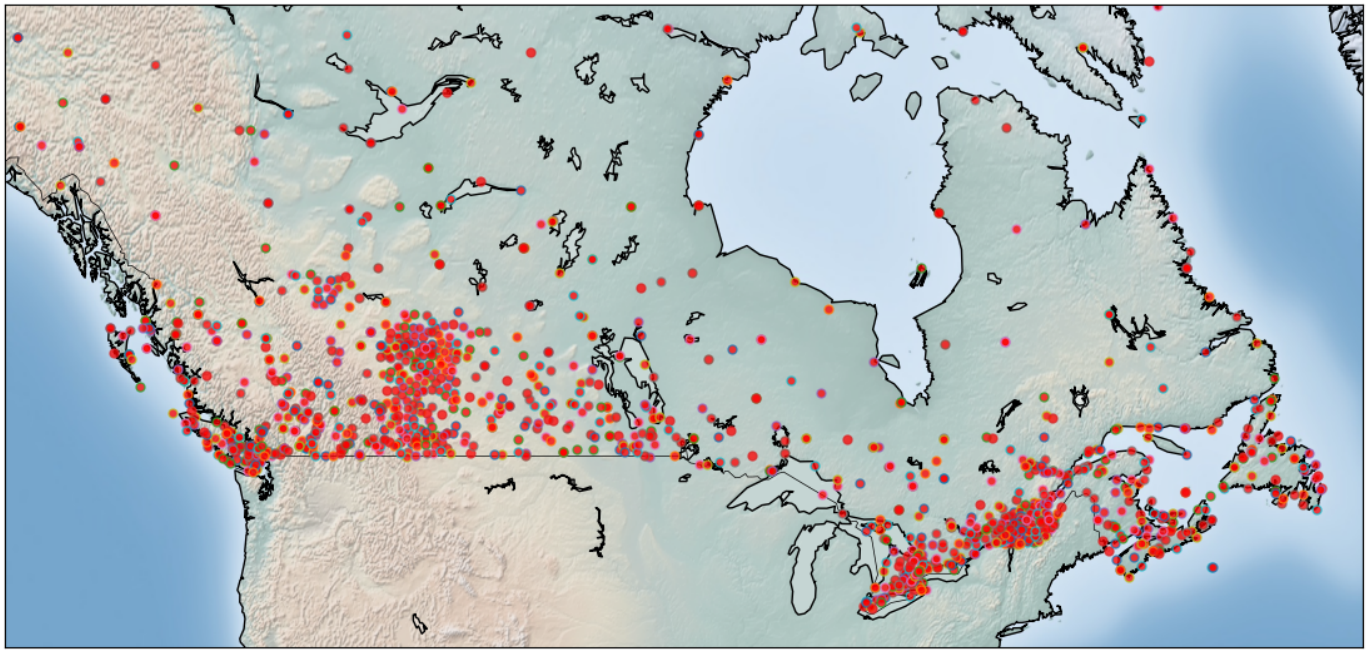
5 rows × 25 columns

4-Visualization

Visualization of stations on map using basemap package. The matplotlib basemap toolkit is a library for plotting 2D data on maps in Python. Basemap does not do any plotting on it’s own, but provides the facilities to transform coordinates to a map projections.
Please notice that the size of each data points represents the average of maximum temperature for each station in a year.

In [15]:

```
# https://stackoverflow.com/questions/52295117/basemap-import-error-in-pycharm-keyerror-
# https://stackoverflow.com/questions/52911232/basemap-library-using-anaconda-jupyter-no
import os
os.environ["PROJ_LIB"] = "J:\Anaconda3\Library\share"; #fixr

from mpl_toolkits.basemap import Basemap
import matplotlib.pyplot as plt
from pylab import rcParams
%matplotlib inline
rcParams['figure.figsize'] = (14,10)

llon=-140
ulon=-50
llat=40
ulat=65

pdf=pdf[(pdf['Long']>llon)&(pdf['Long']<ulon)&(pdf['Lat']>llat)&(pdf['Lat'] < ulat)]

my_map = Basemap(projection='merc',
            resolution = 'l', area_thresh = 1000.0,
            #min longitude (llcrnrlon) and latitude (llcrnrlat)
            llcrnrlon=llon, llcrnrlat=llat,
            #max longitude (urcrnrlon) and latitude (urcrnrlat)
            urcrnrlon=ulon, urcrnrlat=ulat)

my_map.drawcoastlines()
my_map.drawcountries()
# my_map.drawmapboundary()
my_map.fillcontinents(color = 'white', alpha = 0.3)
my_map.shadedrelief()

# To collect data based on stations

xs,ys = my_map(np.asarray(pdf.Long), np.asarray(pdf.Lat))
pdf['xm']= xs.tolist()
pdf['ym'] =ys.tolist()

#Visualization1
for index,row in pdf.iterrows():
#   x,y = my_map(row.Long, row.Lat)
   my_map.plot(row.xm, row.ym,markerfacecolor =([1,0,0]),
               marker='o', markersize= 5, alpha = 0.75)
#plt.text(x,y,stn)
plt.show()
```



5- Clustering of stations based on their location i.e. Lat & Lon

DBSCAN form sklearn library can runs DBSCAN clustering from vector array or distance matrix.
In our case, we pass it the Numpy array Clus_dataSet to find core samples of high density and expands clusters from them.

In [16]:
```
from sklearn.cluster import DBSCAN
import sklearn.utils
from sklearn.preprocessing import StandardScaler
sklearn.utils.check_random_state(1000)
Clus_dataSet = pdf[['xm','ym']]
Clus_dataSet = np.nan_to_num(Clus_dataSet)
Clus_dataSet = StandardScaler().fit_transform(Clus_dataSet)

# Compute DBSCAN
db = DBSCAN(eps=0.15, min_samples=10).fit(Clus_dataSet)
core_samples_mask = np.zeros_like(db.labels_, dtype=bool)
core_samples_mask[db.core_sample_indices_] = True
labels = db.labels_
pdf["Clus_Db"]=labels

realClusterNum=len(set(labels)) - (1 if -1 in labels else 0)
clusterNum = len(set(labels))


# A sample of clusters
pdf[["Stn_Name","Tx","Tm","Clus_Db"]].head(5)
```

Out[16]:

	Stn_Name	Tx	Tm	Clus_Db
0	CHEMAINUS	13.5	8.2	0
1	COWICHAN LAKE FORESTRY	15.0	7.0	0
2	LAKE COWICHAN	16.0	6.8	0
3	DUNCAN KELVIN CREEK	14.5	7.7	0
4	ESQUIMALT HARBOUR	13.1	8.8	0

As you can see for outliers, the cluster label is -1

In [17]:
```
set(labels)
```

Out[17]:
```
{-1, 0, 1, 2, 3, 4}
```

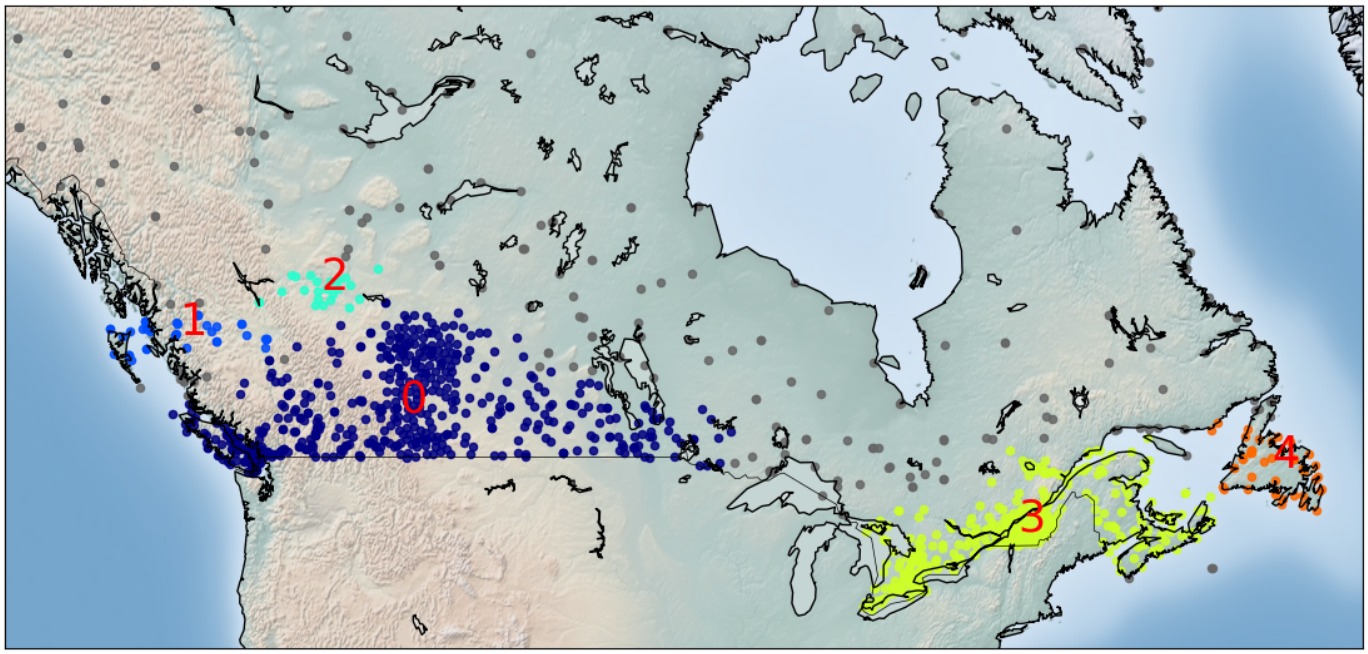
6- Visualization of clusters based on location

Now, we can visualize the clusters using basemap:

In [18]:
```
from mpl_toolkits.basemap import Basemap
import matplotlib.pyplot as plt
from pylab import rcParams
%matplotlib inline
rcParams['figure.figsize'] = (14,10)

my_map = Basemap(projection='merc',
            resolution = 'l', area_thresh = 1000.0,
```

```
            #min longitude (llcrnrlon) and latitude (llcrnrlat)
            llcrnrlon=llon, llcrnrlat=llat,
            #max longitude (urcrnrlon) and latitude (urcrnrlat)
            urcrnrlon=ulon, urcrnrlat=ulat)

my_map.drawcoastlines()
my_map.drawcountries()
#my_map.drawmapboundary()
my_map.fillcontinents(color = 'white', alpha = 0.3)
my_map.shadedrelief()

# To create a color map
colors = plt.get_cmap('jet')(np.linspace(0.0, 1.0, clusterNum))



#Visualization1
for clust_number in set(labels):
    c=(([0.4,0.4,0.4]) if clust_number == -1 else colors[np.int(clust_number)])
    clust_set = pdf[pdf.Clus_Db == clust_number]
    my_map.scatter(clust_set.xm, clust_set.ym, color =c,
                   marker='o', s= 20, alpha = 0.85)
    if clust_number != -1:
        cenx=np.mean(clust_set.xm)
        ceny=np.mean(clust_set.ym)
        plt.text(cenx,ceny,str(clust_number), fontsize=25, color='red',)
        print ("Cluster "+str(clust_number)+', Avg Temp: '+ str(np.mean(clust_set.Tm)))
```

```
Cluster 0, Avg Temp: -5.538747553816046
Cluster 1, Avg Temp: 1.9526315789473685
Cluster 2, Avg Temp: -9.195652173913045
Cluster 3, Avg Temp: -15.300833333333333
Cluster 4, Avg Temp: -7.769047619047619
```



7- Clustering of stations based on their location, mean, max, and min Temperature

In this section we re-run DBSCAN, but this time on a 5-dimensional dataset:

In [19]:
```
from sklearn.cluster import DBSCAN
import sklearn.utils
from sklearn.preprocessing import StandardScaler
sklearn.utils.check_random_state(1000)
```

```
Clus_dataSet = pdf[['xm','ym','Tx','Tm','Tn']]
Clus_dataSet = np.nan_to_num(Clus_dataSet)
Clus_dataSet = StandardScaler().fit_transform(Clus_dataSet)

# Compute DBSCAN
db = DBSCAN(eps=0.3, min_samples=10).fit(Clus_dataSet)
core_samples_mask = np.zeros_like(db.labels_, dtype=bool)
core_samples_mask[db.core_sample_indices_] = True
labels = db.labels_
pdf["Clus_Db"]=labels

realClusterNum=len(set(labels)) - (1 if -1 in labels else 0)
clusterNum = len(set(labels))


# A sample of clusters
pdf[["Stn_Name","Tx","Tm","Clus_Db"]].head(5)
```

Out[19]:

	Stn_Name	Tx	Tm	Clus_Db
0	CHEMAINUS	13.5	8.2	0
1	COWICHAN LAKE FORESTRY	15.0	7.0	0
2	LAKE COWICHAN	16.0	6.8	0
3	DUNCAN KELVIN CREEK	14.5	7.7	0
4	ESQUIMALT HARBOUR	13.1	8.8	0

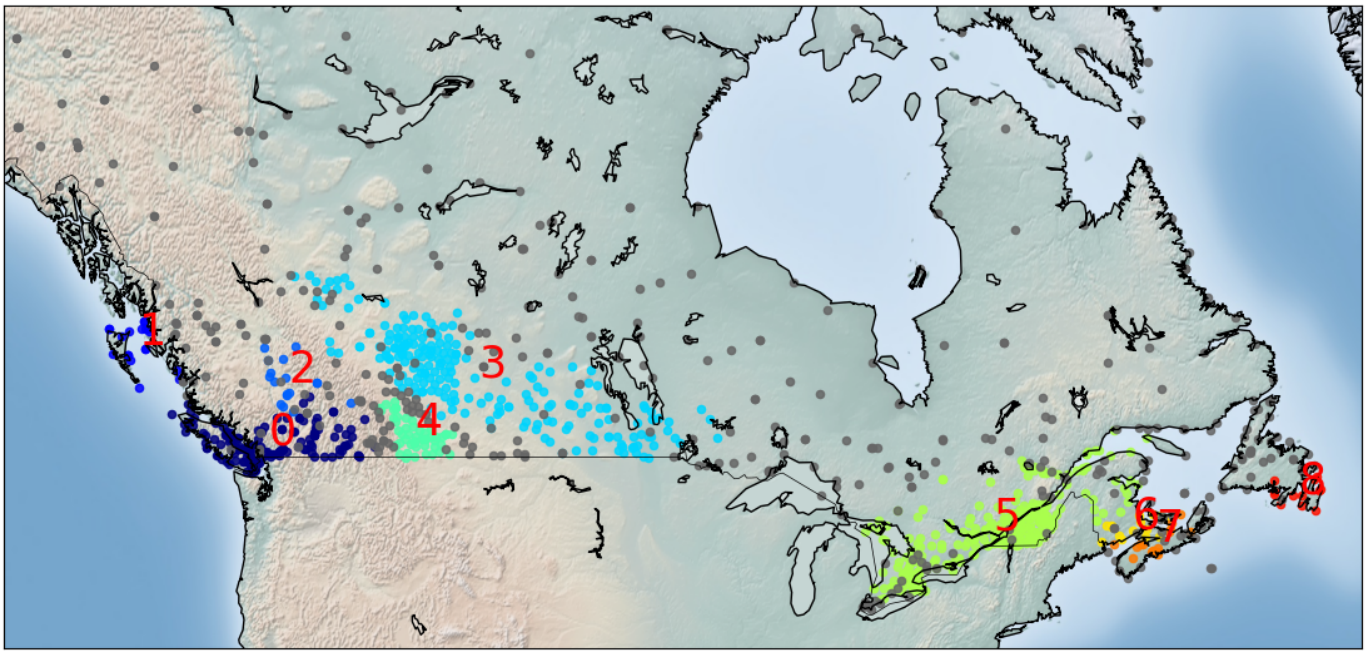
8- Visualization of clusters based on location and Temperature

In [20]:

```
from mpl_toolkits.basemap import Basemap
import matplotlib.pyplot as plt
from pylab import rcParams
%matplotlib inline
rcParams['figure.figsize'] = (14,10)

my_map = Basemap(projection='merc',
            resolution = 'l', area_thresh = 1000.0,
            #min longitude (llcrnrlon) and latitude (llcrnrlat)
            llcrnrlon=llon, llcrnrlat=llat,
            #max longitude (urcrnrlon) and latitude (urcrnrlat)
            urcrnrlon=ulon, urcrnrlat=ulat)

my_map.drawcoastlines()
my_map.drawcountries()
#my_map.drawmapboundary()
my_map.fillcontinents(color = 'white', alpha = 0.3)
my_map.shadedrelief()

# To create a color map
colors = plt.get_cmap('jet')(np.linspace(0.0, 1.0, clusterNum))



#Visualization1
for clust_number in set(labels):
    c=(([0.4,0.4,0.4]) if clust_number == -1 else colors[np.int(clust_number)])
    clust_set = pdf[pdf.Clus_Db == clust_number]
    my_map.scatter(clust_set.xm, clust_set.ym, color =c,
                   marker='o', s= 20, alpha = 0.85)
```

```
    if clust_number != -1:
        cenx=np.mean(clust_set.xm)
        ceny=np.mean(clust_set.ym)
        plt.text(cenx,ceny,str(clust_number), fontsize=25, color='red',)
        print ("Cluster "+str(clust_number)+', Avg Temp: '+ str(np.mean(clust_set.Tm)))
```

```
Cluster 0, Avg Temp: 6.221192052980132
Cluster 1, Avg Temp: 6.790000000000001
Cluster 2, Avg Temp: -0.49411764705882344
Cluster 3, Avg Temp: -13.87720930232558
Cluster 4, Avg Temp: -4.186274509803922
Cluster 5, Avg Temp: -16.301503759398496
Cluster 6, Avg Temp: -13.599999999999998
Cluster 7, Avg Temp: -9.753333333333334
Cluster 8, Avg Temp: -4.258333333333334
```



In [ ]: