

ED5340 - Data Science: Theory and Practise

L14 - Optimization

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Course web page: <https://ed.iitm.ac.in/~raman/datascience.html>

Moodle page: Available at <https://courses.iitm.ac.in/>

Why optimization

- Fundamental to machine and deep learning
- Cost function solving needs optimization (or solve using direct methods)
- Basic differential calculus / linear algebra

Optimization

- Unconstrained (e.g. $\min J(w)$, e.g. $J(w) = w^2$, $J(w) = w^3$, $J(w) = w^2 + 54/w$)
- constrained optimization (e.g. $\min J(w)$, $w > 0$)

Unconstrained optimization

- Single variable (e.g. $\min J(w)$, e.g. $J(w) = w^2$, $J(w) = w^3$, $J(w) = w^2 + 54/w$)
- multivariable (e.g. $\min J(w_0, w_1) = (w_0 - 2)^2 + (w_1 - 2)^2$)

Optimality criteria - single variable

- Single variable (e.g. $J(w) = w^2$, $J(w) = w^3$, $J(w) = w^4$)
- $\min J(w)$
 - The value of w for which the function $J(w)$ has the least (minimum) value
 - Unimodal function
 - Local minimum (in this case, this is also global minimum)

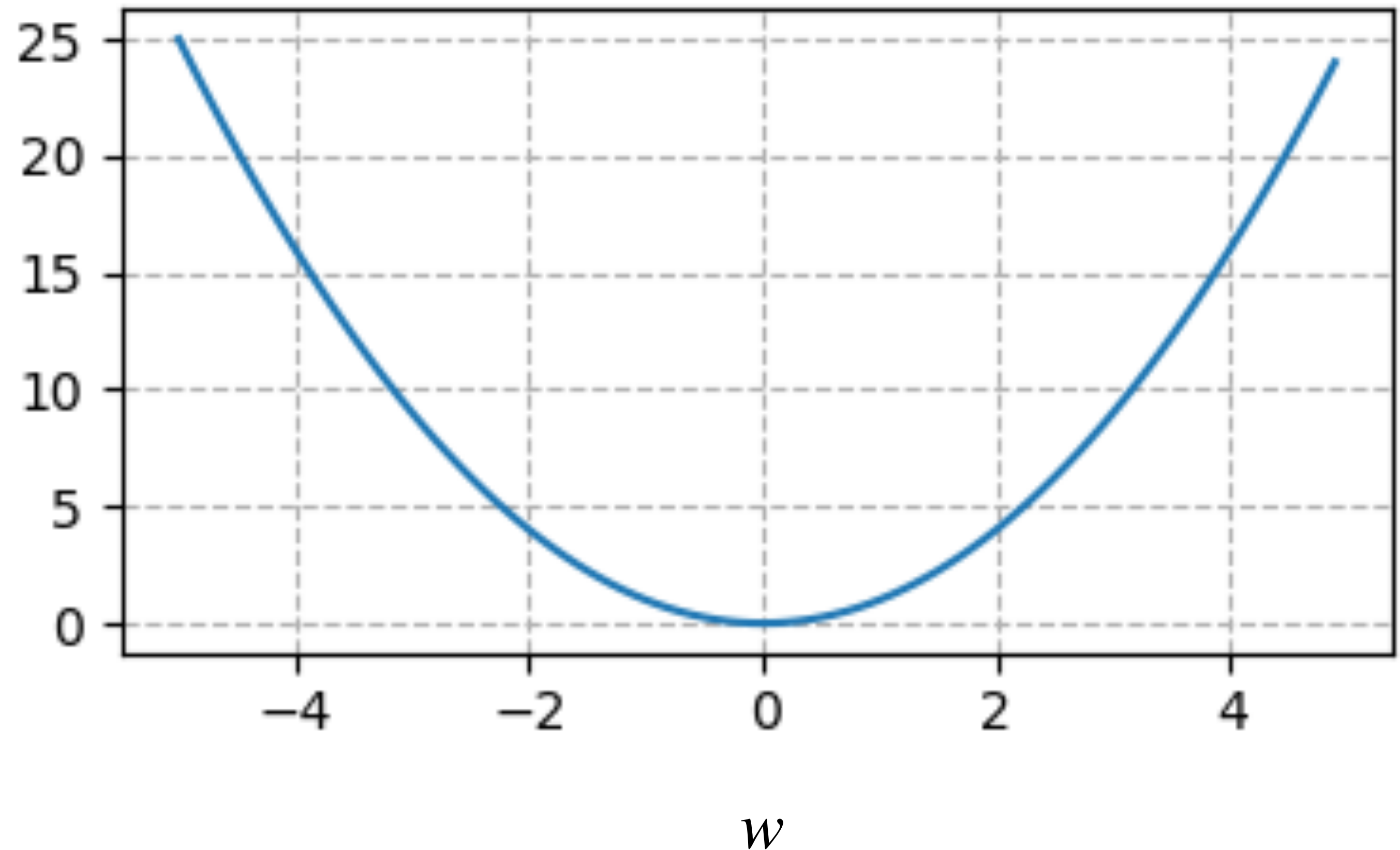
Demo of various power functions

Optimality criteria - single variable

$$J(w) = w^2$$

- $J(w) = w^2$
- $J'(w) = dJ(w)/dw$
- $J''(w) = \frac{d^2 J(w)}{dw^2} = \frac{d}{dw} \left(\frac{dJ}{dw} \right)$

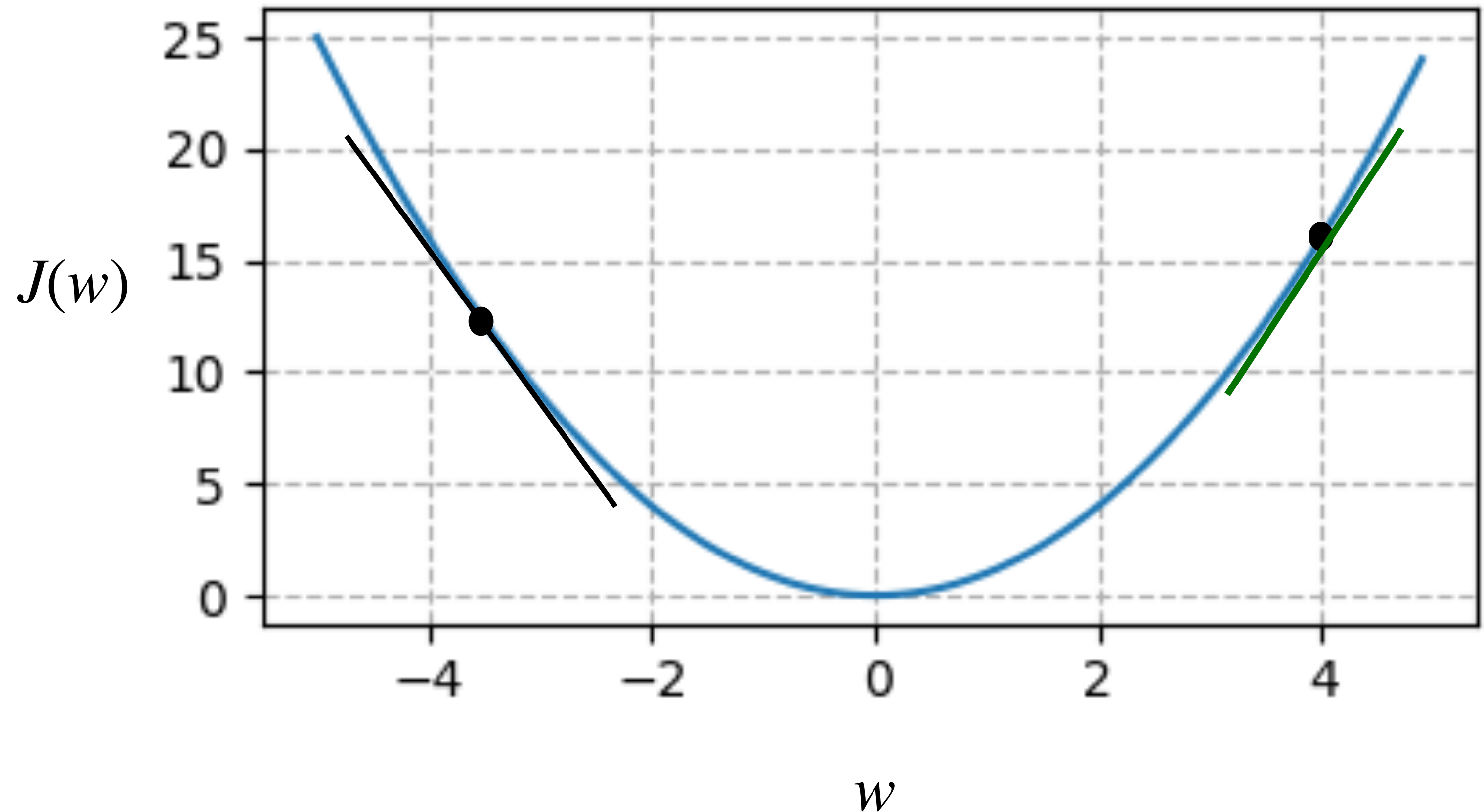
$J(w)$



Optimality criteria - single variable

$$J'(w) = dJ(w)/dw$$

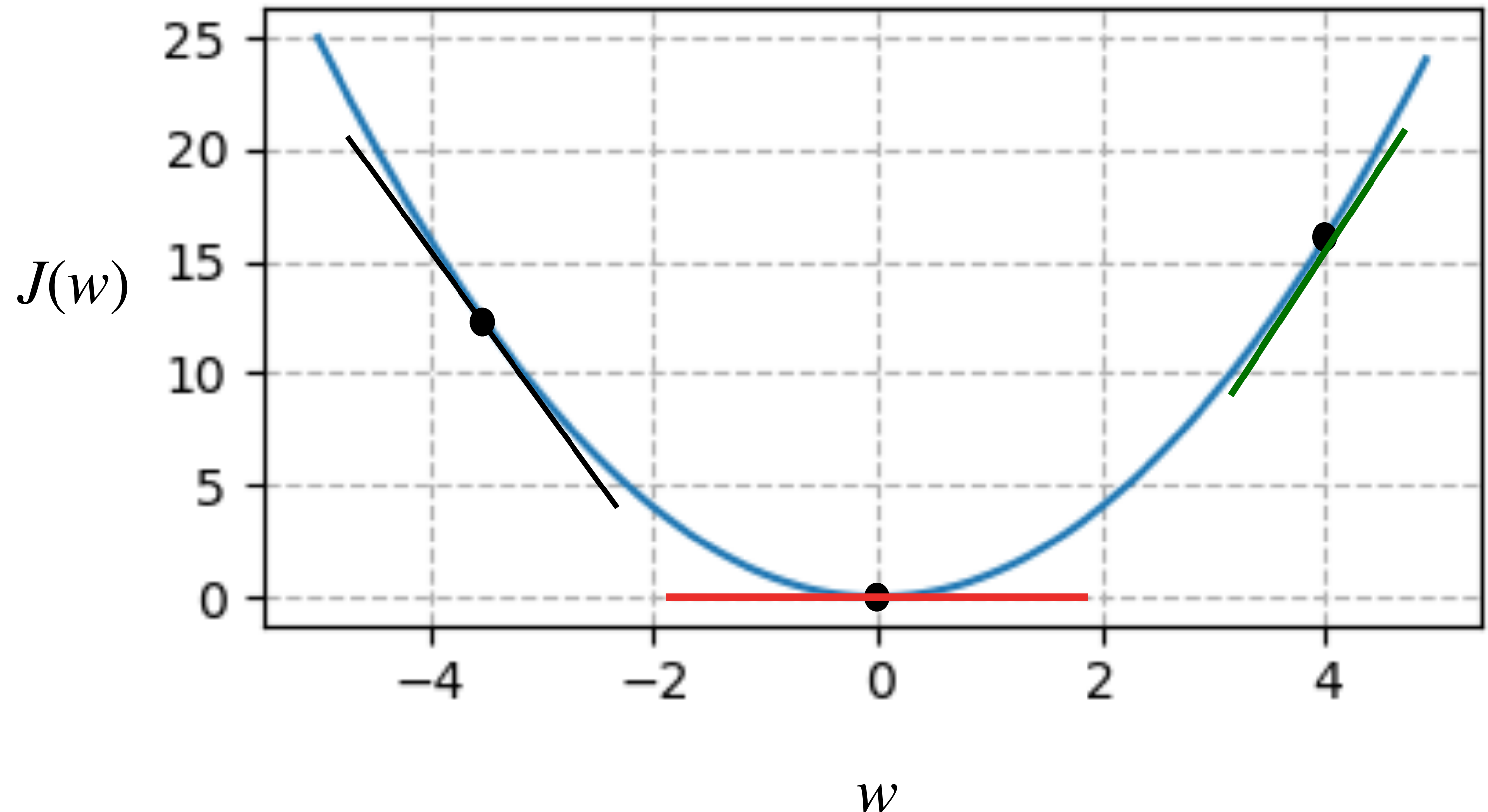
- $J'(w) = dJ(w)/dw$
 - slope / tangent at a point on the curve.
 - Continuous curve



Optimality criteria - single variable

$$J'(w) = dJ(w)/dw$$

- $J'(w) = dJ(w)/dw$
 - slope / tangent at a point on the curve.
- At minimum function value, $J'(w) = 0$
- The corresponding $w = \bar{w}$

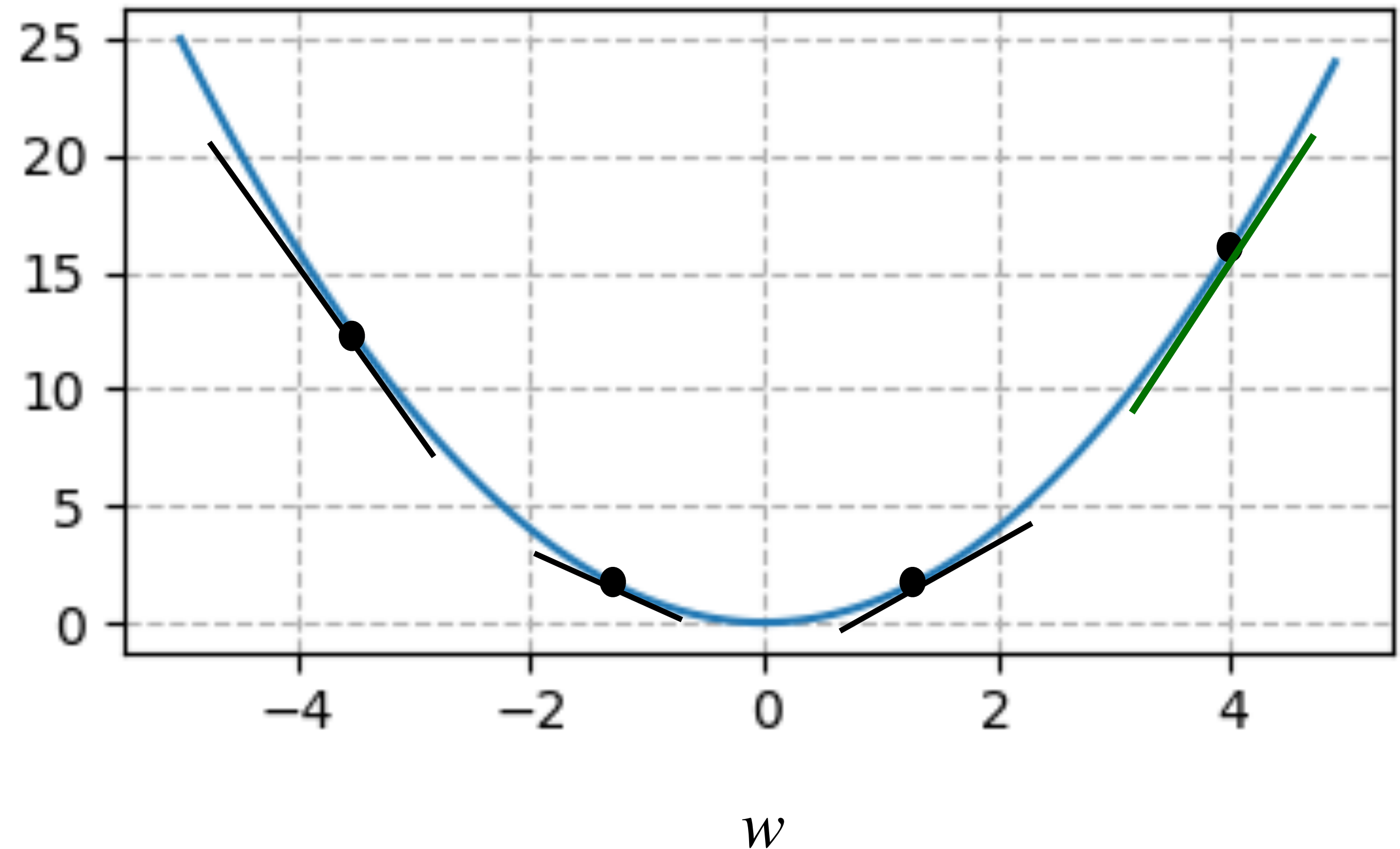


Optimality criteria - single variable

$$J''(w) = \frac{d^2 J(w)}{dw^2} = \frac{d}{dw} \left(\frac{dJ}{dw} \right)$$

- $J''(w) = \frac{d^2 J(w)}{dw^2} = \frac{d}{dw} \left(\frac{dJ}{dw} \right)$ $J(w)$

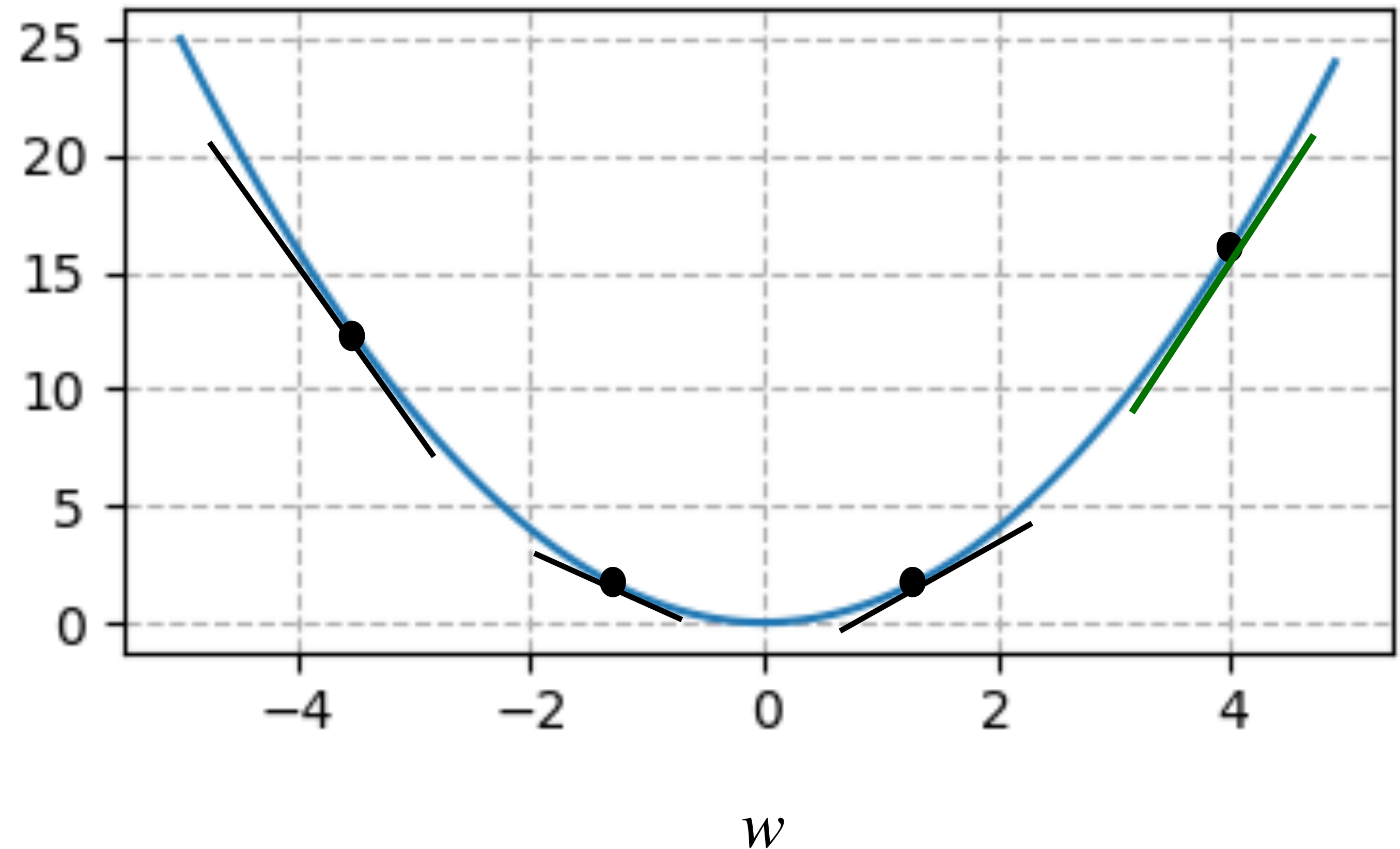
- rate of change of slope / tangent at a point on the curve.



Optimality criteria - single variable

$$J''(w) = \frac{d^2 J(w)}{dw^2} = \frac{d}{dw} \left(\frac{dJ}{dw} \right)$$

- $J''(w) = \frac{d^2 J(w)}{dw^2} = \frac{d}{dw} \left(\frac{dJ}{dw} \right)$
• > 0 in the nbghd of minimum point.



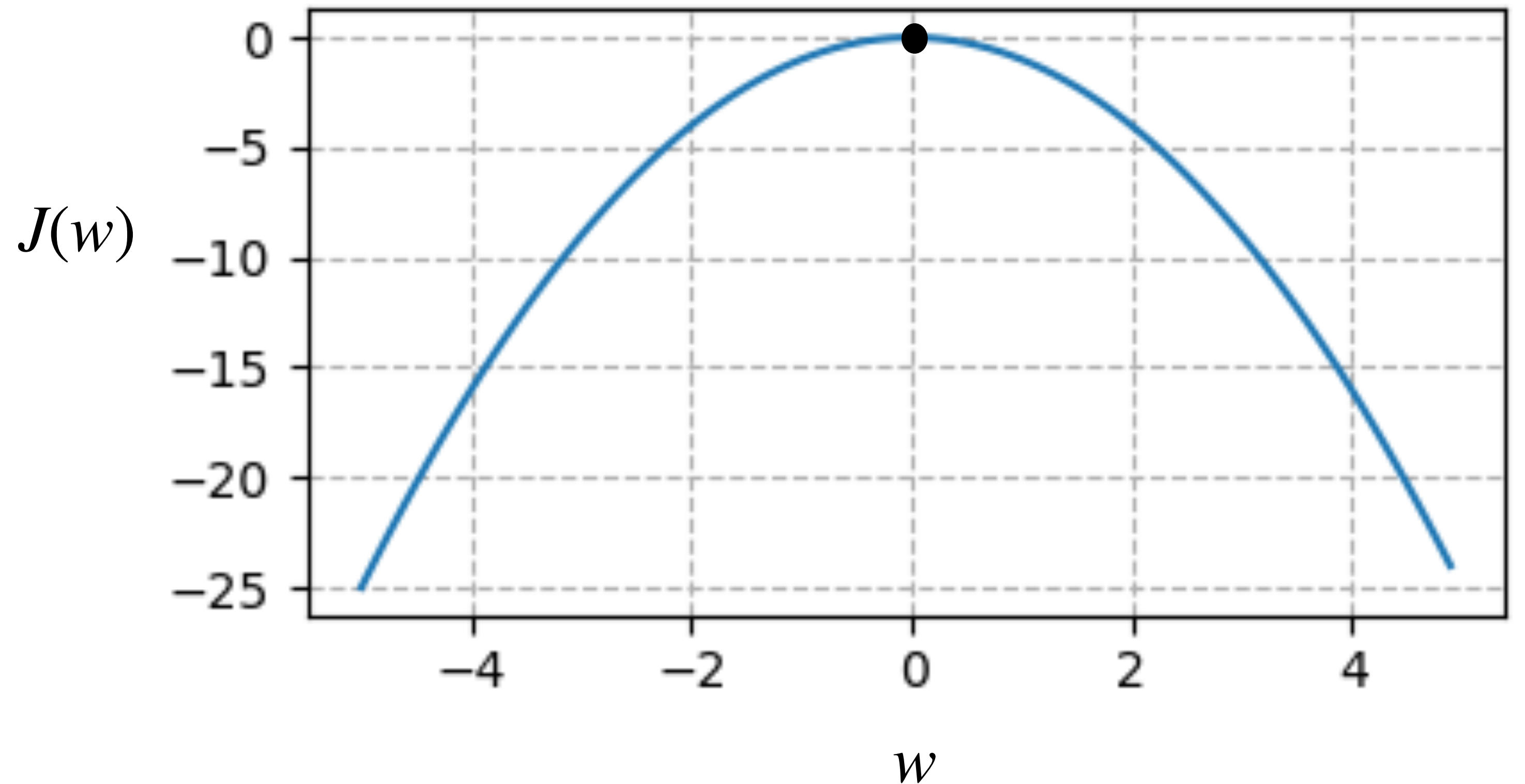
Critical Points

- Minimum
- Maximum
- Inflection

Optimality criteria - Maximum

$$J(w) = -w^2$$

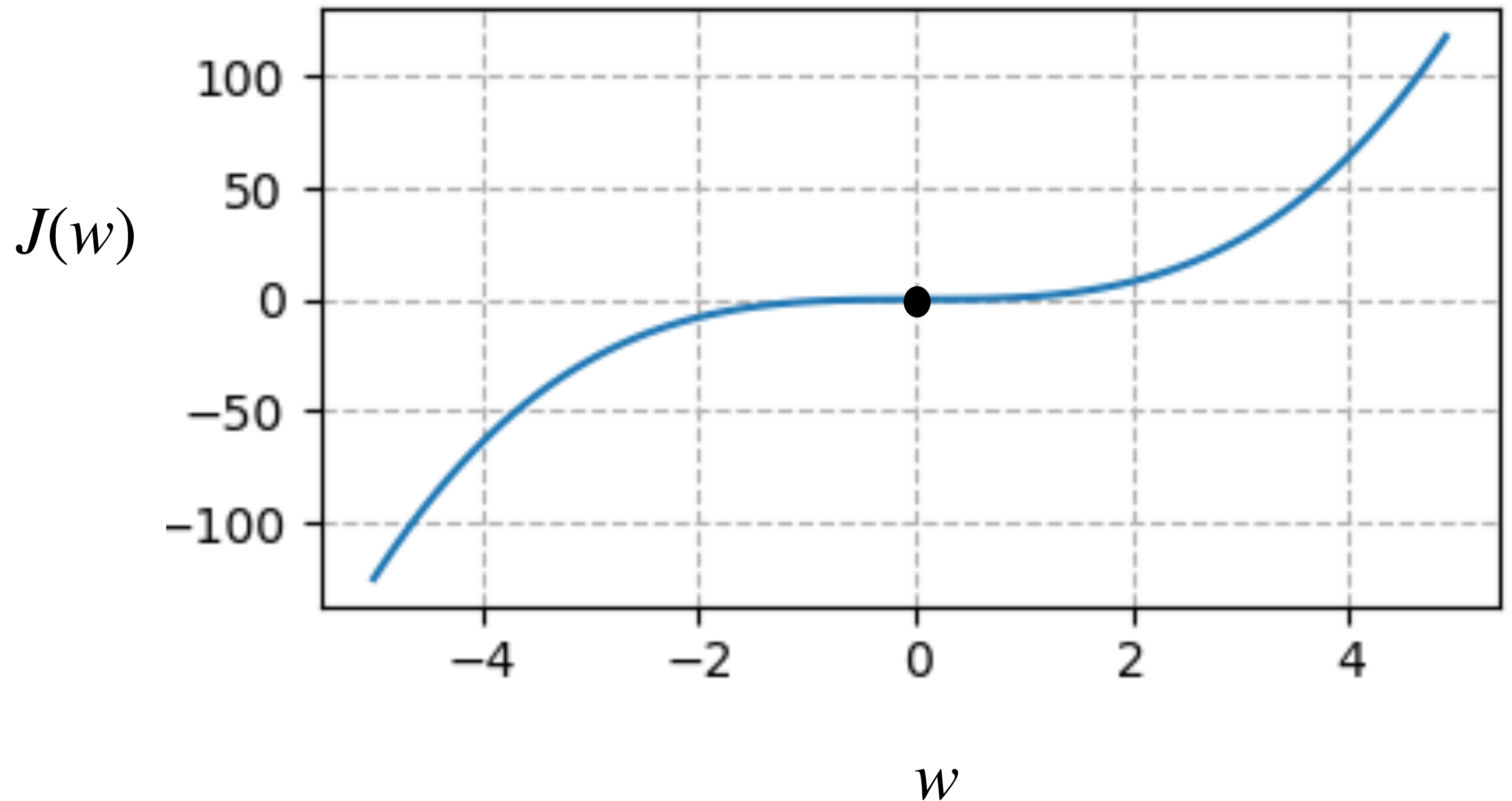
- $J(w) = -w^2$
- $J'(w) = 0$, at $w = \bar{w}$,
- At \bar{w} , $J''(\bar{w}) < 0$



Optimality criteria - Inflection

$$J(w) = w^3$$

- $J(w) = w^3$
- $J'(w) = 0$, at $w = \bar{w}$,
- At \bar{w} , $J''(\bar{w})$ is ?
- At \bar{w} , $J'''(\bar{w})$ is ?

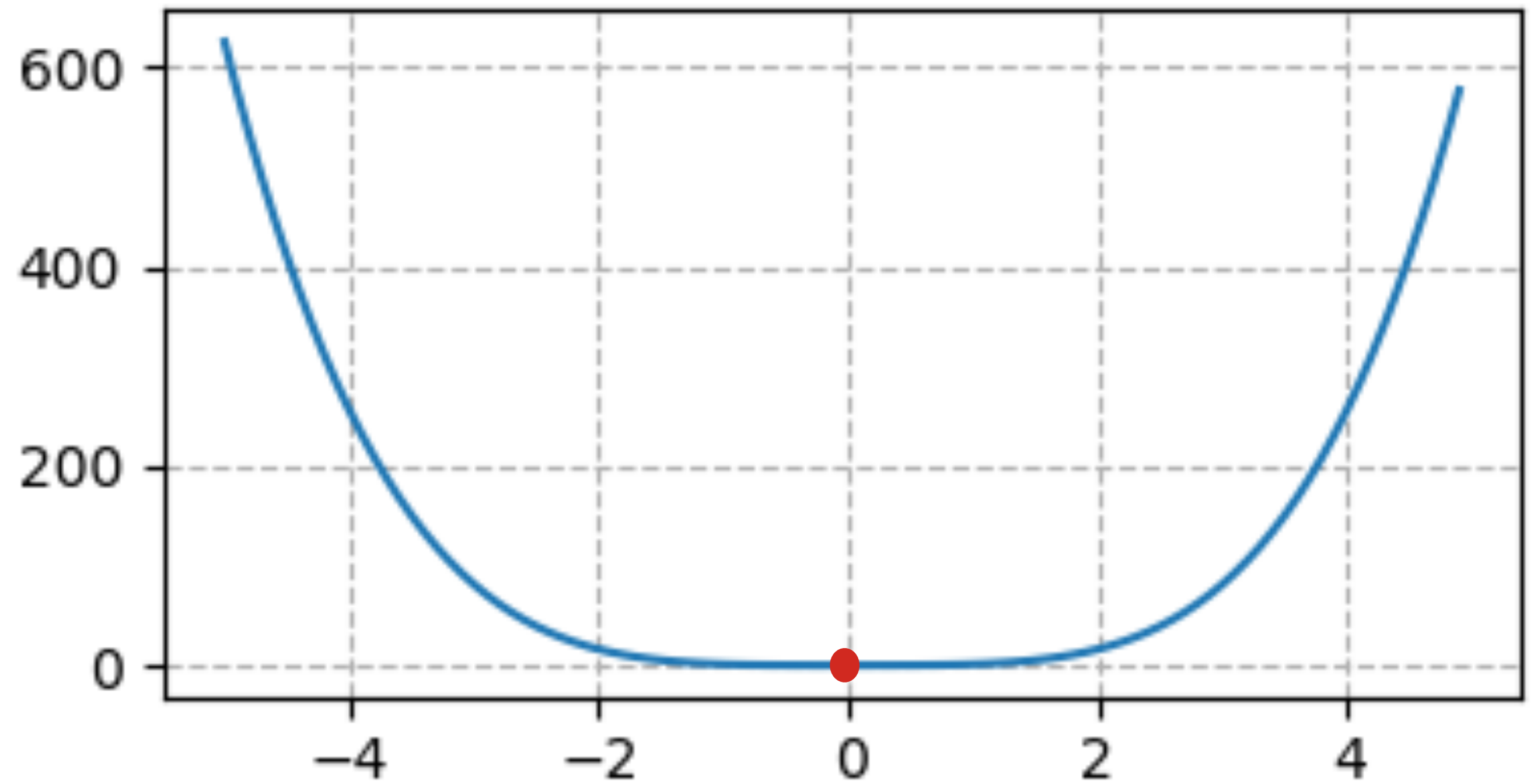


Optimality criteria ?

$$J(w) = w^4$$

- $J(w) = w^4$
- $J'(w) = 0$, at $w = \bar{w}$,
- At \bar{w} , $J''(\bar{w})$ is ?

$J(w)$



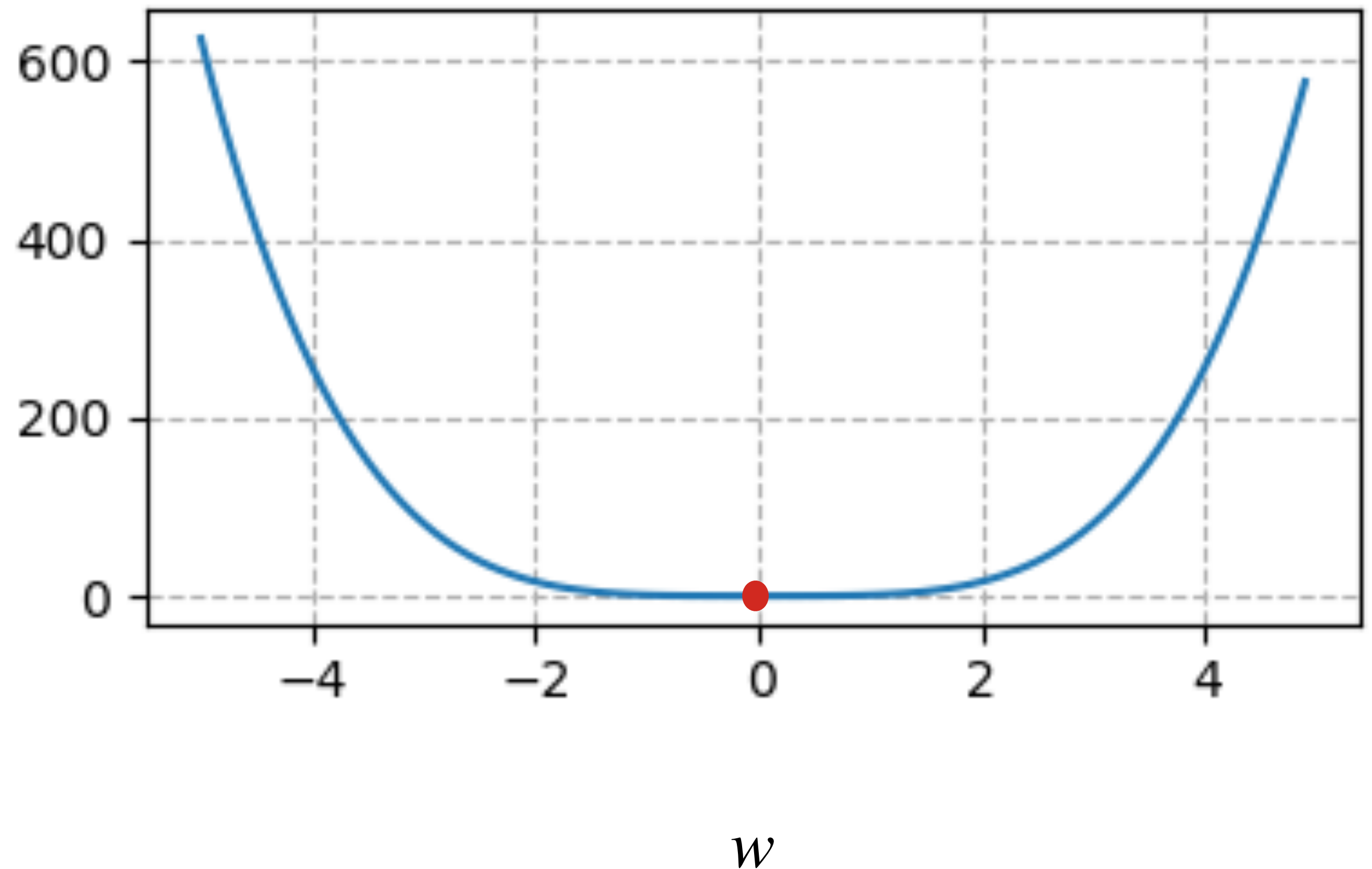
w

Optimality criteria ?

$$J(w) = w^4$$

- $J(w) = w^4$
- $J'(w) = 0$, at $w = \bar{w}$,
- At \bar{w} , $J''(\bar{w})$ is ?
- At \bar{w} , $J'''(\bar{w})$ is ?
- At \bar{w} , $J''''(\bar{w})$ is ?

$J(w)$



Optimality criteria - Generalization

From Kalyanmoy Deb

- Suppose at point \bar{w} the first derivative is zero and the first nonzero higher order derivative is denoted by n ; then
 - If n is odd, \bar{w} an inflection point
 - If n is even, \bar{w} is a local optimum.
 - (i) If the derivative is positive, \bar{w} is a local minimum.
 - (ii) If the derivative is negative, \bar{w} is a local maximum.

Optimality criteria - How to use

- Given a point on the curve, whether it belongs to any of the optimal ones
- The more pressing one - Given a function $J(w)$, how to find the optimal points (in our case, mostly 'min')

Methods to find local minimum

Unimodal functions

- Given a point on the curve, whether it belongs to any of the optimal ones
- The more pressing one - Given a function $J(w)$, how to find the optimal points (in our case, mostly 'min')

Methods to find local minimum

Unimodal functions

- First, a crude approach to find bounds
- Use a more sophisticated method to find the min
- In general, any method takes the following pattern:
 - Identify initial guess and their function values
 - Make appropriate changes in the next values for w 's
 - Continue the procedure till the termination is reached.

Methods (iterative) to find local minimum

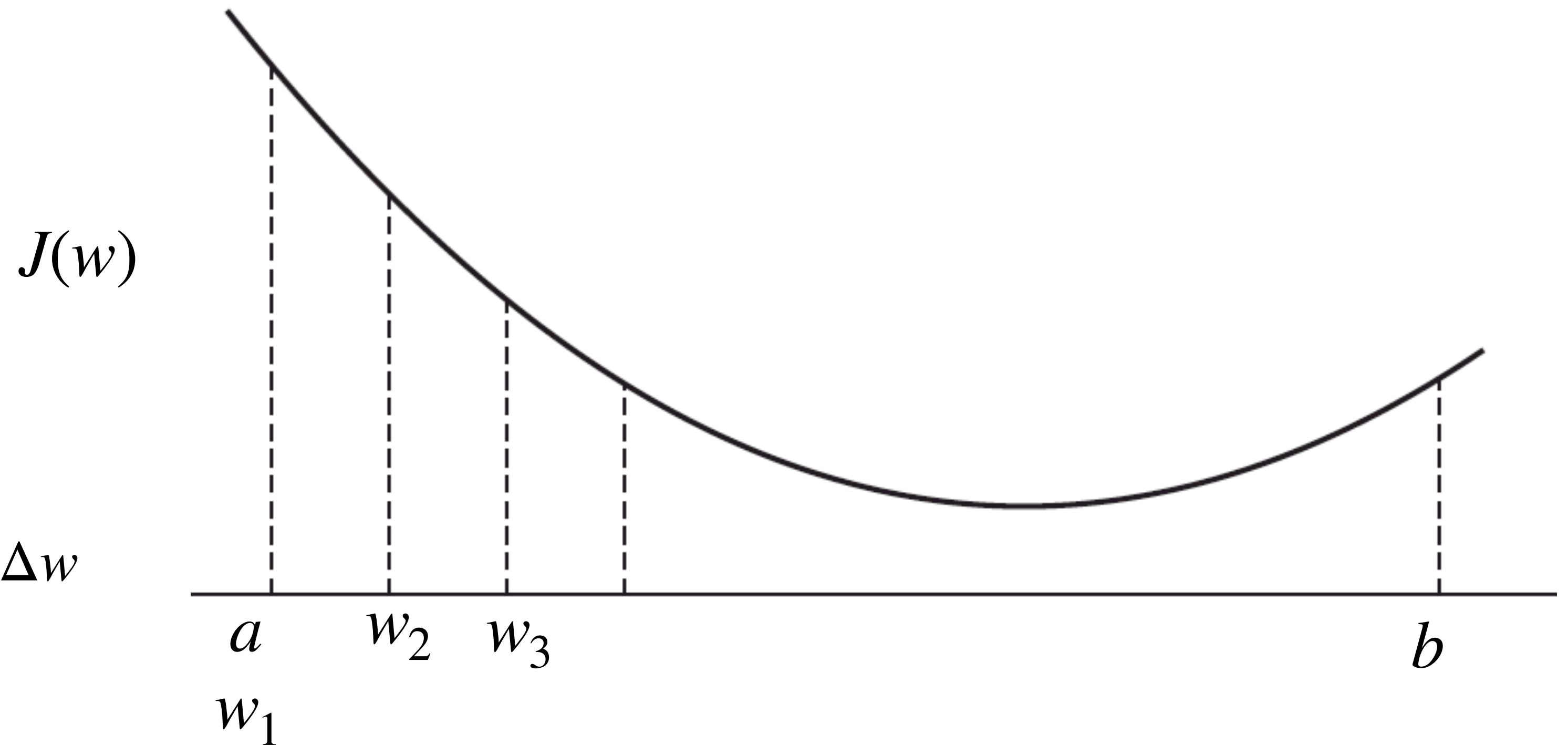
Unimodal functions

- Bracketing methods
 - Exhaustive search
 - Bounding phase
- Region elimination approaches
 - Interval halving
 - Fibonacci search
 - Golden section search
- Gradient-based ones
 - Newton-Raphson
 - Bisection
 - Secant

Bracketing - Exhaustive search method

Unimodal functions

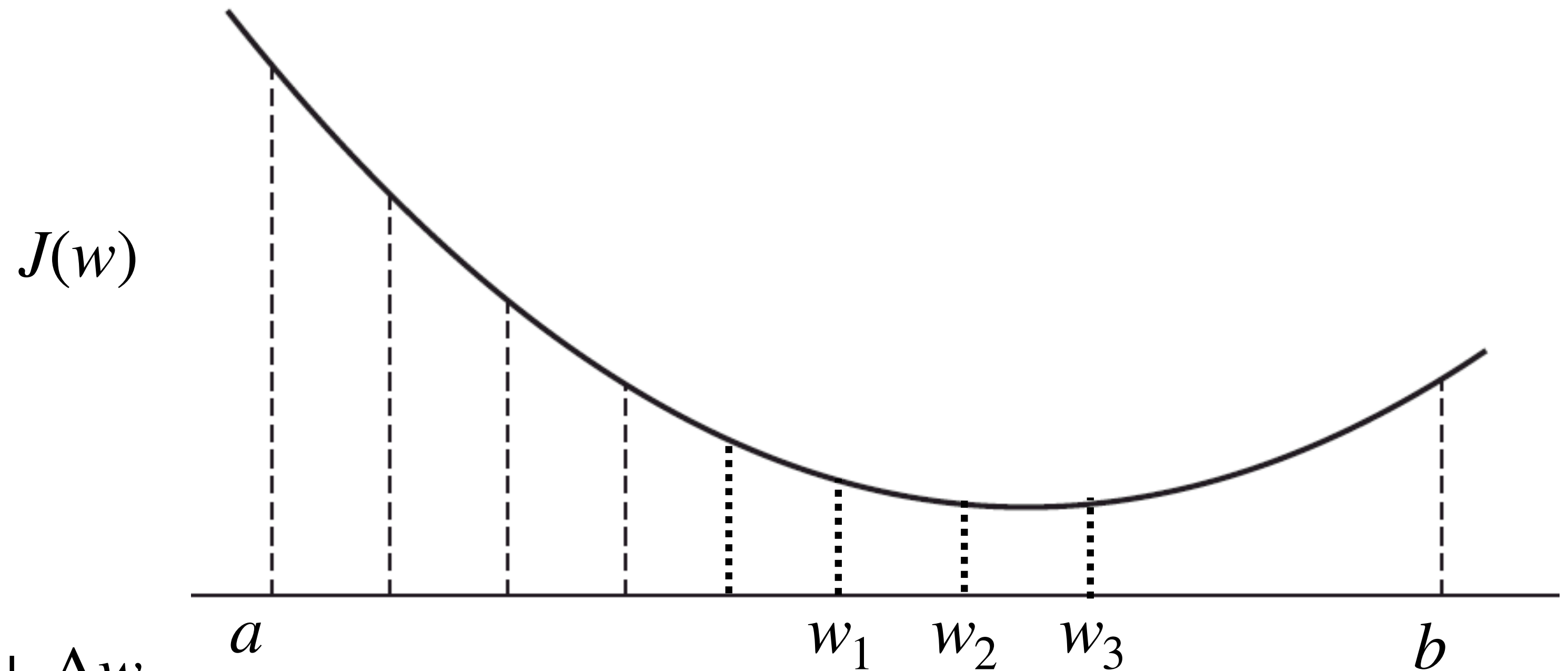
- Let n be the number of intermediate points .
- Step 1:
 - $\Delta w = (b - a)/n$
 - $w_1 = a, w_2 = w_1 + \Delta w, w_3 = w_2 + \Delta w$



Bracketing - Exhaustive search method

Unimodal functions

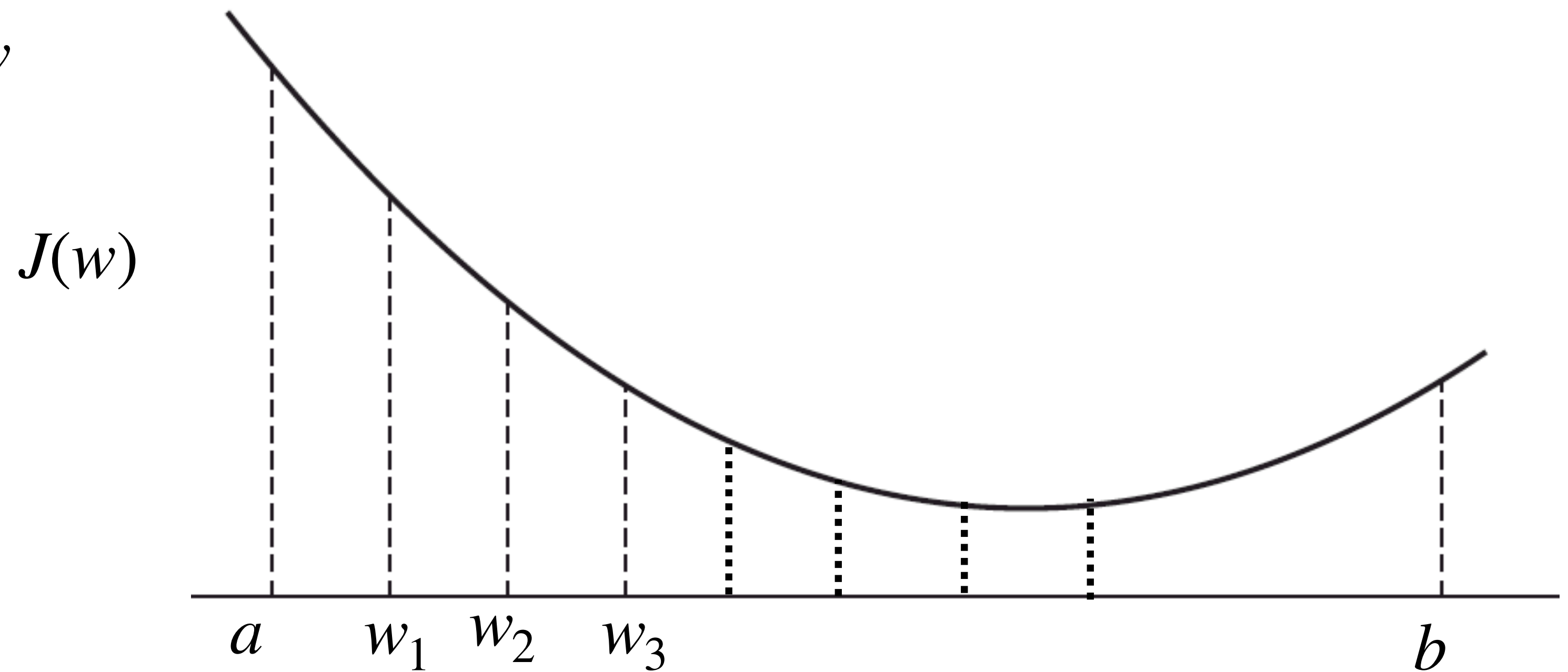
- Step 2:
 - If $J(w_1) \geq J(w_2) \leq J(w_3)$
 - then min lies between (w_1, w_3)
 - Else
 - $w_1 = w_2, w_2 = w_3, w_3 = w_2 + \Delta w$
 - Go to Step 3



Bracketing - Exhaustive search method

Unimodal functions

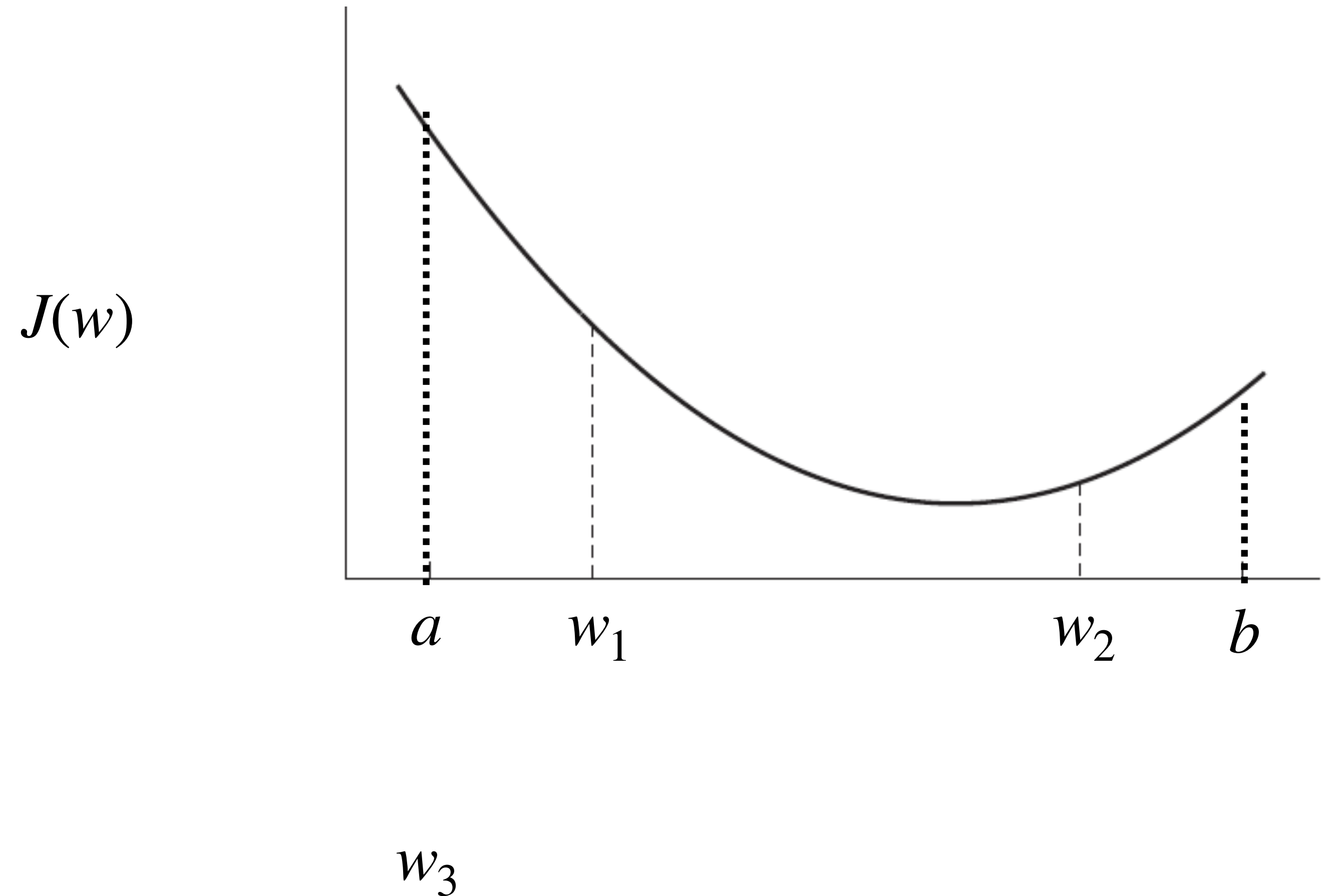
- $w_1 = w_2, w_2 = w_3, w_3 = w_2 + \Delta w$
- Step 3:
 - Is $w_3 \leq b$, then go to Step 2
 - Otherwise, no min exists between (a, b) .
 - Min could be one of the bdry points.



Region elimination method

Overall idea

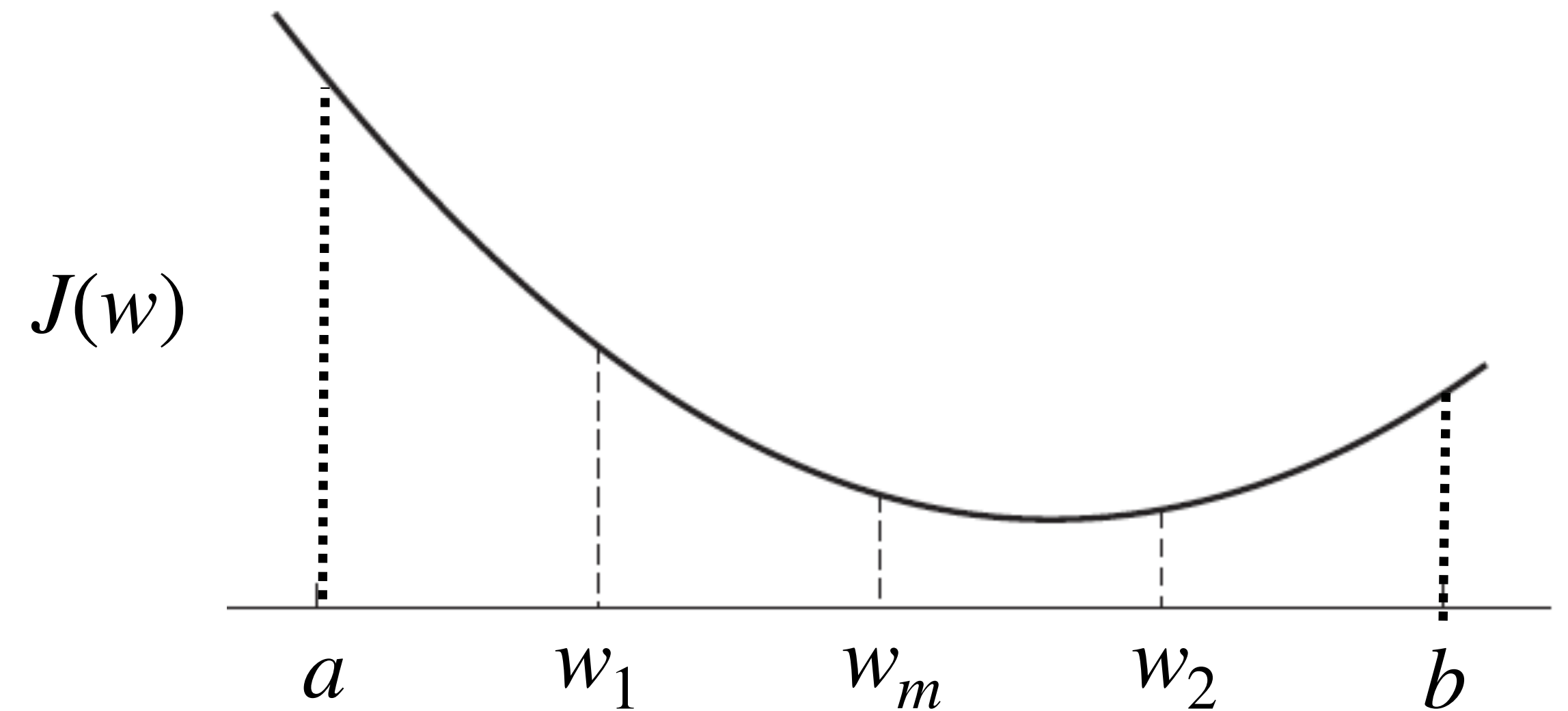
- $w_1 \leq w_2$, if $J(w_1) \geq J(w_2)$
- Region (a, w_1) can be eliminated



Region elimination method

Steps

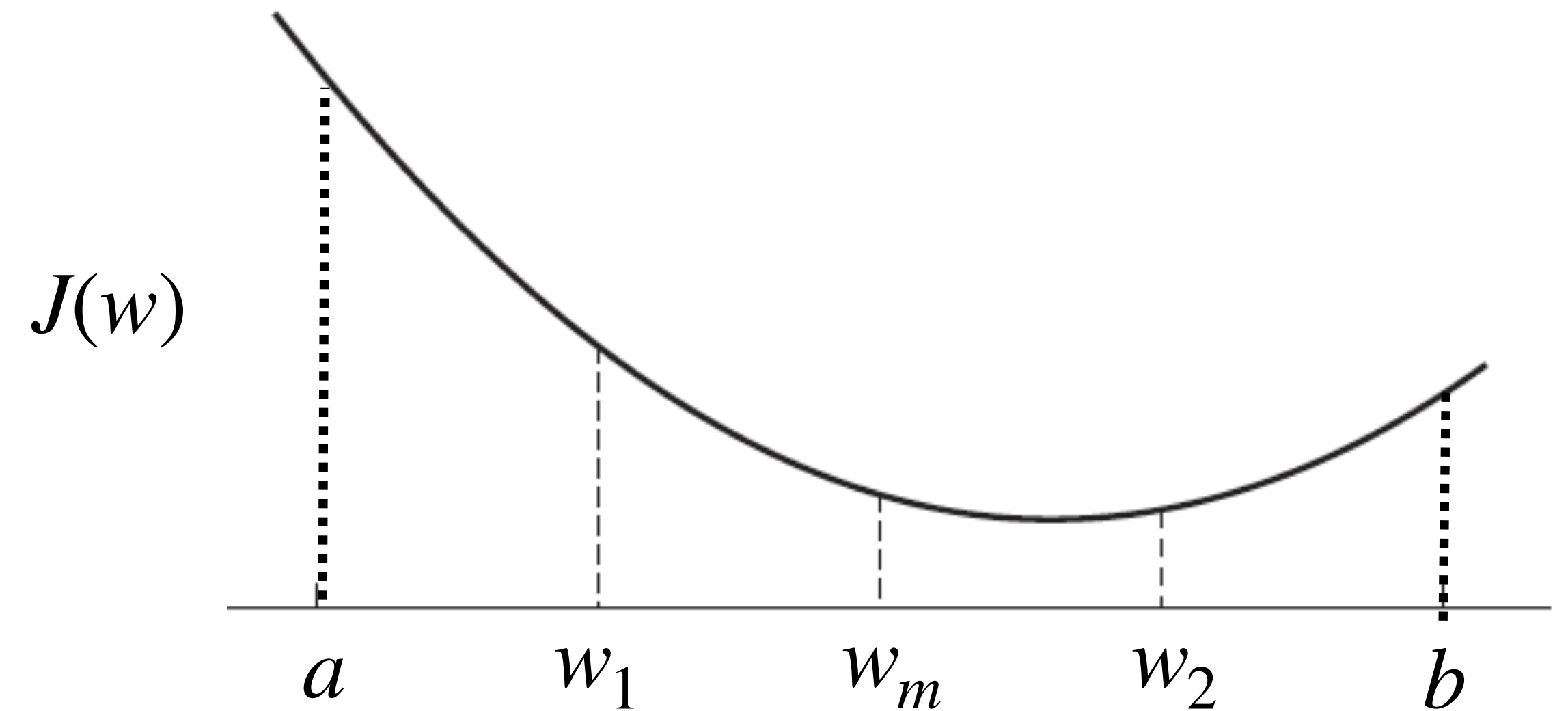
- Step 1
 - Choose
 $a, b, \epsilon, w_m = (a + b)/2, L = (b - a)$
 - Compute $J(w_m)$



Region elimination method

Steps

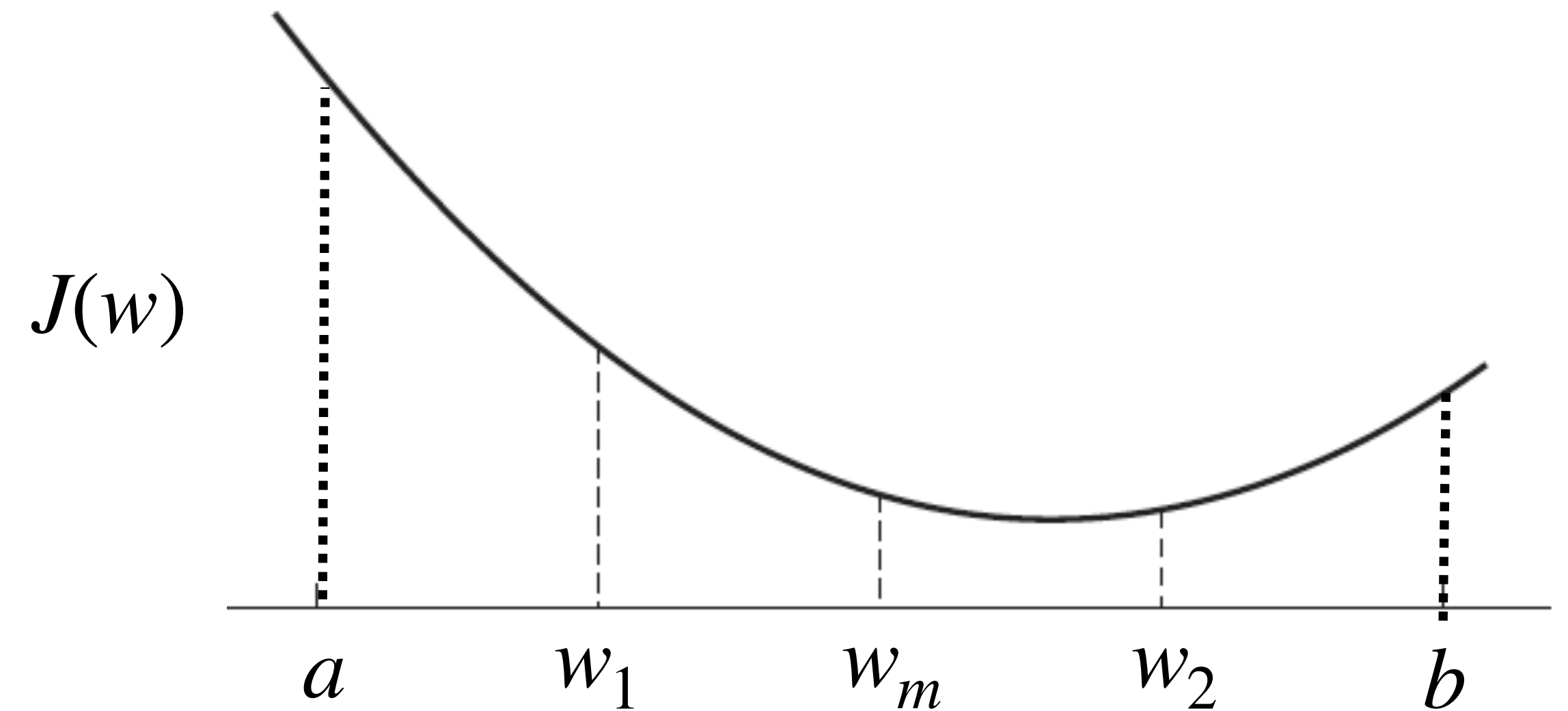
- Step 2
 - Set
$$w_1 = a + L/4, w_2 = b - L/4$$
 - Compute $J(w_1), J(w_2)$



Region elimination method

Steps

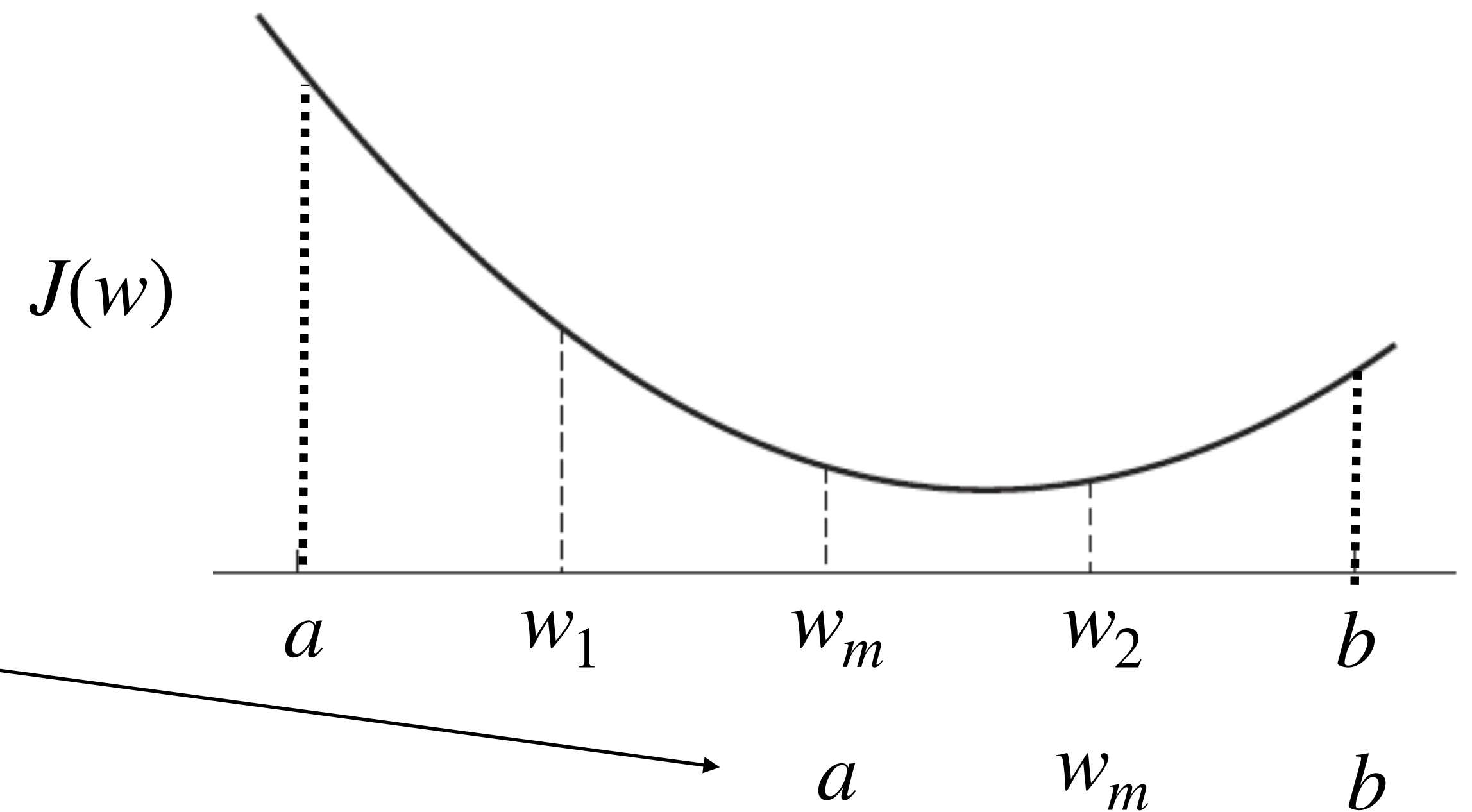
- Step 3
 - If $J(w_1) < J(w_m)$
 - set
 $b = w_m, w_m = w_1$, go
to Step 5
 - Else
 - go to Step 4



Region elimination method

Steps

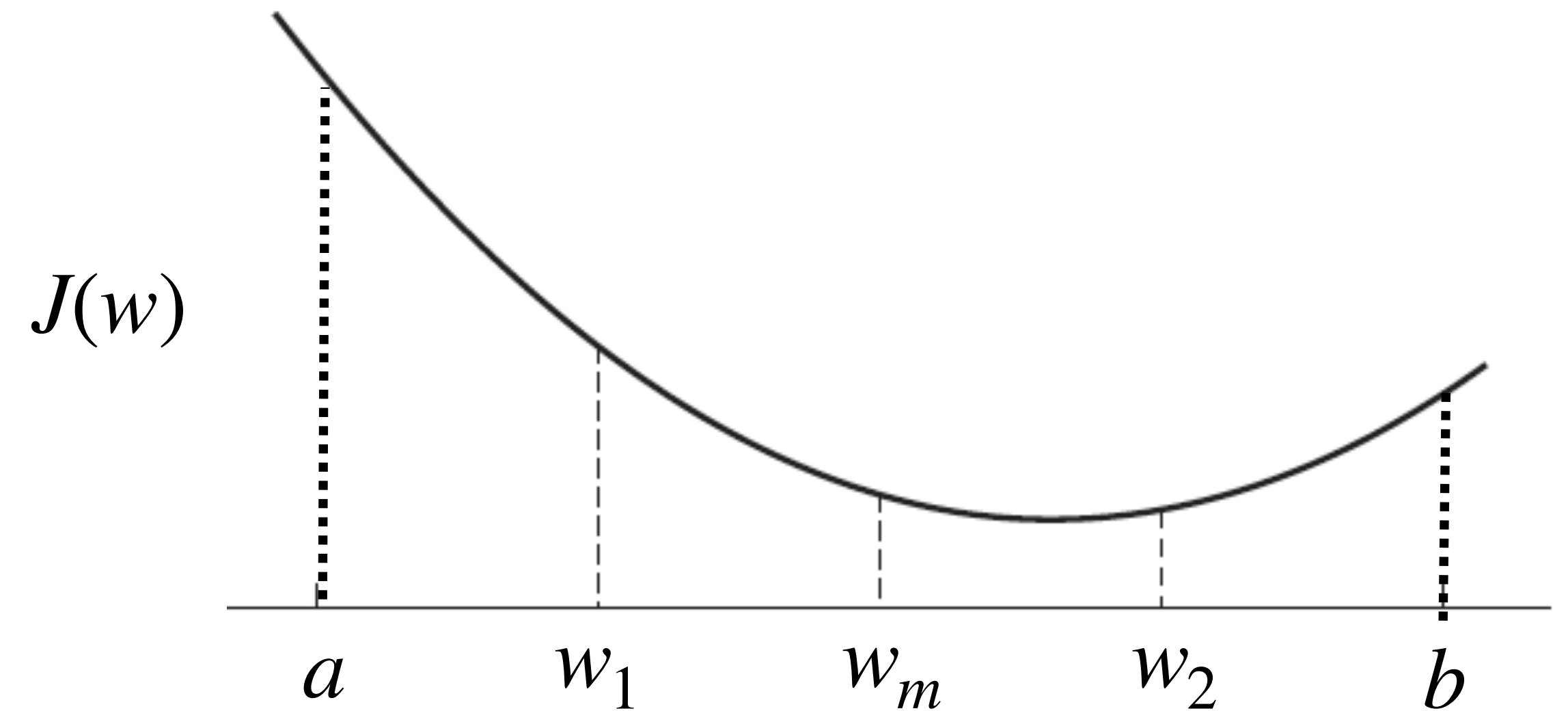
- Step 4
 - If $J(w_2) < J(w_m)$
 - set
 $a = w_m, w_m = w_2$; go
to Step 5
 - Else
 - $a = w_1, b = w_2$; go
to Step 5



Region elimination method

Steps

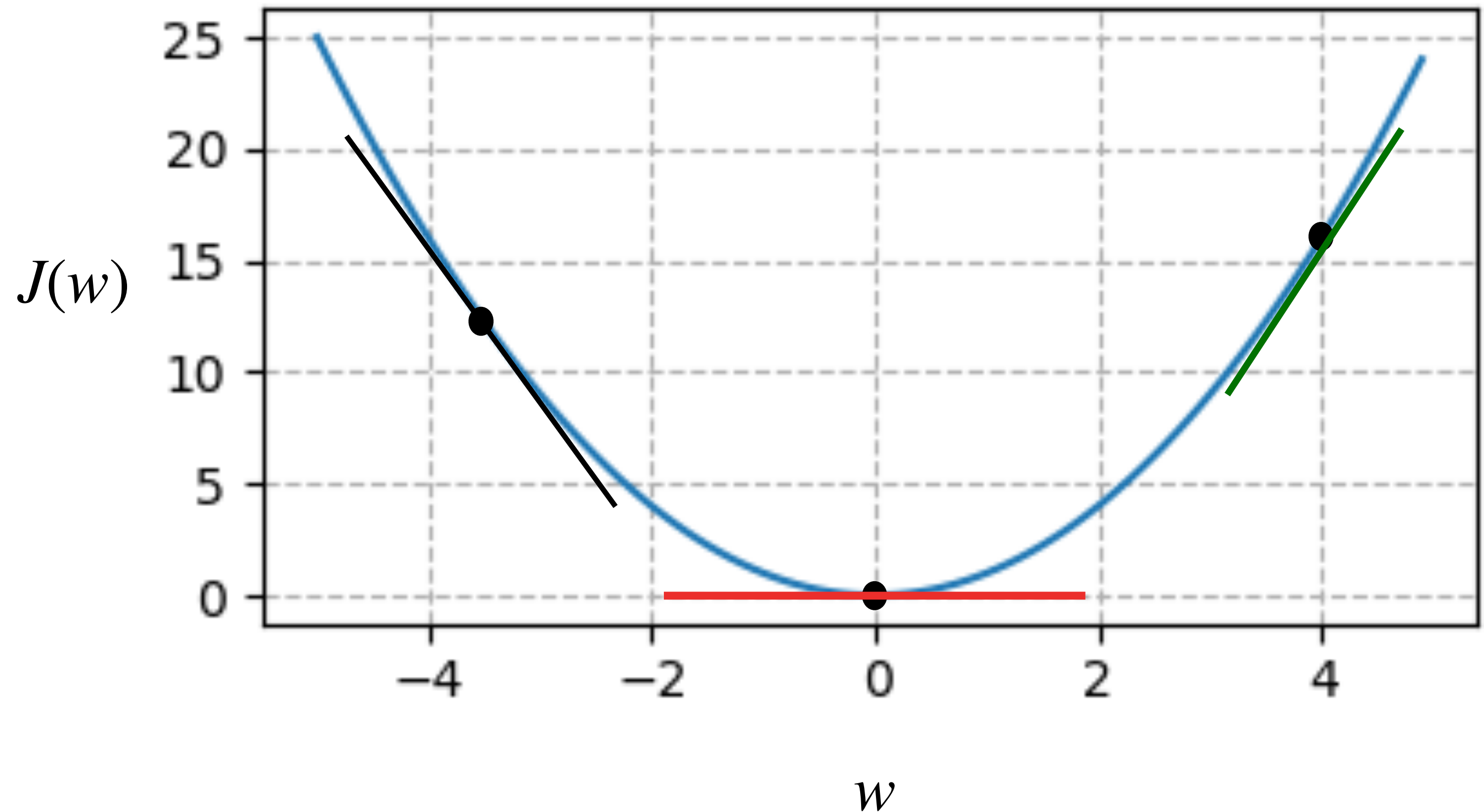
- Step 5
 - Calculate $L = b - a$
 - If $|L| < \epsilon$
 - Terminate
 - Else
 - go to Step 2



Gradient-based approaches

$$J'(w) = dJ(w)/dw$$

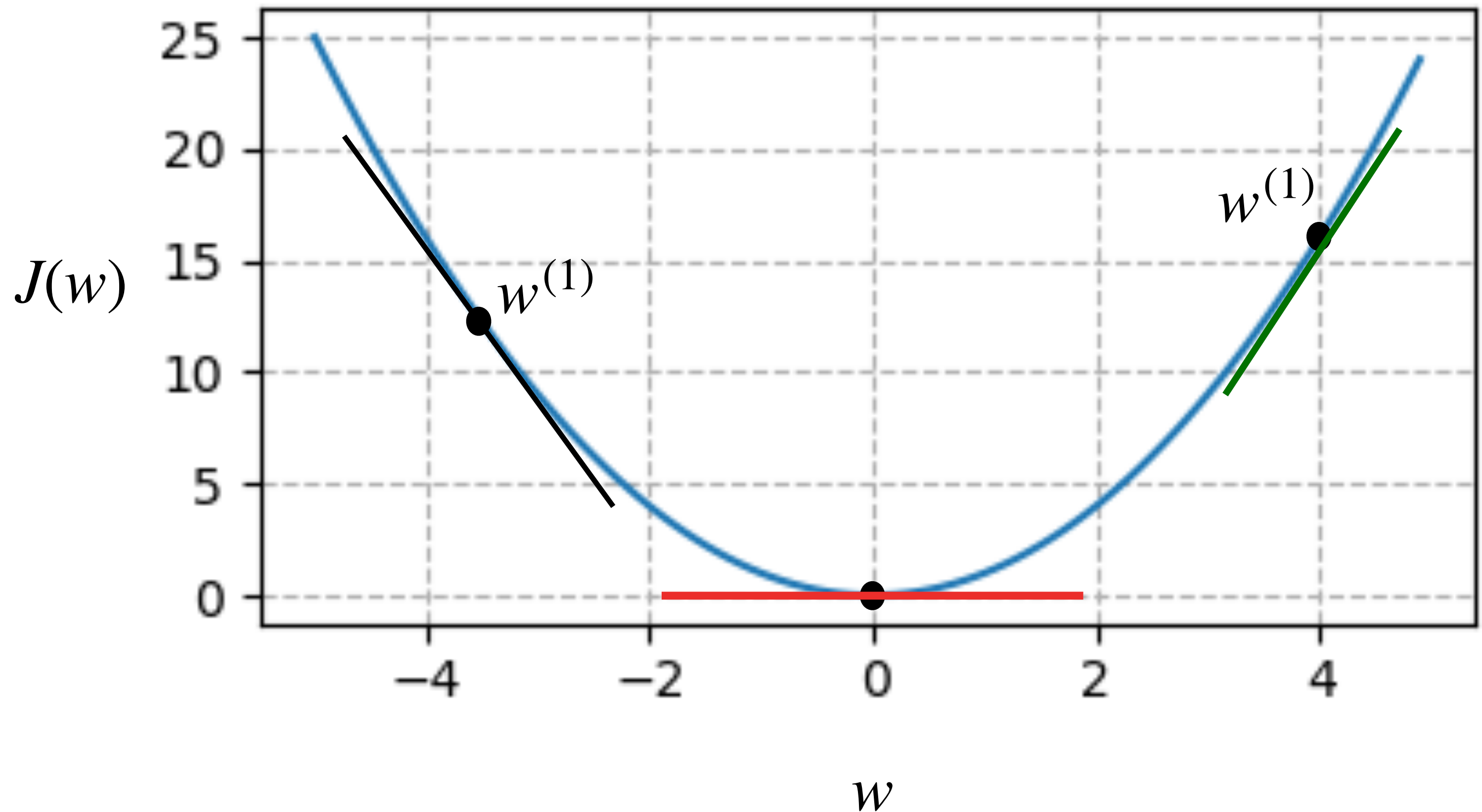
- uses $J'(w) = dJ(w)/dw$ and other higher order derivatives.
- Exact / Numerical approach for derivative
- Min \rightarrow point where $J'(w) \approx 0$



Newton-Raphson

$$J'(w) = dJ(w)/dw$$

- uses $w^{(k)}$ to compute $w^{(k+1)}$
- Using Taylor's appox,
 - $w^{(k+1)} = w^{(k)} - \frac{J'(w)}{J''(w)}$
- $k = 1$ to N (num of iterations)
- Initial guess $w^{(1)}$ is needed.



Newton-Raphson

Steps

- Step 1: Choose $w^{(1)}$, ϵ , set $k = 1$. Compute $J'(w^{(1)})$
- Step 2: Compute $J''(w^{(k)})$
- Step 3: Calculate $w^{(k+1)} = w^{(k)} - \frac{J'(w)}{J''(w)}$. Compute $J'(w^{(k+1)})$
- Step 4: If $|J'(w^{(k+1)})| < \epsilon$, Terminate. Else set $k = k + 1$ go to Step 2