

# Xavier Weber

RESEARCH · AI · COMPUTER VISION

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## Summary

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Driven researcher with experience in implementing, training, and evaluating deep learning models across different computer vision tasks, collaborating with cross-functional teams to develop new tools, and generating high-quality synthetic data.

## Work Experience

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### Queen Mary, University of London

*London, United Kingdom*

#### RESEARCH ASSISTANT

*Sep. 2020 - Present*

- Wrote python scripts to automatically render realistic 3D scenes in Blender. Re-trained existing deep learning models and showed this novel synthetic data improves accuracy for monocular pose and size estimation in 3D of unseen handheld objects.
- Performed an evaluation study to compare existing state-of-the-art monocular 3D human pose estimation models on challenging video data, e.g. people performing ballet routines or fitness exercises.
- Collaborated with interdisciplinary researchers to develop a new tool for automated visual feedback on videos containing human motion, leveraging 3D human pose estimation and 2D segmentation models.

### Google Summer of Code with OpenCV

*Virtual*

#### STUDENT DEVELOPER

*May 2019 - Aug. 2019*

- Implemented two learning-based Super Resolution (SR) models in TensorFlow and added them to the OpenCV library. These outperform previous SR models in OpenCV in terms of speed and accuracy.
- Collaborated with other software engineer to create an intuitive interface in C++, which allows users to employ powerful SR models in only a few lines of code.

### NAVER

*Seongnam-si, South Korea*

#### DEEP LEARNING INTERN

*June 2018 - Oct. 2018*

- Wrote python scripts to automatically render synthetic PDF paper documents containing random folds and creases.
- Implemented a state-of-the-art U-net model in PyTorch for the task of deformed document rectification.

## Education

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### Queen Mary, University of London

*London, United Kingdom*

#### MSC IN ARTIFICIAL INTELLIGENCE - DISTINCTION

*Sep. 2019 - Sep. 2020*

- Thesis: Category-level 6D Pose Estimation in a Human-Robot Handover Scenario
- Supervisor: Prof. Andrea Cavallaro

### Maastricht University

*Maastricht, The Netherlands*

#### BSC IN DATA SCIENCE AND KNOWLEDGE ENGINEERING

*Sep. 2015 - July. 2019*

- Thesis: Semantic Structure Extraction on Deformed Documents via Fully Convolutional Networks
- Supervisor: Asst. Prof. Gerasimos Spanakis

## Skills

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**Programming** Python, C++, Java, MATLAB, Swift

**Technologies** PyTorch, TensorFlow, Keras, Git, OpenCV, NumPy, Blender, Docker, Google Cloud

**Languages** Dutch, English

## Certifications

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**Coursera** Deep Learning Specialization

**Coursera** Computational Neuroscience