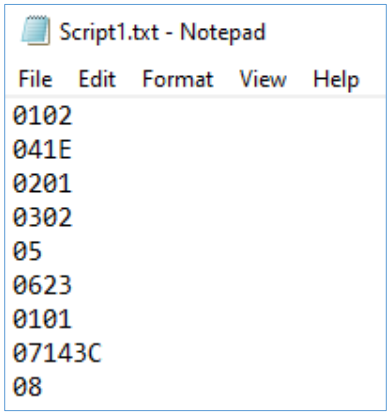
OPC (first Byte)	Instruction	Operand (next Bytes)	Explanation
0x01	blink_rgb	x	Blink RGB LED in series **x** times with delay d
0x02	rlc_leds	x	Rotate **left** circularly a single lighted LED in 8-LED array **x** times with delay d
0x03	rrc_leds	x	Rotate **right** circularly a single lighted LED in 8-LED array **x** times with delay d
0x04	set_delay	d	Set the delay **d** value (***units of 10ms***)
0x05	clear_all_leds		Clear all LEDs (RGB and 16-LED array)
0x06	stepper_deg	p	Points the stepper motor pointer to degree p and show the degree (dynamically) onto PC screen
0x07	stepper_scan	l,r	Scan area between left l angle to right r angle (once) and show the start and final degrees (right on time the motor pinter reaches them) onto PC screen
0x08	sleep		Set the MCU into sleep mode

Note: The default delay d value is 50 (***units of 10ms***)



Script1.txt explanation

```
blink_rgb  2
set_delay 30
rlc_leds  1
rrc_leds 2
clear_all_leds
stepper_deg  35
blink_rgb  1
stepper_scan 20,60
sleep
```