

Proposal of ABM Traffic Flow Thesis

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4 Project Description

4.1 Title of project

4.2 Abstract

This project offers a simple and scalable computational model of a traffic problem in which given a cluster of junctions, cars are sampled that traverse from a random starting point to a destination, traversing intersections, and following traffic rules to get there. At the same time traffic lights are sampled resulting in a problem where cars minimize individual time taken, and lights minimize the collective time taken by the cars. This grid-world representation for traffic problems would expand ABMax, an agent-based modeling framework using JAX, the state of the art when it comes to parallel operations.

4.3 Project Description

Traffic is an integral part of a thriving economy. Transportation access is listed as one of the five pillars of economic development [5]. If infrastructure is of such importance, it is a logical goal to optimize for traffic to maximize efficiency, which can be done through traffic modeling.

My thesis project aims to construct an environment where you can make a traffic problem of multiple junctions fed into each other. This problem could then be used to simulate traffic flows, finding where the bottlenecks are, and allowing traffic lights to find lighting patterns that minimize waiting time. How can adaptive traffic light agents be optimized to minimize overall travel time in a multi-junction road network where individual cars seek the path with the minimal travel time for them?

Traffic flow is a complex system. For a modeling system to be complex, it must involve numerous interacting agents whose aggregate behaviors are non-linear; hence, it cannot simply be derived from summation of individual components' behavior [6]. Traffic jams are the non-linear emerging phenomenon in traffic models: they consist of from interacting cars, and cannot be modeled by the sum of its parts.

For modeling complex systems, agent-based modeling (ABM for short) has been an extensively used tool. ABM is a computational modeling technique that represents individual agents in a system, along with the rules governing their behavior and interactions[2]. The advantage of ABM is that your agents can be as simple or as complex as necessary, and agents can represent anything from people and animals to companies or machines. ABM agents have autonomy: the ability to make their own decisions, given their perceptions and goals. Different agents can have different parameters, which lead to different behavior, facilitating diversity. Finally, due to agents' interactivity: affecting each other and the environment, complex behavior emerges. In our case, traffic jams.

In the past, not many agents could be simulated simultaneously. However, with modern advancements in computational efficiency that has changed. Making use of concurrent programming on hardware accelerators, this number could be vastly increased. JAX is a high-performance computing library for Python. It offers this scalability in the set of agents by leveraging Just-in-Time (JIT) compilation, enabling simulations to run multiple orders of magnitude faster. Traditional ABM implementations often rely on slow, sequential processing, but JAX transforms Python code into optimized machine instructions, allowing for parallel execution on CPUs, GPUs, or TPUs. Key features like *vmap* automatically vectorize operations across agents, eliminating costly loops, while *pmap* distributes computations across multiple processors for even greater efficiency. By integrating JAX into ABM workflows, researchers can simulate considerably larger sets of agents in real time, enabling deeper exploration of emergent behaviors and complex interactions. The approach removes computational bottlenecks, allowing for more extensive scenario testing and real-time experimentation. This thesis project will making use of Abmax, the exact approach described. Abmax is an integration of JAX into ABM, focused on dynamic population size [1]. Its capabilities:

- Adding and removing an arbitrary number of agents.
- Searching and sorting agents based on their attributes.
- Updating an arbitrary number of agents to a specific state.
- Stepping agents in a vectorized way.
- Running multiple such simulations in parallel

4.4 Research

Maerivoet & de Moor and Jiang et al. show great steps forward in this field of modeling traffic flow. Maerivoet and de Moor's work explores cellular automata (CA) models for simulating road traffic, emphasizing their simplicity and efficiency for capturing fundamental traffic dynamics like flow-density relationships and congestion patterns [4]. CA models are discrete in both space and time, making them highly scalable and suitable for simulating large road networks with relatively

low computational overhead. This foundational approach laid the groundwork for understanding self-organized traffic phenomena. Jiang et al. [3] present a simulation framework that leverages multi-GPU parallel computing to dramatically accelerate traffic assignment and propagation processes. Their system enables high-resolution, simulations focused on urban infrastructures, addressing the increasing need for accurate and fast traffic forecasting in smart cities. This project is set apart by the vast data sets which interact with each other in a parallel manner. What makes this project exceptional, is its ability to efficiently handle vast data sets and complex interactions at scale, something that traditional models like cellular automata struggle with. Together, these projects show the progression from simplified modeling to high-performance, data-driven simulations for modern traffic management.

4.5 Workflow and setup

The ABM Traffic Thesis project will consist of two parts, the first being the environment construction and explanation, and the second being the simulations and conclusions that follow from them. The environment allows you to pick a traffic map from a list of pre-made ones. Alternatively, you could randomly generate a map or create one yourself. The traffic map is a grid-world of *Cells*. This grid-world representation means that a *Car* is always in exactly one *Cell*, moving through them one by one. The map consists of a number of junctions and roads with a set number of lanes, all of these being composites of *Cells*. Among the normal *Cells*, there's designated start and destination *Cells*. Once the simulation starts, *Cars* get added and placed in a random selection in the set of start *Cells*, and their goal is to reach a random selection in the set of destination *Cells*. They find the route shortest in time, and then navigate the lanes and junctions accordingly. During the simulation, junctions can be normal intersections or they could be managed by traffic lights, another type of agent. Traffic lights manipulate from which lanes cars are allowed to go onto the intersection, and what turns they may take. The traffic lights' goal is to minimize total within-intersection waiting time. When this all works as described, some additional features such as U-turns, driver chaos and emergency vehicles get added, and then we will move onto the simulations, in which a comparison gets made between waiting time with traffic agents and with static traffic light patterns.

4.6 Schedule

Table 1: Project schedule

Task description	Time estimated	Deadline
Finalize proposal.	5 hours	14/03/2025
Construct robust Cell, Map representation	15 hours	16/03/2025
Implement shortest route algorithm	5 hours	18/03/2025
Implement parallel car movement	8 hours	04/04/2025
Create Car agent	3 hours	06/04/2025
Create Traffic Light agent	3 hours	11/04/2025
Add additional features and finalize Environment	15 hours	13/04/2025
Start thesis drafting process	N.A.	16/04/2025
Conduct research on simulations	5 hours	23/04/2025
Prepare draft thesis for feedback and send it to supervisor	20 hours	10/05/2025
Edit draft thesis following feedback	5 hours	24/05/2025
Hand in draft thesis and plan thesis defence session.	1 hour	25/05/2025
Submit finalized thesis.	10 hours	01/06/2025
Defend thesis	N.A.	xx/06/2025

5 Relevance

There have been few traffic ABM problems that makes use of parallel processing to find optimal traffic light patterns before, and none of the grid-world ABM problems have intersections without traffic lights. Additionally, we are planning on making cells active and inactive on the fly, enabling unique scenarios where lanes get added during a simulation. Although the intersections without traffic lights might not sound like a big step forward, they allow an intersection of roads to be traversed from all four entrances to all four exits without requiring a single update in the cells' directions. Making use of parallel processing, allows the simulation process to be more computationally efficient. It would enable us to test traffic maps much faster and more efficiently to find bottlenecks so that we could potentially find the most optimal setup for a real-world scenario such that car emission pollution and travel time are reduced, limiting environmental damage and enabling a good economy.

6 References

References

- [1] I-M-Iron-Man. *GitHub - i-m-iron-man/abmax: Abmax is an agent-based modelling framework in Jax, focused on dynamic population size*. URL: <https://github.com/i-m-iron-man/abmax/tree/master?tab=readme-ov-file>.
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- [3] Xuan Jiang et al. "Large scale multi-GPU based parallel traffic simulation for accelerated traffic assignment and propagation". In: *Transportation Research Part C Emerging Technologies* 169 (Oct. 2024), p. 104873. DOI: 10.1016/j.trc.2024.104873. URL: <https://doi.org/10.1016/j.trc.2024.104873>.
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