COMPUTABLE FUNCTIONS

Dr. A. Beulah AP/CSE



LEARNING OBJECTIVE

- To Design Turing machines for any Languages (K3)
 - To Understand the concept of Turing Machine



18 August 2022 A. Beulah Unit IV 2

• A total function $\underline{f}: \underline{\Sigma}^* \to \underline{\Sigma}^*$ is Turing-computable if there exists a DTM M such that for every x in $\underline{\Sigma}^*$,

$$(s, BxB) - (h, Bf(x)B).$$

• A partial f: $\Omega \to \Sigma^*$ is Turing-computable if there exists a DTM M such that $L(M) = \Omega$ and for every x in Ω ,

$$(s, BxB) \rightarrow (h, Bf(x)B).$$



Construct a TM for successive function?

$$f: \underline{N} \rightarrow \underline{N}, f(x) = \underline{x}+1.$$

Assume that the input is encoded in UNARY form.

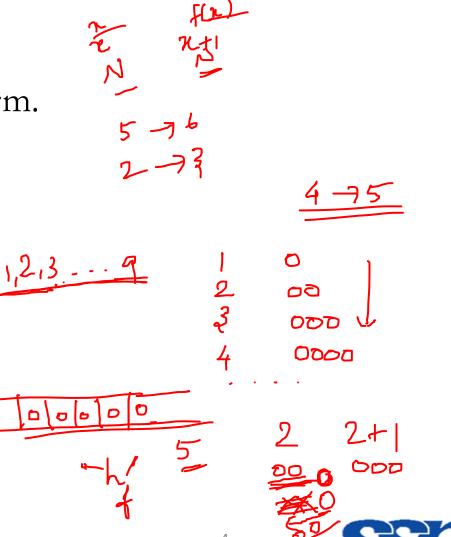
Let
$$M = (Q, \Sigma, \Gamma, \delta, q0, B, F)$$

$$Q = \{q0,q1\}$$
 $q0$ =start state $q1$ =final state

$$\Sigma = \{0\}$$

$$\Gamma = \{0,B\}$$

$$F = \{q1\}$$



Construct a TM for successive function?

$$f: N \rightarrow N, f(x) = x+1.$$

Assume that the input is encoded in UNARY form.

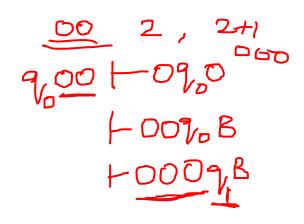
Let
$$M = (Q, \Sigma, \Gamma, \delta, q0, B, F)$$

$$Q = \{q0,q1\}$$
 $q0$ =start state $q1$ =final state

$$\Sigma = \{0\}$$

$$\Gamma = \{0,B\}$$

$$F = \{q1\}$$



States	Tape Symbols		
	0	В	
$q_{_{ m O}}$	$(q_0, 0, R)$	$(\underline{q}_{\underline{1}}, \underline{0}, R)$	
$q_{_1}$	_	_	



Let us consider the input x=3, This is encoded as 000.

$$(q_0, \underline{000B}) \mid -(q_0, 0\underline{00B}) \mid -(q_0, 00\underline{0B})$$

 $\mid -(q_0, 000\underline{B}) \mid -(q_1, \underline{0000B})$

The machine halts in an accepting state q_1

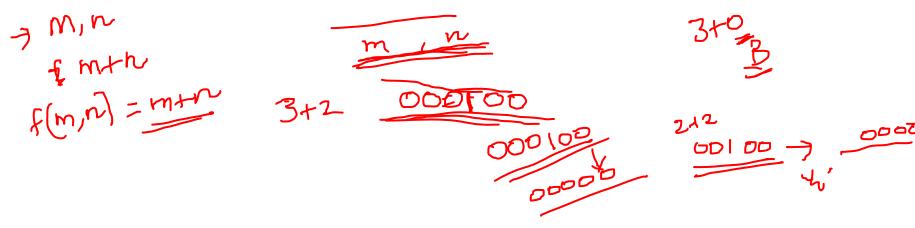
by computing the successive of x



• We can represent numbers on a TM by using the unary representation, which just uses n 0's to represent the number n.

Example:
$$00000 = 5$$

- We can construct a TM to concatenate two strings together.
- If we represent two numbers in unary form, then a TM which concatenates these two strings is actually performing addition!





Unit IV

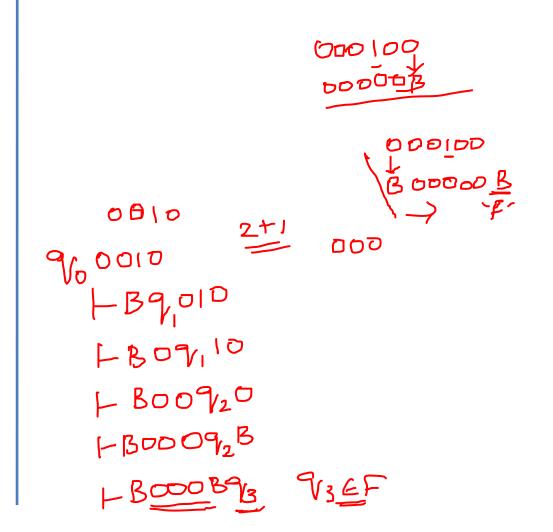
- Addition of two numbers as simple as concatenation of two strings.
- Assume two integers are represented in unary form on the tape of a Turing machine.
- Assume the two integers are separated by a 1 between them.
- Design a Turing machine that will add these two numbers.



• f(m,n)=m+n

in
$$0' \rightarrow B$$

 $8(9_{01}, 0) = (9_{11}, B, R)$
 $8(9_{11}, 0) = (9_{11}, 0, R)$
 $8(9_{11}, 0) = (9_{21}, 0, R)$
 $8(9_{21}, 0) = (9_{21}, 0, R)$
 $8(9_{21}, 0) = (9_{21}, 0, R)$



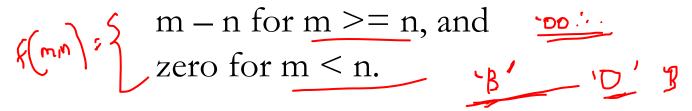


• 3+2



SUBTRACTION M - N

• For example, proper subtraction m – n is defined to be



• The TM M = $(\{q0,q1,...,q6\}, \{0,1\}, \{0,1,B\}, \partial, q0, B, \{\})$



The function ∂ is described below.

$$\partial(q0,0) = (q1,B,R)$$
 Begin. Replace the leading 0 by B.



Unit IV

$$\partial(q1,0) = (q1,0,R)$$
 Search right looking for the first 1.

$$\partial(q1,1) = (\underline{q2},1,R)$$

$$\partial(q2,1) = (q2,1,R)$$
 Search right past 1's until encountering a 0. Change that 0 to 1.

$$\partial(q2,0) = (q3,1,L)$$

$$\partial(q3,0) = (q3,0,L)$$
 Move left to a blank. Enter state q0 to repeat the cycle.

$$\partial(q3,1) = (q3,1,L)$$

$$∂$$
(q3,B) = (q0,B,R)

If in state q2 a B is encountered before a 0, we have situation i described above. Enter state q4 and move left, changing all 1's to B's until encountering a B. This B is changed back to a 0, state q6 is entered and M halts.

$$\partial(q2,B) = (q4,B,L)$$

 $\partial(q4,1) = (q4,B,L)$

$$\partial(q4,1) = (q4,B,L)$$

$$\partial(q4,0) = (q4,0,L) \ /$$

$$\partial(q4,B) = (q6,0,R)$$

If in state q0 a 1 is encountered instead of a 0, the first block of 0's has been exhausted, as in situation (ii) above. M enters state q5 to erase the rest of the tape, then enters q6 and halts.

$$\partial(q0,1) = (q5,B,R)$$

$$\partial(q5,0) = (q5,B,R)$$

$$\partial(q5,1) = (q5,B,R)$$

$$\partial(q5,B) = (q6,B,R)$$

18 August 2022 A. Beulah



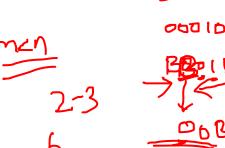


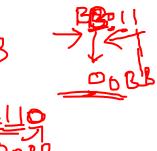












3-1



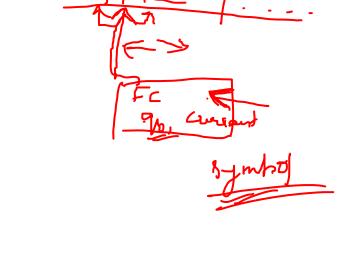
SUBTRACTION M - N

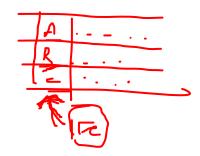
	symbol			
state	0	1	В	
q_0	(q_1, B, R)	(q_5, B, R)	-	
q_1	$(q_1, 0, R)$	$(q_2, 1, R)$	-	
q_2	$(q_3, 1, L)$	$(q_2, 1, R)$	(q_4, B, L)	
q_3	$(q_3, 0, L)$	$(q_3, 1, L)$	(q_0, B, R)	
q_4	$(q_4, 0, L)$	(q_4, B, L)	$(q_6, 0, R)$	
q_5	(q_5, B, R)	(q_5, B, R)	(q_6, B, R)	
q_6	-	-	-	



PROGRAMMING TECHNIQUES OF TURING MACHINES

- Storage in the Finite Control
- Multiple Tracks
- Checking off Symbols
- Subroutines

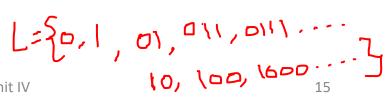






STORAGE IN THE FINITE CONTROL

- The finite control can be used to hold the finite amount of information.
- It is considered as a pair of elements, like (q_0,a) , where one exercising control and second component stores a symbol in the finite control.
- Consider a turing machine M which accepts the language 01* + 10*
- Let $M = (Q, \{0,1\}, \{0,1,B\}, \delta, \{q_0,B\},B,F)$
- $Q = \{q_0,q_1\} \times \{0,1,B\}$ = $([q_0,0], [q_0,1], [q_0,B], [q_1,0], [q_1,1], [q_1,B])$
- $F = \{[q_1,B]\}$







STORAGE IN THE FINITE CONTROL

$$\delta([q_0, B], 0) = ([q_1, 0], 0, R)$$

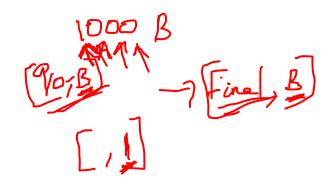
$$\delta([q_0, B], 1) = ([q_1, 1], 1, R)$$

$$\delta([q_1,0],1) = ([q_1,0], 1, R)$$

$$\delta([q_1,1],0) = ([q_1,1],0,R)$$

$$\delta([q_1, 0], B) = ([q_1, B], 0, L)$$

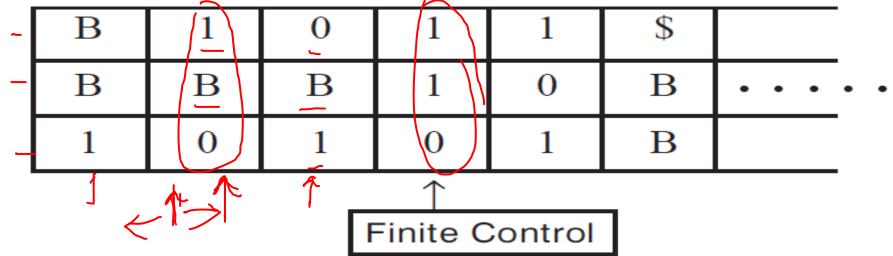
$$\delta([q_1, 1], B) = ([q_1, B], 1, L)$$



$$S\left(\begin{bmatrix} 9, 8y \end{bmatrix}, \begin{bmatrix} ay, 5y^2 \end{bmatrix}\right)$$



MULTIPLE TRACKS

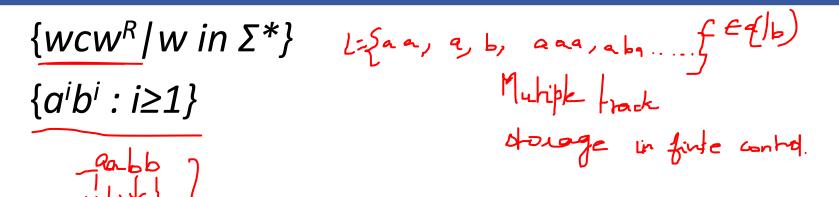


$$S(9/0, 2) = (9/0, \times, R)$$

$$BBI$$

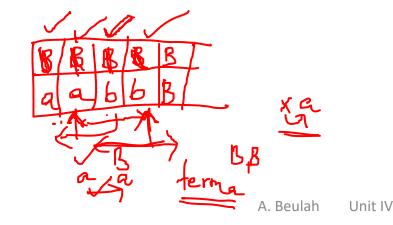






В	В	В	В	>	/	
а	а	b	С	а	b	

extra Track





Consider a turing machine $M = (Q, \Sigma, \Gamma, \delta, q0, B, F)$ for the language $L = \{wcw | w \in \{a, b\}^+\}$

- a) $Q = \{[q,d] \mid q = q_1 \ q_2 \dots \ q_9 \ and \ d = a, b \ or \ B\}$
- b) $\Sigma = \{ [B, d] \mid d = a, b \text{ or } c \}$
- c) $\Gamma = \{[x, d] \mid x = B \text{ or and } d = a, b, c \text{ or } B\}$
- d) $q0 = [q_1, B]$
- e) $F = \{[q_9, B]\}$
- f) B = [B, B]
- g) δ is defined for d = a or b and e = a or b.



Forward

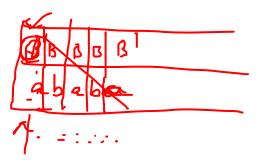
$$\delta([q_1, B], [B, d]) = ([q_2, d], [\checkmark, d], R)$$

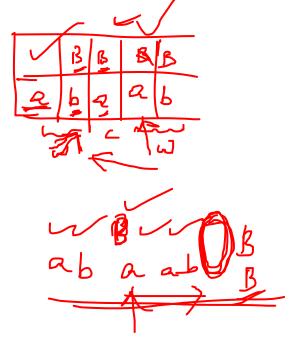
$$\delta([q_2, d], [B, e]) = ([q_2, d], [B, e], R)$$

$$\delta([q_2,d], [B,c]) = ([q_3,d], [B,c], R)$$

$$\delta([q_3,d], [\checkmark, e]) = ([q_3,d], [\checkmark, e], R)$$

$$\delta([q_3,d], [B, d]) = ([q_4,B], [\checkmark, d], \underline{L})$$







Backward

$$\delta([q_4,B], [\checkmark,d]) = ([q_4,B], [\checkmark,d], L)$$

 $\delta([q_4,B], [B,c]) = ([q_5,B], [B,c], L)$
 $\delta([q_5,B], [B,d]) = ([q_6,B], [B,d], L)$
 $\delta([q_6,B], [B,d]) = ([q_6,B], [B,d], L)$
 $\delta([q_6,B], [\checkmark,d]) = ([q_1,B], [\checkmark,d], R)$



Terminate

$$\delta([q_5,B], [\checkmark, d]) = ([q_7,B], [\checkmark, d], R)$$

 $\delta([q_7,B], [B, c]) = ([q_8,B], [B, c], R)$
 $\delta([q_8,B], [\checkmark, d]) = ([q_8,B], [\checkmark, d], R)$
 $\delta([q_8,B], [B, B]) = ([q_9,B], [, B], L)$



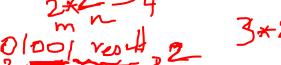
$$\delta(q0,0) = (q6, B, R)$$

$$\delta(q6, 0) = (q6, 0, R)$$

$$\delta(q6, 1) = (q1, 1, R)$$

$$f(m,n) = m + n$$

$$f(m,n) = mxn$$





δ for subroutine COPY.

States	Inputs			
States	0	1	2	В
q_1	$(q_2, 2, R)$	$(q_4, 1, L)$		
q_2	$(q_2, 0, R)$	$(q_2, 1, R)$		$(q_3, 0, L)$
q_3	$(q_3, 0, L)$	$(q_3, 1, L)$	$(q_1, 2, R)$	
q_4		$(q_5, 1, R)$	$(q_4, 0, L)$	

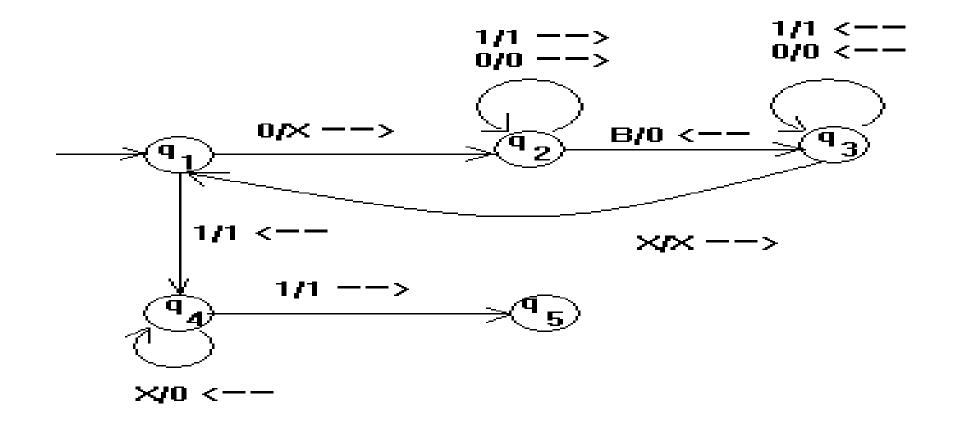


A. Beulah Unit IV

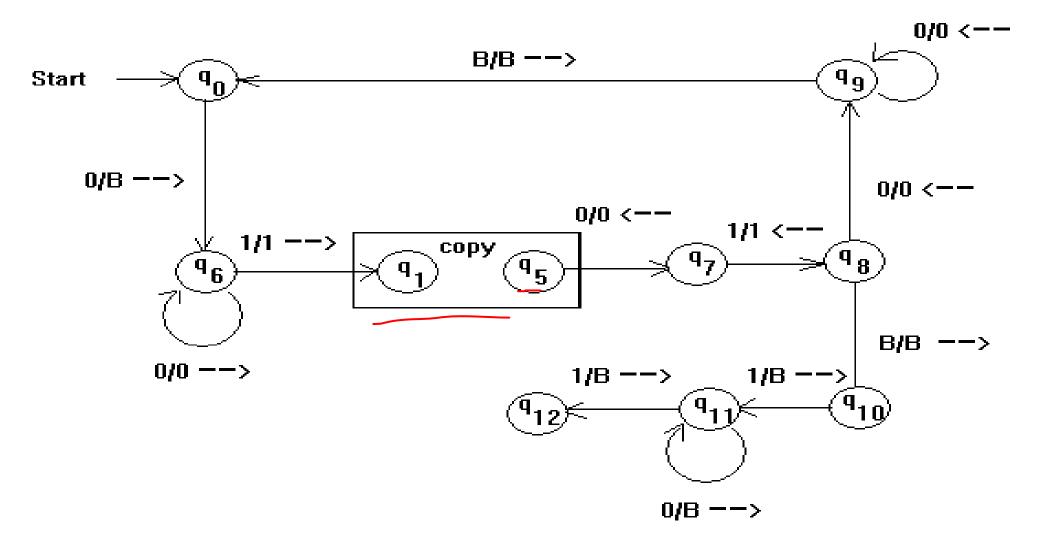
23

States	Inputs			
States	0	1	2	В
$q_{_{5}}$	$(q_{7},0,L)$			
$q_{_{7}}$		$(q_{8},1,L)$		
$q_{_8}$	$(q_{9},0,L)$			(q_{10},B,R)
$q_{_{9}}$	$(q_{9},0,L)$			(q_0, B, R)
$q_{_{10}}$		(q_{11},B,R)		
$q_{_{11}}$	(q_{11},B,R)	(q_{12},B,R)		











 $\delta(q_0, 001001) \mid -Bq_601001B$ $-B0q_{6}1001B$ $B01q_{1}001B$ B01Xq₂01B $B01X0q_{2}1B$ B01X01*q*₂*B* $B01X0q_310$ $B01Xq_3010$ B01*q*₃*X010* B01Xq₁010 B01XX*q*₂10 B01XX1*q*₂*0* B01XX10 q_2B B01XX1*q*₃00 B01XX*q*₃100 B01X q_3 X100 B01XX*q*₁100 B01X*q*₄*X100* B01q₄X0100 B0*q*₄100100 B01q₅00100 B0q₇100100

 $-Bq_{g}0100100$ $-q_9B0100100$ ($-Bq_00100100$ - BBq₆100100 $-BB1q_{1}00100$ - BB1X*q*₂0100 - BB1X0*q*₂100 - BB1X0*q*₂100 - BB1X01*q*₂00 - BB1X010*q*₂0 - BB1X0100*q*₂*B* $-BB1X010q_300$ - BB1X01*q*₃000 - BB1X0*q*₃1000 $-BB1Xq_301000$ $-BB1q_{3}X01000$ – BB1X*q* ₁01000 - BB1XX*q*₂1000 - BB1XX1*q* ₂000 - BB1XX10*q*₂00 - BB1XX100*q*₂0 $-BB1XX1000q_2B$ - BB1XX100*q*₃00 - BB1XX10*q*₃000 – BB1XX1*q*₃0000 - BB1XX*q*₃10000 $-BB1Xq_{3}X10000$ - BB1XX*q*₁10000

- $|-BB1Xq_{4}X10000$
- $|-BB1q_4X010000|$
- $|-BBq_410010000$
- |- BB1*q₅0010000*
- $|-BBq_710010000$
- $|-Bq_8B10010000$
- $|-BBq_{10}10010000$
- $-BBBq_{11}0010000$
- $|-BBBBq_{11}010000$
- $|-BBBBBq_{11}10000$
- |- BBBBBBq₁₂0000



SUMMARY

- Definition of Total and partial function
- Computing a numerical function using Turing Machine
- Programming techniques of Turing Machine



18 August 2022 A. Beulah Unit IV 29

TEST YOUR KNOWLEDGE

- Which of the following statements is/are FALSE?
- 1. For every non-deterministic Turing machine, there exists an equivalent deterministic Turing machine.
- 2. Turing recognizable languages are closed under union and complementation.
- 3. Turing decidable languages are closed under intersection and complementation.
- 4. Turing recognizable languages are closed under union and intersection.
- A. 1 and 4 only
- B. 1 and 3 only
- C. 2 only
- D. 3 only



TEST YOUR KNOWLEDGE

Which of the following is true for the language
 L={a^p/ p is prime}

- A. It is not accepted by a Turing Machine
- B. It is regular but not context-free
- C. It is context-free but not regular
- D. It is neither regular nor context-free, but accepted by a Turing machine



REFERENCE

 Hopcroft J.E., Motwani R. and Ullman J.D, "Introduction to Automata Theory, Languages and Computations", Second Edition, Pearson Education, 2008

