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UCS 1504 - Artifical Intelligence

Application of Hobot Control:

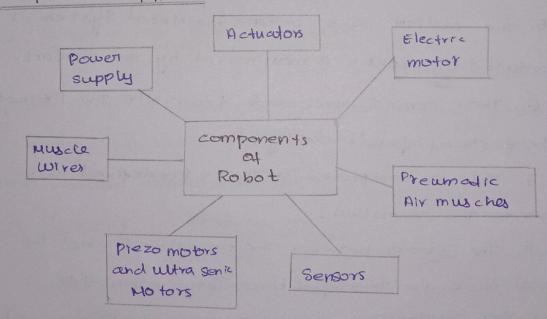
Robot:

A stobot is a machine that looks like a human , and is capable of performing out of box actions and stoplicating contain human movement automatically by means of commands given to its using programming.

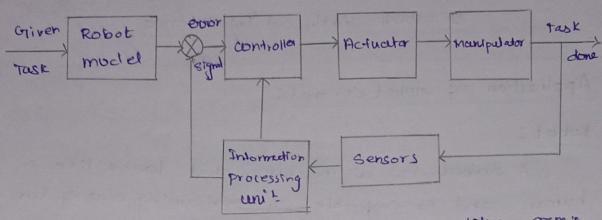
Example:

- 1. Order pickethy Robots
- 2. Drug compounding Robot.
- 3. Automotive Industry Robots.
- 4. Industrial # 1000 scrubbers and Sage Automation Gartry Robots.

components of pobot:



Block Dragram of Robot working:



- 1. An Industral subot how bousta poorts like county
 Sensors actuator, controlles etc.
- 2. These subsystems communicate among thomselves.
 Via Interfaces, whose function consists basically of decoding the transmitted information from one medium to another.
 - 3. Figure shows that block diagram surpresentation of a typical stobatic mechanical system.
 - 4. The input is a preseribed task, which is define exociet.
- 5. The output of a Hobert mechined system is the actual task, which is manifored by the sensors.
- 6. These sensors sence and transmit the information in the form of feedback signals.
- 7. Thus is compared with the predefined task given to the controller.
- 8. The eurors between the prescribed and the actual task are then fed back into controller, which then synthesize the necessary correstive signals.

9. These are in tam fed back to the aductors, which then drive mechanical system though the required task.

10. Thus the given task is performed by the

Application of Robotics:

1. Roboties in defence sectors:

The defence sector is unaboubtedly the one of the main pands of any country. Each country wants their defence system to be strong. Robots help to approach inaccessible and dangerous zone alwing was.

2. Robotics in Industrial sectors:

Robots are used in vaccous industrial manufacturing industries such as cutting, welding, assembly, dissembly, prok and place for pointed assembly, boards, packaging a labelling, padletizing, product inspection and testing, colour coating, drilling, politishing and handing the materials.

3. Robotics in medical sectors:

Robots also help in various medical freld such as tapanoscopy, newroswigery, orthopaedic swigery, disinfecting mooms, dispensing medication and various other medical domains.

of Robotics in Entertainment:

over the last decade, use of Hobots is continuously getting increased in entainment dotea. Robots are being employed in entertainment

Sector, such as morres, animation, games and contoons. Robots are very help-ful where Alepetitive actions are sequired.

Advantages:

- 1. Acouracy
- 2. Flexibility
- 3. Reduced Tabour change
- 4. Low notice operation
- 6. Fewer production domages
- 6. Increase products

5 Farming and Agriculture:

AMR's are helping farmers harvest their crops more quickly and efficiently and they 're using impressive intelligence capabilities to do it. Agricultural robots can also sipeness, more any branches or leves out of the way, and probe the crop precisely and delicately to avoid causing and have to the product.

6. Smoot cities :

Robotics help create smoother and suffer cities. Hamanord stobots offer way-finding and information sorvices. AMR's are used to flether goods and conduct stoutine security patiels.

Robotics also help expective building construction.

Conduct site surveys and collect building modeling imprimation.

Reinforcement Lewining in Robotics:

- 1. Reinforcement Leasining (RL) enables a robots to autonomously discover an optimum behavious thousagh trival and eoror interaction with its environments.
- 2. Instead of explicitly detailing the Solution to a problem in deinforcement leading the designer of a control task provides feedback in term of a scalar objective function that measure the one-step performance at the xobot.

Principles of Robot Reinforcement Leanuing:

- 1. Effective stepresentation -
- a. Approximate models.
- 3. Prior knowledge or information.

