

AI Assignment - 3

Informed Search Strategies – A* Search

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Function Description:

It finds the single source shortest path using A* Search algorithm , which is a slight modification of the Dijkstra shortest path algorithm.

Data Structure : Graph (Adjacency Matrix)

Code :

```
from collections import defaultdict
import sys

sys.stdin = open("input.txt","r")

def minDistance(dist, sptSet, V):
    min = 1000
    for v in range(V):
        if dist[v] < min and sptSet[v] == False:
            min = dist[v]
            min_index = v
    return min_index

def minFind(dist, sptSet, V, heuristic):
    min = 1000
    for v in range(V):
        if dist[v] + heuristic[v] < min and sptSet[v] == False:
            min = dist[v]+heuristic[v]
            min_index = v
    return min_index

def printPath(parent,j):
    if parent[j] == -1 :
        print(j,end=' ')
    return
```

```

printPath(parent,parent[j])
print(j,end=' ')

```

```

def printSolution(dist, parent,src):
    print("Source \t\tDistance \tPath")
    for i in range( len(dist)):
        if i != src:
            print("\n%d --> %d \t\t%d \t\t" %(src, i, dist[i]), end=" ")
            printPath(parent, i)
            print("\n")
    # dist[dist.index(0)]=9999
    # print("The path to choose : ")
    # printPath(parent,dist.index(min(dist)))

```

```

def dijkstra(graph,src,V):
    dist = [1e7] * V
    dist[src] = 0
    sptSet = [False] * V
    parent = [-1]*V

    for cout in range(V):
        u = minDistance(dist, sptSet,V)
        sptSet[u] = True

        for v in range(V):
            if (graph[u][v] > 0 and sptSet[v] == False and dist[v] > dist[u] + graph[u][v]):
                dist[v] = dist[u] + graph[u][v]
                parent[v] = u

    printSolution(dist,parent,src)

```

```

def astar(graph,src,V):
    heuristic = {0:0, 1:10 ,2:16 ,3:9 ,4:9 ,5:0}
    dist = [1e7] * V
    dist[src] = 0
    sptSet = [False] * V
    parent = [-1]*V

    for cout in range(V):

```

```
u = minFind(dist, sptSet,V,heuristic)
sptSet[u] = True
```

```
for v in range(V):
    if (graph[u][v] > 0 and sptSet[v] == False and dist[v] > dist[u] + graph[u][v]):
        dist[v] = dist[u] + graph[u][v]
        parent[v] = u
```

```
printSolution(dist,parent,src)
```

```
n = int(input())
graph = [[0]*n for i in range(n)]
```

```
for _ in range(int(input())):
    a,b,c = map(int,input().split())
    graph[a][b] = c
    graph[b][a] = c
print(graph)
print()
```

```
print("Using Dijkstra search : ")
dijkstra(graph,0,n)
print()
print("Using A * search : ")
astar(graph,0,n)
```

Output :

```
cduser1@sel12-HP-Compaq-Pro-6305-SFF:~/sabari$ python3 main.py
[[0, 2, 0, 4, 0, 0], [2, 0, 8, 15, 5, 0], [0, 8, 0, 2, 8, 8],
[4, 15, 2, 0, 2, 0], [0, 5, 8, 2, 0, 11], [0, 0, 8, 0, 11, 0]]

Using Dijkstra search :
Source          Distance          Path
0 --> 1          2              0 1
0 --> 2          6              0 3 2
0 --> 3          4              0 3
0 --> 4          6              0 3 4
0 --> 5         14              0 3 2 5

Using A * search :
Source          Distance          Path
0 --> 1          2              0 1
0 --> 2          6              0 3 2
0 --> 3          4              0 3
0 --> 4          6              0 3 4
0 --> 5         17              0 3 4 5

cduser1@sel12-HP-Compaq-Pro-6305-SFF:~/sabari$
```