

# OCP/MPC Workshop 2024

## Nonlinear Model Predictive Control



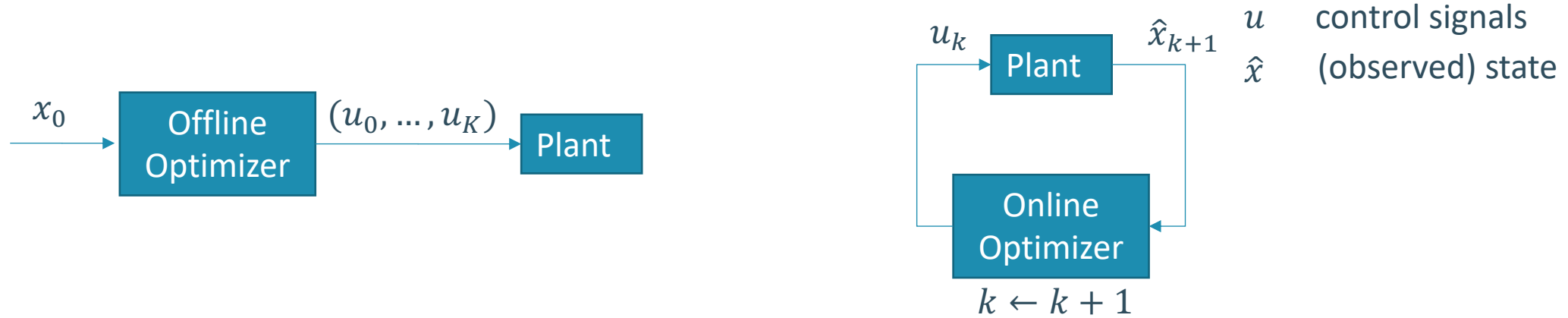
**MISTI**

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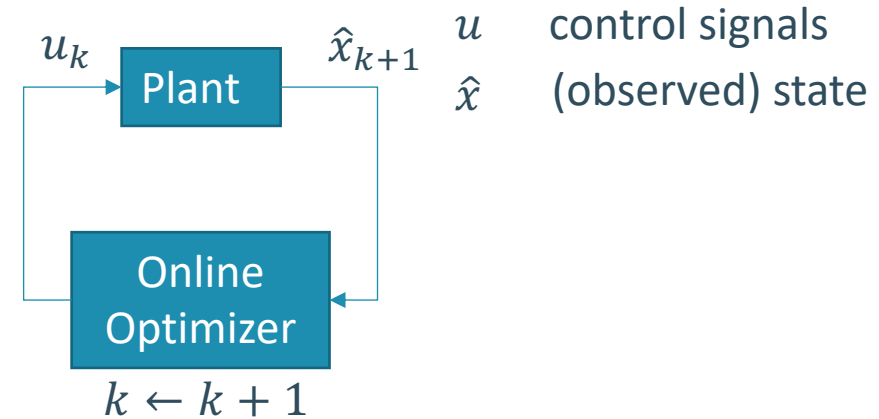
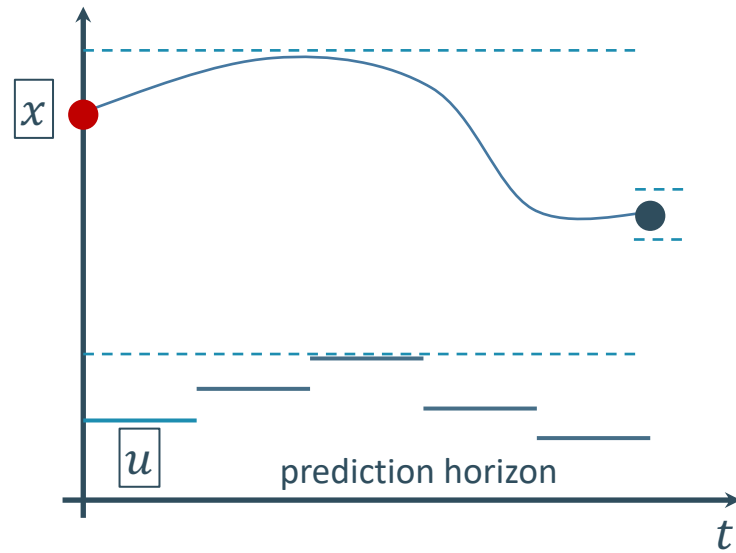
# Model Predictive Control

- Basic idea



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- Basic idea



- recursive feasibility
  - suitable terminal constraints, safety margins, *soft* constraints (penalty terms)
- coping with computational complexity of MPC
  - warm starting, real-time iterations, feasible optimization, ASAP MPC

