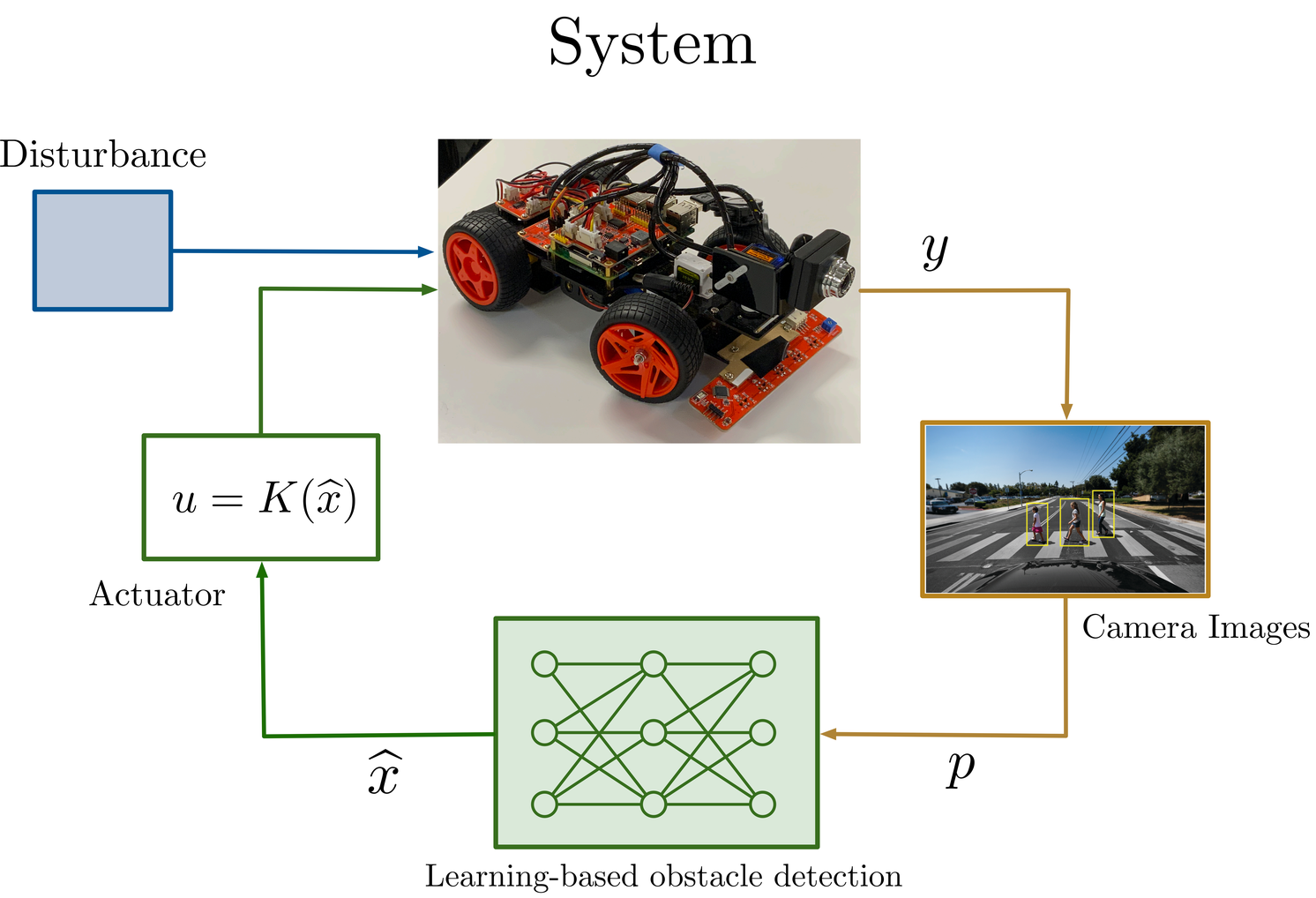
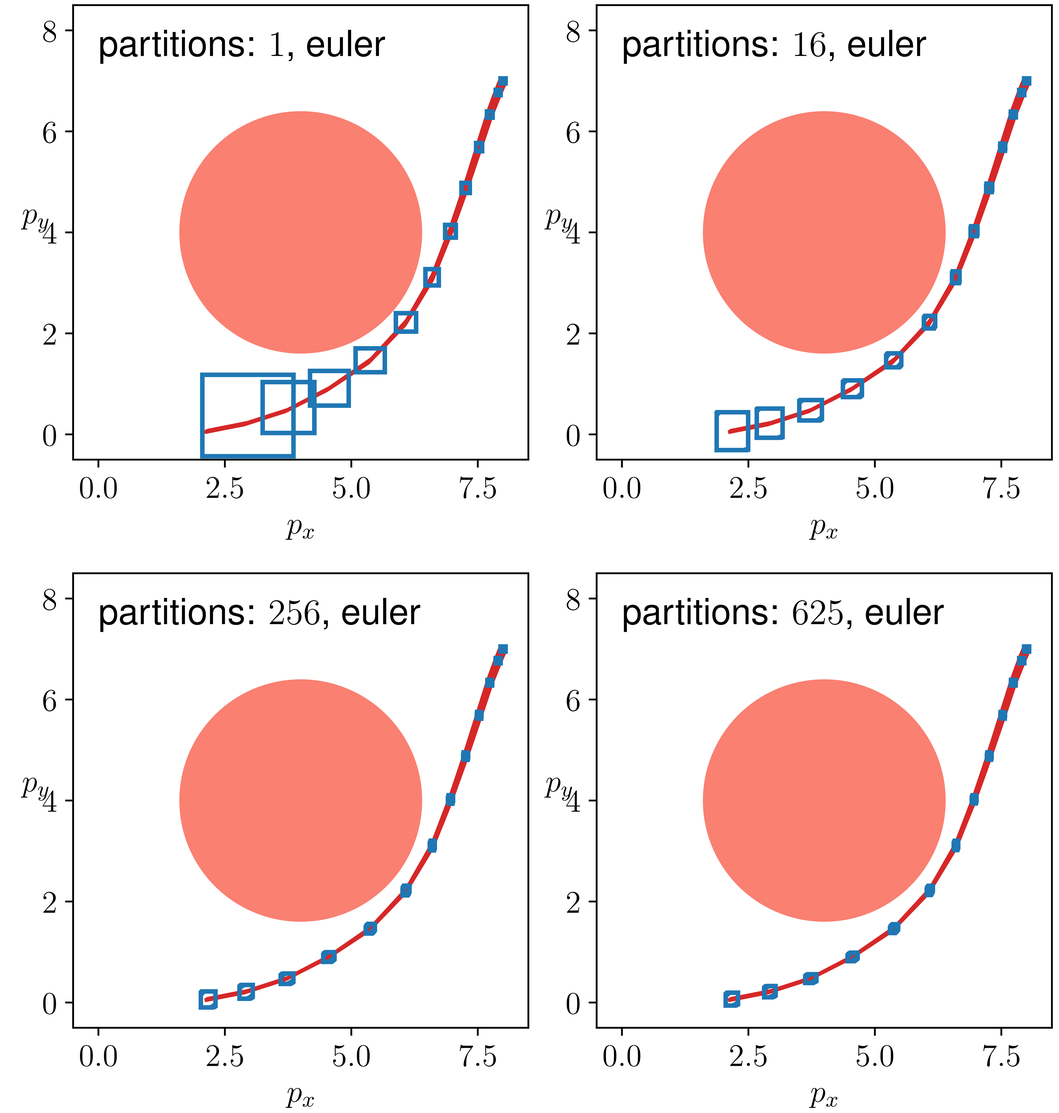

System
Disturbance
y
$u = K(\widehat{x})$
Actuator
Camera Images
$\widehat{x}$
p
Learning-based obstacle detection


partitions: 1, euler
partitions: 16, euler
partitions: 256, euler
partitions: 625, euler
p_x
p_y
0.0
2.5
5.0
7.5
0
2
4
6
8