Saber Jafarpour

CONTACT Information

Decision and Control Laboratory Georgia Institute of Technology Technology Square Research Building Webpage: saberjafarpour.github.io Email: saber@gatech.edu
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Google Scholar: Saber Jafarpour

RESEARCH EXPERIENCE School of Electrical and Computer Engineering Georgia Institute of Technology Sept. 2021–present

Postdoctoral Research Fellow (Advisor: Samuel Coogan)

Center of Control, Dynamical Systems, and Computation

Aug. 2016-Aug. 2021

University of California, Santa Barbara

Postdoctoral Research Fellow (Advisor: Francesco Bullo)

EDUCATION

Department of Mathematics and Statistics, Queen's University Aug. 2011–July 2016

Ph.D. in Applied Mathematics (Advisor: Andrew D. Lewis)

Dissertation: On the Role of Regularity in Mathematical Control Theory

Department of Mechanical Engineering, Shiraz University

Aug. 2008–May 2011

M.Sc. in Applied Mechanics (Advisor: Mojtaba Mahzoon)

Department of Mechanical Engineering, Shiraz University Aug. 2004–Aug. 2008

B.Sc. in Mechanical Engineering

RESEARCH INTERESTS My research interests center around safety, autonomy, and learning in large-scale network systems with applications to power grids, transportation networks, artificial neural networks, and robotic systems. Topics of interest include:

- Stability, resilience, and control of networks
- Reachability and robustness of learning-based systems
- Congestion and multistability in flow networks
- Geometric control and controllability of systems

JOURNAL/ CS-CONFERENCE PAPERS

- [J1] S. Jafarpour*, A. Davydov*, A. V. Proskurnikov, and F. Bullo. Robust implicit networks via non-Euclidean contractions. In *Advances in Neural Information Processing Systems (NeurIPS)*, volume 34, pages 9857–9868, Dec. 2021. URL https://openreview.net/forum?id=SwfsoPuGYku
- [J2] **S. Jafarpour**, E. Y. Huang, K. D. Smith, and F. Bullo. Flow and elastic networks on the *n*-torus: Geometry, analysis and computation. *SIAM Review (Research Spotlight)*, 64(1):59–104, 2021. DOI: 10.1137/18M1242056
- [J3] S. Jafarpour, P. Cisneros-Velarde, and F. Bullo. Weak and semi-contraction for network systems and diffusively-coupled oscillators. *IEEE Transactions on Automatic Control*, 67(3):1285–1300, 2022a. DOI: 10.1109/TAC.2021.3073096
- [J4] S. Jafarpour and F. Bullo. Synchronization of Kuramoto oscillators via cutset projections. IEEE Transactions on Automatic Control, 64(7):2830–2844, 2019. DOI: 10.1109/TAC.2018.2876786
- [J5] S. Jafarpour, V. Purba, S. V. Dhople, B. Johnson, and F. Bullo. Singular perturbation and small-signal stability for inverter networks. *IEEE Transactions on Control of Network Systems*, 9 (2):979–992, 2022c. DOI: 10.1109/TCNS.2021.3084444

- [J6] S. Jafarpour, E. Y. Huang, and F. Bullo. Synchronization of Kuramoto oscillators: Inverse Taylor expansions. SIAM Journal on Control and Optimization, 57(5):3388–3412, 2019. DOI: 10.1137/18M1216262
- [J7] S. Jafarpour. On small-time local controllability. SIAM Journal on Control and Optimization, 58(1):425–446, 2020. DOI: 10.1137/16M1068797
- [J8] S. Jafarpour and A. D. Lewis. Locally convex topologies and control theory. *Mathematics of Control, Signals and Systems*, 28(4):1–29, 2016b. DOI: 10.1007/s00498-016-0179-0
- [J9] A. Davydov, S. Jafarpour, and F. Bullo. Non-Euclidean contraction theory for robust nonlinear stability. IEEE Transactions on Automatic Control, 2022. DOI: 10.1109/TAC.2022.3183966
- [J10] A. Silva, F. Kocayusufoglu, S. Jafarpour, A. Swami, F. Bullo, and A. K. Singh. Combining physics and machine learning for network flow estimation. In *International Conference on Learning Representations*, Online, May 2021. URL https://openreview.net/forum?id=10V53bErniB
- [J11] P. Cisneros-Velarde, S. Jafarpour, and F. Bullo. A contraction analysis of primal-dual dynamics in distributed and time-varying implementations. *IEEE Transactions on Automatic Control*, 67 (7):3560–3566, 2022. DOI: 10.1109/TAC.2021.3103865
- [J12] M. George, S. Jafarpour, and F. Bullo. Markov chains with maximum entropy for robotic surveillance. *IEEE Transactions on Automatic Control*, 64(4):1566–1580, 2019. DOI: 10.1109/TAC.2018.2844120
- [J13] K. D. Smith, **S. Jafarpour**, and F. Bullo. Transient stability of droop-controlled inverter networks with operating constraints. *IEEE Transactions on Automatic Control*, 67(2):633–645, 2022a. DOI: 10.1109/TAC.2021.3053552
- [J14] X. Duan, S. Jafarpour, and F. Bullo. Graph-theoretic stability conditions for Metzler matrices and monotone systems. SIAM Journal on Control and Optimization, 59(5):3447–3471, 2021. DOI: 10.1137/20M131802X
- [J15] V. Purba, B. Johnson, **S. Jafarpour**, F. Bullo, and S. V. Dhople. Dynamic aggregation of gridtied three-phase inverters. *IEEE Transactions on Power Systems*, 35(2):1520–1530, 2020. DOI: 10.1109/TPWRS.2019.2942292
- [J16] V. Purba, B. Johnson, M. Rodriguez, S. Jafarpour, F. Bullo, and S. V. Dhople. Reduced-order aggregate model for parallel-connected single-phase inverters. *IEEE Transactions on Energy Conversion*, 34(2):824–837, 2019. DOI: 10.1109/TEC.2018.2881710
- [J17] K. D. Smith, **S. Jafarpour**, A. Swami, and F. Bullo. Topology inference with multivariate cumulants: The Möbius inference algorithm. *IEEE/ACM Transactions on Networking*, 2022b. DOI: 10.1109/TNET.2022.3164336. To appear

REFEREED CONFERENCE PAPERS

- [C1] S. Jafarpour*, M. Abate*, A. Davydov*, F. Bullo, and S. Coogan. Robustness certificates for implicit neural networks: A mixed monotone contractive approach. In *Learning for Dynamics and Control Conf.*, volume 168, pages 917–930, June 2022. (Oral Presentation: Top 10 percent of submitted papers)
- [C2] S. Jafarpour, A. Davydov, M. Abate, F. Bullo, and S. Coogan. Robust training and verification of implicit neural networks: A non-Euclidean contractive approach. In *ICML Workshop on Formal* Verification of Machine Learning, July 2022b. DOI: 10.48550/arXiv.2208.03889
- [C3] A. Davydov*, S. Jafarpour*, M. Abate, F. Bullo, and S. Coogan. Comparative analysis of interval reachability for robust implicit and feedforward neural networks. In *IEEE Conf. on Decision and Control*, Cancun, Mexico, Dec. 2022. URL https://arxiv.org/abs/2204.00187. To appear
- [C4] A. Davydov*, S. Jafarpour*, A. V. Proskurnikov, and F. Bullo. Non-Euclidean monotone operator theory with applications to recurrent neural networks. In *IEEE Conf. on Decision and Control*, Cancun, Mexico, Dec. 2022. To appear
- [C5] S. Jafarpour and S. Coogan. Resilience of input metering in dynamic flow networks. In *American Control Conference*, pages 126–131, June 2022a. DOI: 10.23919/ACC53348.2022.9867237
- [C6] F. Bullo, P. Cisneros-Velarde, A. Davydov, and S. Jafarpour. From contraction theory to fixed point algorithms on Riemannian and non-Euclidean spaces. In *IEEE Conf. on Decision and Control*, Dec. 2021. DOI: 10.1109/CDC45484.2021.9682883. Invited Tutorial Session

- [C7] E. Y. Huang, S. Jafarpour, and F. Bullo. Synchronization of coupled oscillators: The Taylor expansion of the inverse Kuramoto map. In *IEEE Conf. on Decision and Control*, pages 5340–5345, Miami, USA, Dec. 2018. DOI: 10.1109/CDC.2018.8619559
- [C8] **S. Jafarpour** and A. D. Lewis. The classical and tautological orbit theorems. In 22nd International Symposium on Mathematical Theory of Networks and Systems, July 2016a
- [C9] S. Jafarpour and A. D. Lewis. Real analytic control systems. In *IEEE Conf. on Decision and Control*, pages 5618–5623, Dec. 2014a. DOI: 10.1109/CDC.2014.7040268

Under review Papers

- [U1] S. Jafarpour, A. Davydov, and F. Bullo. Non-Euclidean contraction theory for monotone and positive systems. *IEEE Transactions on Automatic Control*, Apr. 2021. URL https://arxiv. org/abs/2104.01321. Submitted
- [U2] M. Pirani and S. Jafarpour. Network critical slowing down: Data-driven detection of critical transitions in nonlinear networks. *IEEE Transactions on Control of Network Systems*, 2022. URL https://arxiv.org/abs/2208.03881. Submitted
- [U3] S. Jafarpour and S. Coogan. Monotonicity and contraction on polyhedral cones. *IEEE Transactions on Automatic Control*, 2022b. URL http://arxiv.org/abs/2210.11576. Submitted

BOOKS

[B1] S. Jafarpour and A. D. Lewis. *Time-Varying Vector Fields and Their Flows*. SpringerBriefs in Mathematics. Springer International Publishing, 2014b. DOI: 10.1007/978-3-319-10139-2

Invited Talks

- [T1] Robustness of Neural Networks via Non-Euclidean Contraction Theory, *Indian Institute of Technology Delhi (virtual)*, Control Colloquium, Jun. 2022.
- [T2] Safety and Resilience of Large-scale Networks via Contraction Theory, *University of California*, *Riverside*, *Mechanical Engineering Department*, Mar. 2022.
- [T3] Frequency synchronization and multistability in power grids, RSRG Virtual Seminar, Department of Electrical Engineering, California Institute of Technology, May 2021.
- [T4] Non-Euclidean contraction and its extensions with applications to network systems, *Control Seminar*, School of Electrical and Computer Engineering, Georgia Institute of Technology, May 2021.
- [T5] Weak and Semi-Contraction for Network Systems, *Mathematical Biology Seminar*, Department of Mathematics, University of Iowa, Apr. 2021.
- [T6] Stability and Control of Large-scale Nonlinear Networks, Queen's University Control Seminar, Department of Mathematics, Queen's University, Apr. 2021.
- [T7] Synchronization and Multistability in Complex Networks and Power Grids, Control Theory Seminar, Peking University, May 2020.
- [T8] Synchronization in Oscillator Networks and Power Grids, 35th Southern California Control Workshop, UCLA, Nov. 2018.

GRANT WRITING EXPERIENCE

2021

- Collaboration in writing the proposal for grant AFOSR FA9550-22-1-0059 (2021-2024) Title: Contraction Theory for Network Systems: Stability, Control and Optimization PI: Francesco Bullo
- Assistant in writing the proposal for grant HDTRA1-19-1-0017 (2019-2022). Title: Inferring Network Structure and Flows Using Partial Observations PIs: Ambuj K. Singh, Francesco Bullo, and Ananthram Swami

Conference Organizer

Summer 2022 Organizer of the **Whiteboard Seminars** for Decision and Control Lab at Georgia Institute of Technology.

July 2017 Session Chair for **Controlled Networks and System Controllability** at the 14th SIAM Conference on Control & Its Applications, Pittsburgh

Invited Workshops	July 2023 Geometry, Topology and Control System Design Sept. 2021 Autonomous Energy Systems, NREL (Virtual value) Apr. 2019 Innovative Optimization and Control Methods Focus Program on Geometry, Mechanics and Design Systems, NREL (Virtual value) Innovative Optimization and Control Methods Focus Program on Geometry, Mechanics and Design Systems, NREL (Virtual value) Innovative Optimization and Control Methods Focus Program on Geometry, Mechanics and Design Systems, NREL (Virtual value) Innovative Optimization and Control System Design Systems, NREL (Virtual value) Innovative Optimization and Control System Design Systems, NREL (Virtual value) Innovative Optimization and Control Methods Innovative Optimization and Control Methods Innovative Optimization and Control Methods Innovative Optimization Innovative Innov	workshop) workshop) for Autonomous Systems, NREL	
MENTORING	Sept. 2022 - present Sept. 2021 - Jun 2022 Matthew Abate (Ph.D. student, ME Georgia Tech) Sept. 2020 - Mar 2022 Sept. 2018 - Aug. 2021 Sept. 2019 - Jul. 2021 May 2017 - Sept. 2018 Akash Harapanahalli (Ph.D. student, ME Georgia Tech) Matthew Abate (Ph.D. student, ME UCSB) Kevin D. Smith (Ph.D. student, ECE, UCSB) Pedro Cisneros-Velarde (Ph.D. student, ECE, UCSB) Elizabeth Y. Huang (Ph.D. student, ME, UCSB)		
Teaching			
Experience			
	Winter 2015 Instructor, Introduction to Control Theory Winter 2014 Instructor, Lagrangian Mechanics, Dynam Winter 2016 Teaching assistant, Application of Numeri Fall 2012 Teaching assistant, Differential Equations	nics, and Control (MATH 439/836) ical Methods (MATH 272)	
Honors and Awards	2011-2015 Queen's International Tuition Award, Queen's U 2011-2012 Huntly Macdonald Sinclair Tuition Fellowship, O 2011 Ranked 1 st in the M.Sc. Mechanical Engineering 2008 Ranked 26 th in M.Sc. Entrance Exam for Irania 2004 Ranked 288 th in B.Sc. Entrance Exam for Irania	tanding Reviewer, IEEE Control Systems Letters (L-CSS) en's International Tuition Award, Queen's University ely Macdonald Sinclair Tuition Fellowship, Queen's University ked 1 st in the M.Sc. Mechanical Engineering program, Shiraz University ked 26 th in M.Sc. Entrance Exam for Iranian Universities ked 288 th in B.Sc. Entrance Exam for Iranian Universities ked Silver Medal in the 23 th Iranian Student Mathematical Olympiad	
REVIEW ACTIVITY	□ Automatica □ SIAM Journal on Co Transactions on Control of Network Sy Power Systems □ IEEE Transactions on Papers □ IEEE Control Systems Letters Systems Technology □ IEEE Transaction neering □ Nonlinearity □ IEEE Transaction	□ Nature Communications □ IEEE Transactions on Automatic Control □ Automatica □ SIAM Journal on Control and Optimization □ IEEE Transactions on Control of Network Systems □ IEEE Transactions on Power Systems □ IEEE Transactions on Circuits and Systems I: Regular Papers □ IEEE Control Systems Letters □ IEEE Transactions on Control Systems Technology □ IEEE Transactions on Network Science and Engineering □ Nonlinearity □ IEEE Transactions on Energy Conversion □ IEEE Conference on Decision and Control (CDC) □ American Control	
		Conference (ACC) European Control Conference (ECC)	
REFERENCES	Department of Mechanical Engineering Scho University of California, Santa Barbara Geor	nuel Coogan ool of Electrical and Computer Engineering rgia Institute of Technology coogan@gatech.edu	
	Department of Electrical and Computer Department of Engineering Quee	lrew D. Lewis artment of Mathematics and Statistics en's University, Canada rew@mast.queensu.ca	

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