

Communications and Control Engineering Series Editors: A. Fettweis · J. L. Massey · M. Thoma

J. A. Richards

Analysis of Periodically Time-Varying Systems

With 73 Figures

J. A. RICHARDS

School of Electrical Engineering and Computer Science University of New South Wales P.O. Box 1 Kensington, N.S.W. 2033, Australia

ISBN-13:978-3-642-81875-2 e-ISBN-13:978-3-642-81873-8

DOI: 10.1007/978-3-642-81873-8

Library of Congress Cataloging in Publication Data Richards, John Alan, 1945—. Analysis of periodically time-varying systems. (Communications and control engineering series) Bibliography: p. Includes index. 1. System analysis. I. Title, II. Series. QA402.R47 1983 003 82-5978 AACR2

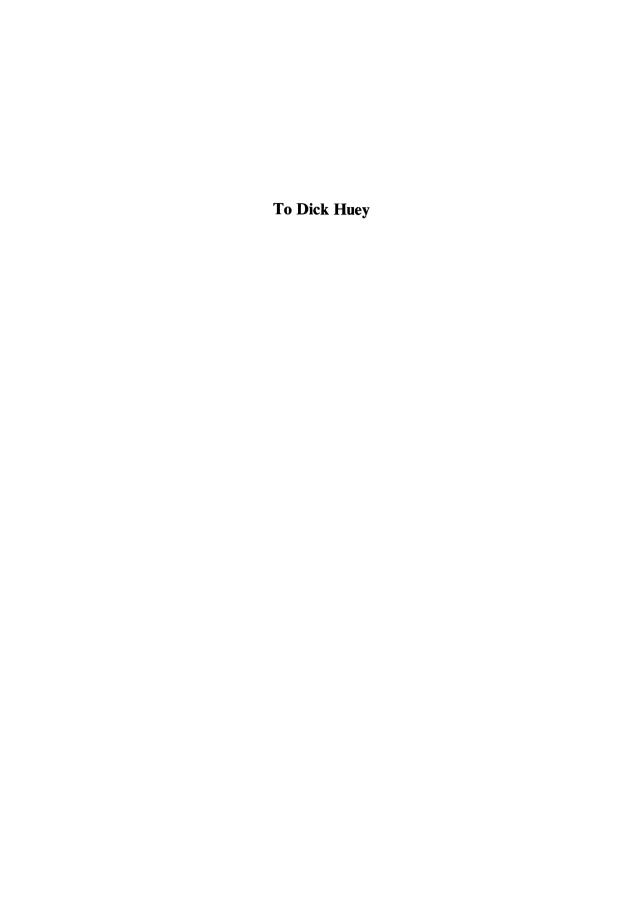
This work is subject to copyright. All rights are reserved, whether the whole or part of the material is concerned, specifically those of translation, reprinting, re-use of illustrations, broadcasting, reproduction by photocopying machine or similar means, and storage in data banks. Under § 54 of the German Copyright Law where copies are made for other than private use, a fee is payable to »Verwertungsgesellschaft Wort«, Munich.

© Springer-Verlag Berlin, Heidelberg 1983 Softcover reprint of the hardcover 1st edition 1983

The use of registered names, trademarks, etc. in this publication does not imply, even in the absence of a specific statement, that such names are exempt from the relevant protective laws and regulations and therefore free for general use.

Typesetting: Asco Trade Typesetting Ltd., Hong Kong

2061/3020-543210



Preface

Many of the practical techniques developed for treating systems described by periodic differential equations have arisen in different fields of application; consequently some procedures have not always been known to workers in areas that might benefit substantially from them. Furthermore, recent analytical methods are computationally based so that it now seems an opportune time for an applications-oriented book to be made available that, in a sense, bridges the fields in which equations with periodic coefficients arise and which draws together analytical methods that are implemented readily. This book seeks to fill that role, from a user's and not a theoretician's view.

The complexities of periodic systems often demand a computational approach. Matrix treatments therefore are emphasized here although algebraic methods have been included where they are useful in their own right or where they establish properties that can be exploited by the matrix approach. The matrix development given calls upon the nomenclature and treatment of H. D'Angelo, Linear Time-Varying Systems: Analysis and Synthesis (Boston: Allyn and Bacon 1970) which deals with time-varying systems in general. It is recommended for its modernity and comprehensive approach to systems analysis by matrix methods. Since the present work is applications-oriented no attempt has been made to be complete theoretically by way of presenting all proofs, existence theorems and so on. These can be found in D'Angelo and classic and well-developed treatises such as

McLachlan, N. W.: Theory and application of Mathieu functions. Clarendon: Oxford U.P. 1947. Reprinted by Dover, New York 1964.

Arscott, F. M.: Periodic differential equations. Oxford: Pergamon 1964. Magnus, W.; Winkler, S.: Hill's equation. New York: Wiley 1966.

Instead, this book relates theory to applications via analytical methods that are, in the main, computationally-based.

The book is presented in two parts. The first deals with theory, and techniques for applying that theory in the analysis of systems. A highlight of this (chapter five) is the development of modelling procedures that allow intractable periodic differential equations to be handled. This is regarded as significant since the great majority of differential equations with periodic coefficients cannot be treated by closed form methods of analysis. The second part presents an overview of the applications of periodic equations. The particular applications chosen have been done so to illustrate the variety of ways periodic differential equation descriptions arise and to demonstrate that the modelling procedures of Part I can be useful in determining system properties.

VIII Preface

The developments in Part I and the applications of Part II are all related to a standard form for the equations, which in the case of second order systems is the canonical Hill equation used by McLachlan, viz.

$$\ddot{x} + (a - 2q\psi(t))x = 0, \psi(t) = \psi(t + \pi)$$

where $\psi(t)$ is a general periodic coefficient. Adopting such a canonical form is of value if the results of the theory and techniques chapters are to be used directly. Original system equations for particular applications presented in Part II are thus transformed into the appropriate canonical form before drawing upon the material of Part I.

The treatment is not intended to provide a text for the study of periodic differential equations but could be used for a single semester senior undergraduate or graduate level subject in systems with periodic parameters, particularly if applications are to be emphasised.

The encouragement and assistance of others is of course essential in producing a book. It is the author's pleasure to acknowledge the inspiration of his mentor and friend Professor Dick Huey to whom this book is dedicated; over the years of their association he has done much to encourage in a quiet, yet effective, manner the completion of this work. The manuscript was typed by Mrs. Gellisinda Galang to whom the author is grateful for the competent and patient manner in which she undertook the task.

Kensington, Australia, March 1982

J. A. Richards

Contents

List of Symbols

Part I	Theory and Techniques	1
Chapter 1	Historical Perspective	3
1.1 1.2	The Nature of Systems with Periodically Time-Varying Parameters 1831–1887 Faraday to Rayleigh-Early Experimentalists and	3
1.3	Theorists	7 9
1.4	Second Generation Applications	10
1.5	Recent Theoretical Developments	12
1.6	Commonplace Illustrations of Parametric Behaviour	12
	References for Chapter 1	14
	Problems	16
Chapter 2	The Equations and Their Properties	17
2.1	Hill Equations	17
2.2	Matrix Formulation of Hill Equations	18
2.3	The State Transition Matrix	19
2.4	Floquet Theory	20
2.5	Second Order Systems	22
2.6	Natural Modes of Solution	23
2.7	Concluding Comments	24
	References for Chapter 2	25
	Problems	25
Chapter 3	Solutions to Periodic Differential Equations	27
3.1	Solutions Over One Period of the Coefficient	27
3.2	The Meissner Equation	28
3.3	Solution at Any Time for a Second Order Periodic Equation	29
3.4	Evaluation of $\phi(\pi, 0)^m$, m Integral	30
3.5	The Hill Equation with a Staircase Coefficient	32
3.6 3.6.1	The Hill Equation with a Sawtooth Waveform Coefficient	32
3.6.2	The Wronskian Matrix with z Negative	35 35
3.6.3	The Wronskian Matrix with z Zero	36
3.7	The Hill Equation with a Positive Slope, Sawtooth Waveform	30
3.1	Coefficient	36
3.8	The Hill Equation with a Triangular Coefficient	37

X Contents

	3.9	The Hill Equation with a Trapezoidal Coefficient	38
	3.10	Bessel Function Generation	38
	3.11	The Hill Equation with a Repetitive Exponential Coefficient	39
	3.12	The Hill Equation with a Coefficient in the Form of a Repetitive	
		Sequence of Impulses	40
	3.13	Equations of Higher Order	41
	3.14	Response to a Sinusoidal Forcing Function	41
	3.15	Phase Space Analysis	44
	3.16	Concluding Comments	46
	2.10	References for Chapter 3	48
		Problems	49
		Troolens	47
Chapter	4	Stability	50
			50
	4.1	Types of Stability	50
	4.2	Stability Theorems for Periodic Systems	51
	4.3	Second Order Systems	52
	4.3.1	Stability and the Characteristic Exponent	52
	4.3.2	The Meissner Equation	53
	4.3.3	The Hill Equation with an Impulsive Coefficient	56
	4.3.4	The Hill Equation with a Sawtooth Waveform Coefficient	57
	4.3.5	The Hill Equation with a Triangular Waveform Coefficient	57
	4.3.6	Hill Determinant Analysis	57
	4.3.7	Parametric Frequencies for Second Order Systems	62
	4.4		63
		General Order Systems	63
	4.4.1	Hill Determinant Analysis for General Order Systems	
	4.4.2	Residues of the Hill Determinant for $q \to 0$	66
	4.4.3	Instability and Parametric Frequencies for General Systems	67
	4.4.4	Stability Diagrams for General Order Systems	67
	4.5	Natural Modes and Mode Diagrams	68
	4.5.1	Nature of the Basis Solutions	68
	4.5.2	P Type Solutions	69
	4.5.3	C Type Solutions	70
	4.5.4	N Type Solutions	70
	4.5.5	Modes of Solution	71
	4.5.6	The Modes of a Second Order Periodic System	71
	4.5.7	Boundary Modes	72
	4.5.8	Second Order System with Losses	73
	4.5.9	Second Order System with Losses	73
		Modes for Systems of General Order	
		Coexistence	74
	4.6	Short Time Stability	75
		References for Chapter 4	79
		Problems	79
Chapter	. 5	A Modelling Technique for Hill Equations	81
Chapter	3	A Wodening Technique for Thir Equations	01
	5.1	Convergence of the Hill Determinant and Significance of the Harmonics	01
		of the Periodic Coefficients	81
	5.1.1	Second Order Systems	81
	5.1.2	General Order Systems	84
	5.2	A Modelling Philosophy for Intractable Hill Equations	84
	5.3	The Frequency Spectrum of a Periodic Staircase Coefficient	85
	5.4	Piecewise Linear Models	87
	5.4.1	General Comments	87
	5.4.2	Trapezoidal Models	87
		•	

Contents	XI

5.5 5.6 5.7 5.8 5.9	Stability Diagram and Characteristic Exponent Modelling 8 Models for Nonlinear Hill Equations 8 A Note on Discrete Spectral Analysis 8 Concluding Remarks 9 References for Chapter 5	38 38 39 90 91
Chapter 6	The Mathieu Equation	93
6.1 6.1.1 6.1.2 6.1.3 6.1.4 6.2 6.3 6.3.1 6.3.2 6.3.3 6.3.4 6.4 6.4.1 6.4.2	Periodic Solutions 9 Mathieu Functions of Fractional Order 9 Fractional Order Unstable Solutions 9 Limitations of the Classical Method of Treatment 9 Numerical Solution of the Mathieu Equation 9 Modelling Techniques for Analysis 9 Rectangular Waveform Models 9 Trapezoidal Waveform Models 10 Staircase Waveform Models 10 Staircase Waveform Models 10 Ferformance Comparison of the Models 10 Stability Diagrams for the Mathieu Equation 10 The Lossless Mathieu Equation 10 The Damped (Lossy) Mathieu Equation 10	01 03 03 05 06
Part II	Applications	
Chapter 7	Practical Periodically Variable Systems	
7.1 7.1.1 7.1.2 7.1.3 7.1.4 7.1.5 7.1.6 7.2 7.3 7.3.1 7.3.2 7.3.3 7.3.4 7.4.1 7.4.2 7.4.2 7.4.4 7.4.5	The Quadrupole Mass Filter 11 The Monopole Mass Spectrometer 11 The Quadrupole Ion Trap 12 Simulation of Quadrupole Devices 12 Non idealities in Quadrupole Devices 12 Dynamic Buckling of Structures 12 Elliptical Waveguides 12 The Helmholtz Equation 12 Rectangular Waveguides 12 Circular Waveguides 13 Elliptical Waveguides 13 Elliptical Waveguides 13 Computation of the Cut-off Frequencies for an Elliptical Waveguide 13 Wave Propagation in Periodic Media 13 Pass and Stop Bands 13 The $\omega - \beta_r$ (Brillouin) Diagram 14 Electromagnetic Wave Propagation in Periodic Media 14 Guided Electromagnetic Wave Propagation in Periodic Media 14 Electrons in Crystal Lattices 14	12 13 17 20 23 23 27 28 29 31 33 36 43 44 45

XII	Contents

7.5	Electric Circuit Applications	150
7.5.1	Degenerate Parametric Amplification	151
7.5.2	Degenerate Parametric Amplification in High Order Periodic Networks	154
7.5.3	Nondegenerate Parametric Amplification	154
7.5.4	Parametric Up Converters	155
7.5.5	N-path Networks	158
	References for Chapter 7	162
	Problems	165
Appendix	Bessel Function Generation by Chebyshev Polynomial Methods	168
•	References for Appendix	169
Subject Index		171

List of Symbols

а	constant coefficient in a Hill or Mathieu equation
	stability boundaries for a Hill or Mathieu equation
$a_0, a_1 \cdots$	
A_{ir}	residues of the Hill determinant
$b_1, b_2 \cdots$	stability boundaries for a Hill or Mathieu equation
B_1, B_2	boundary modes for a Hill equation
c	capacitance per unit length
C	capacitance; discrete transition matrix; solution type of a Hill equation corre-
	sponding to complex eigenvalues of the discrete transition matrix
C_r	expansion coefficients in a Floquet solution
cem	Mathieu function of the first kind of order m
Ce_m	modified Mathieu function of the first kind of order m
ce_v^m	Mathieu function of the first kind of fractional order v
ceu	unstable Mathieu function of the first kind of fractional order v
$d_i(t)$	weighting coefficients
\boldsymbol{D}	electric displacement vector
e	eccentricity; charge on ion
E	Young's modulus
\tilde{E}	electric field vector
E(t)	time varying electric field
E_g	generator voltage
\overline{f}^{g}	semi interfocal distance of an ellipse
f(t), f(t)	forcing function, and vector form, in a periodic system; general function of time
F	force
$g_i(t)$	periodic coefficient in a general order Hill equation
G(t)	periodic coefficient matrix
G_n	complex Fourier coefficient of $g(t)$.
h"	eigenvalue of a waveguide mode
h_k, h_r	step heights in a staircase periodic coefficient
h(t)	impulse response of a linear, time-invariant system
ħ	$h/2\pi$, h is Planck's constant
H	magnetic field vector
i, j, k	unit vectors in a cartesian coordinate system
i(t)	current
I	current phasor; second moment of area
$J_{_{\mathbf{v}}}$	Bessel function of the first kind of order v
\vec{k}	wave number
l	inductance per unit length
L	inductance
m	mass of an ion; distributed mass per unit length; waveguide mode number
M_+, M	state transition matrices
n	waveguide mode number
N	solution type of a Hill equation corresponding to a negative eigenvalue of the
	discrete transition matrix
	The state of the s

XIV List of Symbols

p(t)	periodic staircase modulating function
P	solution type of a Hill equation corresponding to a positive eigenvalue of the
-	discrete transition matrix
P(t)	periodic matrix
P_m	complex Fourier coefficient of $p(t)$
q	half amplitude of the periodic coefficient in a Hill or Mathieu equation
$q_{mn}^{c \text{ or } s}$	nth value of q that gives a zero of the mth order modified Mathieu function of
	the first or second kind
q	charge
q(t)	periodic staircase modulating function
Q_m	complex Fourier coefficient of $q(t)$
r	radial polar coordinate
r_0	field radius in a quadrupole mass filter
R	resistance
R_g	generator impedance
$R_L^{"}$	load impedance
$R_{\rm s}^{\rm L}$	series resistance of varactor diode
s	complex frequency variable; Laplace transform variable
s_i	root of system characteristic equation
se_m	Mathieu function of the second kind of order m
Se_m	modified Mathieu function of the second kind of order m
t t	real time
T	period; tension
$T_r(x)$	Chebyshev polynomial
U	de potential
v	phase velocity
v(t)	voltage
V	Voltage phasor; magnitude of periodic potential
	Wronskian matrix; unit periodic sampling function; impulse response of an N
W(t)	path network
W	Wronskian (determinant)
W_0	state vector for a periodically time-varying system
$\mathbf{x}(t)$	
$\overline{X}(s)$	single sided Laplace transform of the state vector $x(t)$
Y_{v}	Bessel function of the second kind of order v
α	real part of the characteristic exponent
α_k	constant coefficient in a general periodic differential equation
β	imaginary part of the characteristic exponent; phase constant inside a waveguide
β_0	phase constant in an unbounded medium
β_r	phase constant for the rth space harmonic in a periodic structure
γ	propagation constant inside a waveguide
γ_k	amplitude parameter in a general periodic differential equation
γ_{o}	propagation constant in an unbounded medium
Γ	exponent matrix associated with the discrete transition matrix; Gamma function
δ	duty cycle parameter for a rectangular or trapezoidal waveform
$\delta(t)$	Delta (impulse) function
$\Delta(\)$	Hill infinite determinant
3	permittivity; rise or fall time in a trapezoidal waveform
ζ	canonical displacement variable; damping constant
η	normalised rise and fall time in a trapezoidal waveform; elliptic coordinate
heta	period of the periodic coefficients in a general order Hill equation
λ_c	cut-off wavelength in a waveguide
λ_i	eigenvalue of the discrete transition matrix
Λ	matrix of eigenvalues of the discrete transition matrix
μ	permeability
μ, μ_i	characteristic exponent in the solution to a periodic differential equation
	•

List of Symbols XV

Canonical time variable: elliptic coordinate	
 ξ canonical time variable; elliptic coordinate Ξ() periodic function in the solution to a periodic differential equation 	
π pi; periodic the periodic coefficient in a Hill or Mathieu equation	
1 0.1 ***** 1	
ρ_r pole of the Hill determinant σ conductivity	
τ positive porch length in a rectangular or trapezoidal waveform	
τ_r , τ_f rise and fall times in a trapezoidal waveform ϕ scalar electric potential; polar coordinate	
$\phi(t, 0)$ state transition matrix over the interval $(0, t)$ $\phi(\theta, 0)$ discrete state transition matrix for a general periodic differential equation	
$\phi(\pi, 0)$ discrete state transition matrix for a Hill or Mathieu equation	
χ canonical time interval less than π χ_{mn}^e nth zero of the mth order Bessel function of the first kind	
	-:4
χ_{mn}^{h} nth zero of the first derivative of the mth order Bessel function of the first	lina
ψ matrix of eigenvectors of the discrete transition matrix	14
$\psi(t)$ periodic function; voltage applied to the electrodes of a quadrupole mass f	iter
ψ_i eigenvector of the discrete transition matrix	
Ψ_n complex Fourier coefficient of $\psi(t)$	
ω frequency	
ω_c cut-off frequency of a waveguide	
ω_i ith natural frequency of a linear, time-invariant system; system input (for	cing)
frequency	
ω_l idler frequency	
ω_0 resonant frequency of a second order system	
ω_p pump frequency ∇^2 Laplacian in three dimensions	
∇_t^2 transverse (two dimensional) Laplacian	