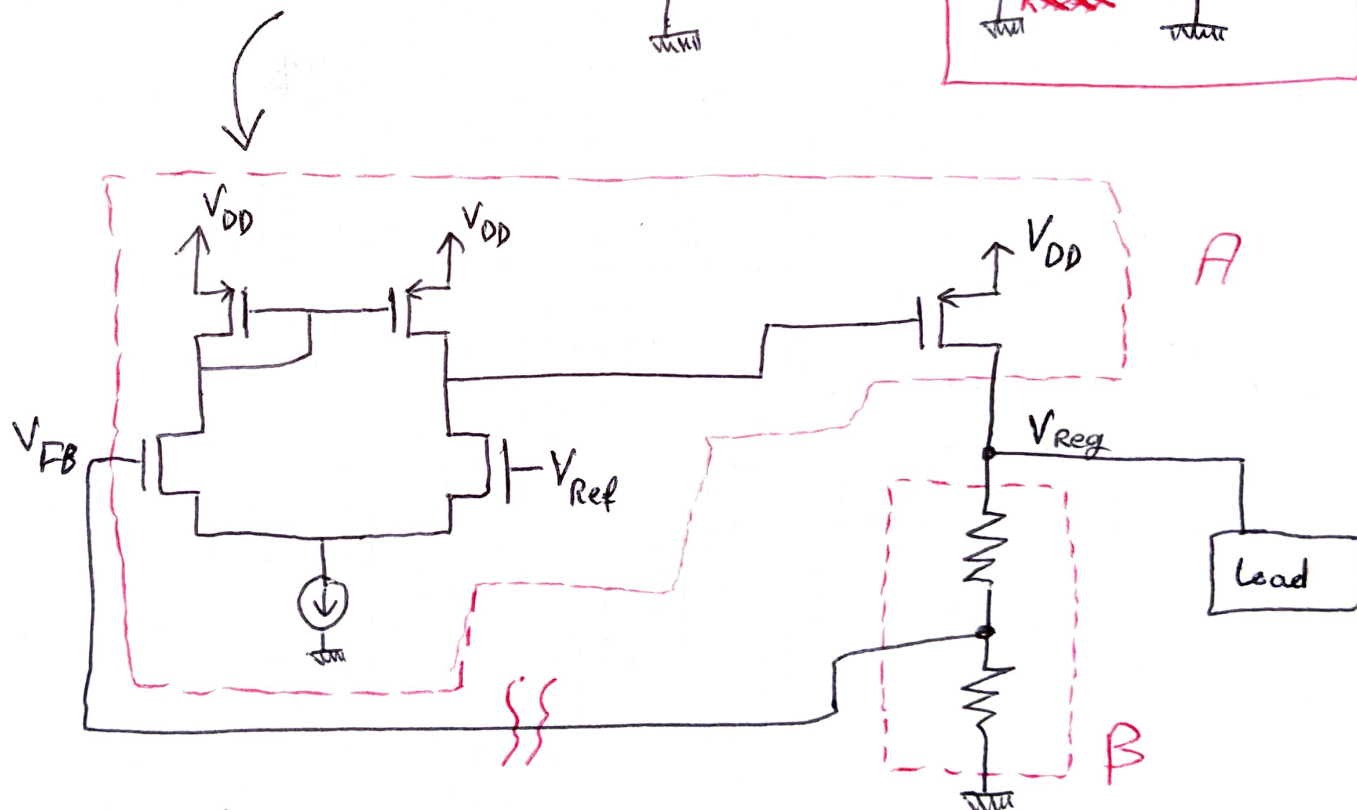
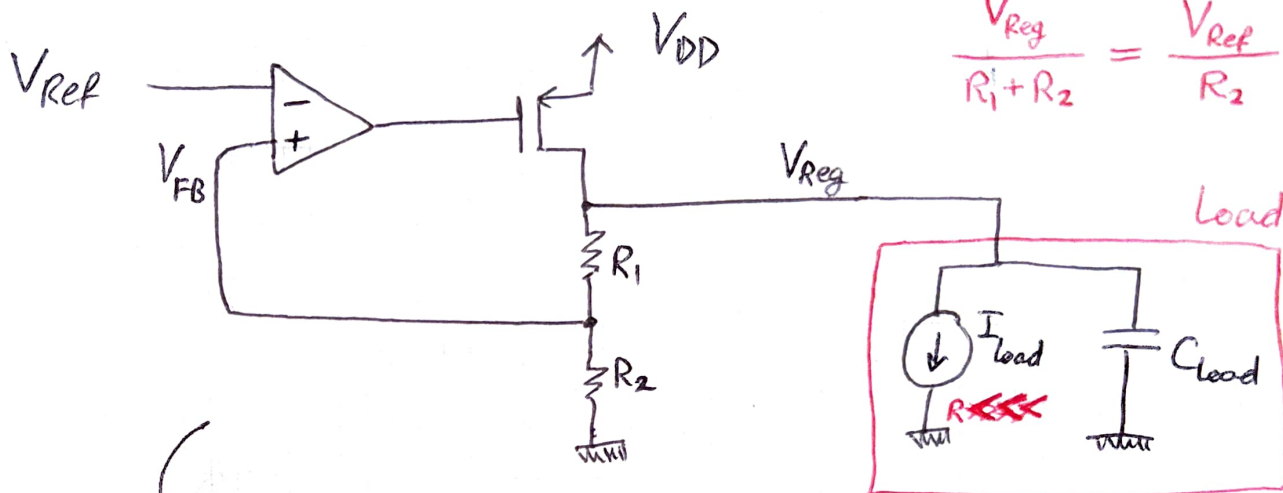
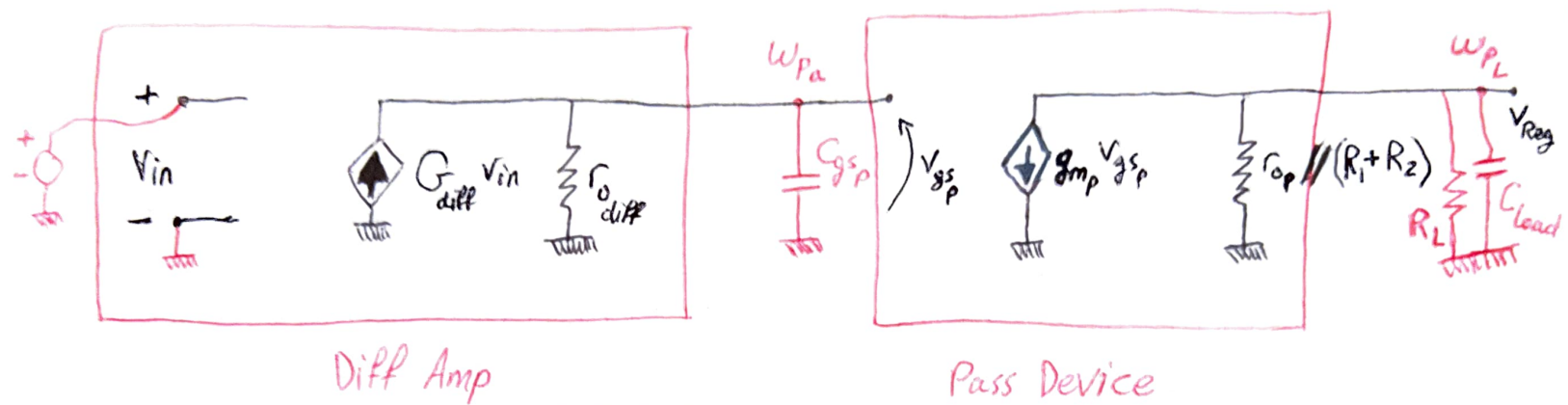


# LDO Analysis



$$A_{cl} = \frac{A}{1 + AB} = \frac{A}{1 + L}$$



$$L = \text{Loop Gain} = \frac{G_{\text{diff}} r_{\text{diff}} \cdot g_{\text{mp}} R_{\text{load}}}{\left(1 + \frac{s}{\omega_{Pa}}\right) \left(1 + \frac{s}{\omega_{PL}}\right)}$$

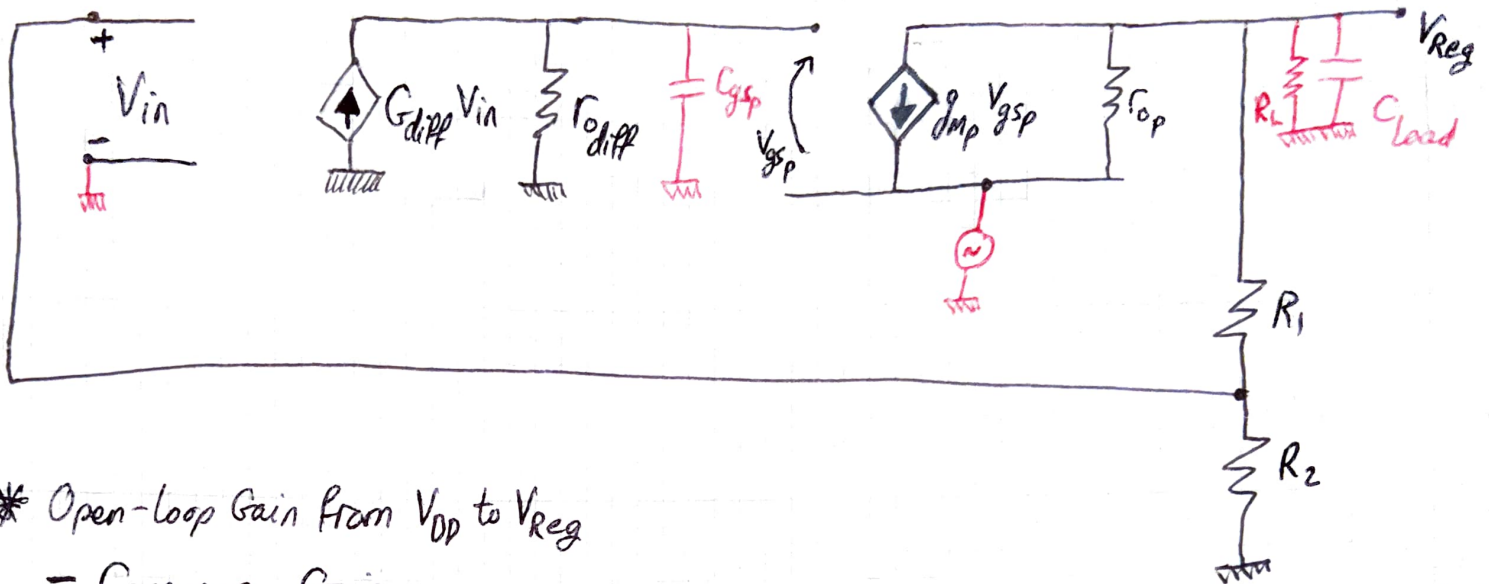
$$R_{\text{load}} = r_{op} \parallel (R_1 + R_2) \parallel R_L$$

➔ For PM

$$\omega_{Pa} = \frac{1}{r_{\text{diff}} \cdot C_{gsP}}$$

$$\omega_{PL} = \frac{1}{R_{\text{load}} \cdot C_{\text{load}}}$$

➔  $\omega_{Pa} < \omega_{PL}$   
↓  
dominant



\* Open-Loop Gain From  $V_{DD}$  to  $V_{reg}$   
= Common-Gain

$$H_{CG} \approx g_{mp} R_{load} \cdot \frac{1}{(1 + \frac{s}{\omega_{out}})}$$

$$R_{load} = r_{op} \parallel (R_1 + R_2) \parallel R_L$$

$$\omega_{out} = \frac{1}{C_{load} \cdot R_{load}}$$

\* Closed-Loop Gain from  $V_{DD}$  to  $V_{reg}$

$$H = \frac{V_{reg}}{V_{DD}} = PSRR^{-1} = \frac{H_{CG}(s)}{1 + L(s)}$$



For PSRR

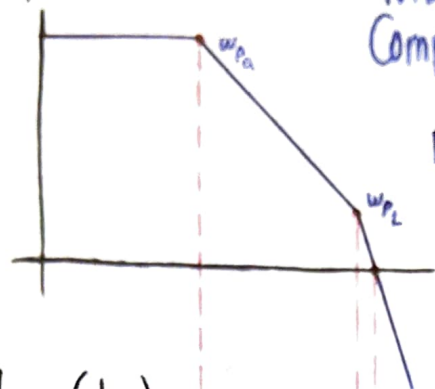
\* Usually: @ low  $I_{load} \rightarrow PM_{min}$

@ high  $I_{load} \rightarrow PSRR_{min}$

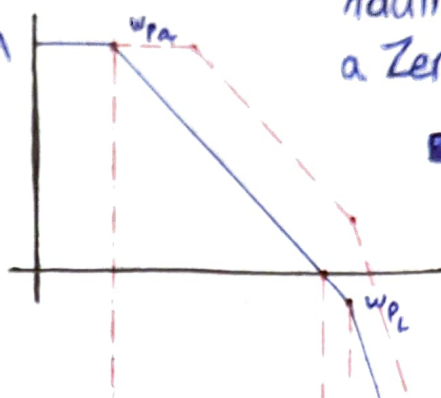
# Loop Gain & PSRR

(Assume  $\omega_p$  dominant)

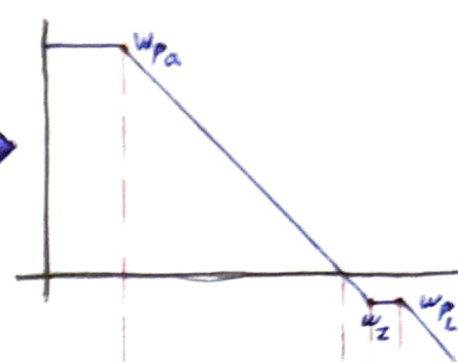
Loop Gain (dB)



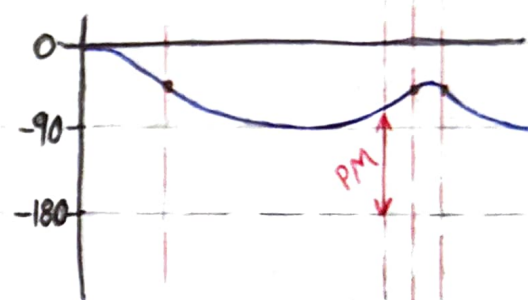
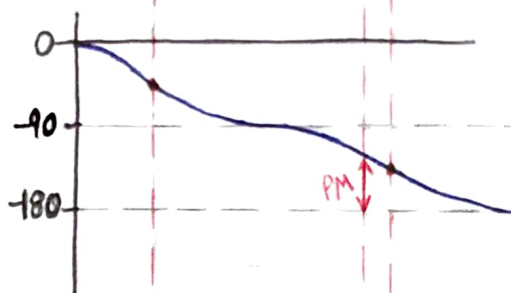
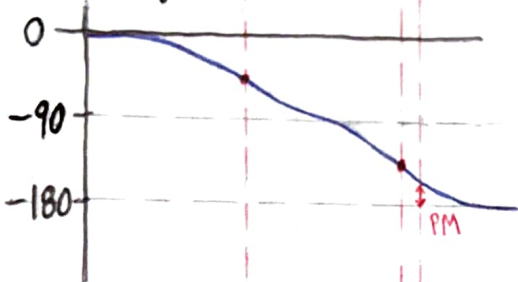
With Miller Compensation



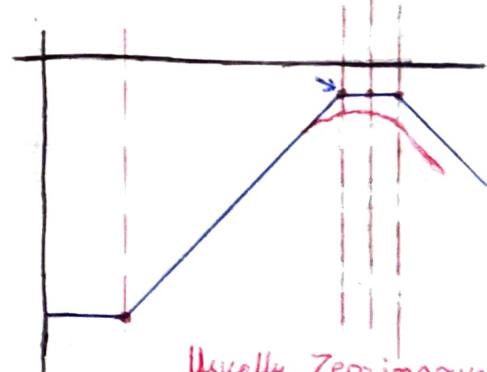
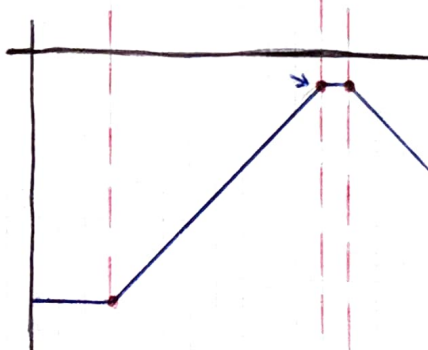
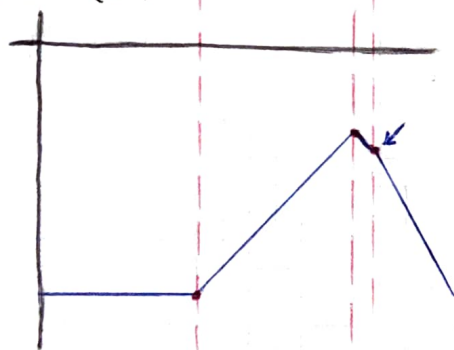
Adding a Zero



Phase (deg)



PSRR<sup>-1</sup> (dB)



Usually, Zero improves both PM & PSRR



Phase Margin Improves

PSRR Worsens (Max PSRR<sup>-1</sup> Increases)

} Tradeoff

\* Note: ①  $\omega_{pL} < \omega_{GB} \rightarrow PM \ll 0$  (Unstable loop)

② As  $\omega_{pa} \gg \omega_{GB} \rightarrow PM \uparrow$  but PSRR<sup>-1</sup>  $\uparrow$

# LDO Compensation

## ① Miller Compensation:

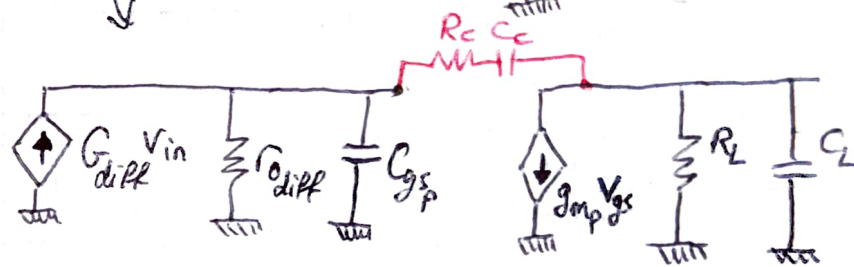
Assuming  $R_e = 0$  for now:

### ① dominant pole

$$\omega_{p_a} = \frac{1}{r_{o_{diff}} (g_{mp} R_L) C_c + C_{gs_p}}$$

### ② Non dominant pole

$$\omega_{p_L} = \frac{g_{mp}}{C_{gs_p} + C_L}$$



### ③ Zero

$$\omega_z = \frac{g_{mp}}{C_c}$$

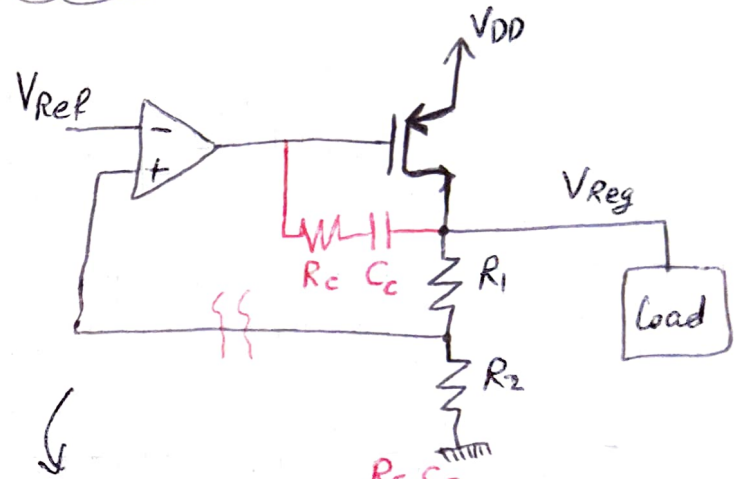
if  $R_e \neq 0$

$$\omega_z = \frac{1}{C_c \left( \frac{1}{g_{mp}} - R_e \right)}$$

↓  
RHP zero, reduces PM  
(undesirable)

→  $R_e > \frac{1}{g_{mp}}$   
to give phase lead  
(improve PM)

→  $U_{GB} = \omega_o = \frac{G_{diff}}{C_c}$





## ② RC Compensation:

Assume  $C_c \gg C_{gs_p}$  (ignore  $C_{gs_p}$  for now)

→ To find the zero, find the condition where  $V_{gs_p} = 0$ :

$$V_{gs_p} = G_{diff} V_{in} (r_o \parallel R_c + \frac{1}{sC_c}) = 0$$

$$\therefore \frac{r_o \cdot (R_c + \frac{1}{sC_c})}{r_o + R_c + \frac{1}{sC_c}} = 0$$

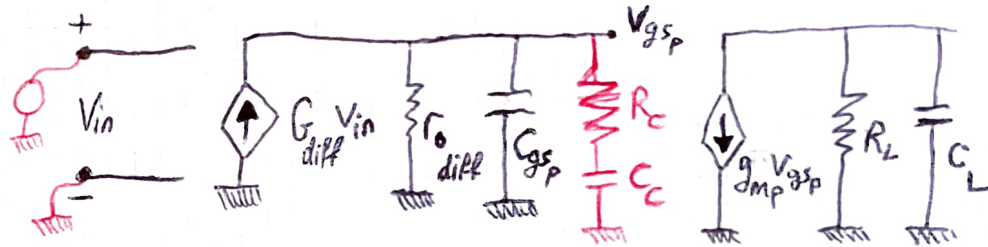
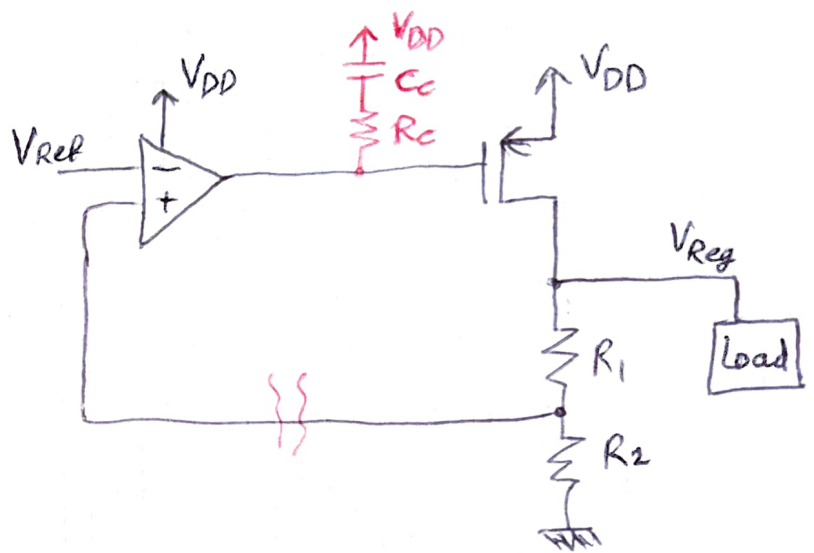
$$\frac{(1 + sR_cC_c)}{(1 + s(r_o + R_c)C_c)} = 0$$

→ ① dominant pole

$$\omega_{p1} = \frac{1}{(r_o + R_c)C_c}$$

② Zero

$$\omega_z = \frac{1}{R_cC_c}$$



③ Non dominant poles

$$\omega_2 = \frac{1}{C_{gs_p} (r_o \parallel R_c)}$$

$$\omega_3 = \frac{1}{C_L R_L}$$

at higher frequencies,  
 $C_c \sim$  as a short