# Software Development for Data Analysis

- A statistical procedure that uses an orthogonal transformation to convert a set of observations of possibly correlated variables into a set of values of linearly uncorrelated variables called principal components.
- The analyzed data consist in a table of observations, having *n* rows and *m* columns.

$$X = \begin{bmatrix} x_{11} & \dots & x_{1m} \\ \dots & & \\ x_{n1} & \dots & x_{nm} \end{bmatrix} \quad \text{, where } x_{ij} \text{ is the value taken by variable } j \text{ for the observation } i.$$

The variable described by table X are also known as *initial*, causal or observed variables.

- $X_j$  is the column vector containing the values of variable j for n observations;
- The goal of the procedure is to describe table X through a reduced number of nonrelated variables:  $C_1, C_2, ..., C_s$ .

#### Phase 1

Determine a new variable  $C_1$ , the first principal component, as linear combination of variables  $X_i$ :

$$C_1 = a_{11}X_1 + ... + a_{i1}X_i + ... + a_{m1}X_m$$

The value taken by  $C_1$  for a given observation i:

$$c_{i1} = a_{11}x_{i1} + \dots + a_{j1}x_{ij} + \dots + a_{m1}x_{im}$$

where 
$$a_{i1}$$
,  $j = \overline{1,m}$ 

#### Phase k

Determine a new variable  $C_k$ , the k principal component, as linear combination of variables X:

$$C_k = a_{1k}X_1 + ... + a_{jk}X_j + ... + a_{mk}X_m$$
,

where  $a_k$  is the vector containing the multipliers  $a_{jk}$ ,  $j = \overline{1, m}$ 

The link between the causal variables (X) and the principal components (C) is given by:

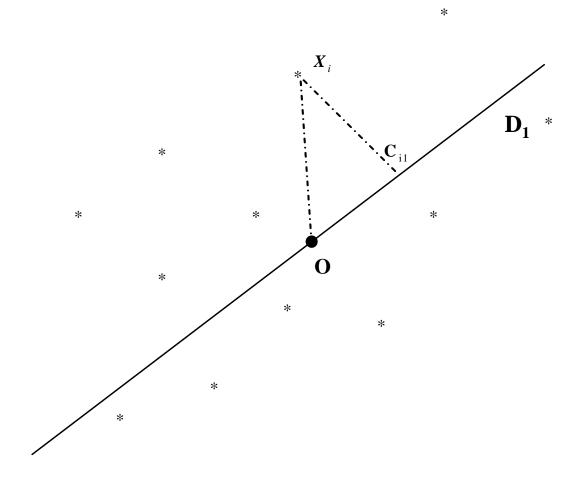
 $C_k = X \cdot a_k$ , k=1,s, where s is the number of principal components.

#### **Observation driven approach**

- The cloud of observations has *n* points within a *m*-dimensional space;
- Those *m* variables determine the *m* axis of coordinates;
- If the data is standardized, then the variables have the mean 0, and the standard deviation 1;
- Consider a system of orthonormal axes (it is orthogonal and having the norm 1) for those *n* points;
- Each axis corresponds to one principal component, and the vectors  $a_k$  are unit vectors (in a normed vector space, it is a vector, often a spatial vector, of length 1):

$$\sum_{j=1}^{m} a_{kj}^{2} = 1, k = \overline{1, s}$$
, where s is the maximum number of axes

## Observation driven approach: projection on D<sub>1</sub> axis



#### **Observation driven approach**

## Step 1

- Determine first axis, corresponding to the first principal component, so the component's variance is maxim;
- O is the center of gravity for the cloud of points;
- The distance from the point (observation)  $X_i$  to the  $D_1$  axis, corresponding to the first principal component is  $d(i, D_1)$ ;
- The distance from  $X_i$  to origin O is d(i, O).

Then we have the following relation between distances in the corresponding right-triangle:

 $d(i, \mathbf{O})^2 = d(i, \mathbf{D}_1)^2 + c_{i1}^2$ , where  $c_{i1}$  is the projection of  $X_i$  on  $D_1$  axis.

#### **Observation driven approach**

• Therefore, for all the points in the cloud we have the following equality of sums:

$$\frac{1}{n}\sum_{i=1}^{n}d(i,O)^{2} = \frac{1}{n}\sum_{i=1}^{n}d(i,D_{1})^{2} + \frac{1}{n}\sum_{i=1}^{n}c_{i1}^{2}$$

#### Observation driven approach

- The sum of the distances toward the center of gravity (*barycenter*) does not depend on the chosen axis;
- The variance explained through axis 1 is  $\frac{1}{n} \sum_{i=1}^{n} c_{i1}^{2}$
- Which in terms of matrixes, knowing that  $(Xa)^t = a^t X^t$ , we then have:  $C_1 = X \cdot a_1$ , then square the equality and divede by n (no. of observations)

$$\frac{1}{n}(C_1)^t C_1 = \frac{1}{n}(a_1)^t X^t X a_1$$

The problem is to dually (complementary) reach the same goal:

- 1. Maximize the explained variance on axis 1;
- 2. Minimize the sum point distances to axis 1.

## Observation driven approach

$$\begin{cases} \mathbf{Max} \frac{1}{n} (a_1)^t X^t X a_1 \\ subject \ of \ (a_1)^t a_1 = 1 \end{cases}$$

Lagrange function (or Lagrangean) associated to the problem is defined by:

$$L(a_1, \lambda) = \frac{1}{n} (a_1)^t X^t X a_1 - \lambda ((a_1)^t a_1 - 1)$$

where  $\lambda$  is a Lagrange multiplier.

#### **Observation driven approach**

#### **Partial derivatives:**

$$\frac{\partial L}{\partial a_1} = 2\frac{1}{n}X^t X a_1 - 2\lambda a_1 = 0 \qquad \frac{\partial L}{\partial \lambda} = (a_1)^t a_1 - 1 = 0$$
Having then  $\frac{1}{n}X^t X a_1 = \lambda a_1$ .

Therefore  $a_1$  is a *eigenvector* of the matrix  $\frac{1}{-}X^tX$ , corresponding to the eigenvalue (characteristic value)  $\lambda$ .

Multiplying on the left with  $(a_1)^t$  we have:

$$\frac{1}{n}(a_1)^t X^t X a_1 = \lambda$$

Then

$$\frac{1}{n}(a_1)^t X^t X a_1$$
 is the quantity we need to maximize.

#### Therefore:

- $\lambda$  is the greatest characteristic value (eigenvalue), and  $a_1$  is the corresponding characteristic vector (eigenvector);
- we shall assign  $\lambda$  to  $\alpha_1$ .

#### Step 2

- Determine axis 2 described by vector  $a_2$  so axis 2 is orthogonal with axis 1;
- Maximize the explained variance (the points are more scattered, disperse on the axis);
- The applied optimization is:

$$\begin{cases} \mathbf{Max} \frac{1}{n} (a_2)^t X^t X a_2 \\ (a_2)^t a_2 = 1 \\ (a_2)^t a_1 = 0 \end{cases}$$

$$L(a_2, \lambda_1, \lambda_2) = \frac{1}{n} (a_2)^t X^t X a_2 - \lambda_1 ((a_2)^t a_2 - 1) - \lambda_2 (a_2)^t a_1$$

## Step 2

Set the partial derivative on  $a_2$  to zero:

$$\frac{\partial L}{\partial a_2} = 2\frac{1}{n}X^t X a_2 - 2\lambda_1 a_2 - \lambda_2 a_1 = 0$$

Multiplying on the left with  $(a_1)^t$  we obtain:

$$2\frac{1}{n}(a_1)^t X^t X a_2 - 2\lambda_1(a_1)^t a_2 - \lambda_2(a_1)^t a_1 = 0$$

## Step 2

Then we have:  $(a_1)^t a_2 = 0$ , since:

$$\frac{1}{n}X^{t}Xa_{1} = \alpha_{1}a_{1}$$
 through transposition, it implies that

$$(a_1)^t \frac{1}{n} X^t X = \alpha_1 (a_1)^t$$

since the matrix  $X^tX$  is symmetrical. Then, multiplying with 2 and  $a_2$  on the right hand side:

$$2\frac{1}{n}(a_1)^t X^t X a_2 = 2\frac{1}{n}\alpha_1(a_1)^t a_2 = 0$$

Therefore  $\lambda_2 = 0$ .

## Step 2

Making the substitution in the derivative

$$\frac{1}{n}X^{t}Xa_{2} = \lambda_{1}a_{2}$$

and therefore  $a_2$  is eigenvector corresponding to eigenvalue  $\lambda_1$ , and this eigenvalue is maximal having given the equality:

$$\frac{1}{n}(a_2)^t X^t X a_2 = \lambda_1$$

Since  $\frac{1}{n}X^tXa_2 = \lambda_1a_2$  it is maximized at this step, we shall assign  $\lambda_1$  to  $\alpha_2$ 

#### Step k

- Determine k axis of  $a_k$  vector, orthogonal on the previous axis and to maximize the explained variance;
- The optimum problem is as follows:

$$\begin{cases} \mathbf{Max} \frac{1}{n} (a_k)^t X^t X a_k \\ (a_k)^t a_k = 1 \\ (a_k)^t a_j = 0, j = \overline{1, k - 1} \end{cases}$$

## Step k

The associated Lagrange function  $L(a_k, \lambda_1, \lambda_2, ..., \lambda_k)$  is as follows:

$$L(a_k, \lambda_1, \lambda_2, ..., \lambda_k) = \frac{1}{n} (a_k) X^t X a_k - \lambda_1 ((a_k)^t a_k - 1) - \lambda_2 (a_k)^t a_1 - ... - \lambda_k (a_k)^t a_{k-1}$$

Setting the derivative on zero:

$$\frac{\partial L}{\partial a_k} = 2\frac{1}{n}X^t X a_k - 2\lambda_1 a_k - \lambda_2 a_1 - \dots - \lambda_k a_{k-1} = 0$$

Then multiply the first relation successively with  $(a_1)^t$ ,  $(a_2)^t$ ,...,  $(a_{k-1})^t$ , and obtain  $\lambda_2 = 0$ ,  $\lambda_3 = 0$ , ...,  $\lambda_k = 0$ . Returning with these results to the first partial derivative we have:

$$\frac{1}{n}X^{t}Xa_{k} = \lambda_{1}a_{k}$$

## Step k

Therefore  $a_k$  is eigenvector of matrix  $\frac{1}{n}X^tX$ , corresponding to eigenvalue  $\lambda_1$ , and since the quantity

$$\frac{1}{n}(a_k)^t X^t X a_k$$

it is the one maximized at this step, then  $\lambda_1$  is eigenvalue of k order.

We shall assign  $\lambda_1$  to  $\alpha_k$ .

#### **PCA** in variable spaces

#### Phase 1

Determine the first principal component  $C_1$  so it is maximally correlated with initial, causal variables:

$$\sum_{j=1}^{m} R^{2}(C_{1}, X_{j})$$
 to be maxim

$$R^{2}(C_{1}, X_{j}) = \frac{Cov(C_{1}, X_{j})^{2}}{Var(C_{1})Var(X_{j})} = \frac{1}{n} \frac{(C_{1})^{t} X_{j} (X_{j})^{t} C_{1}}{(C_{1})^{t} C_{1}}$$

$$\sum_{j=1}^{m} R^{2}(C_{1}, X_{j}) = \frac{1}{n} \sum_{j=1}^{m} \frac{(C_{1})^{t} X_{j} (X_{j})^{t} C_{1}}{(C_{1})^{t} C_{1}} = \frac{1}{n} \frac{(C_{1})^{t} X X^{t} C_{1}}{(C_{1})^{t} C_{1}}$$

#### **PCA** in variable spaces

#### Phase 1

Solve the following problem:

$$Maxim \frac{1}{n} \frac{(C_1)^t XX^t C_1}{(C_1)^t C_1}$$

The solution is the eigenvector of matrix  $\frac{1}{n}XX^t$ , corresponding to the greatest eigenvalue  $\beta_1$ :

$$\frac{1}{n}XX^t \cdot C_1 = \beta_1 \cdot C_1$$

## **PCA** in variable spaces

#### Phase 2

Determine the second principal component  $C_2$ , maximally correlated with initial variables and not correlated at all with the first principal component  $C_1$ .

$$\begin{cases} Maxim \frac{1}{n} \frac{(C_2)^t XX^t C_2}{(C_2)^t C_2} \\ R(C_1, C_2) = 0 \end{cases}$$

The solution is the eigenvector of the matrix  $\frac{1}{n}XX^t$ , corresponding to the second eigenvalue  $\beta_2$ :

$$\frac{1}{n}XX^t \cdot C_2 = \beta_2 \cdot C_2$$

#### **PCA** in variable spaces

#### Phase k

Determine the principal component  $C_k$ , maximally correlated with initial variables and not correlated at all with the components previously determined,  $C_i$ , i=1,k-1.

$$\begin{cases} Maxim \frac{1}{n} \frac{(C_k)^t XX^t C_k}{(C_k)^t C_k} \\ R(C_k, C_i) = 0, i = 1, k-1 \end{cases}$$

The solution is the eigenvector of the matrix  $\frac{1}{n}XX^t$ , corresponding to the k eigenvalue  $\beta_k$ :

$$\frac{1}{n}XX^t \cdot C_k = \beta_k \cdot C_k$$

#### The link between the two approaches

In the observation spaces, at step k it is determined the eigenvector  $a_k$ , which is the unit vector of k axis, corresponding to  $C_k$  component:

$$\frac{1}{n}X^{t}X \cdot a_{k} = \alpha_{k}a_{k}$$

Multiplying this equation on the left with X we obtain:

$$\frac{1}{n}XX^{t}Xa_{k} = X\alpha_{k}a_{k} \implies \frac{1}{n}XX^{t}C_{k} = \alpha_{k}C_{k}$$

#### The link between the two approaches

It is the same equality obtained in the variable spaces approach, if considered  $\beta_k = \alpha_k$ 

$$\frac{1}{n}XX^{t}C_{k} = \beta_{k}C_{k}$$

The maximum number of steps in the observation spaces may be m (the rank

of matrix  $\frac{1}{n}X^{t}X$ ), while in the variable spaces, the maximum number of steps may be n (the rank of matrix  $\frac{1}{n}XX^{t}$ ).

The number of non-zero eigenvalues is min(m, n).