



# Images/video basics & Object detection

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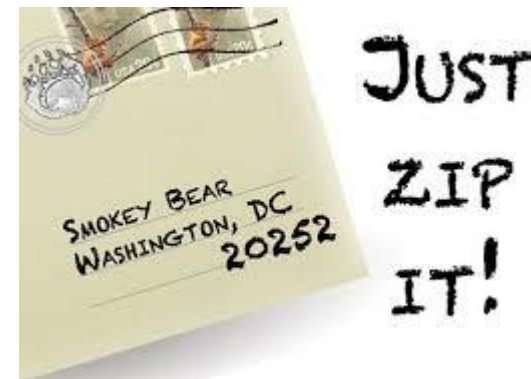


# Image Basics

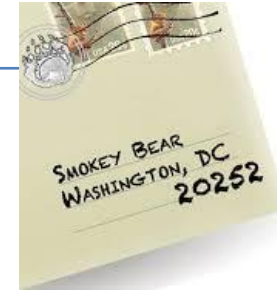
# Grayscale Images



- Before we talk about how to use manipulate image files, let's first discuss **how computers handle images**.
- Let's imagine we wanted to build software that could sort out mails based on the zip code of the address.



# Grayscale Images



JUST  
ZIP  
IT!

- Often mail is handwritten  
=> we would need to begin to understand how to use computer vision to actually read image data of these handwritten numbers.
- How does a computer represent image data?
- Let's imagine we have a simple image of a **handwritten number**:

1

2

3

# Grayscale Images



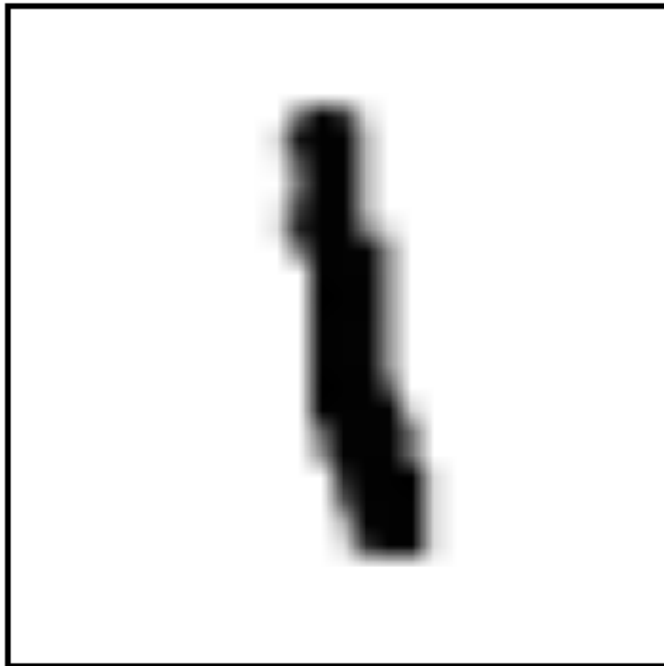
- Each single digit image can be represented as an **array**



# Grayscale Images



- For example, here a number is 28 by 28 pixels



28

0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	.6	.8	0	0	0	0	0	0	0
0	0	0	0	0	0	.7	1	0	0	0	0	0	0	0
0	0	0	0	0	0	.7	1	0	0	0	0	0	0	0
0	0	0	0	0	0	.5	1	.4	0	0	0	0	0	0
0	0	0	0	0	0	0	1	.4	0	0	0	0	0	0
0	0	0	0	0	0	0	1	.4	0	0	0	0	0	0
0	0	0	0	0	0	0	1	.7	0	0	0	0	0	0
0	0	0	0	0	0	0	1	1	0	0	0	0	0	0
0	0	0	0	0	0	0	.9	1	.1	0	0	0	0	0
0	0	0	0	0	0	0	.3	1	.1	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0

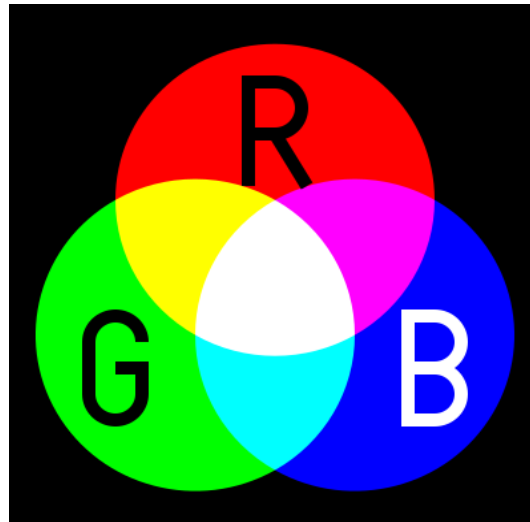
- 1

[illegible]

# Color Images



- Color images can be represented as a combination of Red, Green, and Blue.
- Additive color mixing allows us to represent a wide variety of colors by simply combining different amounts of **R**, **G**, **B**.

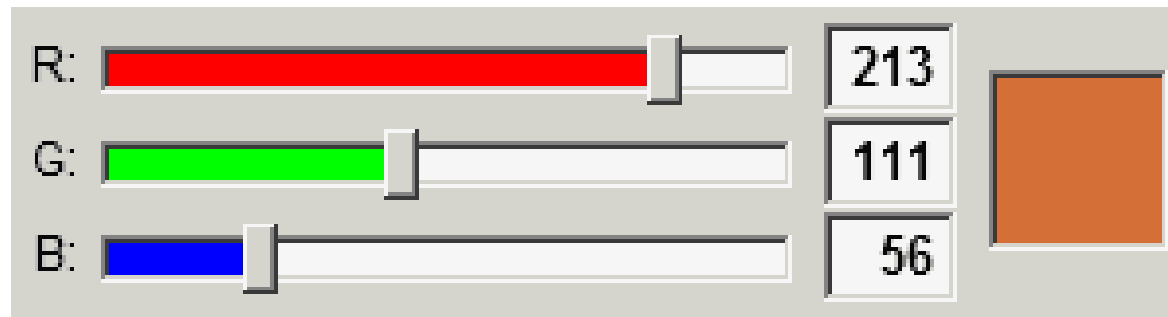




# Color Images



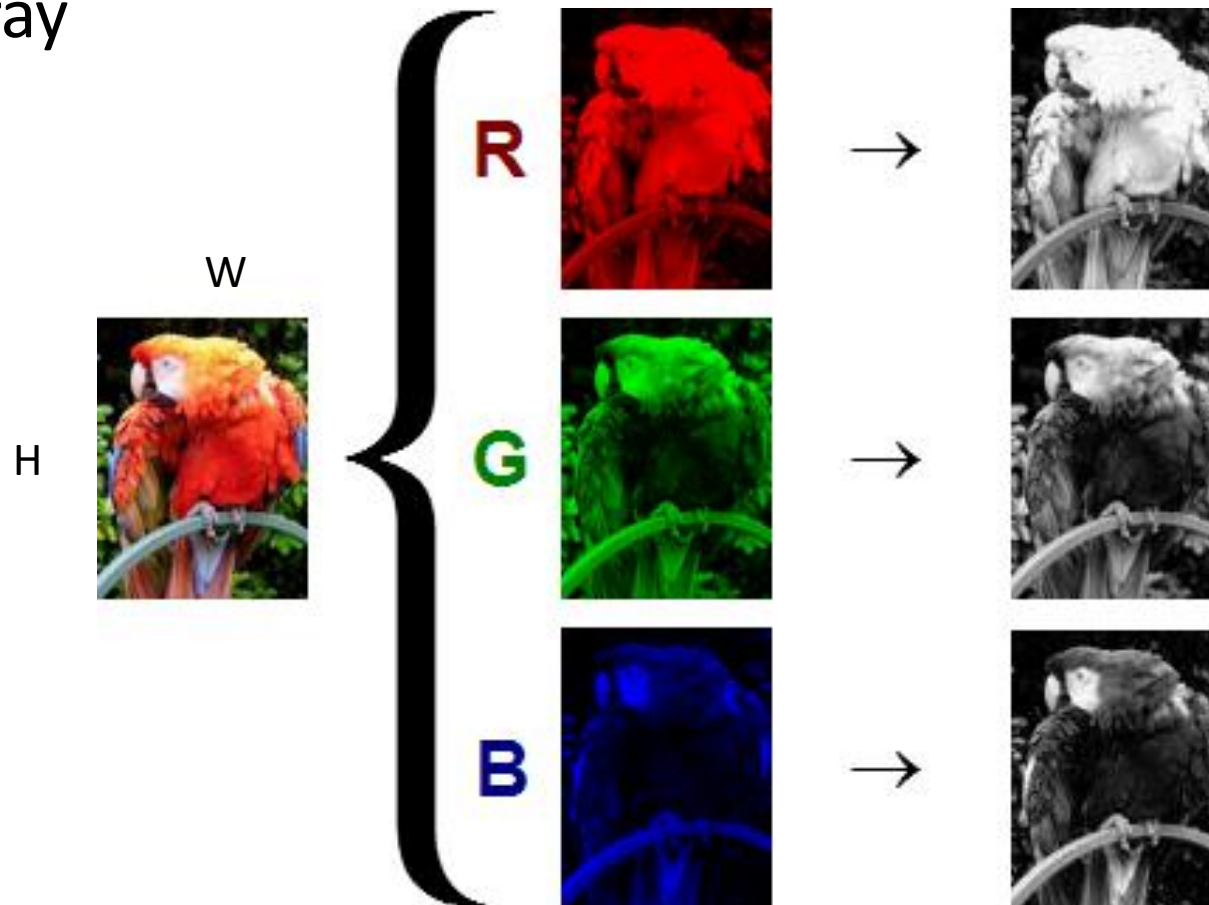
- Each color channel will have intensity values
- You may have already seen this sort of representation in other software with RGB sliders



# Color Images



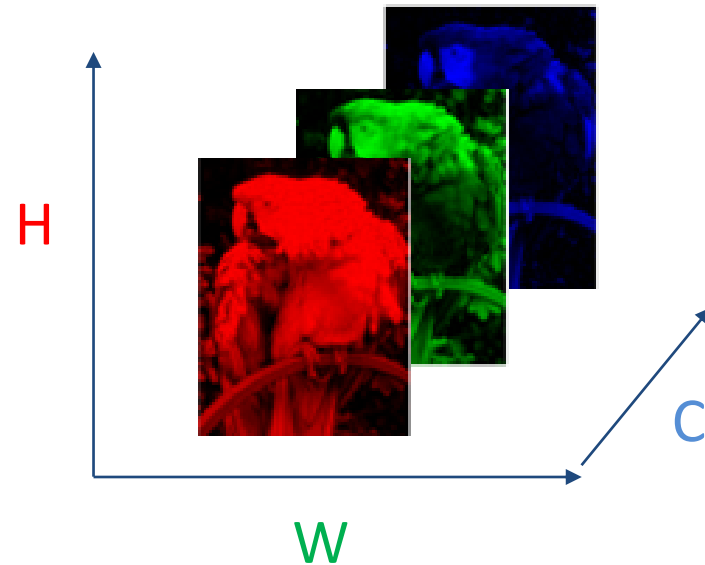
- The shape of the color array then has 3 dimensions.
  - H: Height
  - W : Width
  - C : Color Channels



# Color Images



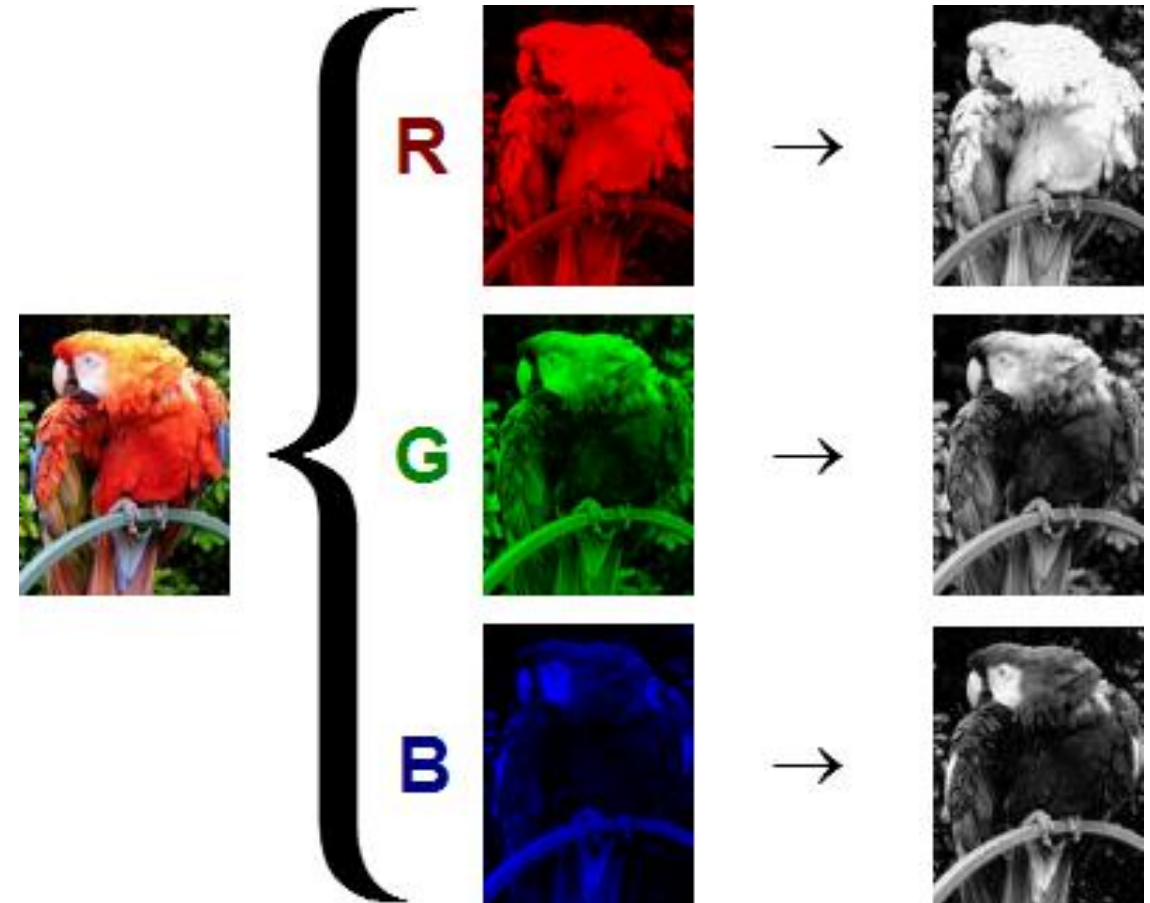
- This means when you read in an image and check its shape, it will look something like:
- (720,1280,3)
- 1280 pixels width
- 720 pixels height
- 3 color channels



# Color Images



- The user needs to specify which channel is for which color.
- Each channel alone is essentially the same as a grayscale image.



# Color Images: More informations

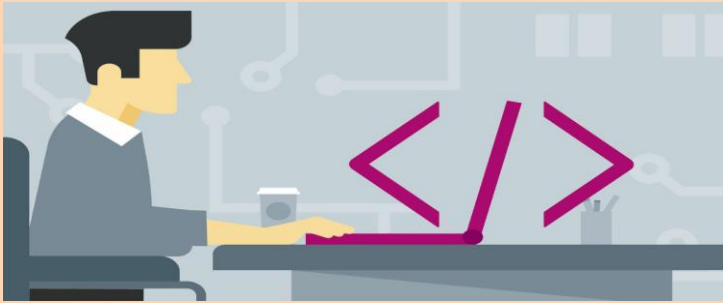
- Please check out the Wikipedia article on RGB color channeling for more interesting details
- Nice youtube video: <https://youtu.be/pmY7pOQCOr8>

# OpenCV for Images

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- OpenCV (**Open** Source **C**omputer **V**ision) is a **library** of **programming** functions mainly aimed at real-time **computer vision**.
- Created by Intel in 1999, it is written in C++ (we will be using the Python bindings)
- It contains many popular algorithms for computer vision, including object detection and tracking algorithms built-in.



# Reference notebook

01-Image\_basics.ipynb

- Section Goals:
  - Be able to open image files with OpenCV in both a notebook and a python script.
  - Draw simple geometries on images.
  - Directly interact with an image through callbacks.



# Video Basics



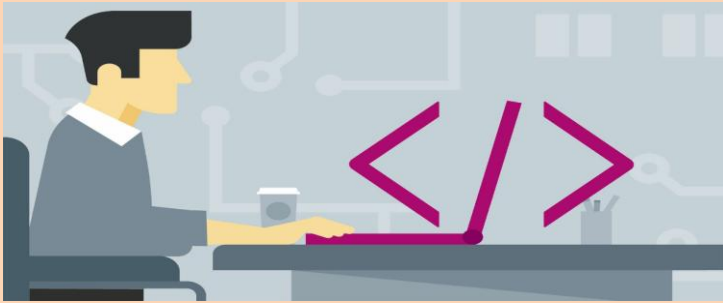
# Goals

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- Goals are:
  - Connect OpenCV to a WebCam
  - Use OpenCV to open a video file
  - Draw shapes on video
  - Interact with video
- You will need a **webcam** to follow along this part!





# Reference notebook

02\_Video Basics.ipynb

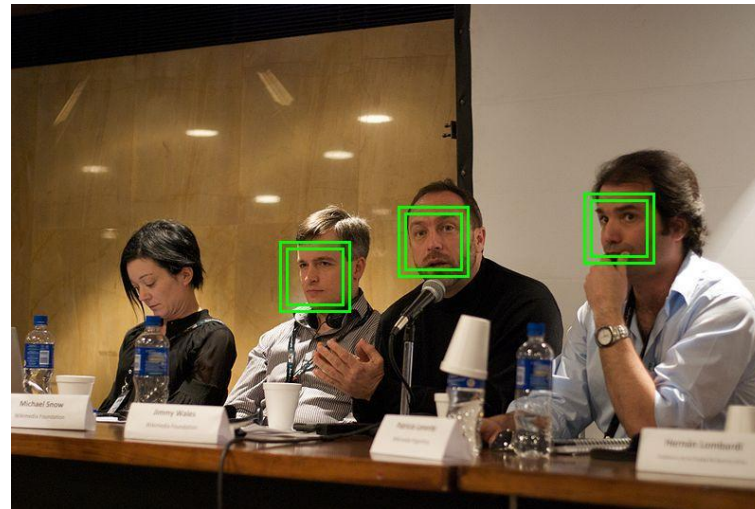


# Object detection

# Face detection



- face detection :
  - Using Haar Cascades
  - detect if a face is in an image and locate it
- Keep in mind, this is **face detection NOT face recognition**.



# Problem definition

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- Facial detection : Where is the face?



- Face recognition: Who is this?



# Haar Cascade Classifiers

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- What is it?
- An object detection method that inputs **Haar features** into a series of classifiers (cascade) to **identify objects in an image**.
- They are trained to identify one type of object! (but can be used in parallel)

# Concept



- HAAR classifiers are trained using a lot of **positive images** and **negative images**.



- We then extract features using sliding windows of rectangular blocks. These features are single valued and are calculated by subtracting the sum of pixel intensities under white rectangles from the black rectangles.



# Face detection

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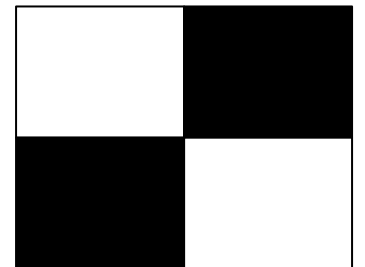
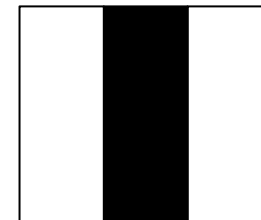
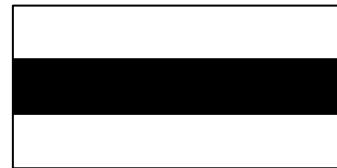
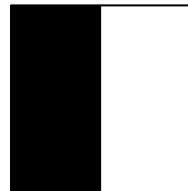
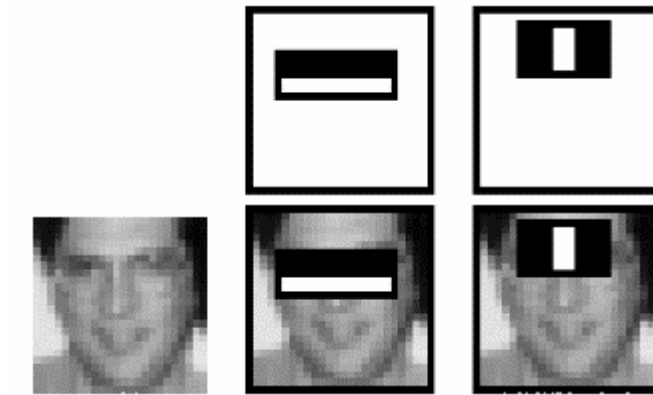
- In 2001 **Paul Viola and Michael Jones** published their method of face detection based on the simple concept of a few key features.
- Let's first **understand** the **main feature types** that Viola and Jones proposed.



# Haar Classifiers



- The main feature types are:
  - Edge Features
  - Line Features
  - Four-rectangle features



# Face detection



- Each feature is a single value obtained by subtracting sum of pixels under white rectangle from sum of pixels under black rectangle.
- Realistically, our images won't be perfect edges or lines.
- These features are calculated by:
  - **mean(dark region) - mean(light region)**

0	0	1	1
0	0	1	1
0	0	1	1
0	0	1	1

0	0.1	0.8	1
0.3	0.1	0.7	0.8
0.1	0.2	0.8	0.8
0.2	0.2	0.8	0.8

# Face detection



- A perfect edge would result in a value of one.

0	0	1	1
0	0	1	1
0	0	1	1
0	0	1	1

0	0.1	0.8	1
0.3	0.1	0.7	0.8
0.1	0.2	0.8	0.8
0.2	0.2	0.8	0.8

# Face detection



- These features are calculated by:
  - **mean(dark region) - mean(light region)**

$\text{sumdark}([0.8, 1, 0.7, 0.8, 0.8, 0.8, 0.8, 0.8]) = 6.5$

$\text{sumlight}([0, 0.1, 0.3, 0.1, 0.1, 0.2, 0.2, 0.2]) = 1.2$

$\text{Meandark} = 6.5 / 8 = 0.8125$

$\text{Meanlight} = 1.2 / 8 = 0.15$

$\text{Delta} = 0.8125 - 0.15 = 0.6625$

0	0	1	1
0	0	1	1
0	0	1	1
0	0	1	1

0	0.1	0.8	1
0.3	0.1	0.7	0.8
0.1	0.2	0.8	0.8
0.2	0.2	0.8	0.8

# Face detection

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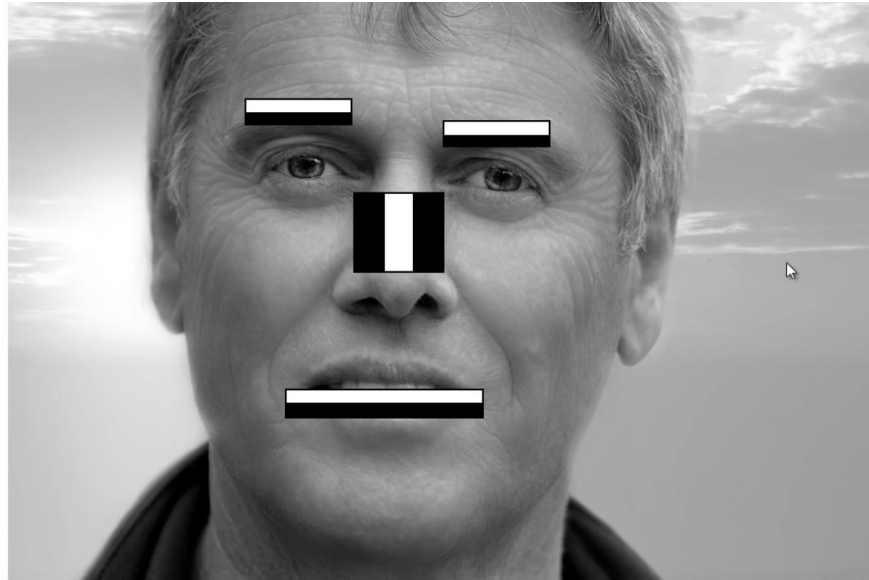


- The algorithm saves time by going through a cascade of classifiers.
- This means we will treat the image to a series (a cascade) of classifiers based on the simple features shown earlier.
- Once an image fails a classifier, we can stop attempting to detect a face.

# Face detection

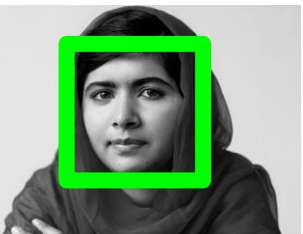
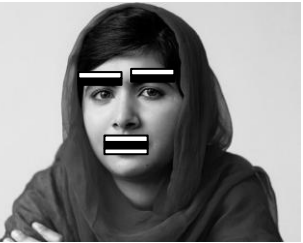


- A common misconception behind face detection with this algorithm is that the algorithm slowly “scans” the entire image looking for a face.
- This would be very inefficient, instead we pass the cascade of classifiers.



# Face detection

- First we need a front facing image of a person's face.
- Then turn it to **grayscale**.
- Then we will begin the search for Haar Cascade Features.
- One of the very first features searched for is an edge feature indicating eyes and cheeks.
  - If the image were to **fail** for the search of this feature, we can quickly say there is no face.
  - If it **passed**, then we search for the next feature, such as the bridge of the nose
- We **continue** through this cascade (which can be thousands of features).
- **Until** the algorithm **detects** the **face**.



# Object detection

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- Theoretically this approach can be used for a variety of objects or detections.
- For example we'll also work with a pre-trained **eye detector**.





# Object detection

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- The **downside** to this algorithm is the very **large data sets** needed to create your own features.
- However, luckily many pre-trained sets of features already exist.
- **OpenCV** comes with pre-trained **xml files** of various Haar Cascades.

# Code example



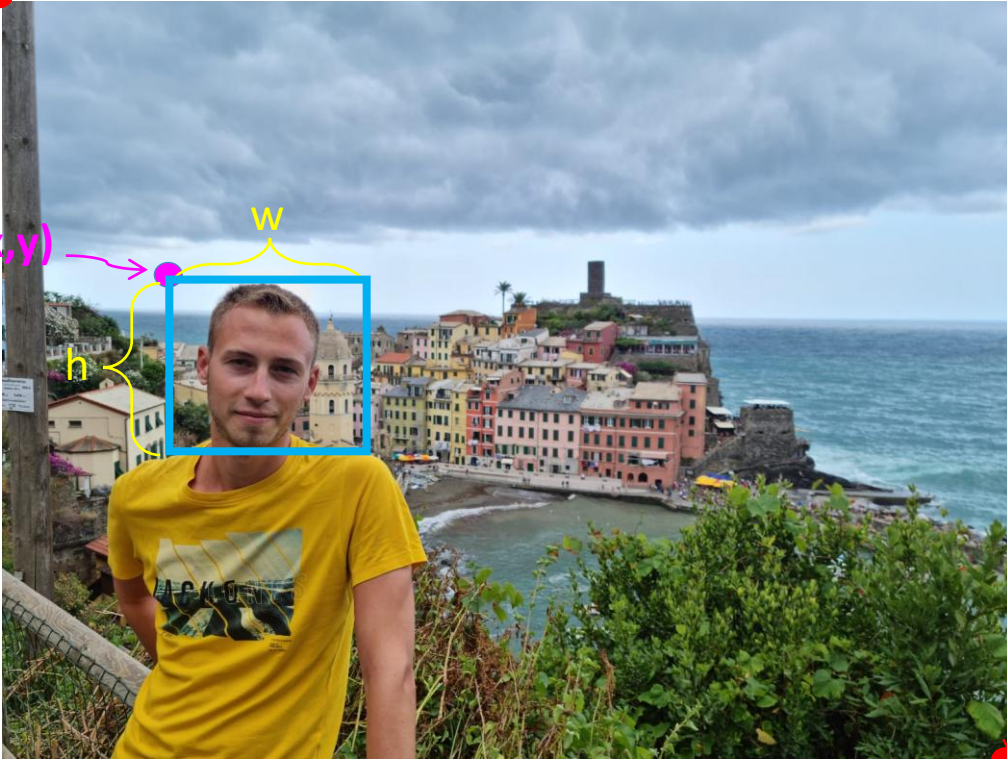
(0,0)



(x,y)

h

w



(640,480)



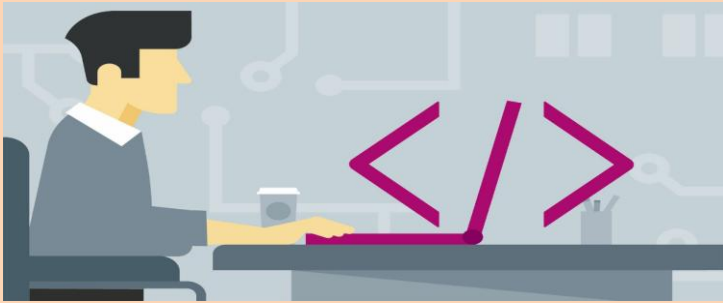
```
import numpy as np
import cv2
faceCascade = cv2.CascadeClassifier('haarcascade_frontalface_default.xml')
cap = cv2.VideoCapture(0)
cap.set(3,640) # set Width
cap.set(4,480) # set Height
while True:
    ret, frame = cap.read()
    #img = cv2.flip(img, -1)
    gray = cv2.cvtColor(frame, cv2.COLOR_BGR2GRAY)

    #----Added code-----
    faces = faceCascade.detectMultiScale(gray,
                                         scaleFactor=1.2,
                                         minNeighbors=5,
                                         minSize=(20, 20))

    for (x,y,w,h) in faces:
        cv2.rectangle(frame,(x,y),(x+w,y+h),(255,0,0),2)
        #roi_gray = gray[y:y+h, x:x+w]
        roi_color = frame[y:y+h, x:x+w]

    #-----

    cv2.imshow('frame',frame)
    cv2.imshow('detected face',roi_color)
    #cv2.imshow('video',frame)
    k = cv2.waitKey(30) & 0xff
    if k == 27: # press 'ESC' to quit
        break
cap.release()
cv2.destroyAllWindows()
```



## Reference notebook

03-Face-Detection.ipynb

04-Detection-Assessment.ipynb

# Questions

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- <https://www.youtube.com/watch?v=x41KFOFGnUE>