



Henallux-Engineering school Pierrard

Introduction to Intelligent Systems

Master 1 auto | 2024-2025

Corentin Domken

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General presentation

General presentation

- Number of hours: 45 hours (80% => **36h**)
- Number of credits: 4
- Evaluation method:
 - 30% Project presentation
 - 10% Group defense
 - 20% Individual defense
 - 40% Final report
- Slides in English, English software, oral presentation in English
- Exam in English (Possible discussion in French)
- The content of this course : **fiche UE, slides, Notebooks & Moodle**

SI course Plan

Theory

- Courses on theory
- Overview on basics of softwares and tools

Exploration

- Explore equipment

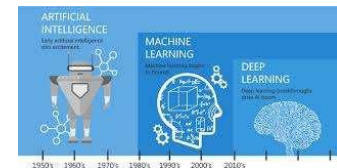
Project

- Propose and realise a project

Theory and exploration

Theory and practice

- Python Virtual environment (learnt implicitly)
 - Matplotlib, numpy, seaborn, pandas, sklearn, OpenCV
- Initiation to Computer vision with python
 - Image processing
 - Video processing
- Intuition on Deep Learning applied in Computer Vision
 - Introduction to DL
 - Main difference between DL and classic ML
 - TD : DL applied to CV
- Git
 - What is a distributed version control system
 - Git basic operations: locally and remotely
 - Working on groups on the same project using git



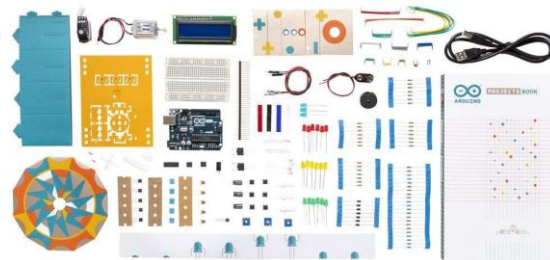
Material exploration

- Equipment:
 - Raspberry Pi
 - Arduino Starter kit
 - Pi camera
 - Niryo
- Explore some projects on Raspberry or Arduino

- Group of 2 students
- Deposit of 50 € / student for the borrowing of the material
- To be returned on the day of the exam



C. Domken

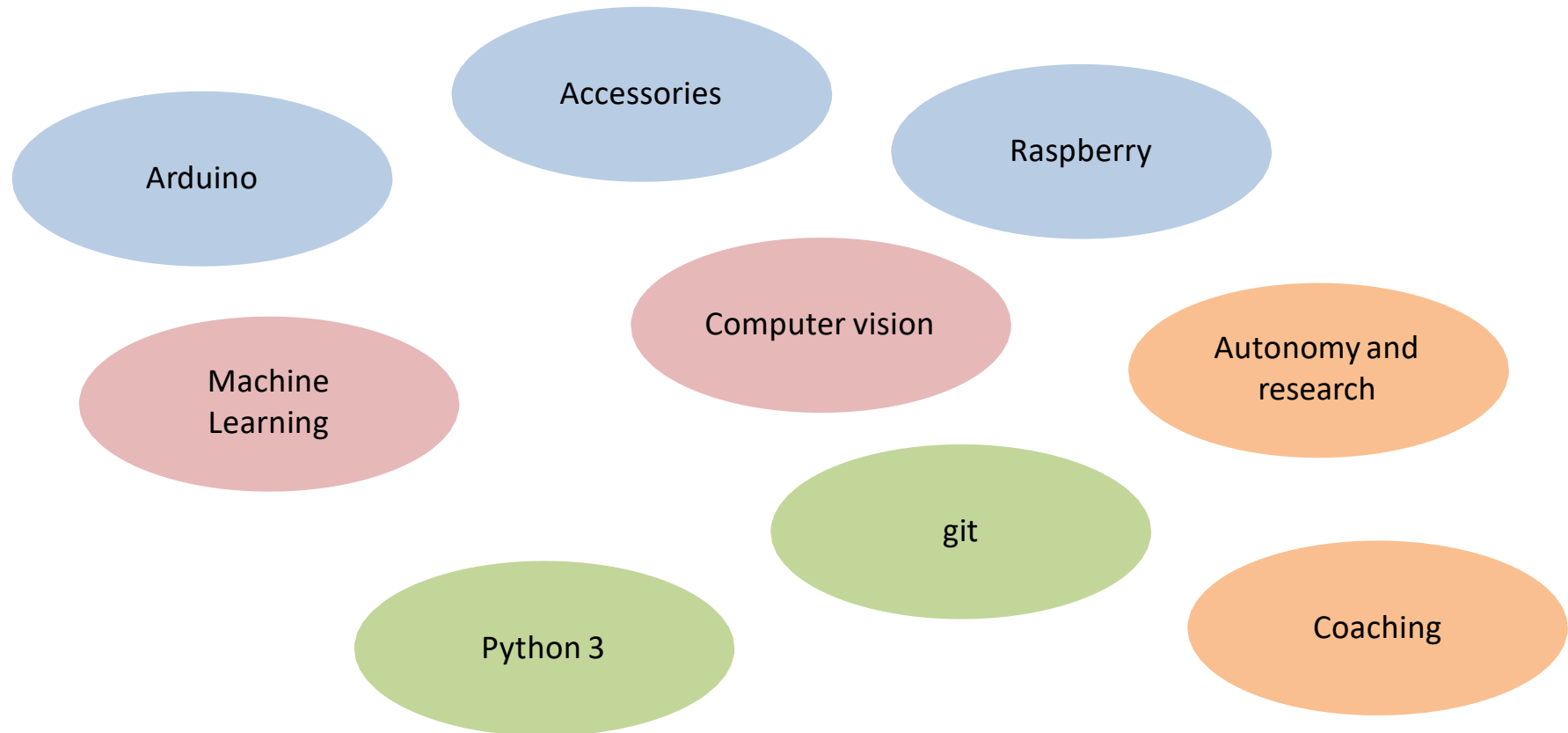


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Project

Project with artificial intelligence!



Project

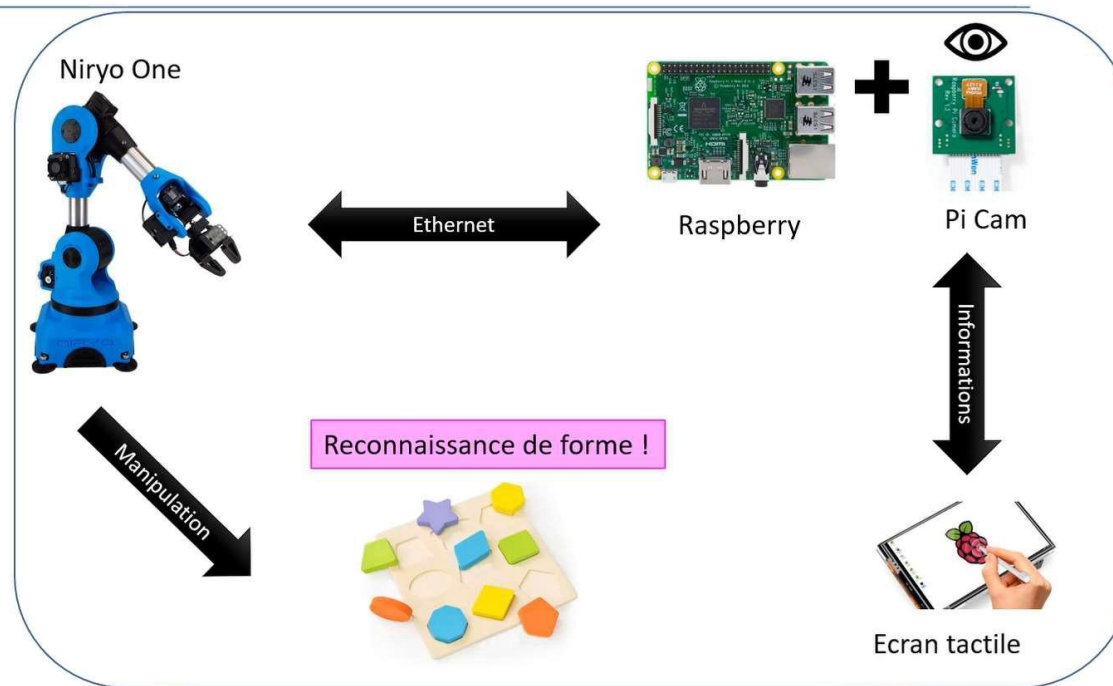
Project SI (2019-2020)	
Part 1 : Analyse	<ul style="list-style-type: none"> • Before carrying out your work, an analysis must be carried out (in the form of a document and presentation). • This analysis will resume: <ul style="list-style-type: none"> • A description of the project • A description of the equipment required • A diagram of the project • The distribution of tasks within the group • A time line with validation steps • A state of the art of the existing (code, web page ...), reviews and reuse plan
Part 2 : Realisation	<ul style="list-style-type: none"> • Install and use git for tracing documents and code! • Do the needed code • Accuracy of the result • Hardware optimization • Intermediate application • Final application
Presentation	Presentation & defense
	Report

Projects of last years!

- Automatisation d'un robot 6 axes
- Borne de jeux arcades avec assistance intelligente
- Reconnaissance de plaques d'immatriculation
- Robot tondeuse
- Emotional recognition
- Sign language translator

Projects of last years!

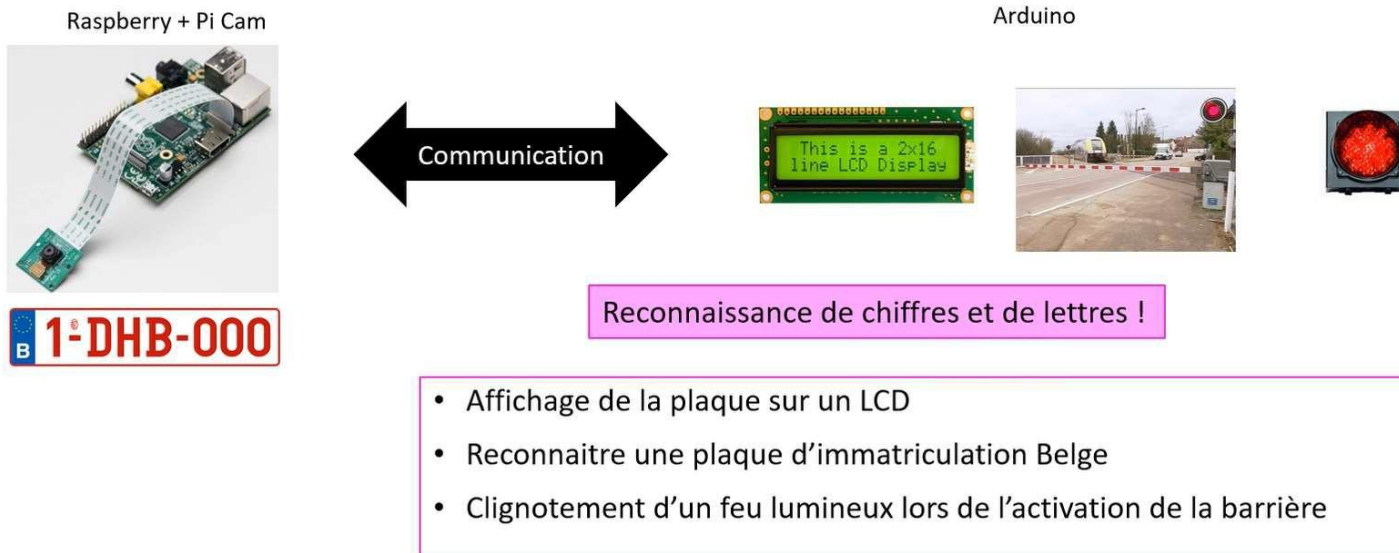
Automatisation d'un robot 6 axes



Projects of last years!

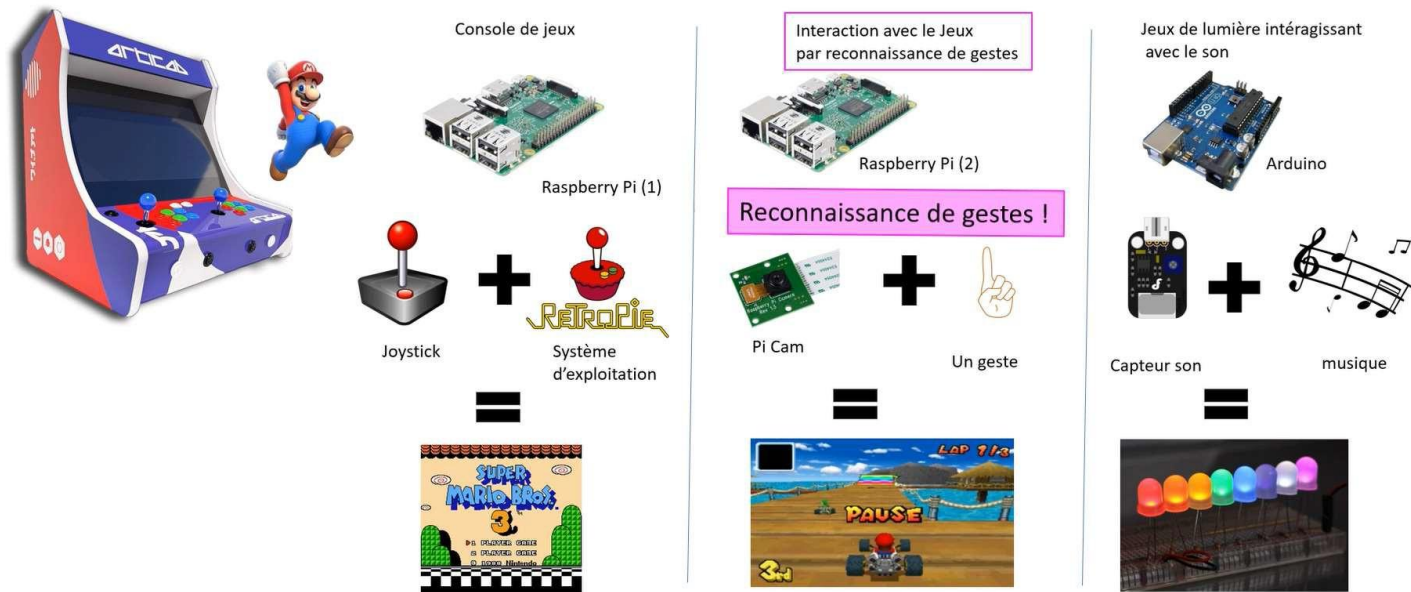
Reconnaissance de plaques d'immatriculation

➤ Détection de plaques d'immatriculation belges



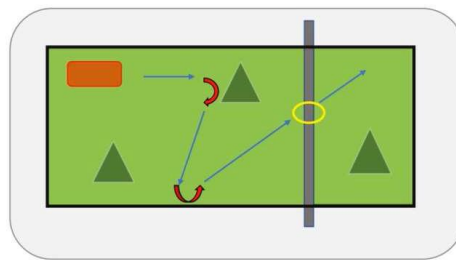
Projects of last years!

Borne de jeux arcades avec assistance intelligente



Projects of last years!

Robot tondeuse



LEGENDE

Robot tondeuse

Arbre ou obstacle

Route qui traverse l'herbe (état de surface différente de celle de l'herbe).

Contour dans lequel le robot ne devra pas sortir.

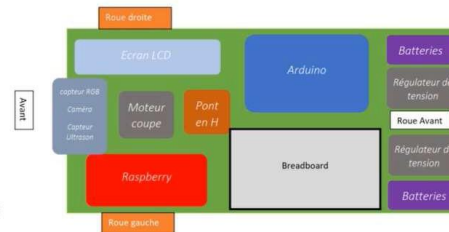
Le robot déclenche un BIP et arrête le moteur de coupe.



Reconnaissance de texture !



Zoom sur le Robot



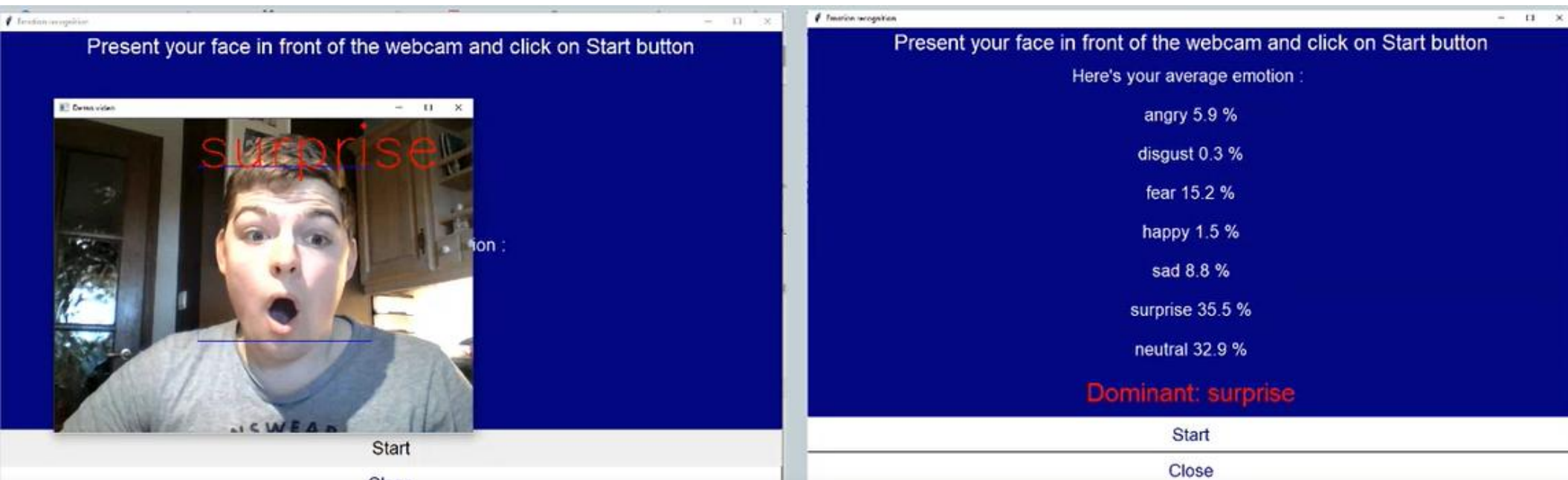
Dr. Rim Slama



Henallux-Engineering school Pi

Projects of last years!

Emotional recognition

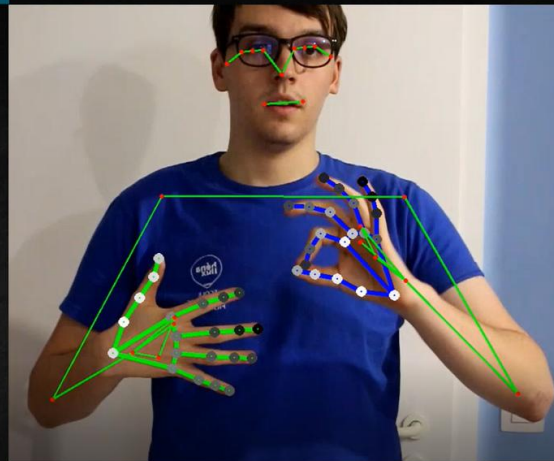


Projects of last years!

Sign language translator

The Dataset

- Total : 230 gestures recorded
- Each gesture done ~12 times
- 38 gestures for the V1.0 of our project
- Use of data augmentation
- Use of a free and open-source solution: **MediaPipe**
- Conversion of images into positions in space



Questions

