

Recap

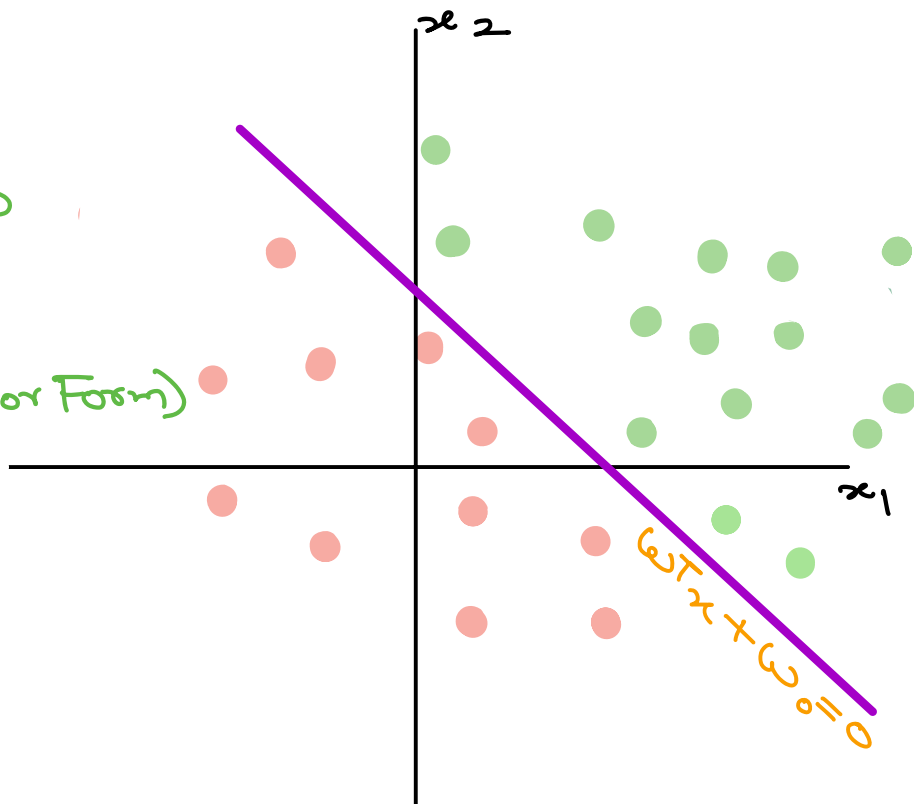
Eqⁿ of Line and Half Spaces

x_1	x_2	y
x_1	x_2	$+1$

$$\omega_1 x_1 + \omega_2 x_2 + \omega_0 = 0$$



$$\omega^T X + \omega_0 = 0 \text{ (Vector Form)}$$



④ Vectors :

\bar{x}

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ \dots \\ x_d \end{bmatrix}$$

$$\bar{x} \in \mathbb{R}^d$$

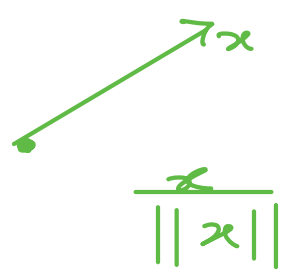
$$X_{\text{matrix}} \in \mathbb{R}^{n \times m}$$

⑤ Norm : Magnitude = Distance = Length

$$||x|| \rightarrow \text{L2 Norm} = \sqrt{x_1^2 + x_2^2 + \dots + x_d^2}$$

$$|x| \rightarrow \text{L1 Norm} = |x_1| + |x_2| + \dots + |x_d|$$

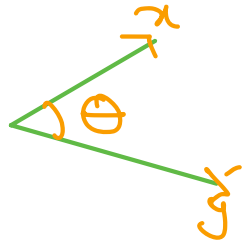
$$\text{Unit Vector } (\hat{x}) = \frac{x}{||x||} = 1$$



1) Dot product:

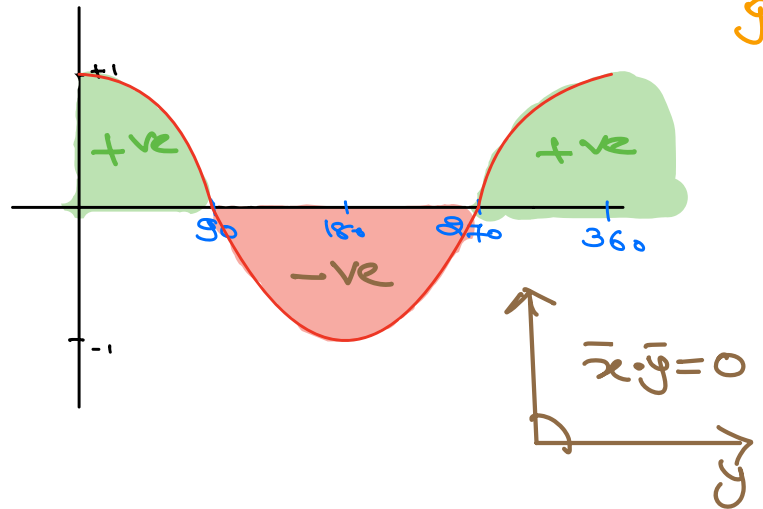
$$\bar{x} \cdot \bar{y} \equiv x^T y \equiv x_1 y_1 + x_2 y_2 + \dots + x_n y_n$$

2) Angle b/w Vectors: \bar{x} and \bar{y}



$$\cos \theta = \frac{\bar{x}^T \bar{y}}{||x|| ||y||}$$

+ and -1



3) 2 dimensional Hyperplane:

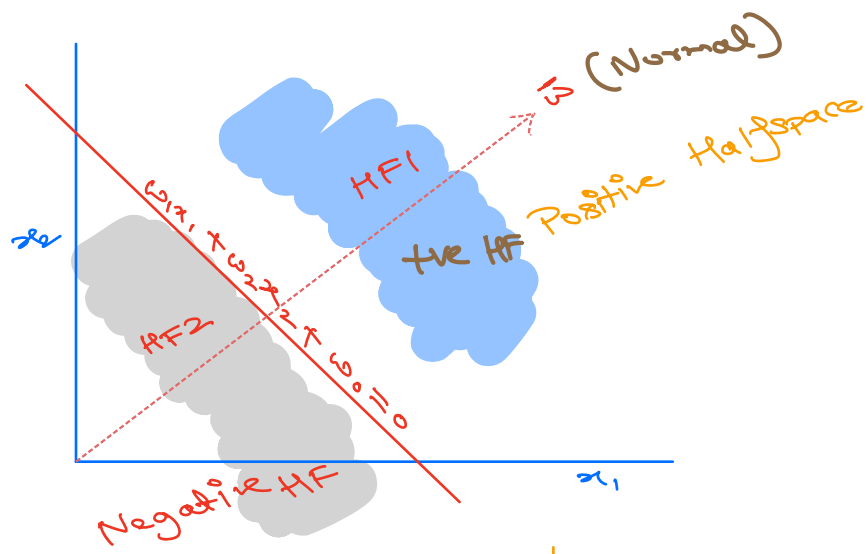
$$\omega^T x + \omega_0 = 0$$

where \bar{x} and $\bar{\omega} \in \mathbb{R}^d$
 $\omega_0 \in \mathbb{R}^1$
 \rightarrow Parameter
 \rightarrow bias

$$\bar{x} \in \mathbb{R}^2$$

$$\bar{\omega} \in \mathbb{R}^2$$

4) HalfSpace



Point $P = (x_1, x_2)$

$$\omega = \begin{bmatrix} \omega_1 \\ \omega_2 \end{bmatrix}$$

$$\omega_0 = \mathbb{R}$$

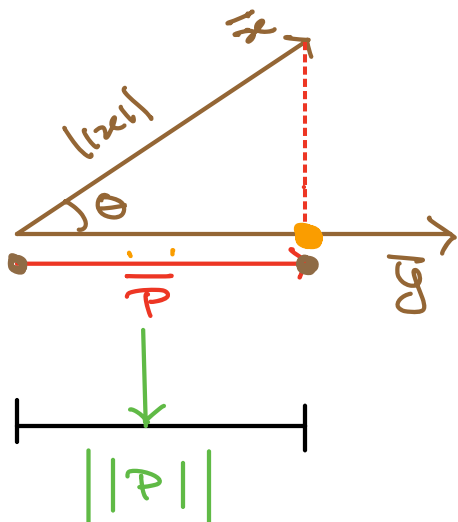
$$\omega \cdot P + \omega_0$$

$$\text{HF1: } \omega \cdot P + \omega_0 < 0$$

$$\text{HF2: } \omega \cdot P + \omega_0 > 0$$

$$\omega^T x + \omega_0 = 0$$

⑧ Projection



Projection of x on y

$$||P|| = \frac{x^T y}{||y||}$$

$$||P|| = x^T \hat{y}$$

⑨ Loss function:

- Gain Function

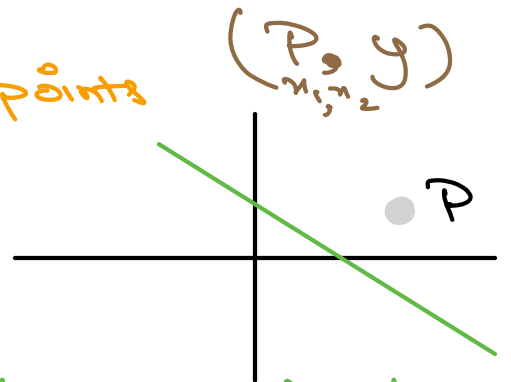
- (Sum of distances b/w CLF and \vec{x})



$$- \frac{1}{2} \sum_{i=1}^n \left(\frac{\vec{w}^T \vec{x}_i + w_0}{\|\vec{w}\|} \right) \times y_i$$

① Perceptron : misclassified points

$$\text{sign}(\vec{w}^T \vec{p} + w_0) \neq \text{sign}(\hat{y})$$



- ① Initialize w and w_0 randomly
- ② Identify misclassified point
- ③ Update using misclassified points

Case 1 : Actual $\geq +1$ Predicted ≥ -1

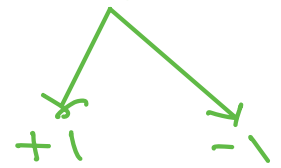
$$w_{\text{new}} = w_{\text{old}} + \vec{p}$$

Case 2 : Actual ≤ -1 Predicted $\geq +1$

$$w_{\text{new}} = w_{\text{old}} - \vec{p}$$

Combining the two

$$w_{\text{new}} = w_{\text{old}} + \vec{p} \cdot \vec{y}$$



Problem 1

suppose we have two vectors

vector $x = [2, 1, -3]$

vector $y = [5, 8, 6]$

- What is the length of the projection of x onto y ?

$$||\vec{p}|| = \frac{x^T y}{||y||}$$

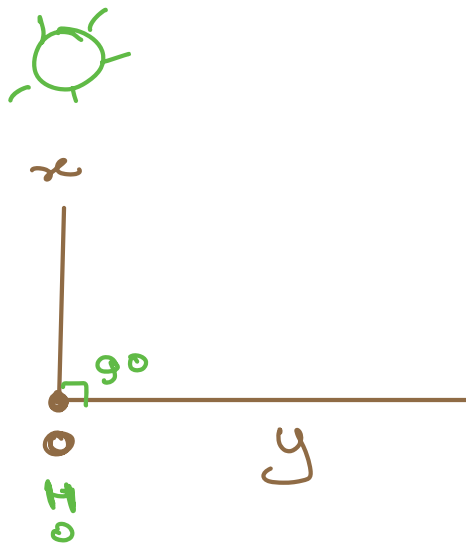
$$||\vec{p}|| = x^T \hat{y} \leftarrow \text{unit vector } y$$

$$x \cdot y \Rightarrow [2, 1, -3] \cdot [5, 8, 6]$$

$$x \cdot y \Rightarrow 2 \times 5 + 1 \times 8 + -3 \times 6$$

$$\Rightarrow 10 + 8 - 18 \Rightarrow 0$$

$$\text{proj} = \frac{x \cdot y}{||y||} \Rightarrow 0 \Rightarrow 0$$



$$\cos \theta = \frac{x \cdot y}{\|x\| \|y\|} \Rightarrow 0$$

90

Problem 2

given a and b are two unit vectors such that,

$$c = a + 2b$$

$$d = 5a - 4b$$

these two are perpendicular, then what is the angle between a and b ?

$$a \rightarrow \|a\| = 1$$

$$b \rightarrow \|b\| = 1$$

$$c = a + 2b$$

$$d = 5a - 4b$$

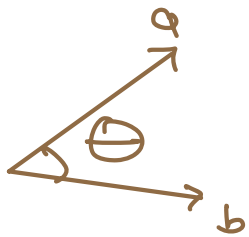
$$c \perp d \rightarrow c \cdot d = 0$$

Q: θ b/w a and b ?

$$C \perp d \rightarrow \underbrace{C \cdot d}_{d} = 0$$

$$\Rightarrow (a + 2b) \cdot (5a - 4b) = 0$$

$$5a^2 + 10a \cdot b - 4ab - 8b^2 = 0$$



$$\Rightarrow 5a^2 + 6a \cdot b - 8b^2 = 0$$

$$5x^2 + 6ab - 8(1) = 0$$

$$-3 + 6a = 0$$

$$ab = \frac{3}{6} \Rightarrow \frac{1}{2}$$

$$a \cdot b \Rightarrow \frac{1}{2}$$

$$\cos \Theta = \frac{\overline{x}^T y}{\|x\| \|y\|}$$

$$\cos \Theta \Rightarrow \frac{a \cdot b}{\|a\| \|b\|}$$

$$\cos \Theta \Rightarrow \frac{1/2}{1 \cdot 1}$$

$$\Theta = \cos^{-1}\left(\frac{1}{2}\right) \rightarrow 60^\circ$$

$$\begin{aligned} a &\rightarrow \|a\| = 1 \\ b &\rightarrow \|b\| = 1 \end{aligned}$$

$$Q \Rightarrow \sqrt{i^2 + j^2} = 1$$

$$\begin{aligned} Q \cdot Q &\Rightarrow i^2 + j^2 = \|a\|^2 \\ (i, j) &(i, j) \Rightarrow (1)^2 \\ &\Rightarrow 1 \end{aligned}$$

If vector $a=[3,4]$ and vector $b=[5,0]$, what is the cos inverse of the angle between a and b?

1 user has participated

- | | | |
|-----|-----------------------|------|
| A | cos inverse of 4 by 5 | 0% |
| ✓ B | cos inverse of 3 by 5 | 100% |
| C | cos inverse of 2 by 5 | 0% |
| D | cos inverse of 1 by 5 | 0% |

[End Quiz Now](#)

$$\cos \theta = \frac{x \cdot y}{\|x\| \|y\|}$$

$$\Rightarrow \frac{[3, 4] \cdot [5, 0]}{\sqrt{3^2 + 4^2} \sqrt{5^2 + 0^2}}$$

$$\Rightarrow \frac{3 \times 5 + 4 \times 0}{\sqrt{25} \sqrt{25}} \Rightarrow \frac{15}{25} \Rightarrow \frac{3}{5}$$

$$\cos \theta = \frac{3}{5}$$

Given 2 lines which are parallel to each other find the distance between them

- $L1 = w_1^T \bar{x} + w_{01}$
- $L2 = w_2^T \bar{x} + w_{02}$

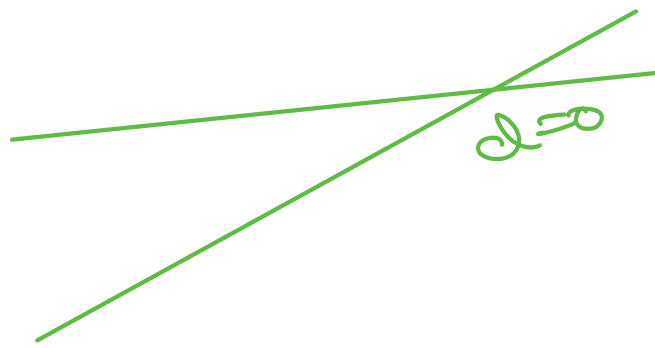
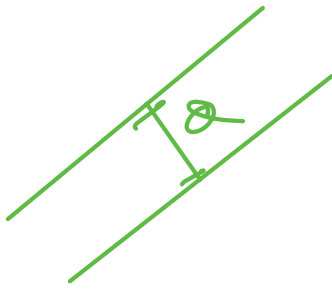
$$-\frac{3}{4} \Rightarrow -\frac{12}{16} \Rightarrow -\frac{3}{4}$$

Where:

- $w_1 = [4, 3]^T$
- $w_2 = [16, 12]^T$
- $w_{01} = 3$
- $w_{02} = 7$

$$m = -\frac{w_2}{w_1}$$

$$\frac{w_{01} - w_{02}}{\|w\|}$$



$$L1 \Rightarrow 4x + 3y + 3 = 0 \times 4$$

$$16x + 12y + 12 = 0 \quad d = ?$$

$$L2 \Rightarrow 16x + 12y + 7 = 0$$

$$\frac{w_01 - w_02}{||w||} \Rightarrow \frac{(12 - 7)}{\sqrt{16^2 + 12^2}}$$

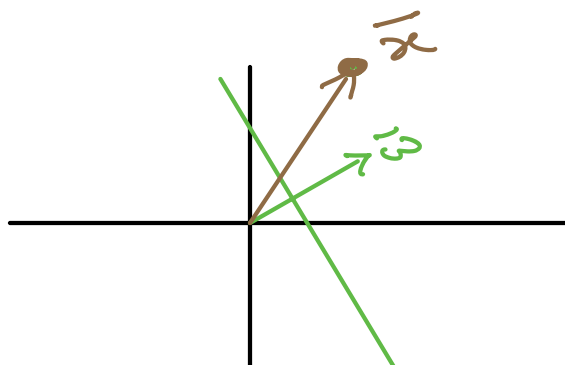
$$\Rightarrow \frac{5}{\sqrt{400}}$$

$$\Rightarrow \frac{5}{20} \Rightarrow \frac{1}{4}$$

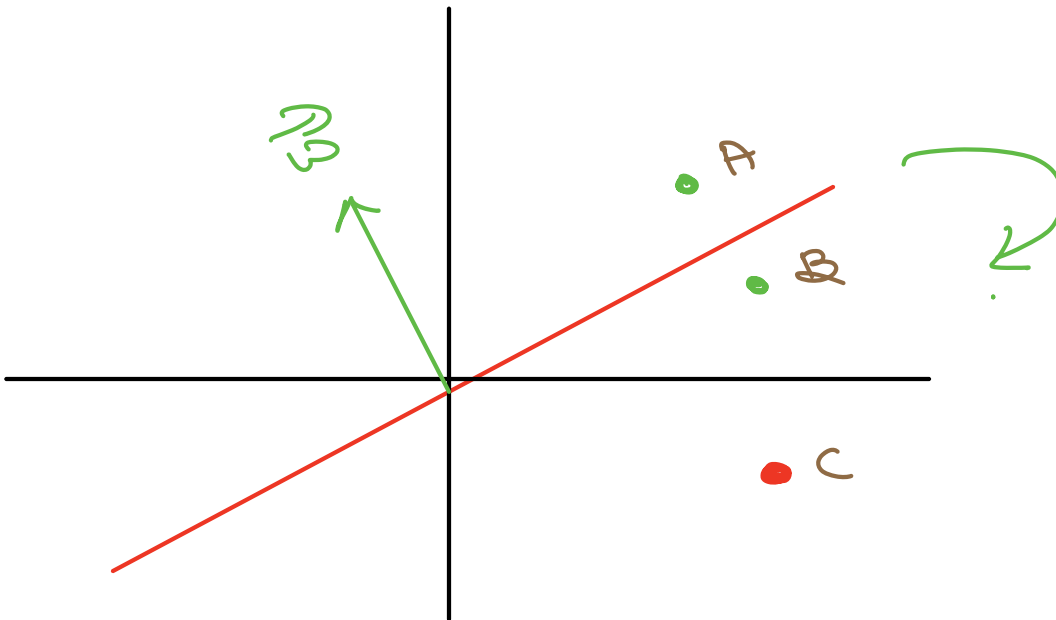
In the classification context we have two vectors x and w Define $v = x + w$

In which direction should we move w to reach v , options are:

- clockwise
- anti-clockwise



$$v = w - x$$



new $\Rightarrow \vec{w} + \vec{B}$

What is the distance from the origin to the line $3x+4y=12$?

6 users have participated

A	7/5	0%
B	3/5	0%
✓ C	12/5	100%
D	4/5	0%

End Quiz Now

$$\textcircled{0} \quad \frac{w_0}{\|w\|} \quad \frac{12}{\sqrt{3^2+4^2}}$$

$$\Rightarrow \frac{12}{5}$$

What is the distance between the point $(2, -3)$ and the line $3x-4y=5$?

0 users have participated

A	2/5	0%
B	3/5	0%
✓ C	13/5	0%
D	4/5	0%

End Quiz Now

$$w_1 x_1 + w_2 x_2 = w_0$$

$$w_1 x_1 + w_2 x_2 - w_0 = 0$$

$$\vec{w} = (3, -4)$$

$$p = (2, -3)$$

$$w_0 = -5$$

$$\frac{w \cdot p + w_0}{\|w\|}$$

$$\frac{3 \times 2 + (-4 \times -3) - 5}{5}$$

$$(6 + 12 - 5)/5$$

$$y = mx + c$$

