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In [3]: import tensorflow.compat.v1 as tf
import tensorflow.compat.v2 as tf_v2
import tensorflow.keras.backend as K
import random
import math
import numpy as np
from matplotlib import pyplot as plt
from matplotlib import patches as mpatches
from sklearn import preprocessing
import tensorflow as tf
from tensorflow.keras import layers
from tensorflow.keras.callbacks import TensorBoard

WARNING:tensorflow:From C:\AnacondaLib\site-packages\tensorflow\python\compat\v2\compat.py:96: disable_resource_variables (from tensorflow.python.ops.variable_scope) is deprecated and will be removed in a future version.
Instructions for updating:
non-resource variables are not supported in the long term

In [4]: linkLength = 2

Q1 = []
Q2 = []
Q3 = []
posX = []
posY = []
titaEnd = []
size = 2000

In [7]: def Xe(a,b,c):
    # return the X,Y,Tita for a given 2 joint angles
    return linkLength*math.cos(a)+linkLength*math.cos(a+b)+linkLength*math.cos(a+b+c)
def Ye(a,f,q):
    return linkLength*math.sin(e) + linkLength*math.sin(e + f) + linkLength*math.sin(e + f + q)
def tita(a,h):
    return math.degrees(h)+math.degrees(i)+math.degrees(j)

In [8]: def costLoss(yTrue,yPred):
    return K.sum((yTrue - yPred)**2)

# NN Model
def build_model():
    model = keras.Sequential()
    model.add(keras.layers.Dense(3))
    model.add(keras.layers.Dense(100,use_bias=True, activation='relu'))
    model.add(keras.layers.Dense(100, use_bias=True, activation='relu'))
    model.add(keras.layers.Dense(50,use_bias=True, activation='relu'))
    model.add(keras.layers.Dense(25,use_bias=True, activation='relu'))
    model.add(keras.layers.Dense(3,use_bias=True, activation='linear'))
    model.compile(optimizer=tf.train.AdamOptimizer(0.01), loss=costLoss, metrics=['accuracy']) # mean squared error
    return model

In [9]: file = open("traing_data.csv","w") # Data Set Creation
for i in range(0,samples):
    q1 = round(random.uniform(0,math.pi),2)
    q2 = round(random.uniform(-math.pi,0),2)
    q3 = round(random.uniform(-math.pi/2, math.pi/2), 2)
    Q1.append(q1)
    Q2.append(q2)
    Q3.append(q3)
    file.write(str(q1))
    file.write(",")
    file.write(str(q2))
    file.write(",")
    file.write(str(q3))
    file.write(",")
    X = Xe(q1,q2,q3)
    posX.append(X)
    file.write(str(round(X, 2)))
    file.write(",")
    Y = Ye(q1,q2,q3)
    posY.append(Y)
    file.write(str(round(Y, 2)))
    file.write(",")
    T = tita(q1,q2,q3)
    titaEnd.append(T)
    file.write(str(round(T, 2)))
    file.write("\n")
file.close()

In [14]: for i in range(0,len(posX)):
    plt.plot([posX[i],posX[i+0.2]*math.cos(math.radians(titaEnd[i]))],[posY[i],posY[i+0.2]*math.sin(math.radians(titaEnd[i]))], 'k-')
    plt.scatter(posX,posY) #Plotting the data set
plt.xlabel("X Axis")
plt.ylabel("Y Axis")
plt.title("Data set of 2000 possible endeffector positions and orientations")

Out[14]: Text(0.5, 1.0, 'Data set of 2000 possible endeffector positions and orientations')

Data set of 2000 possible endeffector positions and orientations

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