

**Digital Signal Processing**  
**Tutorial Questions Booklet**

# Digital Signal Processing

## Solution Sheet 1

### Sampling and z-transforms

1.  $Y(z) = H(z)X(z)$

2. 
$$X(z) = \sum_{n=-\infty}^{\infty} x(n)z^{-n}$$

3. 
$$y(n) = \sum_{m=-\infty}^{\infty} h(m)x(n-m)$$

4. From the definition of the z-transform

$$\begin{aligned} Y(z) &= \sum_{n=-\infty}^{\infty} y(n)z^{-n} \\ &= \sum_{n=-\infty}^{\infty} \sum_{m=-\infty}^{\infty} h(m)x(n-m)z^{-n} \\ &= \sum_{p=-\infty}^{\infty} \sum_{m=-\infty}^{\infty} h(m)x(p)z^{-m}z^{-p} \quad \text{for } p = n - m \\ &= \sum_{m=-\infty}^{\infty} h(m)z^{-m} \sum_{p=-\infty}^{\infty} x(p)z^{-p} \\ &= H(z)X(z) \end{aligned}$$

5. Factor the denominator so that  $X(z) = \frac{7z^2 - 5z}{(z+1)(z-3)}$  in order to find that the poles are at  $z = -1$  and  $z = 3$ . Partial fraction expansion gives  $X(z) = \frac{3z}{z+1} + \frac{4z}{z-3}$ .

a) For  $|z| < 1$ , the ROC is inside both poles, giving two left-sided sequences.

$$x(n) = -3(-1)^n u(-n-1) - 4(3)^n u(-n-1) \quad [\text{anticausal}]$$

b) For  $|z| > 3$ , the ROC is outside both poles, giving right-sided sequences.

$$x(n) = 3(-1)^n u(n) + 4(3)^n u(n) \quad [\text{causal}]$$

b) For  $1 < |z| < 3$ , the ROC is between both poles, giving a two-sided sequence.

$$x(n) = 3(-1)^n u(n) - 4(3)^n u(-n-1) \quad [\text{noncausal}]$$

# **Digital Signal Processing**

## **Solution Sheet 2**

### **Discrete Fourier Transforms**

$$1 \quad X_p[k] = \sum_{n=0}^{N-1} x_p[n] e^{-j \frac{2\pi}{N} n k} \quad k = \dots, -1, 0, 1, \dots$$

- find period  $N$
- compute one period of  $X_p[k]$
- extend for  $-\infty < k < \infty$ .

$$x_p[n] = 10 \sin\left(\frac{2\pi n}{3}\right), \quad N=3$$

$$n=0 \quad x_p[0] = 0$$

$$n=1 \quad x_p[1] = 10 \sin\left(\frac{2\pi}{3}\right) = 8.66$$

$$n=2 \quad x_p[2] = 10 \sin\left(\frac{4\pi}{3}\right) = -8.66$$

$$k=0 \quad X_p[0] = x_p[0] \cdot e^0 + x_p[1] \cdot e^0 + x_p[2] \cdot e^0 = 0$$

$$k=1 \quad X_p[1] = x_p[0] \cdot e^0 + x_p[1] \cdot e^{-j \frac{2\pi}{3}} + x_p[2] \cdot e^{-j \frac{4\pi}{3}}$$

$$= 0 + 8.66(-0.5 - j0.866) + -8.66(-0.5 + j0.866)$$

$$= 0 - j15$$

$$k=2 \quad X_p[2] = x_p[0] \cdot e^0 + x_p[1] \cdot e^{-j \frac{4\pi}{3}} + x_p[2] \cdot e^{-j \frac{8\pi}{3}}$$

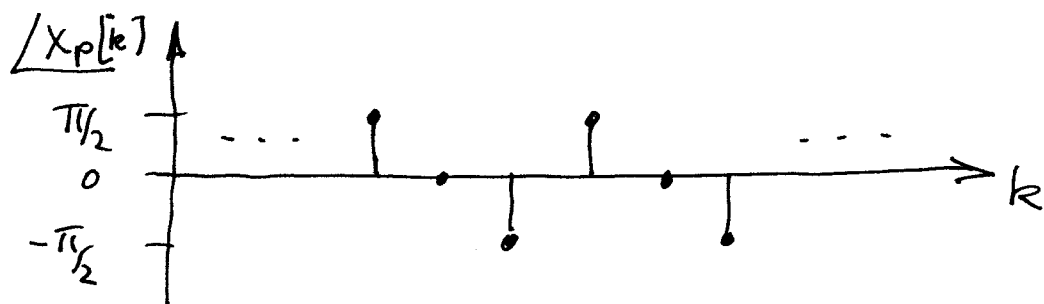
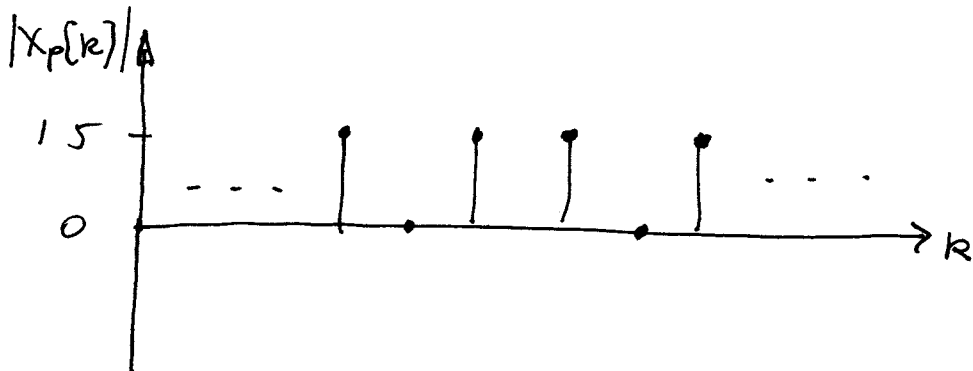
$$= 0 + 8.66(-0.5 + j0.866) + -8.66(-0.5 - j0.866)$$

$$= 0 + j15$$

$$x_p[k] = [ \dots, j15, 0, -j15, j15, 0, \dots ]$$

$$|x_p[k]| = [ \dots, 15, 0, 15, 15, 0, \dots ]$$

$$\angle x_p[k] = [ \dots, \pi/2, 0, -\pi/2, \pi/2, 0, \dots ]$$



2. Method similar to Q1 but using the DFT since the sequence is aperiodic.

$$X[k] = \sum_{n=0}^{N-1} x[n] e^{-j \frac{2\pi}{N} n k}$$

Magnitude spectrum given by  $|X[k]|$

i.e.  $\left( \text{Re}\{X[k]\}^2 + \text{Im}\{X[k]\}^2 \right)^{1/2}$

$$|X[k]| = [10.0 \quad 3.1 \quad 0.7 \quad 0.7 \quad 3.1]$$

3 a) 8 kHz, 1024 samples  $\Rightarrow$  128 ms

b) Freq. resolution =  $\frac{1}{NT}$  = 7.8 Hz

c) One way to view this operation is as a multiplication in the time domain by a rectangular window which is 1 for 512 points and 0 for 512 points. This will be seen in the frequency domain as sinc interpolation.

The formula  $1/NT$  would yield a frequency resolution of 7.8 Hz but, in fact, every-other frequency domain point is due to the interpolation effect.

New a) 64 ms

New b) 7.8 Hz if sinc interpolation is a good fit.

$$4. \quad y[n] = [x[0], 0, x[1], 0, x[2], 0, \dots]$$

$$X[k] = \sum_{n=0}^{N-1} x[n] e^{-j \frac{2\pi}{N} \cdot n \cdot k} \quad \text{where } N=8$$

$$Y[k] = \sum_{n=0}^{2N-1} y[n] e^{-j \frac{2\pi}{2N} \cdot n \cdot k}$$

$$= \sum_{\substack{n=0 \\ n \text{ even}}}^{2N-1} x\left[\frac{n}{2}\right] e^{-j \frac{2\pi}{2N} \cdot n \cdot k} + \sum_{\substack{n=0 \\ n \text{ odd}}}^{2N-1} 0 \cdot e^{-j \frac{2\pi}{2N} \cdot n \cdot k}$$

$X[k]$  is evaluated at  $N$  uniformly spaced frequencies around the unit circle

$Y[k]$  is evaluated at  $2N$  uniformly spaced frequencies around the unit circle and

$$Y[k] \Big|_{k=0,1,\dots,7} = Y[k] \Big|_{k=8,9,\dots,15} = X[k]$$

since values of  $Y[k]$  computed using  $e^{-j \frac{2\pi}{16} \cdot n \cdot 0}$

will be the same as values computed using

$e^{-j \frac{2\pi}{16} \cdot n \cdot 8}$  and so on. The final solution can

be written  $Y[mN+k] = X[k]$ ,  $k=0,1,\dots,N-1$ ,  $m=0,1,\dots$

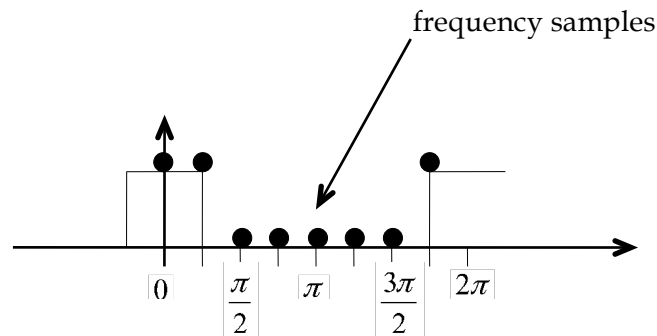


# Digital Signal Processing

## Solution Sheet 3

### Digital Filters

1.



$$H_s(k) = [1, 1, 0, 0, 0, 0, 0, 1]$$

$$h(n) = \frac{1}{8} \sum_{k=0}^7 H(k) e^{j \frac{\pi}{4} nk}$$

$$= [0.375, 0.302, 0.125, -0.052, -0.125, -0.052, 0.125, 0.302]$$

$$\text{delay by } \frac{N}{2}$$

$$= [-0.125, -0.052, 0.125, 0.302, 0.375, 0.302, 0.125, -0.052]$$

In MATLAB this can be expressed as:

```
N=8;
wstep = 2*pi/N;
w = [0:wstep:(2*pi)-wstep];
H=[1 1 0 0 0 0 0 1] .* exp(-j*w*N/2);
h = ifft(H);
```

However, we can see that this solution for  $h(n)$  does not satisfy the symmetry constraints required for linear phase  $h(n) = h(N-1-n)$ . To obtain exactly linear phase we would need to delay the filter's impulse response not by  $N/2$  but by  $(N-1)/2$  so that, in the Matlab code above, the 4th line becomes

```
H=[1 1 0 0 0 0 0 1] .* exp(-j*w*(N-1)/2);
```

and as a consequence  $h(n)$  becomes complex, although with the required conjugate symmetry for complex coefficient linear-phase filters:

$$h(n) = \begin{bmatrix} 0.125-0.096j & 0.125-0.231j & 0.125-0.231j & 0.125-0.096j \\ 0.125-0.096j & 0.125+0.096j & 0.125+0.231j & 0.125+0.231j \\ 0.125+0.096j & 0.125+0.231j & 0.125+0.231j & 0.125+0.096j \end{bmatrix}$$

2.

d.c. gain ( $\omega = 0$ )

$$\left| H(e^{j0}) \right| = k \cdot \left| \frac{1 + e^{j0}}{1 - ce^{j0}} \right| = \frac{2k}{1 - c}$$

3. For unity gain at d.c.

$$k = \frac{1-c}{2}$$

4. 
$$\left| H\left(e^{j\frac{\pi}{2}}\right) \right| = \frac{1-c}{2} \cdot \left| \frac{1+e^{-j\frac{\pi}{2}}}{1-ce^{-j\frac{\pi}{2}}} \right| = \frac{1-c}{2} \cdot \left| \frac{1-j}{1+jc} \right| = \frac{1}{\sqrt{2}} \text{ for -3dB.}$$

This equation is satisfied for  $c = 0$ .

(5)

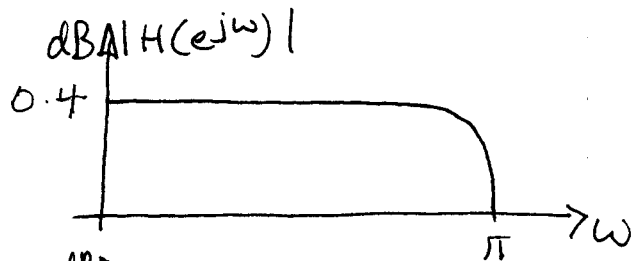
$$H(z) = \frac{1 + z^{-1}}{1 - cz^{-1}}$$

$$|z| > |c|$$

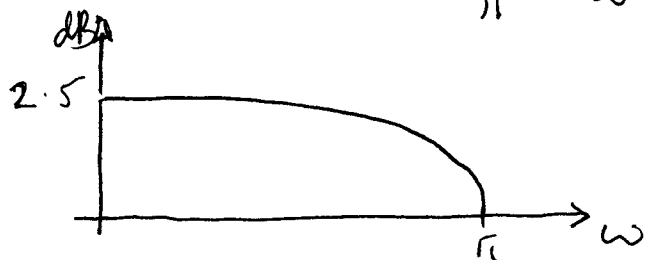
For frequency response write  $z = e^{j\omega}$

$$H(e^{j\omega}) = \frac{1 + e^{-j\omega}}{1 - ce^{-j\omega}}$$

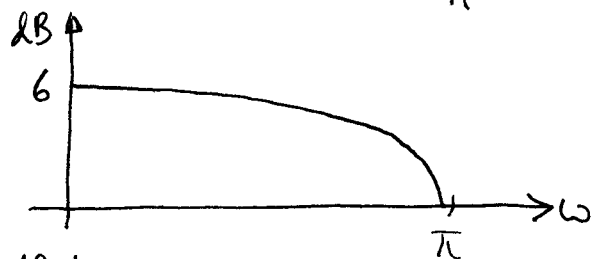
For  $c = -0.9$



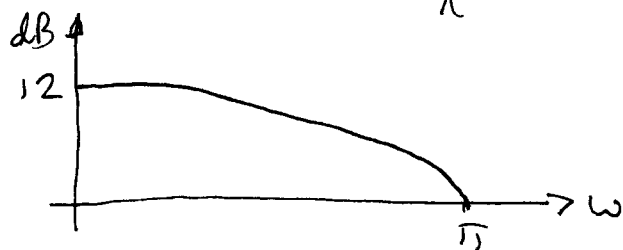
For  $c = -0.5$



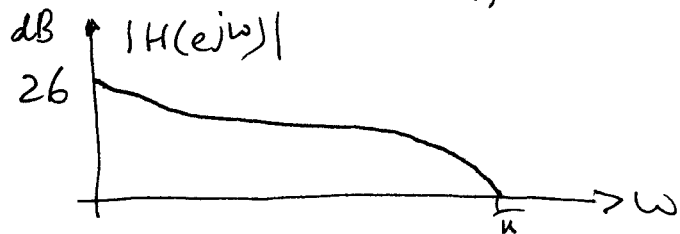
For  $c = 0$



For  $c = 0.5$



For  $c = 0.9$



# **Digital Signal Processing**

## **Solution Sheet 4**

### **Convolution**

$$\begin{aligned}
 1. \quad W(z) &= \sum_{n=-\infty}^{\infty} w[n] z^{-n} \\
 &= \sum_{n=-\infty}^{\infty} \left( \sum_{k=-\infty}^{\infty} x[k] y[n-k] \right) \cdot z^{-n} \\
 &= \sum_{k=-\infty}^{\infty} x[k] \sum_{n=-\infty}^{\infty} y[n-k] \cdot z^{-n} \\
 &= \sum_{k=-\infty}^{\infty} x[k] \cdot z^{-k} \cdot \sum_{n=-\infty}^{\infty} y[n-k] \cdot z^{-(n-k)}
 \end{aligned}$$

Now change the index of summation

$$\begin{aligned}
 & n \rightarrow m = n - k \\
 \therefore W(z) &= \sum_{k=-\infty}^{\infty} x[k] z^{-k} \cdot \sum_{m=-\infty}^{\infty} y[m] \cdot z^{-m} \\
 &= X(z) \cdot Y(z).
 \end{aligned}$$

2. See page 413, Strum & Kirk.

### 3. Overlap Add

$$x = [3, 2, 1, 4, 1, 2, 3, 2, 1]$$

$$\begin{aligned} \text{Choose } L + M - 1 &= 4 \\ m &= 2 \\ L &= 3 \end{aligned}$$

- 4 point ffts
- zero-pad  $x$  blocks by 1 zero
- zero-pad  $h$  blocks by 2 zeros

$$x_1 = [3, 2, 1, 0]$$

$$\begin{aligned} h &= [1, 1, 0, 0] \\ H &= [2, 1-j, 0, 1+j] \end{aligned}$$

$$X_1 = [6, 2-j^2, 2, 2+j^2]$$

$$Y_1 = X_1 \times H = [12, -j4, 0, j4]$$

$$y_1 = [3, 5, 3, 1]$$

$$x_2 = [4, 1, 2, 0]$$

$$X_2 = [7, 2-j, 5, 2+j]$$

$$Y_2 = X_2 \times H = [14, 1-j^3, 0, 1+3j]$$

$$y_2 = [4, 5, 3, 2]$$

$$x^3 = [3, 2, 1, 0] \quad (\text{as before})$$

$$y^3 = [3, 5, 3, 1]$$

$$\begin{array}{cccccccccc} y^1: & 3 & 5 & 3 & 1 & & & & & & \\ y^2: & & & & 4 & 5 & 3 & 2 & & & \\ y^3: & & & & & & & 3 & 5 & 3 & 1 \\ y: & 3 & 5 & 3 & 5 & 5 & 3 & 5 & 5 & 3 & 1 \end{array}$$

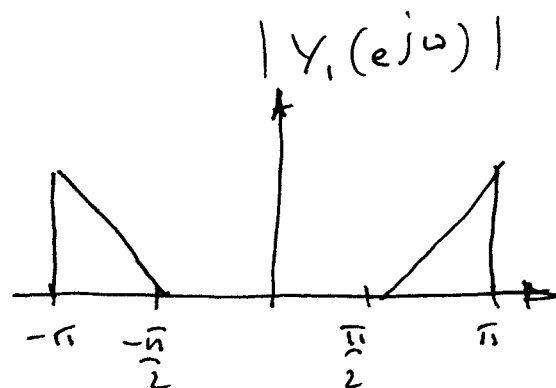
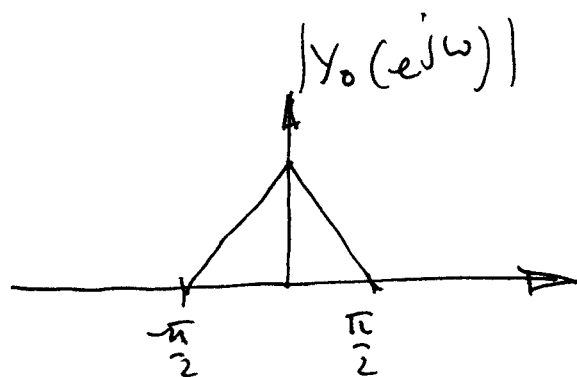
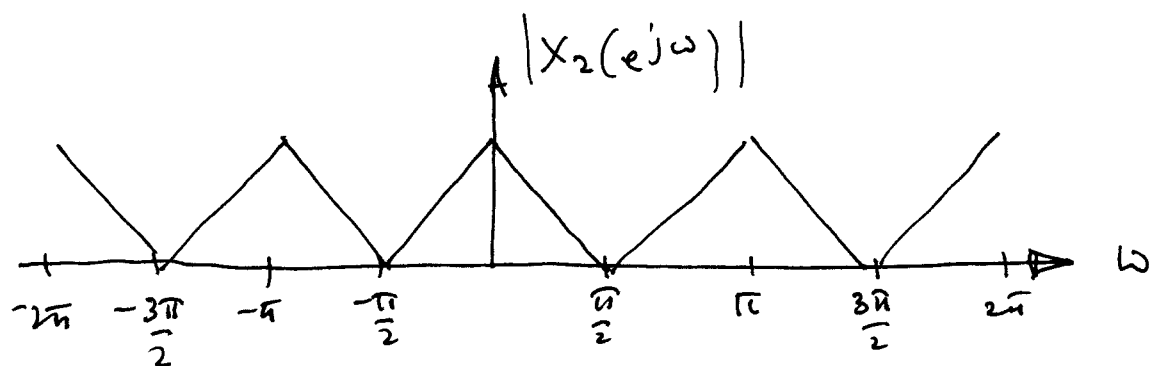
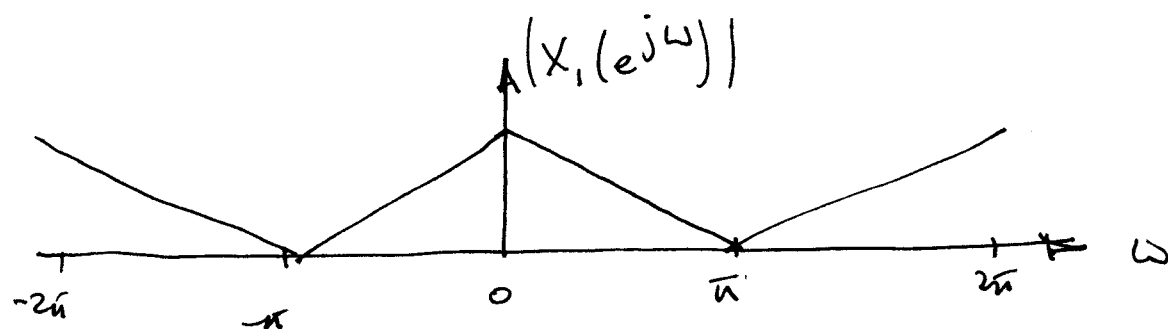
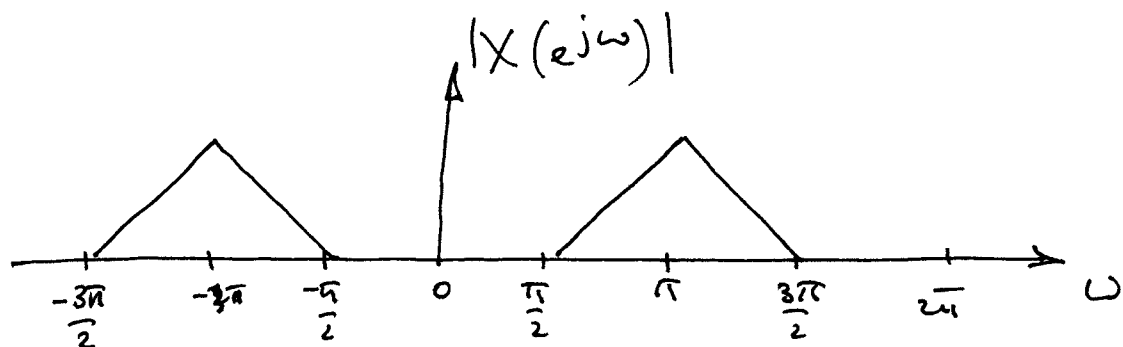
# **Digital Signal Processing**

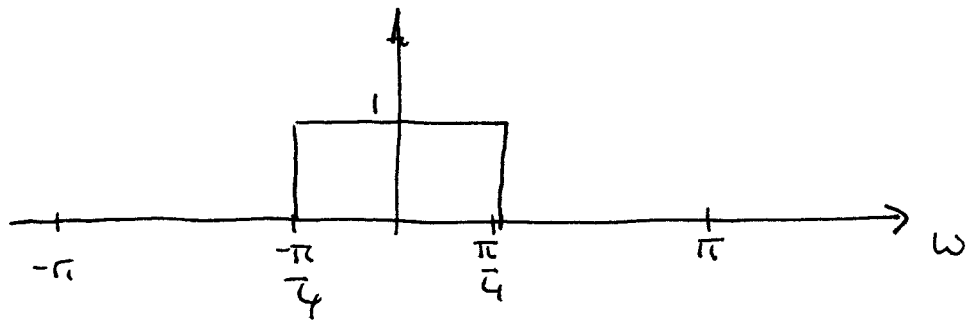
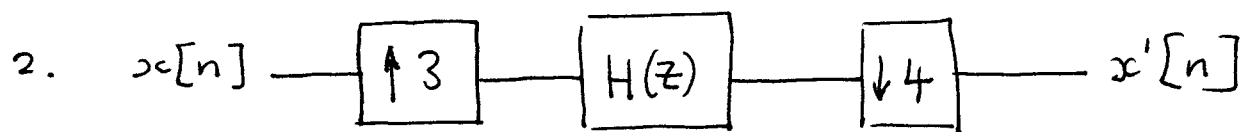
## **Solution Sheet 5**

### **Multirate Signal Processing**



1





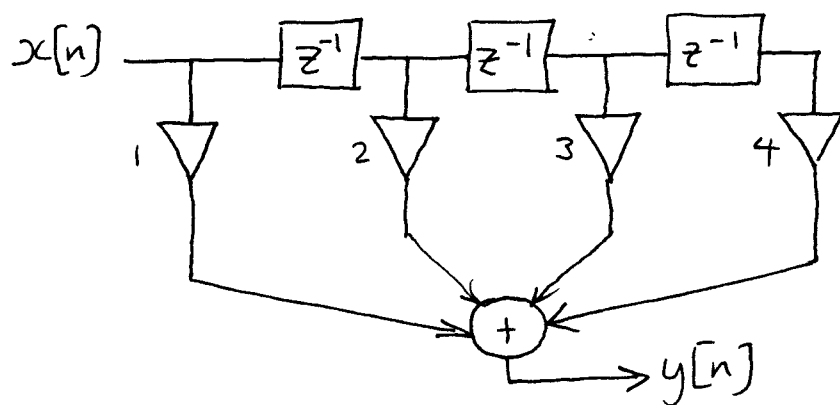
3  $H(z) = 1 + 2z^{-1} + 3z^{-2} + 4z^{-3}$

We can write  $H(z) = E_0(z^2) + z^{-1} E_1(z^2)$

for  $E_0(z) = 1 + 3z^{-1}$

and  $E_1(z) = 2 + 4z^{-1}$

Direct Implementation



Polyphase Implementation

