

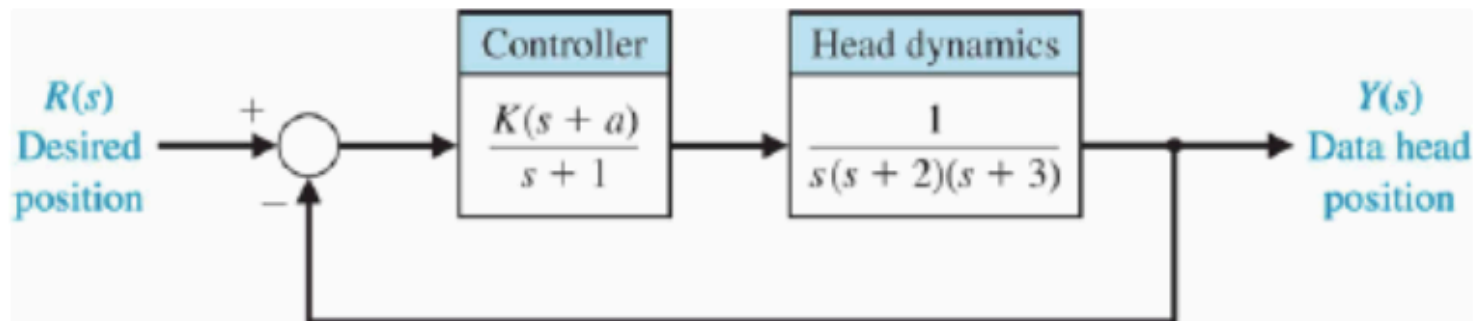
Further notes on the Routh-Hurwitz Stability Criterion

2 examples



1. Stability of a disk-drive controller

Disk-drives require fast and accurate motion of the data head above the spinning disk and so the controller must be highly responsive. We want to understand how to guarantee a stable control for the disk drive head for a typical system as shown below, where K and a are internal controller gains:



The overall system transfer function is given by:

$$\frac{Y(s)}{R(s)} = \frac{G(s)}{1 + G(s)H(s)} = \frac{\frac{K(s+a)}{s(s+1)(s+2)(s+3)}}{\left(1 + \frac{K(s+a)}{s(s+1)(s+2)(s+3)}\right)}$$



So, we take $1 + G(s)H(s)$ and write that as the left hand side of the characteristic equation to get:

$$1 + \frac{K(s + a)}{s(s + 1)(s + 2)(s + 3)} = 0$$

Therefore we can rationalise this to:

$$\frac{s(s + 1)(s + 2)(s + 3) + K(s + a)}{s(s + 1)(s + 2)(s + 3)} = 0$$

So obviously we just need to consider:

$$s(s + 1)(s + 2)(s + 3) + K(s + a) = 0$$

Expanding this out gives:

$$s^4 + 6s^3 + 11s^2 + (K + 6)s + Ka = 0$$

From this we can build up the Routh-Hurwitz array.



We start by noting that in this example $n = 4$, and then we can compare our disk-drive characteristic equation (above) with the general characteristic equation from which the array elements are calculated.

$$a_0 s^n + a_1 s^{n-1} + a_2 s^{n-2} + \dots + a_{n-1} s + a_n = 0$$

$$\text{So, } a_0 = 1, \quad a_1 = 6, \quad a_2 = 11, \quad a_3 = K + 6, \quad a_4 = Ka$$

$$b_1 = \frac{a_1 a_2 - a_0 a_3}{a_1} = \frac{6 \cdot 11 - 1 \cdot (K + 6)}{6} = \frac{(60 - K)}{6}$$

$$b_2 = \frac{a_1 a_4 - a_0 a_5}{a_1} = \frac{6 \cdot Ka - 1 \cdot 0}{6} = Ka$$

$$c_1 = \frac{b_1 a_3 - a_1 b_2}{b_1} = \frac{\frac{(60 - K)}{6} \cdot (K + 6) - 6 \cdot Ka}{\frac{(60 - K)}{6}} = (K + 6) - \frac{6Ka}{\frac{(60 - K)}{6}} = (K + 6) - \frac{36Ka}{(60 - K)}$$

$$d_1 = \frac{c_1 b_2 - b_1 c_2}{c_1} = \frac{\left[(K + 6) - \frac{36Ka}{(60 - K)} \right] \cdot Ka - \frac{(60 - K)}{6} \cdot 0}{\left[(K + 6) - \frac{36Ka}{(60 - K)} \right]} = Ka$$



So, the R-H array now looks like this:

$$\begin{array}{ll}
 s^n : a_0 & a_2 & a_4 & a_6 & \dots & s^4 : 1 & 11 & Ka & \dots \\
 s^{n-1} : a_1 & a_3 & a_5 & a_7 & \dots & s^3 : 6 & (K+6) & \dots \\
 s^{n-2} : b_1 & b_2 & b_3 & \dots & & s^2 : \frac{(60-K)}{6} & Ka & \dots \\
 s^{n-3} : c_1 & c_2 & \dots & & & s^1 : \left[(K+6) - \frac{36Ka}{(60-K)} \right] & \dots \\
 s^{n-4} : d_1 & \dots & & & & s^0 : Ka & \dots
 \end{array}$$

The first column contains these terms:

$$\begin{array}{l}
 1 \\
 6 \\
 \frac{(60-K)}{6} \\
 \left[(K+6) - \frac{36Ka}{(60-K)} \right] \\
 Ka
 \end{array}$$



The third element b_1 requires that $K < 60$ and the fifth element requires that $a > 0$, and the fourth element sets the relationship between K and a .

To find the most general relationship possible, whilst also satisfying the Routh-Hurwitz stability criterion that there are no sign changes in the first column, we set $c_1 = 0$. This means that we have:

$$(K + 6) - \frac{36Ka}{(60 - K)} = 0$$

Therefore we can write:

$$(K - 60)(K + 6) + 36Ka = 0$$

From which we obtain:

$$a \leq \frac{(60 - K)(K + 6)}{36K}$$

noting the previous condition for a being positive.

So, for example, if we take a practical plant value of $K = 40$ then we get $a \leq 0.64$.

