SE456 /CS 456 Computer Vision Section W1 Fall 2018

| Instructor | Syed Farooq Ali | | | | |
|----------------------|---|------------------|--|--|--|
| Lectures | | Contact | farooq.ali@umt.edu.pk | | |
| Office | Hall#: STD 404 Office Hours: Mon (2:00-4:00 pm) Thr (2:00-4:00 pm) | TA | Name: TBA Office Hours and Venue: TBA | | |
| Lab | Lab Engineer Name: TBA Labs Day & Timings: TBA Venue: | | | | |
| Pre- Requisites | None | Moodle Group, | | | |
| VIP Research Grp. | VIP stands for Vision and Image Processing Research Group at UMT URL: http://sst.umt.edu.pk/vip/home.aspx https://sites.google.com/site/farooq1us/home | | | | |
| Course Objectives | Computer Vision combines and integrates ideas from different areas, including statistics, linear algebra, pattern recognition, machine intelligence, decision theory and image processing. To enable students to learn different techniques and algorithms of computer vision. As this course is designed with an application perspective, hence, implementation of different concepts of computer vision (taught in this course) is an integral part of this course. To introduce a new area of study, in which students can pursue research and development. | | | | |
| Textbooks | There is no single text book for this course. However, following is the recommended reading material. [Shah] Fundamentals of Computer Vision, Mubarak Shah, 1992 [Shapiro] Computer Vision, Linda G. Shapiro, George C. Stockman, Prentice Hall, 2001 [Snyder] Machine Vision, Wesley E. Snyder and Hairong Qi, Cambridge, 2004 [Gonzalez, Woods] Digital Image Processing, 2nd Edition (Freely Available Online) | | | | |
| Technology | The course provides hands on experience on • Matlab Programming • Irfan View, Video Editing Tools (RV Tool, Sequence Viewer) • C/C++ (optional) | | | | |
| Midterms | A single 75-minute midter | m Final | Will cover the entire course. At least 75% | | |

| | from the material covered during the first 8 weeks | of the material would be post midterm. | | |
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| Classroom Policy | The plagiarism and cheating cases would be reported to the Disciplinary Committee or Management. Keep your mobiles switched off. In case of late absent, it would be the choice of the instructor to either ask you to write a complete lecture again on a white paper signed by the instructor or to mark you Absent. The complete lecture needs to be submitted by 5 pm in the same day in Instructor's office. It is your responsibility not to delete your assignment even after its submission. Quizzes can be announced or unannounced. 1 quiz would be dropped out of 5 or 6 quizzes. No retake for quizzes. | | | |
| Grading Policy | Class Exercise Assignments Project Quizzes Mid-Term Exam/Term Test Final Exam | 10% 20% 15% 10% 20% 25% | | |

Tentative Course Plan:

| Week | Contents | Module | Assessments |
|------|--|------------------------|--------------------------------|
| 1 | Introduction Course introduction, along with an overview of the computer | 1. Imaging Geometry | Quiz 1 |
| | vision, digital images, | and | Assign 1: PPM, |
| | imaging devices and the human eye, PPM and PGM formats | Transform | PGM File |
| | | ations | Manipulation using C |
| 2, 3 | Transformations | 1 | Quiz 2, Quiz 3 |
| | 2D Transformations (Translation, Scaling, Shear, Rotation, | | |
| | Affine, Projective) | | Assign. 2(week 2): |
| | | | Transformations, |
| | Matlab Tutorial | | Image Warping |
| | | | (Matlab) |
| | Recovering best affine transformations | | |
| | Image Warping, Image Registrations, | | Assign 3 |
| | 3D transformations (optional) | | (Handwritten): Tranformations, |
| | | | imaging geometry |
| | | | imaging geometry |
| 4, 5 | Imaging Geometry | 1 | Assign 3 (CONT.) |
| | Camera Model, Perspective and Orthographic Cameras, Camera | | |
| | Calibration, Stereo | | Quiz 4, Quiz 5 |
| 5 | Pyramids | 2. Motion | |
| | Gaussian Pyramids, | (Optional) | |
| | Sampling and Aliasing | | |
| 6 | Optical Flow | 2 | Quiz 6 |
| | Brightness constancy equation, normal vs. perpendicular flow, | | |
| | Lucas-Kanade method | | |
| | | | |

| 7 | Global Motion Estimation Affine global motion estimation, Projective global motion estimation, applications Tentative: Motion Tracking | 2 | |
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| 8 | Revision | | Mid Term |
| 9, 10 | Basic Binary Operations Thresholding, morphology, region properties, moments (optional), connected component labeling Smoothing and Denoising Low Pass Filter, Averaging Filter, Noise, Denoising Edge Detection | 3. Binary Image Processing | Assign 4: Connected Component Labeling, Canny, Hough Transform (Matlab) |
| | Difference masks, Laplacian of Gaussian (LoG), Canny | | |
| 10, 11, | Shape Representation Hough Transform, Generalized Hough Transform | 3 | |
| 13 | Correlation and Template Matching Correlation, Normalized Correlation, Distance Transform, Medial Axis Transform, Hausdorff Distance Applications: Background subtraction, Change Detection, skin detection | 4. Segmentat ion and Clustering | Quiz 7 Assign 5/Project (optional) (Matlab) |
| 14 | Clustering and Segmentation (Optional) K-Means, How to choose K, Split and Merge, Agglomerative and Divisive Clustering, Motion Segmentation, Color Segmentation Relevant Areas and Courses Digital Image Processing, Computer Graphics, Image and Video Coding | 4 | |
| 15 | Pattern Recognition, Machine Learning, Artificial Intelligence | 4 | |
| | Revision | | |