

Recall: $f: \mathbb{R}^n \rightarrow \mathbb{R}^m$ is diffble at x_0 if

\exists matrix $Df(x_0) \in \mathbb{R}^{mn}$ st. $\lim_{h \rightarrow 0} \frac{\|f(x_0+h) - f(x_0) - Df(x_0)h\|}{\|h\|} = 0$
 (can be locally linear approximated by a linear map)

And directional derivative: linear approximation $Df(x_0)u \in \mathbb{R}^m$ of the effect of $f: \mathbb{R}^n \rightarrow \mathbb{R}^m$ on a direction $u \in \mathbb{R}^n$

$$Df(x_0)u = \lim_{t \rightarrow 0} \frac{f(x_0+tu) - f(x_0)}{t}$$

Thm Let $f: A \subseteq \mathbb{R}^n \rightarrow \mathbb{R}^m$ diffble at x_0 (A open.)

$$\Rightarrow \forall u \in \mathbb{R}^n, Df(x_0)u = Df(x_0)u$$

Pf for $u=0 \Rightarrow$ obviously $Df(x)=0 \forall x$
 $= Df(x_0)u$

$$\text{for } u \neq 0, \text{wts: } \lim_{t \rightarrow 0} \frac{\|f(x_0+tu) - f(x_0) - Df(x_0)u\|}{t} = 0$$

$$\text{equivalently } \lim_{t \rightarrow 0} \frac{\|f(x_0+tu) - f(x_0) - Df(x_0)u\|}{|tu|} = 0$$

(since u is const)

This is true. by taking $h=tu$, as the def of derivative.

Def Partial derivative

$f: A \rightarrow \mathbb{R}^m, A \subseteq \mathbb{R}^n$ open

$$\text{then } \frac{\partial f}{\partial x_j}(x_0) = D_{e_j} f(x_0) \in \mathbb{R}^m \Rightarrow \text{the } j^{\text{th}} \text{ partial derivative of } f \text{ at } x_0 \in \mathbb{R}^n$$

$$= \frac{d}{dt} \Big|_{t=0} f(x_0 + te_j)$$

ex when $m=1$

$$\begin{aligned} \frac{\partial f}{\partial x_j}((x_1, x_2, \dots, x_n)) &= \frac{d}{dt} \Big|_{t=0} f(x_1, \dots, x_{j-1}, x_j+t, x_{j+1}, \dots, x_n) \\ &= \frac{d}{ds} \Big|_{s=x_j} f(x_1, \dots, x_{j-1}, s, x_{j+1}, \dots, x_n) \\ &= y'(x_j) \text{ where } y(s) = f(x_1, \dots, x_{j-1}, s, x_{j+1}, \dots, x_n) \end{aligned}$$

(treat all above vars as const except s)

If $m=1$, we can write $f = \begin{pmatrix} f_1 \\ f_2 \\ \vdots \\ f_m \end{pmatrix}$ for any $u \in \mathbb{R}^n$

$$\begin{aligned} \text{then } Df(x_0) &= \lim_{t \rightarrow 0} \frac{f(x_0+tu) - f(x_0)}{t} \\ &= \lim_{t \rightarrow 0} \begin{pmatrix} \frac{f_1(x_0+tu) - f_1(x_0)}{t} \\ \vdots \\ \frac{f_m(x_0+tu) - f_m(x_0)}{t} \end{pmatrix} = \begin{pmatrix} Df_1(x_0) \\ Df_2(x_0) \\ \vdots \\ Df_m(x_0) \end{pmatrix} \end{aligned}$$

$$\text{In particular, } \frac{\partial f}{\partial x_j}(x_0) = \begin{pmatrix} \frac{\partial f_1}{\partial x_j}(x_0) \\ \vdots \\ \frac{\partial f_m}{\partial x_j}(x_0) \end{pmatrix}$$

$$\text{ex let } F: \mathbb{R}^2 \rightarrow \mathbb{R}^3, (x, y) \mapsto \begin{pmatrix} x^2+y^2 \\ xy \\ \sin y \end{pmatrix}$$

$$\text{then } \frac{\partial F}{\partial x}(x, y) = \begin{pmatrix} \frac{\partial}{\partial x}(x^2+y^2) \\ \frac{\partial}{\partial x}(xy) \\ \frac{\partial}{\partial x}(\sin y) \end{pmatrix} = \begin{pmatrix} 2x \\ y \\ 0 \end{pmatrix}$$

$$\frac{\partial F}{\partial y}(x, y) = \begin{pmatrix} 2y \\ x \\ \cos y \end{pmatrix}$$

$$\text{if } u = (1, 2) \text{ then } D_u F(x, y) = \frac{d}{dt} \Big|_{t=0} \begin{pmatrix} (xt)^2 + (yt)^2 \\ (xt)(yt) \\ \sin(yt) \end{pmatrix} = \begin{pmatrix} 2xt+2yt \\ xt+yt \\ 2\cos(yt) \end{pmatrix}$$

In this case we can check

$$D_{(1,2)} F(x, y) = 1 D_{e_1} F(x, y) + 2 D_{e_2} F(x, y)$$

which suggests (but not prove) F being diffble

Thm 1 let $f: A \subseteq \mathbb{R}^n \rightarrow \mathbb{R}^m$ (A open). $f = \begin{pmatrix} f_1 \\ \vdots \\ f_m \end{pmatrix}$

(a) If f is diffble at $x_0 \in \mathbb{R}^n$

$\boxed{Df(x_0)}$ is \uparrow mxn matrix B3 $\boxed{(i, j)^{\text{th}} \text{ entry } \Rightarrow \frac{\partial f_i}{\partial x_j}(x_0)}$

(scalar value function)
 这是一个 $\mathbb{R}^n \rightarrow \mathbb{R}$ 的概念

$$Df(x_0) = \begin{pmatrix} \frac{\partial f}{\partial x_1}(x_0) & \frac{\partial f}{\partial x_2}(x_0) & \cdots & \frac{\partial f}{\partial x_n}(x_0) \\ | & | & \ddots & | \\ 1 & 1 & \cdots & 1 \end{pmatrix}$$

Def gradient
 这是一个 $\mathbb{R}^n \rightarrow \mathbb{R}$ 的概念

$$\nabla g(x) = \begin{pmatrix} \frac{\partial g}{\partial x_1}(x) \\ \vdots \\ \frac{\partial g}{\partial x_n}(x) \end{pmatrix} = Dg(x) = \begin{pmatrix} \nabla f_1^T \\ \vdots \\ \nabla f_m^T \end{pmatrix}$$

(b) f is diffble at x_0 iff ∇f_i is diffble at x_0

$$\text{Pf (a) } \forall j, D_{e_j} f(x_0) = D_{e_j} f(x_0) = \frac{\partial f}{\partial x_j}(x_0)$$

(b) f is diffble at $x_0 \Leftrightarrow \exists$ matrix A st.

$$\frac{|f(x_0+h) - f(x_0) - Ah|}{\|h\|} \rightarrow 0 \text{ as } \|h\| \rightarrow 0$$

$$\Leftrightarrow \forall i, \frac{|f_i(x_0+h) - f_i(x_0) - A_i h|}{\|h\|} \rightarrow 0 \text{ as } \|h\| \rightarrow 0$$

$\Leftrightarrow f_i$ is diffble at x_0 with $Df_i(x_0) = A_i$ (ith row of A)

ex let $f(x,y) = \begin{pmatrix} x^2+y^2 \\ xy \\ \sin y \end{pmatrix}$

if f is diffble then its derivative should be

$$Df(x,y) = \begin{pmatrix} \frac{\partial}{\partial x}(x^2+y^2) & \frac{\partial}{\partial y}(x^2+y^2) \\ \frac{\partial}{\partial x}(xy) & \frac{\partial}{\partial y}(xy) \\ \frac{\partial}{\partial x}(\sin y) & \frac{\partial}{\partial y}(\sin y) \end{pmatrix} = \begin{pmatrix} 2x & 2y \\ y & x \\ 0 & \cos y \end{pmatrix}$$

Def this matrix for $f: \mathbb{R}^n \rightarrow \mathbb{R}^m$
with $\frac{\partial f_i}{\partial x_j}(x_0)$ is called the Jacobian at x_0

Rmk $\exists Df(x_0) \Rightarrow$ Jacobian at x_0 exists

但是 $\exists Df(x_0) \not\Rightarrow$ Jacobian at x_0 exists

Rmk f diffble at $x_0 \Leftrightarrow f_1, \dots, f_m$ diffble at x_0

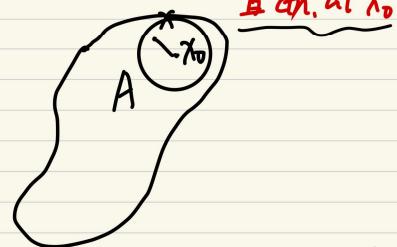
是一个自然且令人舒适的结论，因为这就表示了在处理
vector-value 的函数的导数时只需把它拆成 m 个 scalar-value 的函数即可

Thm Let $f: A \subseteq \mathbb{R}^n \rightarrow \mathbb{R}^m$ (A open)

对于 $x_0 \in A$, 如果 \exists some $B_\epsilon(x_0)$

s.t. $\forall x \in B_\epsilon(x_0)$, all $\frac{\partial f_i}{\partial x_j}$ exists ($i \in \mathbb{N}, j \in \mathbb{N}$)

$\Rightarrow f$ diffble at x_0



Def $f \in C^1$ if all $\frac{\partial f_i}{\partial x_j}$ exists & ctn on A (defn)

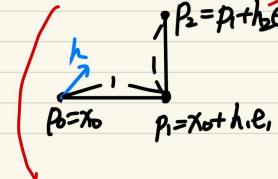
(so the thm states: $f \in C^1$ around $x_0 \Rightarrow f$ diffble at x_0
 $f \in C^1 \Rightarrow f$ diffble)

Pf Since f is diffble at x_0 iff its components are,

we may assume $m=1$ (that's why thm 1(b) 要
let $r>0$ s.t. $B_r(x_0) \subseteq A$ 在考虑任何 $\mathbb{R}^n \rightarrow \mathbb{R}^m$ 函数时)

And $h = (h_1, \dots, h_n) \in \mathbb{R}^n$ with $\|h\| < r$ 性质时只需考虑 $\mathbb{R}^n \rightarrow \mathbb{R}$ 时)

Set $p_0 = x_0$
 $p_1 = p_0 + h_1 e_1$
 $p_2 = p_1 + h_2 e_2$
 \vdots
 $p_n = p_{n-1} + h_n e_n = x_0 + h$



Let $y_j(s) = f(p_{j-1} + se_j)$

$y_j : I_j \rightarrow \mathbb{R}$ where $I_j \supseteq B_{h_j}(0)$

$\Rightarrow y'_j(s) = \frac{\partial f}{\partial x_j}(p_{j-1} + se_j)$ so! $e_j \in B_{h_j}(0)$

By MVT, $\exists c_j$ between 0 & h_j s.t. $Df(x_0) \in \mathbb{R}$

$y_j(h_j) - y_j(0) = y'_j(c_j) \cdot h_j$ which means

$f(p_{j-1} + h_j e_j) - f(p_{j-1}) = \frac{\partial f}{\partial x_j}(p_{j-1} + \underbrace{c_j e_j}_{\text{只用第一项}}) h_j$

$f(x_0 + h) - f(x_0) = \sum_{j=1}^n (f(p_j) - f(p_{j-1}))$

$= \sum_{j=1}^n \frac{\partial f}{\partial x_j}(q_j) h_j$

$f(x_0 + h) - f(x_0) - \sum_{j=1}^n \frac{\partial f}{\partial x_j}(p_0) \cdot h_j = \sum_{j=1}^n \left(\frac{\partial f}{\partial x_j}(q_j) - \frac{\partial f}{\partial x_j}(p_0) \right) h_j$

If $A = \left(\frac{\partial f}{\partial x_1}(p_0), \dots, \frac{\partial f}{\partial x_n}(p_0) \right)$

$\Rightarrow |f(x_0 + h) - f(x_0) - Ah| \leq \|h\| \sum_{j=1}^n \left| \frac{\partial f}{\partial x_j}(q_j) - \frac{\partial f}{\partial x_j}(p_0) \right|$

$\Rightarrow \frac{|f(x_0 + h) - f(x_0) - Ah|}{\|h\|} \leq \sum \left| \frac{\partial f}{\partial x_j}(q_j) - \frac{\partial f}{\partial x_j}(p_0) \right|$

continuity of partials gives this $\rightarrow 0$
as $\|h\| \rightarrow 0$

Intuition: We want to change one variable at a time

Rmk The converse of this thm is false

counterex $f: \mathbb{R} \rightarrow \mathbb{R}$
 $x \mapsto x^2 \sin(\frac{1}{x})$

diffble but f' not ctn. ($\notin C^1$)

Pf 备注

let $r > 0$ s.t. $B_r(x_0) \subseteq A$, and all partials are defined
and ctn. at A .

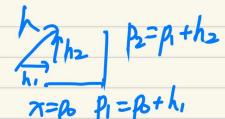
let $h = \begin{pmatrix} h_1 \\ \vdots \\ h_n \end{pmatrix} \in \mathbb{R}^n$ s.t. $\|h\| < r$

$p_0 = x$

$p_1 = p_0 + h_1 e_1$

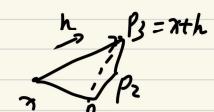
$p_2 = p_1 + h_2 e_2$

\vdots
 $p_n = p_{n-1} + h_n e_n = x + h$



Then $f(x + h) - f(x) = f(p_n) - f(p_0)$
 $= \sum_i f(p_i) - f(p_{i-1})$

Define: $y_j(s) = f(p_{j-1} + se_j)$ ($y_j: [0, h_j] \rightarrow \mathbb{R}$)



$$\text{ex } \varphi_i(s) = f(p_0 + se_i), \varphi_i(h_i) = f(p_i)$$

$$\varphi_i(s) = f(p_i + se_2), \varphi_2(h_2) = f(p_2)$$

$$y_i: s \mapsto f(p_{i-1} + se_i)$$

e_i 是这个方向

s 是沿这个方向: φ_i 表示 f 的值随 i 方向量的变化而变化的量
方向的变化量
note: $y'_i(s) = \frac{\partial}{\partial x_i} f(p_{i-1} + se_i)$, $y'_i(s) = \lim_{s \rightarrow 0} \frac{\varphi_i(s+s_0) - \varphi_i(s_0)}{s}$

$f(p_{i-1} + se_i)$ 是 f

随 s 在这个方向上

的变化量产生的变化量 因而 $y'_i(s) \geq 0$

因而 y_i 把不在 e_i 上

由 MVT: $y_i(h_i) - y_i(0) = h_i y'_i(c_i)$ for some

的点在 $[0, h_i]$ 间

$f(x)$ 相应变化量

因而 y'_i 是偏导数 $\frac{\partial}{\partial x_i}$

$y'(s)$ 即 f 随 (在 e_i 上的变化) 从 0 到 h_i

过程中在 $s \in [0, h_i]$ 时的变化速率

$$\begin{aligned} \Rightarrow f(x+th) - f(x) &= \sum_i (f(p_i) - f(p_{i-1})) \\ &= \sum_i (y_i(h_i) - y_i(0)) \\ &= \sum_i h_i y'_i(c_i) \\ &= \sum_i h_i \frac{\partial}{\partial x_i} f(p_{i-1} + t e_i) \end{aligned}$$

Rmk my thought on directional derivative

完全可以令 $m=1$

$$D_u f(x) = \lim_{t \rightarrow 0} \frac{f(x+tu) - f(x)}{t}$$

t 是一个和 h 一样的量级差量, 表示在 u 方向上的(微小)变化量

因而 $D_u f(x)$ 即: 在 u 方向上的微小变化量

引起的 f 在 x 处的变化量有多大

特别地, $u = e_i$ 时, 表示 (x_1, \dots, x_n) 中 x_i 的微小变化量
引起的 f 在 x 处的变化量有多大

因而 t 是一个初值 (const), $D_u f(x) = \frac{d}{dt} \Big|_{t=0} f(x+ut)$

note: $D_u f(x)$ 对于 u 是 linear 的

\text{即 } D_{a_1 u_1 + a_2 u_2} f(x) = a_1 D_{u_1} f(x) + a_2 D_{u_2} f(x)

if