

Problem A: Let $F : \mathbb{R}^3 \rightarrow \mathbb{R}^3$ be defined by

$$F(x, y, z) = (\exp(x^2 + 2y^2), \sin(z^2 - y^2) \cdot (x^2 + 2z^2), (x^2 + y^2 + z^2)^9).$$

Explain why F is differentiable, and then prove why $DF(x, y, z)$ always has zero determinant. You may not actually compute any derivatives your solution.

$$\textcircled{1} \quad F_1(x, y, z) = \exp(x^2 + 2y^2)$$

$$\text{let } g: \mathbb{R} \rightarrow \mathbb{R} \text{ and } f: \mathbb{R}^3 \rightarrow \mathbb{R} \\ \pi \mapsto e^\pi \quad (x, y, z) \mapsto x^2 + 2y^2$$

g is exponential, in $C^\infty(\mathbb{R})$; f is polynomial, in $C^\infty(\mathbb{R}^3)$
 $\therefore F_1 = g \circ f \in C^\infty(\mathbb{R}^3)$

(note: f is C^r and g is $C^r \Rightarrow g \circ f$ is C^r , by applying chain rule and product rule recursively.)

$$\textcircled{2} \quad F_2(x, y, z) = (\sin(z^2 - y^2)) (x^2 + 2z^2)$$

$$\text{let } g: \mathbb{R} \rightarrow \mathbb{R} \in C^\infty(\mathbb{R}), f: \mathbb{R}^3 \rightarrow \mathbb{R} \in C^\infty(\mathbb{R}^3), h: \mathbb{R}^3 \rightarrow \mathbb{R} \in C^\infty(\mathbb{R}^3) \\ \pi \mapsto \sin \pi \quad (\text{trig}) \quad (x, y, z) \mapsto z^2 - y^2 \quad (\text{poly}) \quad (x, y, z) \mapsto x^2 + 2z^2 \quad (\text{poly})$$

$\therefore F_2 = (g \circ f) \cdot h$ is C^∞

$$\textcircled{3} \quad F_3(x, y, z) = (x^2 + y^2 + z^2)^9$$

$$\text{let } g: \mathbb{R} \rightarrow \mathbb{R} \in C^\infty(\mathbb{R}), f: \mathbb{R}^3 \rightarrow \mathbb{R} \in C^\infty(\mathbb{R}^3) \\ \pi \mapsto \pi^9 \quad (\text{positive power}) \quad (x, y, z) \mapsto x^2 + y^2 + z^2 \quad (\text{poly})$$

$\therefore F_3 = g \circ f$ is C^∞

Thus all entries of the Jacobian matrix of F are in C^∞ , thus F is differentiable.

$$\text{let } F_i: \mathbb{R}^3 \rightarrow \mathbb{R}^3 \quad F_2: \mathbb{R}^3 \rightarrow \mathbb{R}^3 \\ \begin{pmatrix} x \\ y \\ z \end{pmatrix} \mapsto \begin{pmatrix} x^2 + 2y^2 \\ x^2 + 2z^2 \\ z^2 - y^2 \end{pmatrix} \quad \begin{pmatrix} a \\ b \\ c \end{pmatrix} \mapsto \begin{pmatrix} \exp(a) \\ b \sin(c) \\ \frac{1}{2}(a + b)^9 \end{pmatrix}$$

$$\text{note: } F = F_2 \circ F_1$$

Thus by the chain rule: $\forall a \in \mathbb{R}^3, DF(a) = DF_2(F_1(a)) \cdot DF_1(a)$

$$\text{so } \det(DF(a)) = \det(DF_2(F_1(a))) \det(DF_1(a))$$

$$\text{note that } \forall a = \begin{pmatrix} x \\ y \\ z \end{pmatrix} \in \mathbb{R}^3, DF_1(a) = \begin{pmatrix} 2x & 0 & 0 \\ 0 & 2x & 0 \\ 0 & 0 & 2z \end{pmatrix}$$

$$\text{where } \text{row}_3 = \frac{1}{2}(\text{row}_2 - \text{row}_1) \Rightarrow \text{linearly dependent} \Rightarrow \text{row rank} \leq 3 \\ \Rightarrow \det(DF_1(a)) = 0$$

This finishes the proof the $\forall a \in \mathbb{R}^3, \det(DF(a)) = 0$ \square

Problem B: Suppose

$$F: A \subset \mathbb{R}^n \rightarrow B \subset \mathbb{R}^m$$

and

$$G: B \subset \mathbb{R}^m \rightarrow A \subset \mathbb{R}^n$$

are both differentiable and are inverses of each other (A, B open). Show that $n = m$ and that, for all pairs $a \in A, b \in B$ with $F(a) = b$

$$DG(b) = DF(a)^{-1}.$$

Pf wlog suppose $n = m$

Then take arbitrary $x \in A$

Since F, G are differentiable and inverse of each other,

$$\text{we have } GF(x) = x \Rightarrow D(GF)(x) = I_m$$

$$\Rightarrow DG(F(x)) DF(x) = I_m \text{ by chain rule}$$

Similarly we have:

$$\forall y \in B, FG(y) = y \Rightarrow D(FG)(y) = I_m$$

$$\Rightarrow DF(G(y)) DG(y) = I_m \text{ by chain rule}$$

$$\text{By taking } y = F(x) \Rightarrow DF(x) DG(F(x)) = I_m \quad \textcircled{1}$$

Claim: if matrix $AB = I_m$ and $BA = I_n$ then we must have $m = n$ and $A = B^{-1}$.

If of claim $AB = I_m \Rightarrow m = \text{rank}(AB) \leq \text{rank}(A) \leq \min\{m, n\}$

$BA = I_n \Rightarrow n = \text{rank}(BA) \leq \text{rank}(B) \leq \min\{m, n\}$

if $m \geq n \Rightarrow$ must have $m \leq n$; if $m \leq n \Rightarrow$ must have $m \geq n$

Therefore $m = n$

By claim, we have $m = n$ and $DG(x) = DG(F(x))^{-1}$

Since x is taken arbitrary, this proves that $\forall a \in A, b \in B$ s.t. $F(a) = b$ we have $DG(b) = DG(F(a))^{-1}$

Problem C: Give an example of a differentiable homeomorphism from \mathbb{R} to itself whose inverse is not differentiable at every point. (For your example, you need to find only a single point where the inverse isn't differentiable.)

$$\text{ex } f: \mathbb{R} \rightarrow \mathbb{R}$$

sending $x \mapsto x^3$ is a differentiable homeomorphism

since it is invertible and differentiable

on the whole domain



its inverse: $f^{-1}: x \mapsto \sqrt[3]{x}$ is not differentiable at $x=0$

$$\text{Since } \frac{d}{dx} f^{-1}(x) = \frac{1}{3\sqrt[3]{x^2}}$$

does not exist at $x=0$

Problem D: Suppose $F: \mathbb{R}^2 \rightarrow \mathbb{R}$ is continuous at the origin. Show

$$\lim_{h \rightarrow 0} \lim_{k \rightarrow 0} F(h, k) = \lim_{k \rightarrow 0} \lim_{h \rightarrow 0} F(h, k),$$

assuming all these limits exist. Give an example where F is not continuous, both double limits exist, but the two double limits are not equal.

Pf By continuity at the origin we have $\lim_{\sqrt{h^2 + k^2} \rightarrow 0} F(h, k) = F(0, 0)$

$$\Rightarrow \forall \varepsilon > 0, \exists \delta > 0 \text{ s.t. } \forall \sqrt{h^2 + k^2} < \delta, |F(h, k) - F(0, 0)| < \varepsilon$$

$$\text{let } \varphi_1(h) = \lim_{k \rightarrow 0} F(h, k), h \in \mathbb{R}$$

$$\text{Claim 1 } \varphi_1(0) = \lim_{h \rightarrow 0} F(h, 0) = F(0, 0)$$

let $\varepsilon > 0$. By continuity of F at origin,

$$\exists \delta > 0 \text{ s.t. } \forall \sqrt{h^2 + k^2} < \delta, |F(h, k) - F(0, 0)| < \varepsilon$$

take the same $\delta \Rightarrow |F(0, k) - F(0, 0)| < \varepsilon$ for all $k \in B_\delta(0)$

$$\text{Thus } \varphi_1(0) = F(0, 0)$$

$$\text{Claim 2} \quad \lim_{h \rightarrow 0} \varphi_1(h) = \varphi_1(0) = F(0,0)$$

(i.e. φ_1 is continuous at $h=0$)

let $\varepsilon > 0$. By continuity of F at origin,

$$\text{take } \delta > 0 \text{ s.t. } h, \sqrt{h^2 + k^2} < \delta, |F(h,k) - F(0,0)| < \varepsilon \quad \textcircled{1}$$

WTS: $\exists \delta_2 > 0$ s.t. $|\varphi_1(h) - \varphi_1(0)| < \varepsilon$ for all $|h| < \delta_2$

$$\text{consider } \delta_2 = \frac{\delta}{\sqrt{2}}, \text{ let } |h| < \delta_2$$

$$\Rightarrow |\varphi_1(h) - \varphi_1(0)| = \left| \lim_{k \rightarrow 0} F(h, k) - F(0,0) \right| < \varepsilon$$

since $\sqrt{|k|} < \delta_2$, we always have $\sqrt{h^2 + k^2} < \delta$

$$\text{thus } F(h,k) \in B_\varepsilon(F(0,0)) \Rightarrow \lim_{k \rightarrow 0} F(h,k) \in B_\varepsilon(F(0,0))$$

(since the limit exists, it is bounded by all values of $F(h,k)$ near $(0,0)$)

$$\Rightarrow \left| \lim_{k \rightarrow 0} F(h,k) - F(0,0) \right| < \varepsilon$$

that is, $|\varphi_1(h) - \varphi_1(0)| < \varepsilon$

This proves that $\lim_{h \rightarrow 0} \varphi_1(h) = \varphi_1(0)$

$$\text{i.e. } \lim_{h \rightarrow 0} \lim_{k \rightarrow 0} F(h,k) = F(0,0)$$

By taking $\varphi_2(k) = \lim_{h \rightarrow 0} F(h,k)$, $k \in \mathbb{R}$

we can dually prove that $\varphi_2(0) = F(0,0)$

$$\text{and } \lim_{k \rightarrow 0} \varphi_2(k) = \varphi_2(0)$$

$$\text{thus } \lim_{k \rightarrow 0} \lim_{h \rightarrow 0} F(h,k) = F(0,0)$$

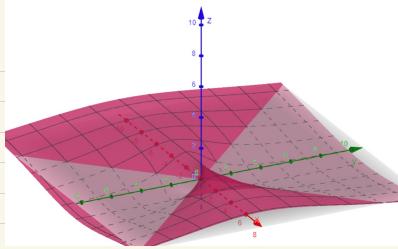
This finishes the proof that $\lim_{k \rightarrow 0} \lim_{h \rightarrow 0} F(h,k) = \lim_{h \rightarrow 0} \lim_{k \rightarrow 0} F(h,k)$ \square

counterexample when f is not continuous:

$$F(h,k) = \begin{cases} \frac{h^2+k^2}{h^2+k^2}, & (h,k) \neq (0,0) \\ 0, & (h,k) = (0,0) \end{cases}$$

$$\lim_{h \rightarrow 0} \lim_{k \rightarrow 0} F(h,k) = \frac{1}{1} = 1$$

$$\lim_{k \rightarrow 0} \lim_{h \rightarrow 0} F(h,k) = \frac{-1}{1} = -1$$



Just for fun (don't hand in): Give an example where $F : \mathbb{R}^2 \rightarrow \mathbb{R}$ is continuous at the origin but $\lim_{h \rightarrow 0} \lim_{k \rightarrow 0} F(h,k)$ does not exist.

Just for fun (don't hand in): Also note that for $a_{n,m} = 2^{n-m}$ it is not true that

$$\lim_{n \rightarrow \infty} \lim_{m \rightarrow \infty} a_{n,m} = \lim_{m \rightarrow \infty} \lim_{n \rightarrow \infty} a_{n,m}.$$

~~Problem E~~: If F is a function of 4 variables, how many terms (in general) are in the degree 10 Taylor series of F ? (Degree 10 means you use multi-indices α of degree at most 10.) You do not need to show your work; just give the final answer.

actually: $\#\{|\alpha|=k, \text{ and } \#d=\binom{k-1}{4-1}\}$, $\#d \leq \binom{k-1}{4-1}$

$$\begin{aligned} \alpha = (\alpha_1, \alpha_2, \alpha_3, \alpha_4) \\ |\alpha| \leq 10 \quad \binom{10+4}{4} = 286 \\ \#\{\alpha \mid |\alpha| \leq 10\} = \sum_{k=0}^{10} \binom{k+3}{3} = \binom{10+3}{3} = \binom{10+3+1}{3+1} = \binom{14}{4} = 1001 \end{aligned}$$

~~Problem F~~: Suppose that $F : A \subset \mathbb{R}^m \rightarrow \mathbb{R}^n$ is differentiable with A open and connected and $Df(a) = 0$ for all $a \in A$. Show that F is constant.

Claim 1 for all $a \in A$, F is locally constant on A

($\exists \varepsilon > 0$ s.t. $f|_{B_\varepsilon(a)}$ is const.)

Pf of claim 1

$$\begin{aligned} \text{(let } a \in A. \text{ Take } \varepsilon > 0 \text{ s.t. } B_\varepsilon(a) \subseteq A \text{ (by openness)}} \\ \text{let } x = \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix}, y = \begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{pmatrix} \in B_\varepsilon(a). \end{aligned}$$

$$\text{let } S_0 = x, \varphi_0 : t \mapsto F(S_0 + te), t \in [0, y_1 - x_1]$$

$$S_1 = x + (y_1 - x_1), \varphi_1 : t \mapsto F(S_1 + te_2), t \in [0, y_2 - x_2]$$

:

$$S_n = x + (y_1 - x_1) + (y_2 - x_2) + \dots + (y_n - x_n) = y$$

Since for all points $C \in A$, all entries of $Df(t)$ are 0, every partial is constant 0 (thus continuous) on A

Note: for each y_i , $0 \leq i \leq n-1$, we have $y'_i(t) = \frac{\partial F}{\partial x_i}(S_i + te_{i+1}) = 0$ for all $t \in [0, y_{i+1} - x_{i+1}]$

$$\Rightarrow \forall i=1, \dots, n-1, F(S_i) - F(S_{i+1}) = (y_i - x_i) \varphi'_i(t) = 0 \text{ by MVT}$$

$$\text{Thus } F(y) - F(x) = \sum_{i=1}^n (F(S_i) - F(S_{i+1})) = 0$$

$$\Rightarrow F(y) = F(x)$$

Since x, y are arbitrary, we have proved that $\forall x, y \in B_\varepsilon(a), F(x) = F(y)$

Therefore F is locally constant around a .

Claim 2 $S = \{x : F(x) = F(a)\}$ is both closed and open in A

Pf of Claim 2

S is open since ($\forall a \in S, \exists \varepsilon > 0$ s.t. $B_\varepsilon(a) \subseteq S$), proved in claim 1

Let (a_n) be a sequence in S s.t. $(a_n) \rightarrow x$ for some $x \in A$

Since F is diffible thus ctn, $F(x) = \lim_{n \rightarrow \infty} F(a_n) = F(a) \Rightarrow x \in S$

Thus S is closed

The fact that A is connected implies that the only set both open and closed in A is A itself.

$\Rightarrow S = A$.

$\Rightarrow \forall x \in A, F(x) = F(a)$, which shows that F is constant. \square

Problem G: Let $f_1, f_2, \dots, f_m : \mathbb{R} \rightarrow \mathbb{R}$ be C^k . Show that

$$\partial^k(f_1 \cdots f_m) = \sum_{|\alpha|=k} \frac{k!}{\alpha!} \partial^{\alpha_1} f_1 \cdots \partial^{\alpha_m} f_m.$$

Pf We prove by induction on $k \in \mathbb{N}$

$$\begin{aligned} \text{Base case: } k=1, \partial(f_1 \cdots f_m) &= \partial(f_1 \cdot (f_2 \cdots f_m)) \\ &= (f_2 \cdots f_m) \partial f_1 + f_1 \partial(f_2 \cdots f_m) \text{ by product rule} \\ &= (f_2 \cdots f_m) \partial f_1 + (f_1 f_2 \cdots f_m) \partial f_2 + f_1 f_2 \cdots \partial(f_3 \cdots f_m) \\ &= \left(\sum_{i=1}^k \partial f_i \prod_{j \neq i} f_j \right) + \left(\prod_{i=1}^{k-1} f_i \right) \left(\partial \prod_{i=k+1}^m f_i \right) \\ &= \sum_{i=1}^m \left(\partial f_i \prod_{j \neq i} f_j \right) \\ &= \sum_{|\alpha|=1} \frac{1}{\alpha!} \partial^{\alpha_1} f_1 \cdots \partial^{\alpha_m} f_m, \text{ statement holds true} \end{aligned}$$

Inductive step: Suppose the equality holds for $1, 2, \dots, k$

$$\text{Then } \partial^{k+1}(f_1 f_2 \cdots f_m) = \partial(\partial^k(f_1 f_2 \cdots f_m))$$

$$= \partial \left(\sum_{|\alpha|=k} \frac{k!}{\alpha!} \partial^{\alpha_1} f_1 \cdots \partial^{\alpha_m} f_m \right)$$

$$= \sum_{|\beta|=k} \frac{k!}{\beta!} \partial \left(\partial^{\beta_1} f_1 \cdots \partial^{\beta_m} f_m \right) = \sum_{|\beta|=k} \frac{k!}{\beta!} \partial^{\beta_1} f_1 \cdots \partial^{\beta_m} f_m$$

$$= \sum_{|\alpha|=k} \sum_{|\beta|=1} \frac{k!}{\alpha! \beta!} \left(\partial^{\beta_1} f_1 \cdots \partial^{\beta_m} f_m \right) = \sum_{|\beta|=1} \partial^{\beta_1} f_1 \cdots \partial^{\beta_m} f_m \quad \text{by base case}$$

$$= \sum_{|\alpha|=k} \frac{k!}{\alpha!} \left(\sum_{i=1}^m \partial^{\alpha_1} f_1 \cdots \partial^{\alpha_{i-1}} f_{i-1} \cdots \partial^{\alpha_m} f_m \right)$$

every term corresponds to a multi-index β s.t.
for some $j \in \{1, \dots, m\}$, $\beta_i = \alpha_i + 1$ while for $i \neq j$, $\beta_i = \alpha_i$
So each β has $|\beta| = k+1$

$$\text{Thus } \partial^{k+1}(f_1 \cdots f_m) = \sum_{|\beta|=k+1} (\text{coeff}) \partial^{\beta_1} f_1 \cdots \partial^{\beta_m} f_m$$

$$\begin{aligned} \text{The coeff} &= \sum_i \text{coeff of } \left(\partial^{\beta_1} f_1 \cdots \partial^{\beta_{i-1}} f_{i-1} \cdots \partial^{\beta_m} f_m \right) \\ &= \sum_{i=1}^m \frac{k!}{\beta_i!} \\ &= \sum_{i=1}^m \frac{k! \beta_i}{\beta_i!} = \frac{k!(k+1)}{\beta!} = \frac{(k+1)!}{\beta!} \end{aligned}$$

Therefore the expression simplifies to:

$$\partial^{k+1} \left(\prod_{i=1}^m f_i \right) = \sum_{|\beta|=k+1} \frac{(k+1)!}{\beta!} \prod_{i=1}^m \partial^{\beta_i} f_i$$

This finishes the proof by induction. \square

3/S

Problem H: Let $f : \mathbb{R}^n \rightarrow \mathbb{R}$ be in C^{k+1} . Show that the Taylor polynomial of degree k centered at $x_0 \in \mathbb{R}^n$ is the best polynomial approximation of $f(x)$ near x_0 in the following sense: Suppose that $P(x)$ is a polynomial of degree k . Then

$$P(x) - f(x) = o(|x - x_0|^k)$$

if and only if P is the Taylor polynomial of degree k centered at x_0 . (Recall that a quantity Q is $o(|x - x_0|^k)$ if $\lim_{x \rightarrow x_0} \frac{Q}{|x - x_0|^k} = 0$.)

Pf Backward direction

Let $f : \mathbb{R}^n \rightarrow \mathbb{R}$ be in C^{k+1}

Let $T_k : \mathbb{R}^n \rightarrow \mathbb{R}$ be the Taylor polynomial of degree k centered at x_0

$$\text{i.e. } T_k(x) = \sum_{|\alpha| \leq k} \frac{\partial^\alpha f(x_0)}{\alpha!} (x - x_0)^\alpha, x \in \mathbb{R}^n$$

Then by Taylor's Theorem we have

$$T_k(x) - f(x) = R_{x_0, k}(x) = \sum_{|\alpha|=k+1} \frac{\partial^\alpha f}{\alpha!} (c)(x - x_0)^\alpha$$

for some c on the line segment connecting x, x_0 .

note that $(\alpha!)(\alpha!)$ is finite, $\frac{\partial^\alpha f}{\alpha!}(c)$ is constant for all α

It suffices to show that $R(x) - f(x)$ is $O(|x - x_0|^{k+1})$ by

showing that for any α s.t. $|\alpha|=k+1$,

$$\lim_{x \rightarrow x_0} \frac{(x - x_0)^\alpha}{||x - x_0||^{k+1}} = 0, \text{ i.e. } \lim_{x \rightarrow x_0} \frac{x^\alpha}{||x||^{k+1}} = 0$$

note: $\forall x \in \mathbb{R}^n, x^\alpha = x_1^{\alpha_1} x_2^{\alpha_2} \cdots x_n^{\alpha_n} = |x_1|^{\alpha_1} \cdots |x_n|^{\alpha_n} \leq ||x||^{\alpha_1 + \cdots + \alpha_n} = ||x||^{k+1}$

$$\text{So } \lim_{x \rightarrow x_0} \frac{x^\alpha}{||x||^{k+1}} \leq \lim_{x \rightarrow x_0} ||x|| = 0 \quad \square$$

Forward Direction

let $P(x)$ be a polynomial of degree k that is not T_k

$$f(x) - P(x) = C_1 x^{\alpha_1} + \cdots + C_m x^{\alpha_m} \text{ for some}$$

constants C_1, \dots, C_m and multi-index $\alpha_1, \dots, \alpha_m$ s.t. $|\alpha_i| \leq k$ for each i

$$\text{WTS: } \lim_{x \rightarrow 0} \frac{C_1 x^{\alpha_1} + \cdots + C_m x^{\alpha_m}}{||x||^k} \neq 0$$

$$\text{Case 1: } \sum_{i=1}^m C_i \neq 0$$

Consider the sequence $(t_n = \frac{x}{n})$ now in \mathbb{R}^d

for each t_n , let $x_n = (t_n, t_n, \dots, t_n)$

Then $(x_n) \rightarrow 0$ in \mathbb{R}^d

$$\text{Hence } \sum_{i=1}^m C_i x^{\alpha_i} = \sum_{i=1}^m C_i t_n^{\alpha_i} = t_n^k \sum_{i=1}^m C_i$$

$$\Rightarrow \frac{C_1 x^{\alpha_1} + \cdots + C_m x^{\alpha_m}}{||x||^k} = \frac{\sum_{i=1}^m C_i t_n^{\alpha_i}}{t_n^k} = \frac{\sum_{i=1}^m C_i}{t_n^k} \text{ is constant while } x \rightarrow 0$$

This suffices to show that $\lim_{x \rightarrow 0} \frac{C_1 x^{\alpha_1} + \cdots + C_m x^{\alpha_m}}{||x||^k} \neq 0$

$$\text{Case 2: } \sum_{i=1}^m C_i = 0$$

idk α

Try another way to prove the forward direction:

Claim a polynomial homogeneous of degree k in \mathbb{R}^d is not $O(|x|^k)$

(by homogeneous of degree k we mean:
 $\forall c \in \mathbb{R}, x \in \mathbb{R}^d, P(cx) = c^k P(x)$)

let $P(x)$ be a polynomial homogeneous of degree k in \mathbb{R}^d

let $t_n = \frac{1}{n}$ be a sequence in \mathbb{R}^d

so $((t_n x_0, \dots, t_n x_0))_{n \in \mathbb{N}} \rightarrow 0$ in \mathbb{R}^d

Denote each term of this seq as x_n

$$\Rightarrow \frac{P(x_n)}{|x_n|^k} = \frac{c^k P(x_0)}{t_n^k |x_0|^k} = \frac{P(x_0)}{|x_0|^k} \text{ is const.}$$

This implies that $\lim_{n \rightarrow \infty} \frac{P(x_n)}{|x_n|^k} \neq 0$

Note that a polynomial of degree k is a homogeneous of degree k .

Problem I: Let $f : \mathbb{R} \rightarrow \mathbb{R}$ be a differentiable function, and define $F : \mathbb{R}^2 \rightarrow \mathbb{R}$ by $F(x, y) = f(x^2 + y^2)$, so F is differentiable.

$$(1) \text{ Prove } 4.75/5 \quad (\text{minor mistake}) \quad x \frac{\partial F}{\partial y} = y \frac{\partial F}{\partial x}.$$

(2) Suppose $f : \mathbb{R}^3 \rightarrow \mathbb{R}$, $g : \mathbb{R}^2 \rightarrow \mathbb{R}$, $h : \mathbb{R} \rightarrow \mathbb{R}$ are differentiable. Define $\phi : \mathbb{R}^3 \rightarrow \mathbb{R}^2$ via

$$\phi(x, y, z) = (f(h(x), g(x, y), z), g(y, z)).$$

Find a formula for the matrix of the derivative $D\phi(p) : \mathbb{R}^3 \rightarrow \mathbb{R}^2$ at an arbitrary point $p \in \mathbb{R}^3$ in terms of the partial derivatives of f , g , and h at p .

(3) In (ii), compute $D\phi(1, 1, 1)$ when $f(x, y, z) = x^2 + yz$, $g(x, y) = y^3 + xy$, and $h(x) = e^x$. Do this in two ways: using your general formula in (ii) and also by explicitly computing ϕ in this case and directly computing the Jacobian matrix from this.

(1) Pf Let $(x, y) \in \mathbb{R}^2$

$$\frac{\partial F}{\partial x} = 2x Df(x^2 + y^2) \text{ by chain rule}$$

$$\frac{\partial F}{\partial y} = 2y Df(x^2 + y^2) \text{ by chain rule}$$

$$\Rightarrow y \frac{\partial F}{\partial x} = x \frac{\partial F}{\partial y} = 2xy Df(x^2 + y^2)$$

(2) $\psi : \mathbb{R}^3 \rightarrow \mathbb{R}^2$

$$\begin{aligned} \text{let } \varphi_m : \mathbb{R}^3 \rightarrow \mathbb{R}^4 &\text{ map } \begin{pmatrix} x \\ y \\ z \end{pmatrix} \mapsto \begin{pmatrix} h(x) \\ g(x, y) \\ g(y, z) \end{pmatrix} & \mathbb{R}^3 &\xrightarrow{\psi} \mathbb{R}^2 \\ \varphi_n : \mathbb{R}^4 \rightarrow \mathbb{R}^2 &\text{ map } \begin{pmatrix} a \\ b \\ c \\ d \end{pmatrix} \mapsto \begin{pmatrix} f(a, b, c) \\ d \end{pmatrix} & \varphi_m \downarrow & \varphi_n \uparrow \end{aligned}$$

Then $\psi = \varphi_n \circ \varphi_m$

$$\varphi : p = \begin{pmatrix} x \\ y \\ z \end{pmatrix} \xrightarrow{\varphi_m} \begin{pmatrix} a = h(x) \\ b = g(x, y) \\ c = z \\ d = g(y, z) \end{pmatrix} \xrightarrow{\varphi_n} \begin{pmatrix} f(a, b, c) \\ d \end{pmatrix}$$

$$\Rightarrow D\psi(p) = D\varphi_m(\varphi_m(p)) D\varphi_n(\varphi_m(p)) \text{ by chain rule.}$$

$$= \begin{pmatrix} \frac{\partial f(h(p))}{\partial x_1} & \frac{\partial f(h(p))}{\partial x_2} & \frac{\partial f(h(p))}{\partial x_3} & 0 \\ 0 & \frac{\partial g(p_1, p_2, p_3)}{\partial x_1} & \frac{\partial g(p_1, p_2, p_3)}{\partial x_2} & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & \frac{\partial g(p_2, p_3)}{\partial x_1} & \frac{\partial g(p_2, p_3)}{\partial x_2} \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} h'(p) & 0 & 0 \\ \frac{\partial g(p_1, p_2, p_3)}{\partial x_1} & \frac{\partial g(p_1, p_2, p_3)}{\partial x_2} & 0 \\ 0 & 0 & 1 \\ 0 & \frac{\partial g(p_2, p_3)}{\partial x_1} & \frac{\partial g(p_2, p_3)}{\partial x_2} \end{pmatrix}$$

$$(3) p = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}, f(x, y, z) = x^2 + yz, g(x, y) = y^3 + xy, h(x) = e^x \\ h'(p) = e, g(p_1, p_2) = 2, \frac{\partial f}{\partial x_1}(x, y, z) = 2x, \frac{\partial f}{\partial x_2}(x, y, z) = 0, \frac{\partial f}{\partial x_3}(x, y, z) = y \\ h'(x) = e^x, \frac{\partial g}{\partial x_1}(x, y) = y, \frac{\partial g}{\partial x_2}(x, y) = 3y^2$$

By the formula in (2),

$$D\psi(1, 1, 1) = \begin{pmatrix} e & 0 & 0 \\ 2e & 1 & 2 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} e & 0 & 0 \\ 1 & 4 & 0 \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} e^2 & 4 & 2 \\ 0 & 1 & 4 \end{pmatrix}$$

Compute directly:

$$\psi(x, y, z) = \begin{pmatrix} e^{x^2} + 2(y^3 + xy) \\ x^3 + yz \end{pmatrix}$$

$$D\psi(1, 1, 1) = \begin{pmatrix} 2x^2 e^{x^2+1/2} & 3y+1/1 & 1^2+1/1 \\ 0 & 1 & 3y+1 \end{pmatrix} = \begin{pmatrix} e^2 & 4 & 2 \\ 0 & 1 & 4 \end{pmatrix}$$

same result. \square

Problem J: Problem 2(a) on page 63 of the text.

$$\begin{aligned} \text{Problem} \quad f : \mathbb{R}^2 \rightarrow \mathbb{R}^3 &\quad g : \mathbb{R}^3 \rightarrow \mathbb{R}^2 \\ \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \mapsto \begin{pmatrix} e^{2x_1+x_2} \\ 3x_2 - \cos x_1 \\ x_1^2 + x_2 + 2 \end{pmatrix} &\quad \begin{pmatrix} y_1 \\ y_2 \\ y_3 \end{pmatrix} \mapsto \begin{pmatrix} 3x_1 + 2y_2 + y_3^2 \\ y_1^2 - y_3 + 1 \end{pmatrix} \\ F(x) = g \circ f(x). \text{ Find } DF(0) \end{aligned}$$

Sol $DF(0) = Dg(f(0)) Df(0)$ by chain rule

$$Df = \begin{pmatrix} 2e^{2x_1+x_2} & e^{2x_1+x_2} \\ \sin x_1 & 3 \\ 2x_1 & 1 \end{pmatrix} \quad Dg = \begin{pmatrix} 3 & 2 & 2y_3 \\ 2y_1 & 0 & -1 \end{pmatrix}$$

$$f(0) = \begin{pmatrix} e^0 = 1 \\ 0 - \cos 0 = -1 \\ 2 \end{pmatrix}$$

$$\Rightarrow DF(0) = \begin{pmatrix} 3 & 2 & 4 \\ 2 & 0 & -1 \end{pmatrix} \begin{pmatrix} 2 & 1 \\ 0 & 3 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} 6 & 13 \\ 4 & 1 \end{pmatrix}$$

Problem K: Find the 3rd order Taylor series of $F(x, y) = e^{x+y^2}$ about the origin $(F(x, y) = e^{x+y^2} \text{ is in } C^\infty \text{ so we can do this})$

$$T_3(x, y) = \sum_{|\alpha| \leq 3} \frac{\partial^\alpha f(0)}{\partial x^\alpha} (x, y)^\alpha \quad \frac{\partial}{\partial y} f \Big|_{(0,0)}^{x+y^2}$$

possible α : $|\alpha|=0 : (0, 0) \Rightarrow f(0, 0) = e^0 = 1$

$$|\alpha|=1 : (0, 1), (1, 0) \Rightarrow \partial^{(0,1)} f(0, 0) = 2ye^{x+y^2} \Big|_{(0,0)} = 0$$

$$\partial^{(1,0)} f(0, 0) = e^{x+y^2} \Big|_{(0,0)} = 1$$

$$|\alpha|=2 : (0, 2), (2, 0), (1, 1)$$

$$\Rightarrow \partial^{(0,2)} f(0, 0) = 2e^{x+y^2} + 4y^2 e^{x+y^2} \Big|_{(0,0)} = 2$$

$$\partial^{(2,0)} f(0, 0) = e^{x+y^2} \Big|_{(0,0)} = 1$$

$$\partial^{(1,1)} f(0, 0) = 2ye^{x+y^2} \Big|_{(0,0)} = 0$$

$$|\alpha|=3 : (1, 2), (2, 1), (3, 0), (0, 3)$$

$$\Rightarrow \partial^{(1,2)} f(0, 0) = 2e^{x+y^2} + 4y^2 e^{x+y^2} \Big|_{(0,0)} = 2$$

$$\partial^{(2,1)} f(0, 0) = 2ye^{x+y^2} \Big|_{(0,0)} = 0$$

$$\partial^{(3,0)} f(0, 0) = e^{x+y^2} \Big|_{(0,0)} = 1$$

$$\partial^{(0,3)} f(0, 0) = 4ye^{x+y^2} + 8ye^{x+y^2} + 8y^2 e^{x+y^2} \Big|_{(0,0)} = 0$$

$$\text{Thus } T_3(x, y) = 1 + x + \frac{1}{2}x^2 + y^2 + xy^2 + \frac{x^3}{6}$$

6.5/8

Bonus: A real symmetric $n \times n$ matrix A is called positive definite if $x^T Ax > 0$ for all $x \in \mathbb{R}^n$.

- (1) Show that a real symmetric matrix is positive definite if and only if it is invertible and, for all non-zero x , the angle between Ax and x is less than 90 degrees.
- (2) Show that a real symmetric matrix is positive definite if and only if all its eigenvalues are positive.
- (3) Let A_d be the top left d by d minor of A . Show that if A is positive definite, so is each A_d , $1 \leq d \leq n$.
- (4) Prove that A is positive definite if and only if $\det(A_d) > 0$ for all $1 \leq d \leq n$.

You may use without proof that a real symmetric matrix has an orthonormal basis of eigenvectors. A hint for the last part is available on the office door, but as always try it without first!

(1) Let $A \in \mathbb{R}^{n \times n}$ be positive definite

Suppose A is not invertible $\Rightarrow \exists x \in \mathbb{R}^n$ s.t. $Ax = 0$

Thus A is invertible. $\Rightarrow x^T Ax = 0$, contradicts

let $x \in \mathbb{R}^n$, θ be the angle between Ax and x

$$\Rightarrow \cos \theta = \frac{x^T Ax}{\|x\| \|Ax\|} = \frac{\|Ax\|^2}{\|x\| \|Ax\|} > 0 \Rightarrow \theta \in (0, \frac{\pi}{2})$$

Then we prove the backward direction.

let A be invertible with $\forall x \in \mathbb{R}^n$,

angle between Ax and x $\theta \in (0, \frac{\pi}{2})$

let $x \in \mathbb{R}^n$, we have $\frac{x^T Ax}{\|x\| \|Ax\|} = \frac{\|Ax\|^2}{\|x\| \|Ax\|} > 0 \Rightarrow x^T Ax > 0$

This proves the iff statement

(2) Suppose $A \in \mathbb{R}^{n \times n}$ is positive definite

let λ be an eigenvalue of A .

$$\Rightarrow \text{for some } x \in \mathbb{R}^n, Ax = \lambda x \Rightarrow x^T Ax = x^T \lambda x = \lambda \|x\|^2 > 0 \Rightarrow \lambda > 0$$

This proves the forward direction.

For the backward direction:

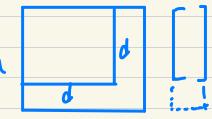
Suppose all eigenvalues of A are positive.

Since A is real symmetric it has an orthonormal eigenvectors $\{b_1, \dots, b_n\}$

So for any $x \in \mathbb{R}^n$, $x = \sum_{i=1}^n c_i b_i$ for some $c_1, \dots, c_n \in \mathbb{R}$

$$\Rightarrow x^T Ax = \sum_{i=1}^n \lambda_i c_i^2 > 0 \text{ since each } \lambda_i > 0$$

This proves the proof. \square



(3) Suppose $A \in \mathbb{R}^{n \times n}$ is positive definite.

let $1 \leq d \leq n$, $\pi \in \mathbb{R}^d$.

$$\text{Take } \tilde{x} = (\underbrace{x, 0, 0, \dots, 0}) \in \mathbb{R}^n$$

By A being positive definite, we have $\tilde{x}^T A \tilde{x} > 0$

$$\text{Note that } \tilde{x}^T A \tilde{x} = \begin{bmatrix} \tilde{x}_1 \\ \vdots \\ \tilde{x}_d \\ 0 \\ \vdots \\ 0 \end{bmatrix} \cdot \begin{bmatrix} \text{row}(A)_1 \cdot \tilde{x} \\ \vdots \\ \text{row}(A)_d \cdot \tilde{x} \\ \vdots \\ 0 \end{bmatrix} = \sum_{i=1}^d \tilde{x}_i (\text{row}(A)_i \cdot \tilde{x}) = \sum_{i=1}^d \pi_i (\text{row}(A)_i \cdot \pi) = \pi^T A \pi > 0$$

Therefore A_d is positive definite, $1 \leq d \leq n$. \square

(4) pf

Forward direction:

Suppose A is positive definite $\Rightarrow \forall 1 \leq d \leq n$, A_d is positive definite.

By (2), each A_d has its all eigenvalues positive

$$\text{So } \det(A_d) = \prod \lambda_i > 0.$$

Backward direction:

.... (dirty work at all)

$$a_{ij} = \text{row}_i \cdot \text{row}_j^\top$$

$$\sum_{j=1}^n b_{ij} b_j$$

$$\begin{array}{c} \sqrt{a_{11}} \\ \text{---} \\ r_1 \cdot r_1 \\ r_1 \cdot r_2 \\ r_2 \cdot r_2 \\ \text{---} \\ r_1 \end{array}$$

$$a_{ij} = \sum_{x=1}^n b_{ix} b_{xj}$$

$$a_{11} = b_{11}^2$$

$$\left(\begin{array}{c} b_{11} \\ b_{12} \end{array} \right)^2$$

$$a_{21} = b_{11} b_{12} + b_{22} b_{11}$$

$$(b_{11} + b_{22}) b_{11}$$

$$a_{31} = b_{11} b_{13} + b_{31}$$