

## Implicit Function Thm

Let  $f: A \subseteq \mathbb{R}^{k+n} \rightarrow \mathbb{R}^n$ ,  $A$  open,  $b \in \mathbb{R}^n$  ( $r \geq 1$ )  
 $(x,y) \mapsto z$   
 $\mathbb{R}^k \times \mathbb{R}^n \rightarrow \mathbb{R}^n$

Suppose  $a \in \mathbb{R}^k$ ,  $b \in \mathbb{R}^n$ ,  $(a,b) \in A$  and  $f(a,b) = 0 \in \mathbb{R}^n$

If  $\frac{\partial f}{\partial y}(a,b)$  is non singular  $Df = \begin{bmatrix} \frac{\partial f}{\partial x_1} & \dots & \frac{\partial f}{\partial x_k} & \frac{\partial f}{\partial y_1} & \dots & \frac{\partial f}{\partial y_n} \end{bmatrix}$

$\Rightarrow \exists$  nbh  $B_\epsilon(a) \subseteq \mathbb{R}^k$   
 and unique cn function  $g: B_\epsilon(a) \rightarrow \mathbb{R}^n$

s.t.  $g(a) = b$  and  $\forall x \in B_\epsilon(a)$ , we have  $f(x, g(x)) = 0$

( $\exists$  by implicit differentiation:

$$\forall x \in B_\epsilon(a), \frac{\partial f}{\partial x}(x, g(x)) + \frac{\partial f}{\partial y}(x, g(x)) \cdot Dg(x) = 0$$

$$Dg(x) = - \left[ \frac{\partial f}{\partial y}(x, g(x)) \right]^{-1} \frac{\partial f}{\partial x}(x, g(x))$$

Implicit Function Thm告诉我们:

$\mathbb{R}$  里  $f(z) = 0$  且  $\frac{\partial f}{\partial y}(z)$  non singular

那么 locally - 一定存在某个 implicit function  $g$

使得  $g$  可以定义  $f$  在  $z$  局部的 level set  $\{f=0\}$

$$\text{by } \{f|_{B_\epsilon(z)} = 0\} = \{(x, g(x)) \mid x \in U\}$$

IFT 和 Implicit FT 都告诉我们  $C^r$  function 的“局部变化一致”的性质  
 IFT 告诉我们要点的导数 nonsingular 可得到局部的 invertibility,  
 从而得到局部  $C^r$  diffeo

Implicit FT 告诉我们点属于 level set (kernel)

可得到它周围的一圈由某个 implicit function (一定存在)  
 定义的 surrounding manifold 都在  $f$  的 kernel 里

## Pf of Implicit Function Thm

① Define an auxiliary function

$$F: A \subseteq \mathbb{R}^{k+n} \rightarrow \mathbb{R}^{k+n}$$

$$\begin{pmatrix} x \\ y \end{pmatrix} \mapsto \begin{pmatrix} x \\ f(x,y) \end{pmatrix}$$

$$DF(x,y) = \begin{pmatrix} DF_1 \\ \vdots \\ DF_{k+n} \end{pmatrix} = \begin{pmatrix} I_k \\ DF \end{pmatrix}$$

$$= \begin{pmatrix} I_k & 0 \\ \frac{\partial f}{\partial x} & \frac{\partial f}{\partial y} \end{pmatrix}$$

$$\Rightarrow \det DF(x,y) = (\det I_k) \left( \det \frac{\partial f}{\partial y} \right) = \det \frac{\partial f}{\partial y} \quad \star$$

by block matrices

$$\text{So } \det DF(a,b) \neq 0$$

$\Rightarrow$  By IFT,  $\exists U \times V \ni (a,b)$

s.t.  $U$  is open in  $\mathbb{R}^k$ ,  
 $V$  is open in  $\mathbb{R}^n$

s.t.  $F|_{U \times V}$  is a local  $C^r$  diffeo

$U \times V \rightarrow W$  for some  $W \subseteq \mathbb{R}^{k+n}$

Let  $G: W \rightarrow U \times V$  be the inverse of  $F|_{U \times V}$

$$\Rightarrow \forall (x,y) \in U \times V, (x,y) = G(x, f(x,y))$$

So let  $(x,z) \in W$ ,

$$(x,z) = F \circ G(x,z)$$

$\downarrow$   
 $= (x,y)$

因而  $G = \begin{pmatrix} G_1 \\ \vdots \\ G_k \\ G_{k+n} \end{pmatrix}$  中,  $G_1, \dots, G_k$  都是 identity function

(因为  $F$  的前  $k$  个是 identity,  $F \circ G$  的前  $k$  个也是 identity, 因而  $G$  的前  $k$  个必须也是 identity)

Let  $h: W \rightarrow V$  表示  $G$  的后  $n$  个 coordinate functions  
 $(x,z) \mapsto y$  (s.t.  $f(x,y) = z$ )

$$\text{or } h = \begin{pmatrix} G_{k+1} \\ \vdots \\ G_{k+n} \end{pmatrix}$$

Since  $G$  is  $C^r$  (by IFT),  $h$  is  $C^r$  too.

Step 2 Construct the implicit function  $g$ .

Let  $B \ni a$  s.t.  $B \times \{0\} \subseteq W$

$$\Rightarrow \forall (x,y) \in B \times V$$

$$f(x,y) = 0 \text{ iff } F(x,y) = (x,0)$$

$$\text{iff } (x,y) = G(x,0) = (x, h(x,0))$$

$$\text{Let } g: \mathbb{R}^k \rightarrow \mathbb{R}^n$$

$$x \mapsto \underline{h(x,0)} = G(x,0) = (x,y)$$

Then we have  $f(x,y) = 0$  iff  $y = g(x)$   
 for  $x \in B$

Clearly  $g$  is  $C^r$  since  $h$  is  $C^r$   
 (Existence  $\square$ )

(And clearly:  $(a,b) = G(a,0) = (a, h(a,0))$   
 $b = h(a,0) = g(a)$  as desired)

### Step 3 Prove Uniqueness of $g$ .

Suppose  $g': B \rightarrow V$  is another ctn. function  
 satisfying the implicit condition

$$\text{Let } S = \{x \in B \mid g(x) = g'(x)\}$$

$$\text{WTS: } S = B \text{ (which implies } g = g')$$

It suffices to show that  $S$  is nonempty,  
 both open and closed

(Since  $B$  is connected and  $B \subseteq \mathbb{R}^k$ ,  
 $S$  open and closed in  $B \Rightarrow S = B$ )

nonempty: Consider  $g'(a) = g(a) \Rightarrow S$  nonempty  $\checkmark$  ①

closed: Since  $g, g'$  both ctn and  $S = (g - g')^{-1}(\{0\})$   
 $\Rightarrow S$  is closed  $\uparrow$  ctn  $\uparrow$  closed ②

open: Let  $x_0 \in S \Rightarrow g'(x_0) = g(x_0) \in V$  is open  
 $\Rightarrow \exists$  nbh  $B'_\epsilon(x_0)$  s.t.  $g'(B'_\epsilon(x_0)) \subseteq V$

$$\text{So } f(x, g'(x)) = 0 \quad \forall x \in B' \subseteq B$$

$$F(x, g'(x)) = (x, 0) \Rightarrow \underline{g'(x)} = \underline{g(x_0)} \\ = (x, h(x, 0)) = (x, g(x_0))$$

$$\text{So } \forall x \in B'_\epsilon(x_0), \text{ we have } g'(x) = g(x) \\ \Rightarrow x \in S$$

This proves that  $S$  is open

$$\text{By ①②③} \Rightarrow S = B \Rightarrow g' = g$$

(Uniqueness  $\square$ )  
 $\square$

### Application of Implicit Function Thm

Suppose  $f: A \subseteq \mathbb{R}^5 \rightarrow \mathbb{R}^2$  is  $C^r$

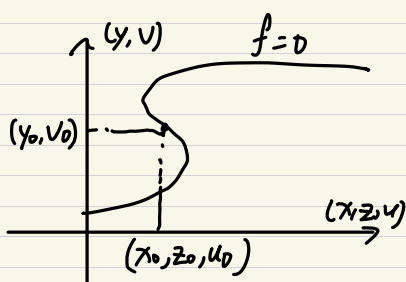
we can solve for  $(y, z)$  in terms of  $(x, u)$

for  $f=0$ , near a pt.  $(x_0, y_0, z_0, u_0, v_0)$

if  $f(x_0, y_0, z_0, u_0, v_0) = 0$  and  $Df(x_0, y_0, z_0, u_0, v_0) \neq 0$

write  $y = \phi(x, z, u)$ ,  $v = \psi(x, z, u)$

$$\text{We have } \frac{\partial(\phi, \psi)}{\partial(x, z, u)}(x_0, z_0, u_0) = - \left[ \frac{\partial f}{\partial(y, v)}(x_0, \dots, v_0) \right]^{-1} \frac{\partial f}{\partial x}(x_0, g(x_0))$$



$$\text{ex } f: \mathbb{R}^3 \rightarrow \mathbb{R}^2$$

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} \mapsto \begin{pmatrix} x^3 - y^3 + z^3 \\ z \cos(\pi x) + \sin(\pi y) \end{pmatrix}$$

note that  $f(1, 1, 0) = 0$

$$Df = \begin{pmatrix} 3x^2 & -3y^2 & 2z \\ -\pi z \sin \pi x & \pi \cos \pi y & \cos \pi x \end{pmatrix}$$

$$Df(1, 1, 0) = \begin{pmatrix} 3 & -3 & 0 \\ 0 & \pi & -1 \end{pmatrix}$$

$$\frac{\partial f}{\partial(x, z)} = \begin{pmatrix} 3 & 0 \\ 0 & -1 \end{pmatrix}, \text{ non-singular.}$$

Therefore, can solve for  $(x, z)$  in term of  $y$   
near  $y=1$

$$\exists \phi, \psi: B \subseteq \mathbb{R} \rightarrow \mathbb{R}^2$$

$$\text{s.t. } f(\phi(y), y, \psi(y)) = 0 \quad \forall y \in B$$

The sol set is a one-parameter family of sols.  
 (a manifold of dimension one)