Saeed Bazargan

Updated October 2, 2023

July 12, 1994

🖂 SaeedBazargan@hotmail.com | 🎢 SaeedBazargan.github.io | 🖸 SaeedBazargan | in saeed-bazargan-sbzrgn | Bazargan0241@qiau.ac.ir

Research Experience _____

Iran Electricity Meter Manufacturing Company (SKI)

Qazvin, Iran

RESEARCH DEVELOPMENT ELECTRONIC ENGINEER

August 2023 - Present

 FreeLancer
 Qazvin, Iran

 IoT Researcher
 July 2022 - June 2023

• Designed and implemented a **GSM** circuit to control smart home relays using **Sim800**.

- Drive a DC motor made by a Turkish company called Kormas using a high-power relay.
- Recognize the floor of a roller where a product is located using a button method and **Ethernet** transmission.
- Design an Ethernet to RS-485 protocol converter, which was done by Wiznet W5500.
- Designed a custom career board for the **STM32F103** Nucleo microcontroller.
- Programmed an AVR microcontroller using C language to develop a **GSM** circuit, utilizing **USART** for data communication and control of smart home relays.
- Developed a custom software application using C#.NET to enable an Xbox360 or PlayStation joystick to function as a computer mouse.
- Developed a custom software application using C#.NET and **OpenCV** to capture video streams from multiple cameras simultaneously. Utilized multi-threading techniques to efficiently manage data processing and ensure smooth video playback.

Mechatronic Research Laboratory (MRL) - Humanoid Soccer Robot Team

Qazvin, Iran

ELECTRONIC RESEARCHER

August 2016 - Present

- Design a modified version of the USB2Dynamixel (USB2DXL) board, which is the interface between the Dynamixel actuators and the controller. This board is designed to communicate with both **TTL and RS-485** Dynamixel series at the same time.
- Developed communication with Dynamixel actuators using the **UART** interface and queue algorithms in the humanoid robot's platform, effectively dividing communication into 5 independent lanes.
- Configured BNO055 and MPU9250 IMU sensors using FreeRTOS and the queue method to efficiently manage data processing. Utilized STM32F405 microcontroller and HAL to optimize the system's performance and reliability, and transfer via USB to UART converter.
- Managed the electronic section of a robotics team, overseeing tasks such as project planning, task management, and recruitment of new members. Conducted thorough testing and debugging to ensure the reliable operation of the electronic systems.

Zanjan Sama Robotic Group (ZSR)

Zanjan, Iran

ELECTRONIC RESEARCHER

November 2008 - February 2014

- Programming and designing the Mars-rover robot's mainboard using an Atmega128 microcontroller. Utilizing its high-power DC Motor, we
 were able to control them and perform tasks such as digging.
- Implemented object detection and manipulation in an Omni-Directional **Festo Mobile robot** using C#.NET programming language. I was responsible for recognizing shapes and placing objects in the correct location.
- Designing and programming rescue robot's board. It is similar to a follow-line robot, but there are obstacles in the path that the robot needs to overcome.

Research Interest

- Robotics
- FPGA
- Embedded Systems
- PCB Design
- Radio Frequency

Publication _

MRL Team Extended Abstract for Humanoid Kid Size League of RoboCup 2023

Bordeaux, France

THE 26TH INTERNATIONAL ROBOCUP SYMPOSIUM.

July 2023

 Hamed Mahmudi, Saeed Bazargan, Arash Rahmani, Abolfazl Ashayeri, Fatemeh Rashnozadeh, Alireza Golchin, Ramtin Kosari, Sina Khoshzaban Khosroshahi, Mehdi Zeinali and Maryam Shaban

MRL Champion Team Paper in Humanoid TeenSize League of RoboCup 2019

Sydney, Australia

Springer

July 2019

• Meisam Teimouri, Hamed Mahmudi, Amir Gholami, Mohammad Hossein Delavaran, Soheil Khatibi, **Saeid Bazargan**, Milad Moradi, Bita Alaee, Arash Rahmani, Kazem Firouzmandi Bandpey, Peyman Fallahzadeh

Skills _

Programming and Libraries MATLAB, Python, C Programming Language, C#.NET, LaTeX, OpenCV, Python Libraries

Software and Tools Altium Designer, Circuit Maker, Micro Vision Keil(ARM), STM32CubeIDE, CodeVision(AVR), Git(familiar)

Languages Persian (Mother Tongue), English (Foreign Language)

Soft Skills Easily Get Into Teams, Time Management, Problem Solving, Self-learning.

Education

Qazvin I. Azad University (QIAU)

Qazvin, Iran

MASTER OF SCIENCE IN DIGITAL ELECTRONICS

January 2021 - Present

Department Of Electrical, Computer, and Biomedical Engineering

Qazvin I. Azad University (QIAU)

Qazvin, Iran

BACHELOR OF ENGINEERING IN ELECTRICAL ENGINEERING

December 2016 - January 2021

· Department Of Electrical, Computer, and Biomedical Engineering

CGPA: 14.30/20 (3.06/4.0)

Zanjan I. Azad University

Zanjan, Iran

ASSOCIATE DEGREE IN ELECTRICAL ENGINEERING

January 2013 - May 2015

• Department Of Electrical and Computer Engineering

• CGPA: 16.76/20 (3.55/4.0)

Honors _

First place in Humanoid Soccer Robot League, International Robotic Competition 2023 Tehran, Iran

THE 17TH IRANOPEN ROBOCUP.

April 2023

Second place in Humanoid Soccer Robot League, Robocup Competition 2021

Bordeaux, France

Sydney, Australia

ROBOCUP FEDERATION

First place in Humanoid Soccer Robot League, Robocup Competition 2019

ROBOCUP FEDERATION

July 2019

First place in Humanoid Soccer Robot League, International Robotic Competition 2018

THE 15TH IRANOPEN ROBOCUP.

Kish, Iran October 2018

Second place in Humanoid Soccer Robot League, Robocup Competition 2018

ROBOCUP FEDERATION

Montreal, Canada

July 2018

First place in Humanoid Soccer Robot League, RoboCup Asia-Pacific 2017

ROBOCUP FEDERATION

Bangkok, Thailand

Third place in Manually Quadcopter League, International Robotic Competition 2013

AUTCUP ROBOCUP

Tehran, Iran

October 2017

November 2013