Baager Farhat

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Summary

Passionate about robotics engineering, with a track record of leadership in international competitions and prestigious awards. Particularly interested in robots/manufacturing, EVs, and mechatronics.

EDUCATION

California Institute of Technology

Pasadena, CA

EE / Robotics Engineering with minor in Control Systems and Dynamics

Sept 2023 - Present

SKILLS

o Python/Java Programming o Gazebo Robot Simulations

o 3-D printing (gcode)

o Solidworks/Fusion/Onshape o Wiring/Electronics

o Robot Arms (FANUC)

o Altium/KiCAD: PCBs

o PID controller

o Microcontrollers

o Matlab/Simulink

o JMOL Protein Modeling

o Soldering / Quick Prototyping

o PLC Programming

o CNC Machining

o Communication/Leadership

HIGHLIGHTED COURSE WORK

o EE 10: Digital Logic and Embedded Systems

o ME 129: Experimental Robotics (ROS)

o ME 13: Prototyping (Solidworks and CNC)

o EE 13: Electronic Systems Prototyping

o Altium Training: Caltech Racing (FSAE) Team

o CS 1: Python and Java Programming

o Vue.js Certificate: LinkedIn Learning

o Android App Development With Java

o 1 Month Robotics Challenge

o Intro to Def/of Hacking Certificate

Internships and Awards

- o Avalon Robotics Engineering Internship (Spring 2024): Worked on autonomous manufacturing through mechatronics projects and FANUC Robot arm
- o CPS Office of Computer Science Robotics Summer Internship (Summer 2023): Group leader for building and programming a mecanum robot chassis
- o Morningstar Summer Internship (Summer 2022): Front-End Developer on Institutional products team
- o United by STEM: One Team, Two Continents (Fall 2023): Robotics mentoring in South Africa
- o FIRST Robotics: Deans List Award (Midwest): First place in State for student leaders
- o 2x FTC Chicago City Championship (robotics): Best FTC team in City
- o FTC Chicago City Control Award: Most advanced robot design
- o FRC Midwest Regional Judge Award and Inspire Award

Projects

- o RFID Invetory System for autonomous manufacturing
- o Automatic Coolent/water Pump for CNC automation through PLC NEXTEngineer
- o KRYTN and MACI Robot Arm ROS programming and integration
- o Spinning Drone paradox (built drone from scratch to save energy consumption)
- o Multipurpose probe (Designed Schematic, PCB, and Assembled)
- o PID Self Balancing Robot (ran Simulink simulations)
- o Odometry localization
- o FRC Chassis (gearbox assembly, wire harness, etc) and Ball Shooter Actuator
- o FTC Cone Delivery Robot
- o International Robotics Mentor Through One Team, Two Continents Project