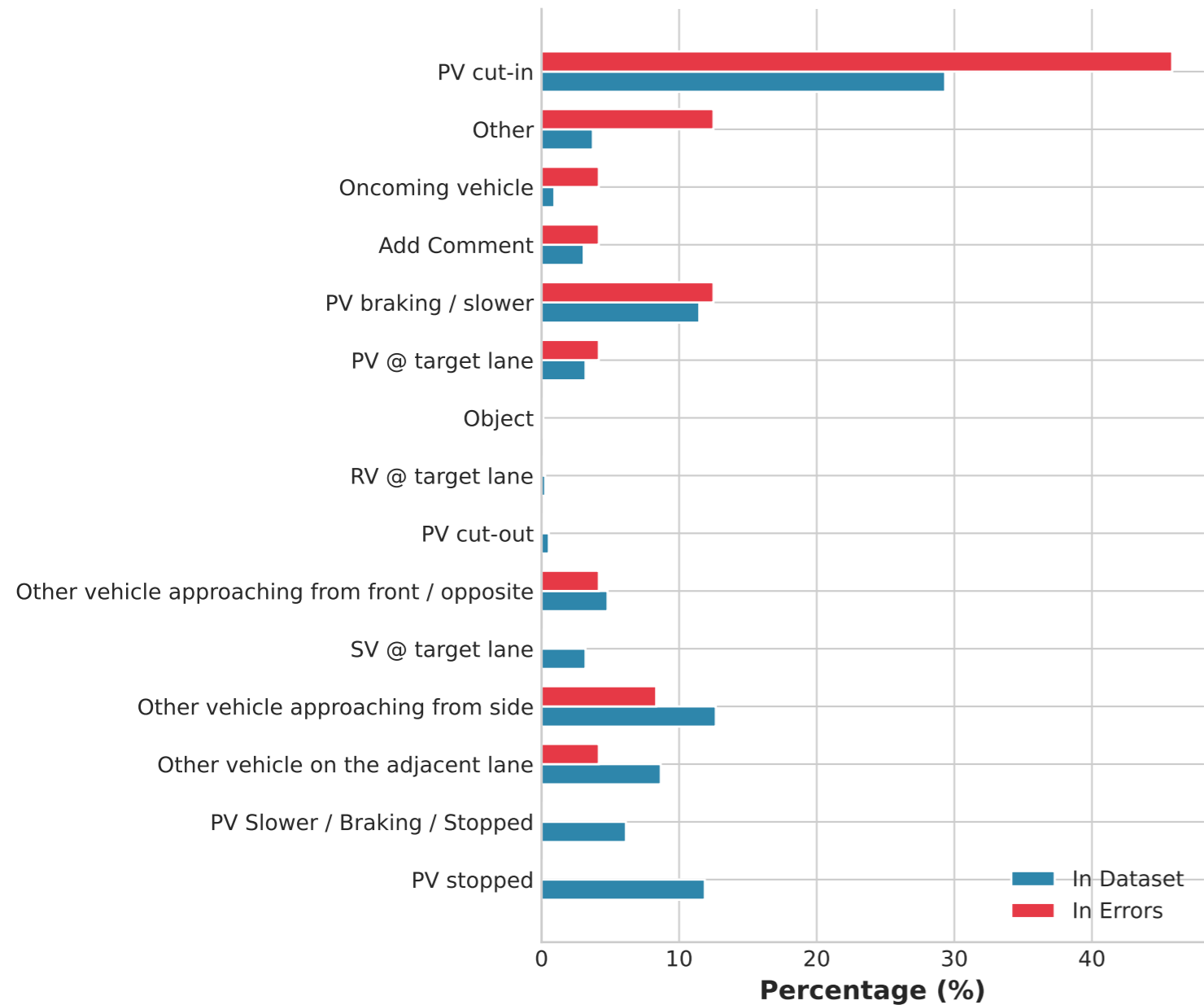**Scenario Representation: Dataset vs Errors - Level 2**

Dataset vs Error Distribution

Over/Under-representation in Errors
(Red = over-represented, Green = under-represented)

Category	Difference (Errors % - Dataset %)
PV cut-in	+16.5%
Other	+8.8%
Oncoming vehicle	+3.2%
Add Comment	+1.1%
PV braking / slower	+1.0%
PV @ target lane	+1.0%
Object	-0.1%
RV @ target lane	-0.3%
PV cut-out	-0.5%
Other vehicle approaching from front / opposite	-0.6%
SV @ target lane	-3.2%
Other vehicle approaching from side	-4.3%
Other vehicle on the adjacent lane	-4.5%
PV Slower / Braking / Stopped	-6.1%
PV stopped	-11.9%

Legend: In Dataset, In Errors