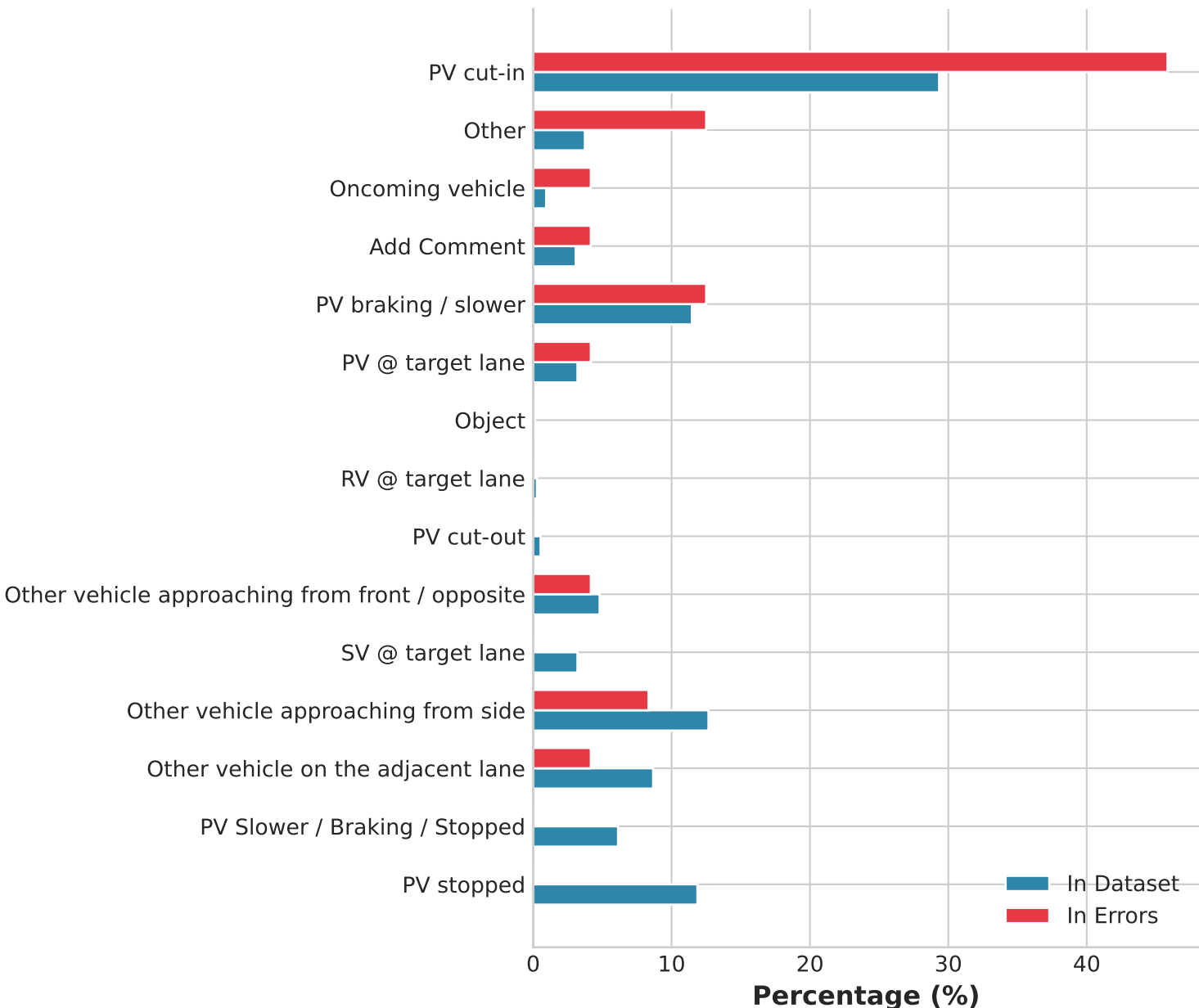# Scenario Representation: Dataset vs Errors - Level 2

Dataset vs Error Distribution

Over/Under-representation in Errors
(Red = over-represented, Green = under-represented)

Left chart categories (top to bottom): PV cut-in, Other, Oncoming vehicle, Add Comment, PV braking / slower, PV @ target lane, Object, RV @ target lane, PV cut-out, Other vehicle approaching from front / opposite, SV @ target lane, Other vehicle approaching from side, Other vehicle on the adjacent lane, PV Slower / Braking / Stopped, PV stopped

Legend: In Dataset, In Errors

X-axis: Percentage (%)

Right chart differences:
- PV cut-in: +16.5%
- Other: +8.8%
- Oncoming vehicle: +3.2%
- Add Comment: +1.1%
- PV braking / slower: +1.0%
- PV @ target lane: +1.0%
- Object: -0.1%
- RV @ target lane: -0.3%
- PV cut-out: -0.5%
- Other vehicle approaching from front / opposite: -0.6%
- SV @ target lane: -3.2%
- Other vehicle approaching from side: -4.3%
- Other vehicle on the adjacent lane: -4.5%
- PV Slower / Braking / Stopped: -6.1%
- PV stopped: -11.9%

X-axis: Difference (Errors % - Dataset %)