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Chapter 7 Deadlocks

Deadlocks

e.g. DiningPhilosopher 每個人都在等別人的筷子

- A set of process is in a *deadlock* state when every process in the set is waiting for an event that can be caused by only another process in the set.
- A System Model
 - Competing processes distributed?
 - Resources:
 - Physical Resources, e.g., CPU, printers, memory, etc.
 - Logical Resources, e.g., files, semaphores, etc.

e.g. Two processes each wait for the semaphore of each other.

Deadlocks

- A Normal Sequence
 - Request: Granted or Rejected
 - Use

e.g. block()

- Release
- Remarks
 - No request should exceed the system capacity!
 - Deadlock can involve different resource types!
 - Several instances of the same type!

Deadlocks

```
void *do_work_one(void *param) {
                   pthread_mutex_lock(&first_mutex);
                   pthread_mutex_lock(&second_mutex);
                   /* Do some work */
                    pthread_mutex_unlock(&second_mutex);
                   pthread_mutex_unlock(&first_mutex);
                   pthread_exit(0); }
                void *do_work_two(void *param) {
                   pthread_mutex_lock(&second_mutex);
            2.
                    pthread_mutex_lock(&first_mutex);
                   /* Do some work */
first_mutex 時,發現
已經被 P1 鎖住,所以
                   pthread_mutex_unlock(&first_mutex);
切回 P1, P1 又發現
                    pthread_mutex_unlock(&second_mutex);
second_mutex 已經被
                   pthread exit(0); }
P2 鎖住,於是產生
                pthread_mutex_init(&first_mutex, NULL);
                pthread_mutex_init(&second_mutex, NULL);
```

當 P2 打算鎖住

deadlock •

Deadlock Characterization

Necessary Conditions

(deadlock → conditions or ¬ conditions → ¬ deadlock)

- Mutual Exclusion At least one resource must be held in a non-sharable mode! 若 resource is sharable, 不可能會有 mutual exclusion
- Hold and Wait Pi is holding at least one resource and waiting to acquire additional resources that are currently held by other processes!

Deadlock Characterization

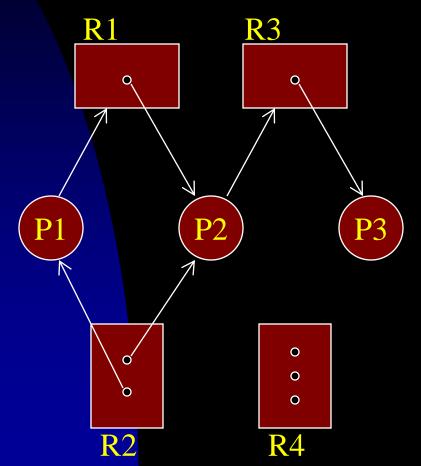
- No Preemption Resources are nonpreemptible!
- Circular Wait There exists a set $\{P_0, P_1, ..., P_n\}$ of waiting process such that $P_0 \xrightarrow[\text{wait}]{} P_1, P_1 \xrightarrow[\text{wait}]{} P_2, ..., P_{n-1} \xrightarrow[\text{wait}]{} P_n$, and $P_n \xrightarrow[\text{wait}]{} P_0$.

if A -> B,這 4 個 condition 只要有一個 fail,就不會有 deadlock!

- Remark:
 - Condition 4 implies Condition 2.
 - The four conditions are not completely independent!

Resource Allocation Graph

System Resource-Allocation Graph



```
Vertices

Processes:

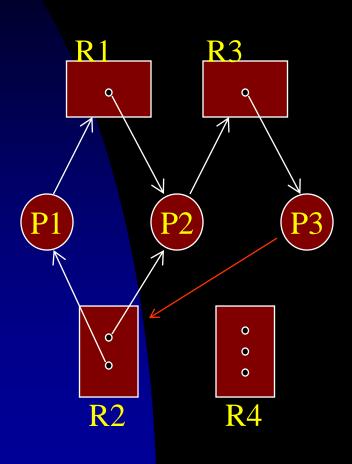
{P1,..., Pn}

Resource Type:

{R1,..., Rm}
```

Edges
Request Edge:
Pi → Rj
Assignment Edge:
Ri → Pj

Resource Allocation Graph

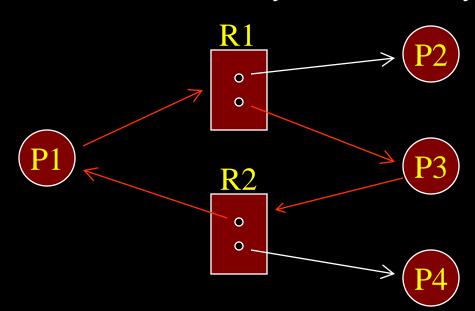


Example

- No-Deadlock
 - Vertices
 - P = { P1, P2, P3 }
 - R = { R1, R2, R3, R4 }
 - Edges
 - E = { P1 \rightarrow R1, P2 \rightarrow R3, R1 \rightarrow P2, R2 \rightarrow P2, R2 \rightarrow P1, R3 \rightarrow P3 }
- Resources
 - **R1:1**, R2:2, R3:1, R4:3
- results in a deadlock.

Resource Allocation Graph

- Observation
 - The existence of a cycle
 - One Instance per Resource Type → Yes!!
 - Otherwise → Only A Necessary Condition!!



Methods for Handling Deadlocks

Solutions:

- Make sure that the system never enters a deadlock state!
 - Deadlock Prevention: Fail at least one of the necessary conditions
 if A -> B, 這 4 個 condition 只要有一個 fail, 就不會有 deadlock!
 Deadlock Avoidance: Processes
 - Deadlock Avoidance: Processes provide information regarding their resource usage. Make sure that the system always stays at a "safe" state!

Methods for Handling Deadlocks

- Do recovery if the system is deadlocked.
 - Deadlock Detection
 - Recovery
- Ignore the possibility of deadlock occurrences!
 - Restart the system "manually" if the system "seems" to be deadlocked or stops functioning.
 - Note that the system may be "frozen" temporarily!

- Observation:
 - Try to fail anyone of the necessary condition!
 - \therefore \neg (\land i-th condition) \rightarrow \neg deadlock

- Mutual Exclusion
 - ?? Some resources, such as a printer, are intrinsically non-sharable??

- Hold and Wait
 - Acquire all needed resources before its execution. 拿東西,又想要別人的東西
 - Release allocated resources before request additional resources!

```
1. TD + Disk -> Disk + Printer
2. TD + Disk + Printer
(全部 hold 在手上,不要去 wait)
```

```
[ Tape Drive → Disk ] [ Disk & Printer ]

Hold Them All

Tape Drive & Disk Disk & Printer

當在使用 TD & Disk 時,
```

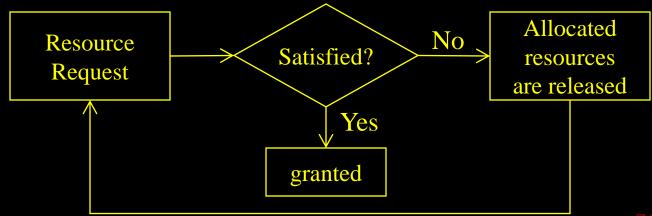
Disadvantage:

Printer 沒事;同理,當在使用 Disk & Printer 時,TD 沒事

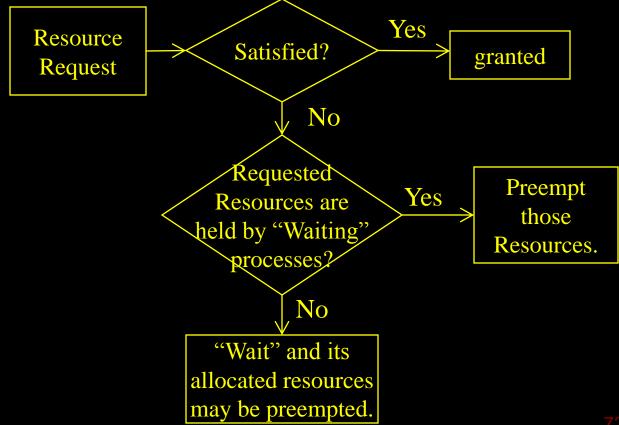
- Low Resource Utilization
- Starvation

No Preemption

- Resource preemption causes the release of resources.
- Related protocols are only applied to resources whose states can be <u>saved and restored</u>, e.g., CPU register & memory space, instead of printers or tape drives.
- Approach 1: e.g. printer 印到一半,還有 100 頁: 先等我把這頁印完,印完 再給你印。



Approach 2



Circular Wait

A resource-ordering approach:

```
F: R → N

Resource requests must be made in an increasing order of enumeration.
```

- Type 1 strictly increasing order of resource requests.
 - Initially, order any # of instances of Ri
 - Following requests of any # of instances of Rj must satisfy F(Rj) > F(Ri), and so on.
 - * A single request must be issued for all needed instances of the same resources.

- Type 2
 - Processes must release all Ri's when they request any instance of Rj if F(Ri) ≥ F(Rj)
- F: R → N must be defined according to the <u>normal order</u> of resource usages in a system, e.g.,

```
F(tape drive) = 1
F(disk drive) = 5
?? feasible ??
F(printer) = 12
```

- Motivation:
 - Deadlock-prevention algorithms can cause low device utilization and reduce system throughput!
 - Acquire additional information about how resources are to be requested and have better resource allocation!
 - Processes declare their maximum number of resources of each type that it may need.

- A Simple Model
 - A resource-allocation state
 <# of available resources,
 # of allocated resources,
 max demands of processes>
- A deadlock-avoidance algorithm dynamically examines the resource-allocation state and make sure that it is safe.
 - e.g., the system never satisfies the circularwait condition.

- Safe Sequence
 - A sequence of processes <P1, P2, ..., Pn> is a safe sequence if

$$\forall Pi, need(Pi) \leq Available + \sum_{j < i} Allocated(Pj)$$



- The existence of a safe sequence
- Unsafe



Deadlocks are avoided if the system can allocate resources to each process up to its maximum request in some order. If so, the system is in a safe state!

Example:

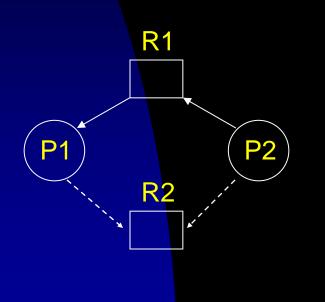
	Max Needs	Allocated	Available
P0	10	5	3
P1	4	2	
P2	9	2	

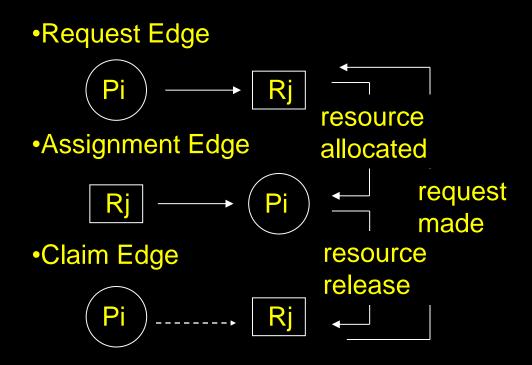
- •The existence of a safe sequence <P1, P0, P2>.
- If P2 got one more, the system state is unsafe. ((P0, 5), (P1, 2), (P2, 3), (available, 2))

How to ensure that the system will always remain in a safe state?

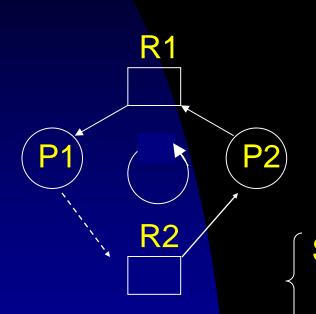
Deadlock Avoidance – Resource-Allocation Graph Algorithm

One Instance per Resource Type





Deadlock Avoidance – Resource-Allocation Graph Algorithm



A cycle is detected!

- → The system state is unsafe!
- R2 was requested & granted!

Safe state: no cycle

Unsafe state: otherwise

Cycle detection can be done in O(n²)

Deadlock Avoidance – Banker's Algorithm

- Available [m]
 - If Available [i] = k, there are k instances of resource type Ri available.
- Max [n,m]
 - If Max [i,j] = k, process Pi may request at most k instances of resource type Rj.
- Allocation [n,m]
 - If Allocation [i,j] = k, process Pi is currently allocated k instances of resource type Rj.
- Need [n,m]
 - If Need [i,j] = k, process Pi may need k more instances of resource type Rj.

n: # of processes, m: # of resource types

Need [i,j] = Max [i,j] - Allocation [i,j]

Deadlock Avoidance – Banker's Algorithm

- Safety Algorithm A state is safe??
 - 1. Work := Available & Finish [i] := F, $1 \le i \le n$
 - 2. Find an i such that both
 - 1. Finish [i] =F
 - 2. Need[i] ≤ WorkIf no such i exist, then goto Step4
 - 3. Work := Work + Allocation[i] Finish [i] := T; **Goto** Step2
 - **4. If** Finish [i] = T for all *i*, **then** the system is in a safe state.

Where Allocation[i] and Need[i] are the *i*-th row of Allocation and Need, respectively, and $X \le Y$ if $X[i] \le Y[i]$ for all i, X < Y if $X \le Y$ and $Y \ne X$

n: # of processes, m: # of resource types

Deadlock Avoidance – Banker's Algorithm

Resource-Request Algorithm

Request_i [/] =k: P_i requests k instance of resource type Rj

- 1. If Request_i \leq Need_i, then Goto Step2; otherwise, Trap
- If Request_i ≤ Available, then Goto Step3; otherwise, Pi must wait.
- Have the system pretend to have allocated resources to process P_i by setting

Available := Available - Request;

Allocation; := Allocation; + Request;

Need; := Need; - Request;;

Execute "Safety Algorithm". If the system state is safe, the request is granted; otherwise, Pi must wait, and the old resource-allocation state is restored!

An Example

	Allocation			Max			Need			Available		
	A	В	С	A	В	С	Α	В	С	Α	В	С
P0	0	1	0	7	5	3	7	4	3	3	3	2
P1	2	0	0	3	2	2	1	2	2			
P2	3	0	2	9	0	2	6	0	0			
P3	2	1	1	2	2	2	0	1	1			
P4	0	0	2	4	3	3	4	3	1			

- A safe state
 - :: <P1,P3,P4,P2,P0> is a safe sequence.

Let P1 make a request Requesti = (1,0,2)Request_i \leq Available (i.e., $(1,0,2) \leq (3,3,2)$)

	Allocation				Need		Available			
	A	В	С	Α	В	С	Α	В	С	
P0	0	1	0	7	4	3	2	3	0	
P1	3	0	2	0	2	0				
P2	3	0	2	6	0	0				
P3	2	1	1	0	1	1				
P4	0	0	2	4	3	1				

→ Safe :: <P1,P3,P4,P0,P2> is a safe sequence!

- If Request4 = (3,3,0) is asked later, it must be rejected.
- Request0 = (0,2,0) must be rejected because it results in an unsafe state.

Deadlock Detection

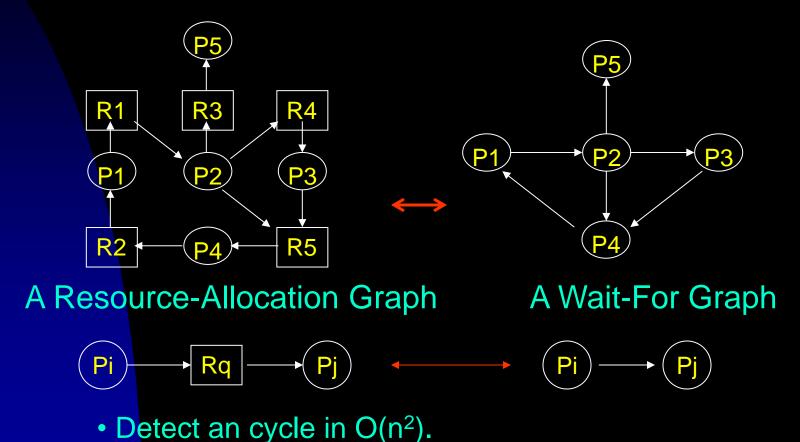
Motivation:

 Have high resource utilization and "maybe" a lower possibility of deadlock occurrence.

Overheads:

- Cost of information maintenance
- Cost in executing a detection algorithm
- Potential loss inherent from a deadlock recovery

Deadlock Detection – Single Instance per Resource Type



- The eveter reads to maintain the weit for
- The system needs to maintain the wait-for graph

Deadlock Detection – Multiple Instance per Resource Type

Data Structures

- Available[1..m]: # of available resource instances
- Allocation[1..n, 1..m]: current resource allocation to each process
- Request[1..n, 1..m]: the current request of each process
 - If Request[i,j] = k, Pi requests k more instances of resource type Rj

n: # of processes, m: # of resource types

Deadlock Detection – Multiple Instance per Resource Type

Complexity = $O(m * n^2)$

- Work := Available. For i = 1, 2, ..., n, if Allocation[i] ≠ 0, then Finish[i] = F; otherwise, Finish[i] = T.
- 2. Find an i such that both
 - a. Finish[i] = F
 - b. Request[i] \leq Work

If no such i, Goto Step 4

3. Work := Work + Allocation[i] Finish[i] := T

Goto Step 2

4. If Finish[i] = F for some i, then the system is in a deadlock state. If Finish[i] = F, then process Pi is deadlocked.

Deadlock Detection – Multiple Instances per Resource Type

An Example

	Allocation			R	leque	st	Available		
	A	В	С	Α	В	С	Α	В	С
P0	0	1	0	0	0	0	0	2	0
P1	2	0	0	2	0	2			
P2	3	0	3	0	0	0			
P3	2	1	1	1	0	0			
P4	0	0	2	0	0	2			

> Find a sequence <P0, P2, P3, P1, P4> such that Finish[i] = T for all i. If Request2 = (0,0,1) is issued, then P1, P2, P3, and P4 are deadlocked.

Deadlock Detection – Algorithm Usage

- When should we invoke the detection algorithm?
 - How often is a deadlock likely to occur?
 - How many processes will be affected by a deadlock?

```
rejected + overheads - coverheads - coverhea
```

- Time for Deadlock Detection?
 - CPU Threshold? Detection Frequency? ...

Deadlock Recovery

- Whose responsibility to deal with deadlocks?
 - Operator deals with the deadlock manually.
 - The system recover from the deadlock automatically.
- Possible Solutions
 - Abort one or more processes to break the circular wait.
 - Preempt some resources from one or more deadlocked processes.

Deadlock Recovery – Process Termination

- Process Termination
 - Abort all deadlocked processes!
 - Simple but costly!
 - Abort one process at a time until the deadlock cycle is broken!
 - Overheads for running the detection again and again.
 - The difficulty in selecting a victim!

But, can we abort any process? Should we compensate any damage caused by aborting?

Deadlock Recovery – Process Termination

- What should be considered in choosing a victim?
 - Process priority
 - The CPU time consumed and to be consumed by a process.
 - The numbers and types of resources used and needed by a process
 - Process's characteristics such as "interactive or batch"
 - The number of processes needed to be aborted.

Deadlock Recovery – Resource Preemption

- Goal: Preempt some resources from processes and give them to other processes until the deadlock cycle is broken!
- Issues
 - Selecting a victim:
 - It must be cost-effective!
 - Roll-Back
 - How far should we roll back a process whose resources were preempted?
 - Starvation
 - Will we keep picking up the same process as a victim?
 - How to control the # of rollbacks per process efficiently?

Deadlock Recovery – Combined Approaches

- Partition resources into classes that are hierarchically ordered.
 - ⇒ No deadlock involves more than one class
 - Handle deadlocks in each class independently

Deadlock Recovery – Combined Approaches

Examples:

- Internal Resources: Resources used by the system, e.g., PCB
 - → Prevention through resource ordering
- Central Memory: User Memory
 - → Prevention through resource preemption
- Job Resources: Assignable devices and files
 - → Avoidance : This info may be obtained!
- Swappable Space: Space for each user process on the backing store
 - → Pre-allocation : the maximum need is known!