



BIFURCATIONS

Introduction

- A **bifurcation** of a dynamical system is a qualitative change in its dynamics produced by varying parameters.
- A **bifurcation** occurs when a small smooth change made to the parameter values (the bifurcation parameters) of a system causes a sudden qualitative or topological change in its behavior.
- **Types of bifurcations**
 - Local bifurcations, which can be analyzed entirely through changes in the local stability properties of equilibrium, periodic orbits or other invariant sets as parameters cross through critical thresholds.
 - Global bifurcations, which often occur when larger invariant sets of the system 'collide' with each other, or with equilibrium of the system. They cannot be detected purely by a stability analysis of the equilibrium (fixed points).

Bifurcation types

Local

Saddle-node

Transcritical

Pitchfork

Period-doubling

Hopf

Neimark

Global

Homoclinic

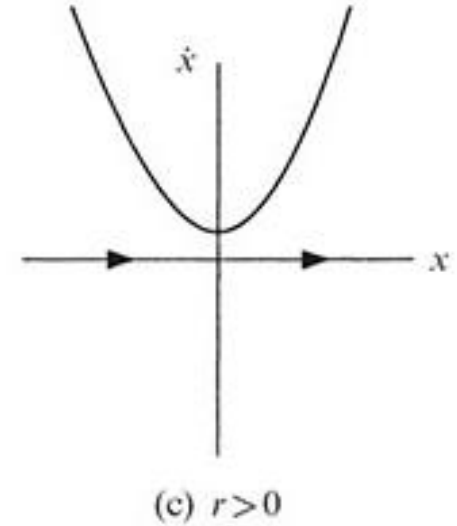
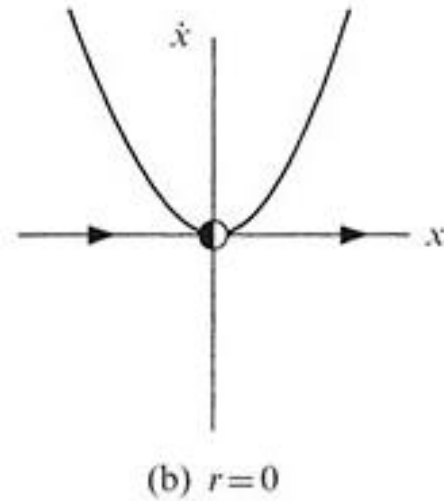
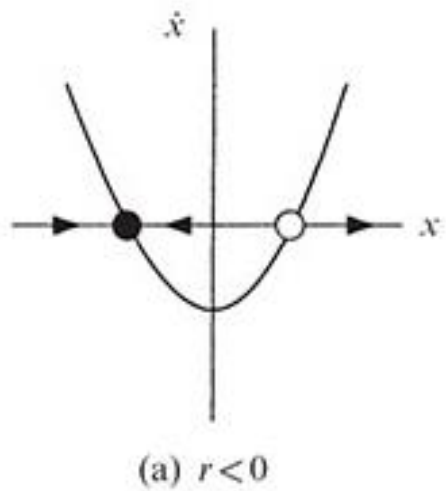
Heteroclinic

Infinite-period

Blue sky catastrophe

Saddle-Node Bifurcation

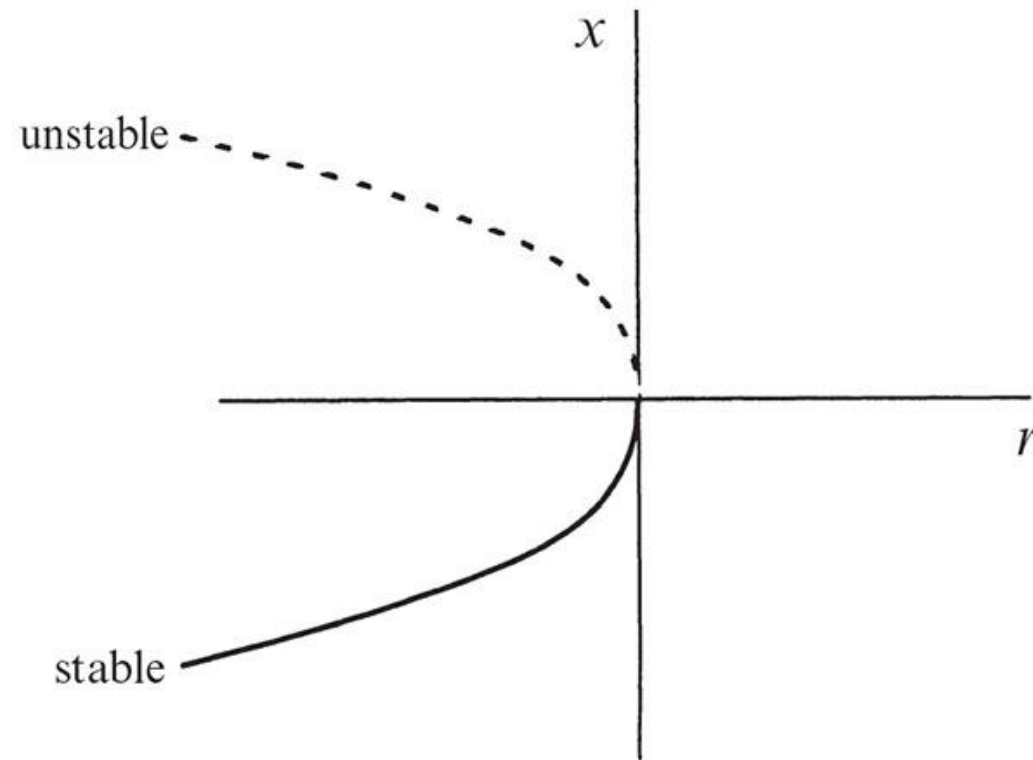
- The saddle-node bifurcation is the basic mechanism by which fixed points are *created, collided and destroyed*



Saddle-Node Bifurcation

► Bifurcation diagram:

$$\dot{x} = r + x^2$$



Saddle-Node Bifurcation

► Normal Forms

Taylor's expansion:

$$\begin{aligned}\dot{x} &= f(x, r) \\ &= f(x^*, r_c) + (x - x^*) \left. \frac{\partial f}{\partial x} \right|_{(x^*, r_c)} + (r - r_c) \left. \frac{\partial f}{\partial r} \right|_{(x^*, r_c)} + \frac{1}{2} (x - x^*)^2 \left. \frac{\partial^2 f}{\partial x^2} \right|_{(x^*, r_c)} + \dots\end{aligned}$$

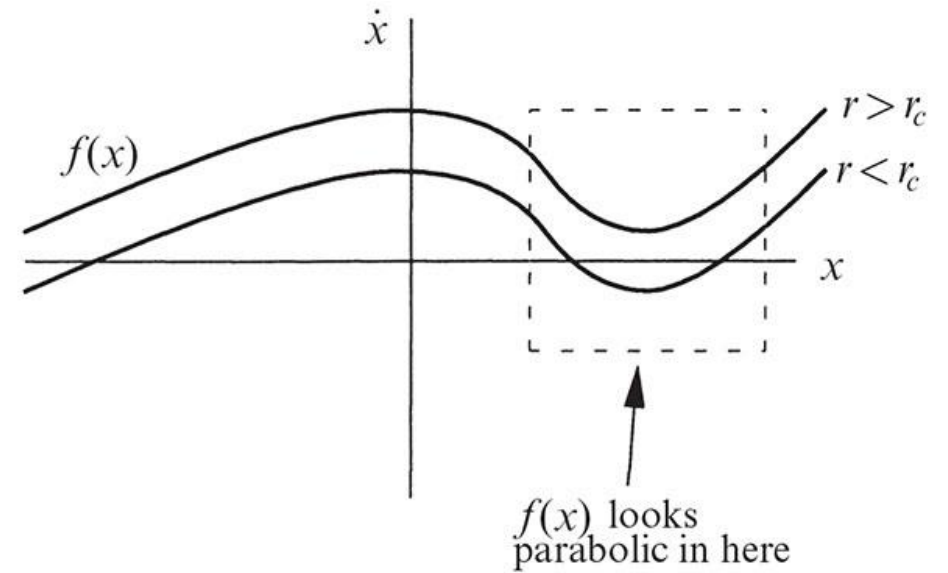
$$\text{Which } \begin{cases} f(x^*, r_c) = 0 \\ \left. \frac{\partial f}{\partial x} \right|_{(x^*, r_c)} = 0 \end{cases} \quad \longrightarrow \quad \dot{x} = (r - r_c) \left. \frac{\partial f}{\partial r} \right|_{(x^*, r_c)} + \frac{1}{2} (x - x^*)^2 \left. \frac{\partial^2 f}{\partial x^2} \right|_{(x^*, r_c)} + \dots$$

Saddle-Node Bifurcation

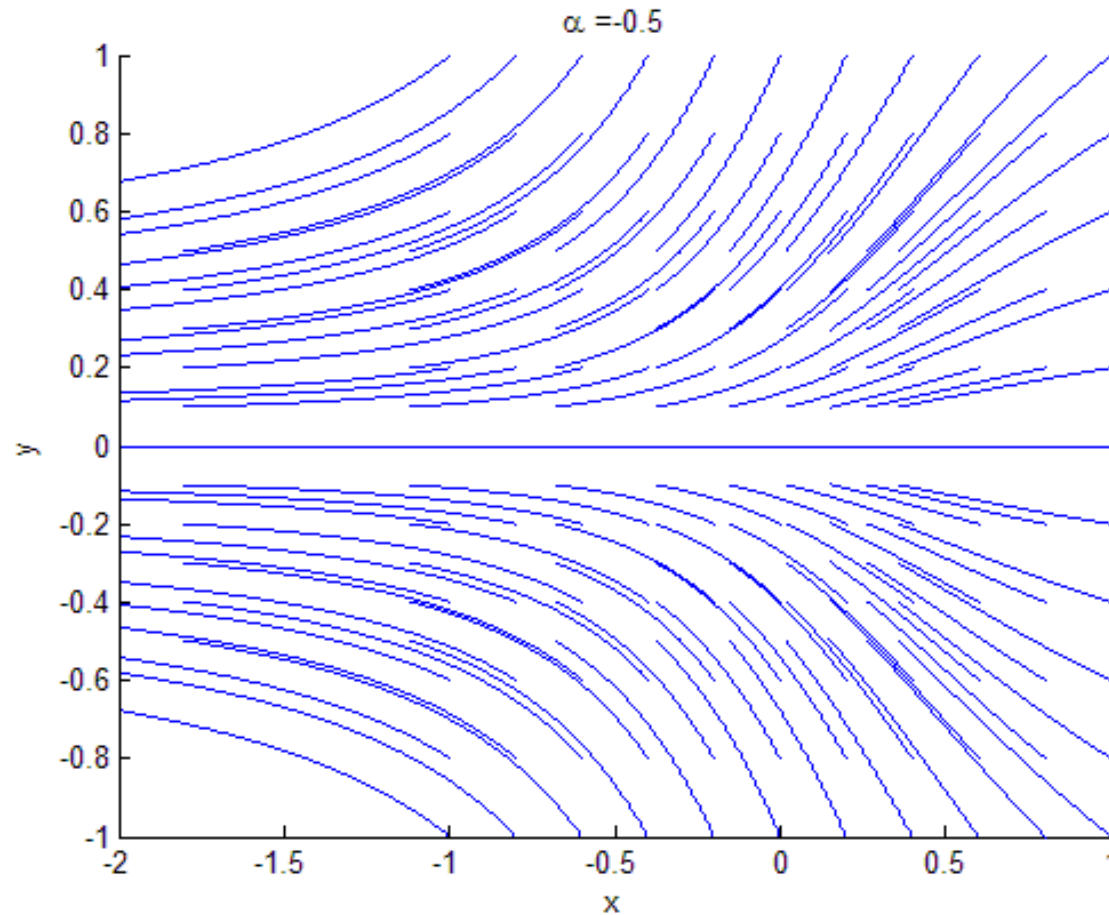
Normal Forms

$$\begin{aligned}\dot{x} &= r - x - e^{-x} \\ &= r - x - \left[1 - x + \frac{x^2}{2!} + \dots \right] \\ &= (r - 1) - \frac{x^2}{2} + \dots\end{aligned}$$

$$\dot{x} = a(r - r_c) + b(x - x^*)^2 + \dots$$



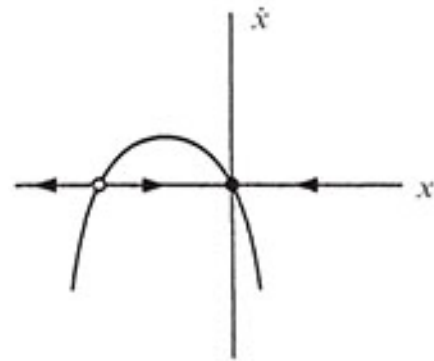
Saddle-Node Bifurcation



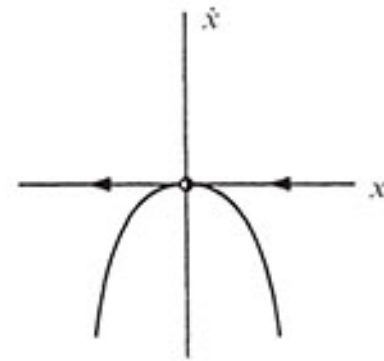
Transcritical Bifurcation

- There are certain scientific situations where a fixed point **must exist for all values of a parameter** and can never be destroyed.

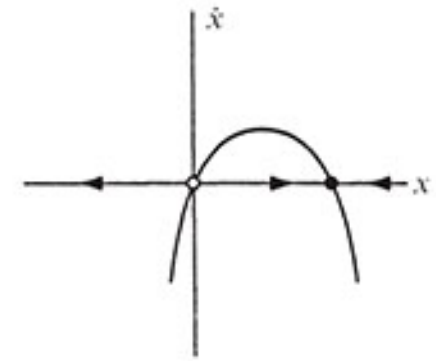
$$\dot{x} = rx - x^2.$$



(a) $r < 0$



(b) $r = 0$

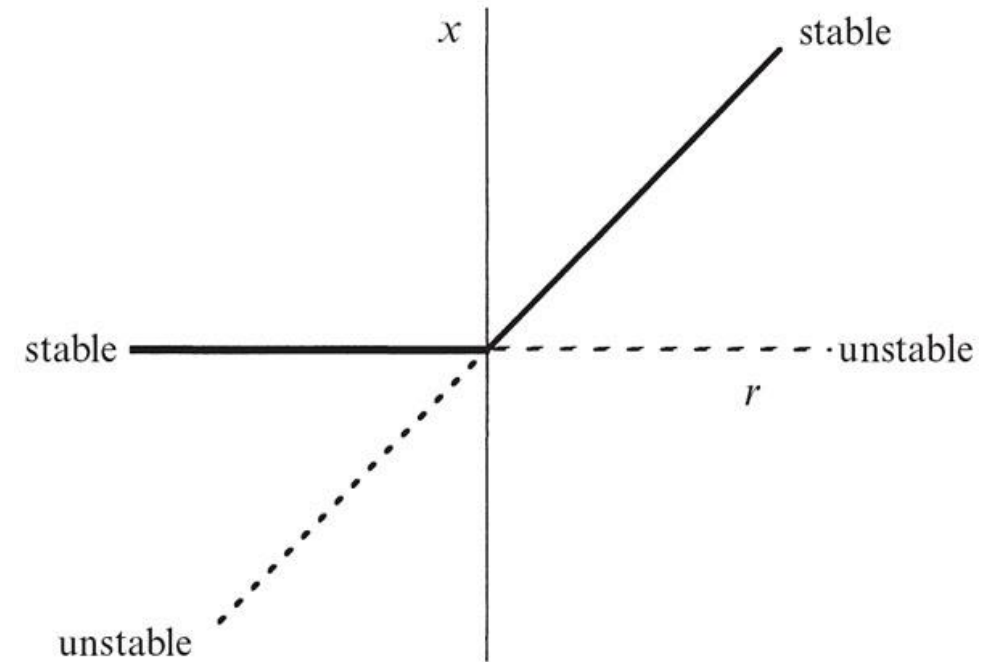


(c) $r > 0$

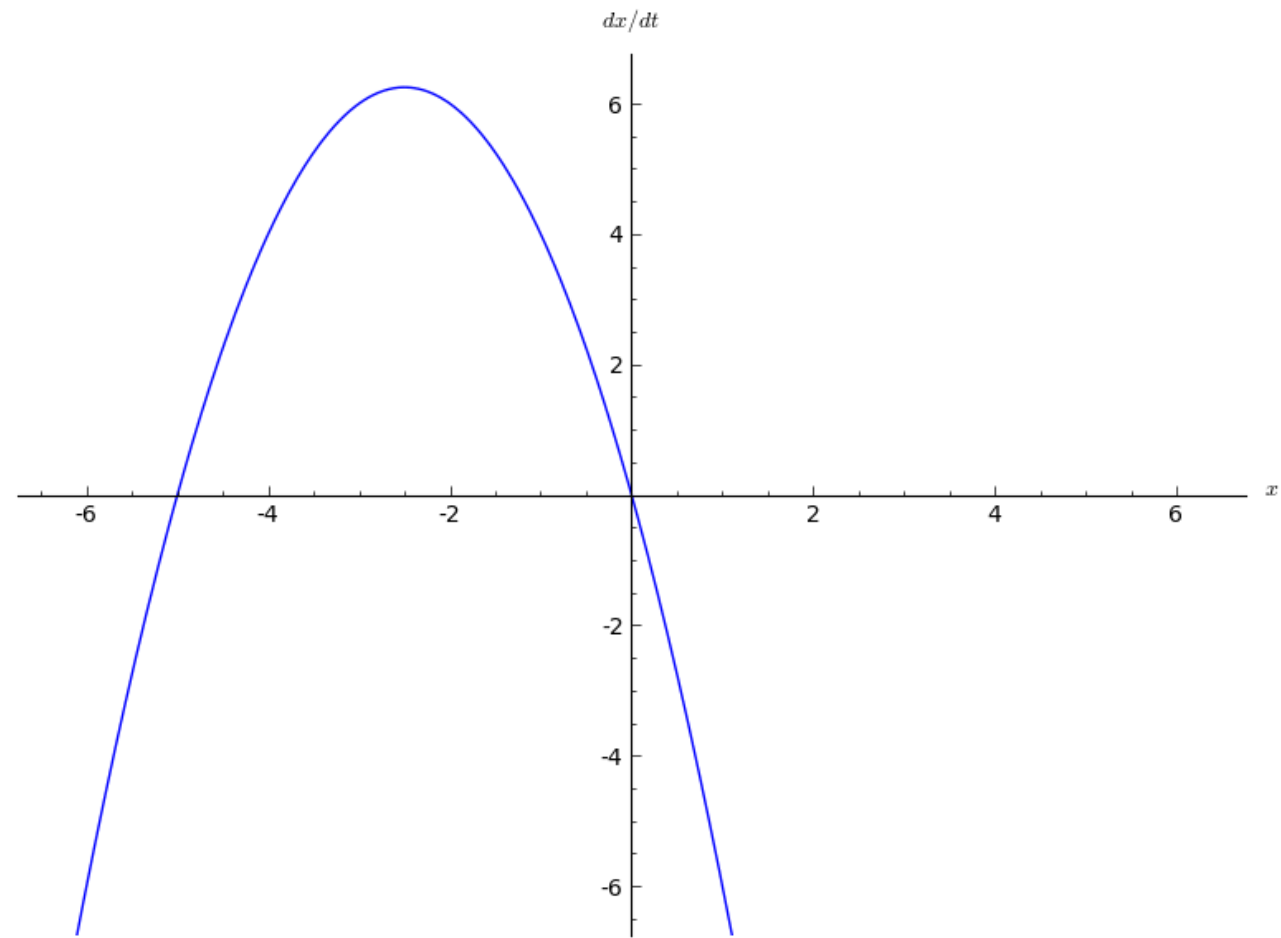
Transcritical Bifurcation

“ in the transcritical case, the two fixed points don't disappear after the bifurcation instead they just **switch their stability** ”

$$\dot{x} = rx - x^2.$$



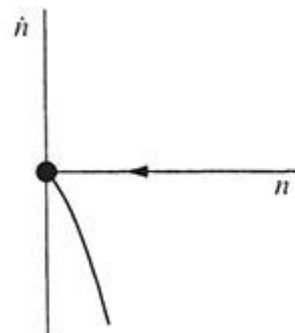
Transcritical Bifurcation



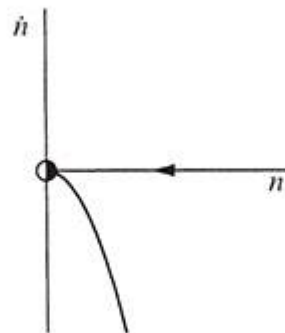
Transcritical Bifurcation

➤ Laser Threshold

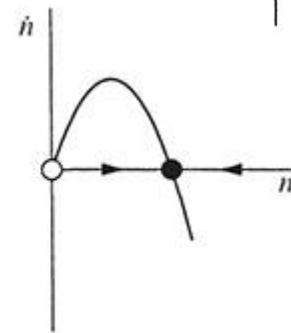
$$\begin{aligned}\dot{n} &= Gn(N_0 - \alpha n) - kn \\ &= (GN_0 - k)n - (\alpha G)n^2.\end{aligned}$$



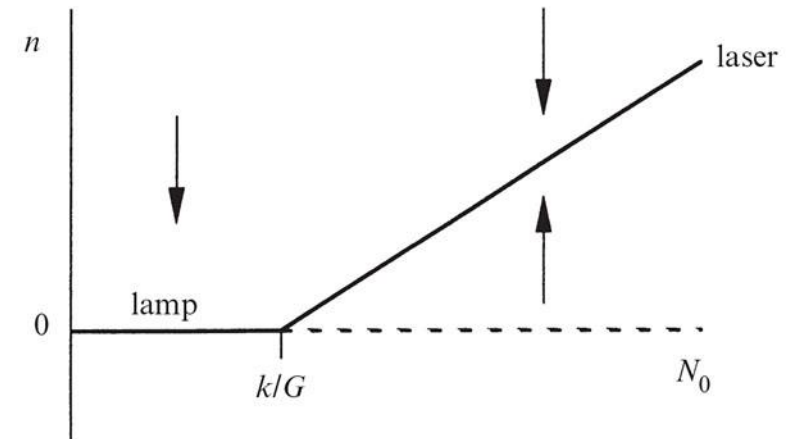
$$N_0 < k/G$$



$$N_0 = k/G$$



$$N_0 > k/G$$



Pitchfork Bifurcation

- This bifurcation is common in physical problems that have a **symmetry**.
- There are two very different types of pitchfork bifurcation:

- **Supercritical Pitchfork Bifurcation**

Normal Form:

$$\dot{x} = rx - x^3$$

- **Subcritical Pitchfork Bifurcation**

Normal Form:

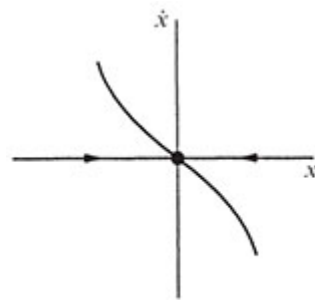
$$\dot{x} = rx + x^3$$

Pitchfork Bifurcation

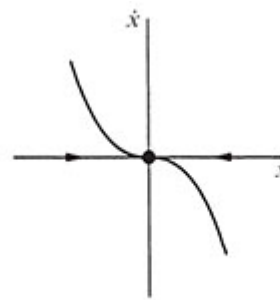
► Supercritical Pitchfork Bifurcation

Pitchfork Trifurcation!

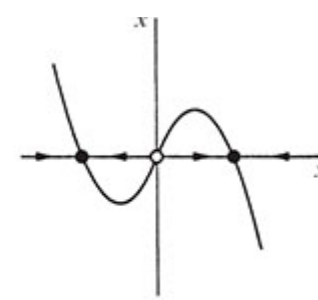
$$\dot{x} = rx - x^3$$



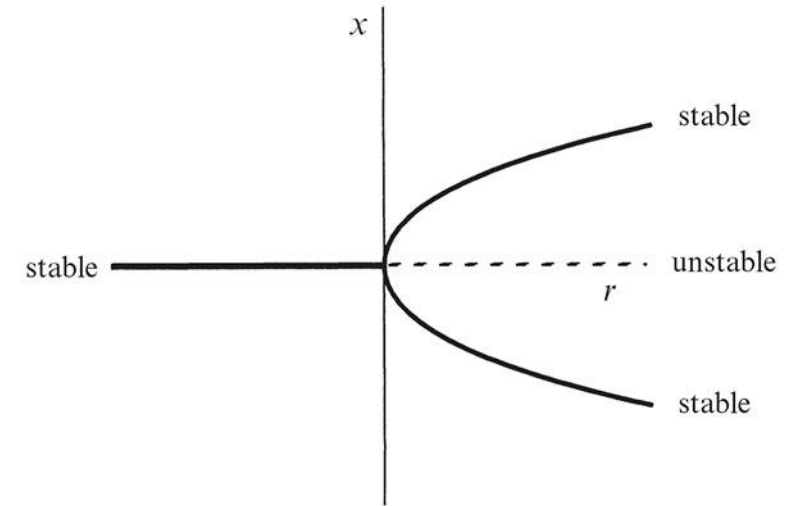
(a) $r < 0$



(b) $r = 0$



(c) $r > 0$



Pitchfork Bifurcation

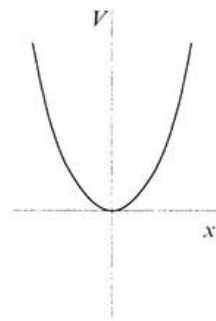
► The potential of System

$$\dot{x} = rx - x^3$$

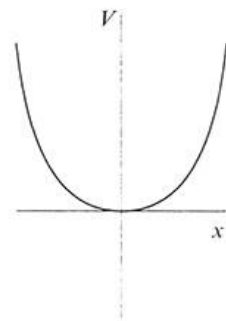
The potential is defined by $f(x) = -dV/dx$

Then

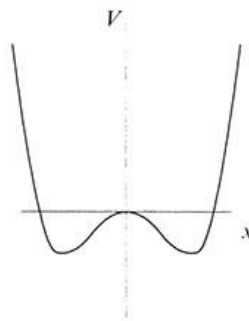
$$-dV/dx = rx - x^3 \longrightarrow V(x) = -\frac{1}{2}rx^2 + \frac{1}{4}x^4$$



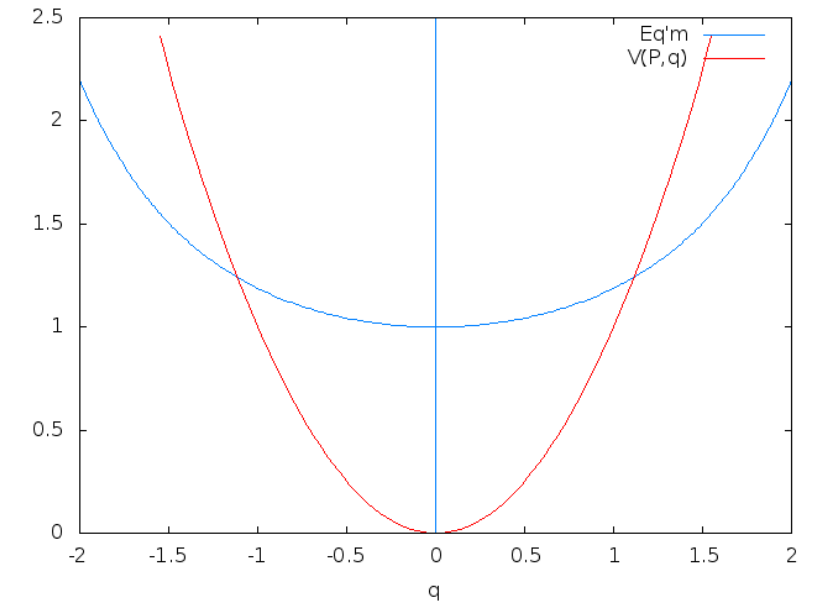
$r < 0$



$r = 0$



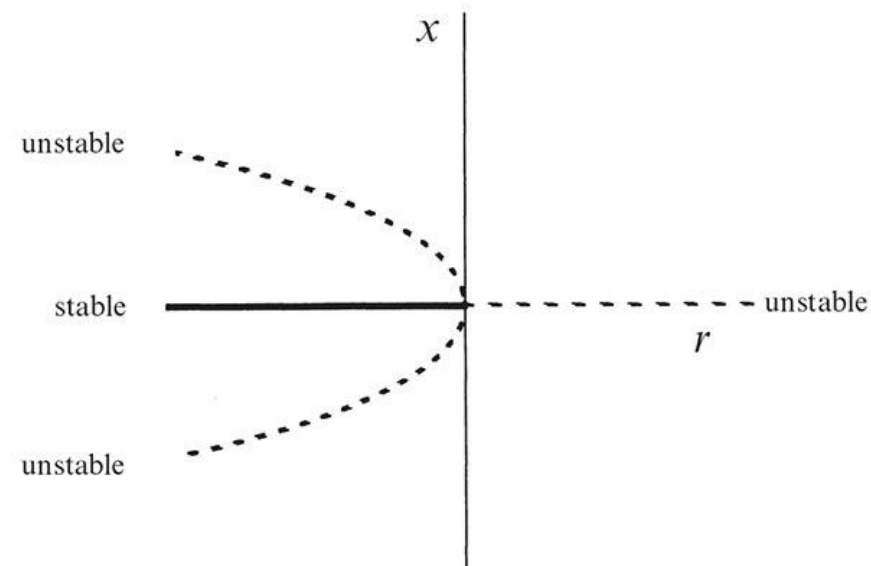
$r > 0$



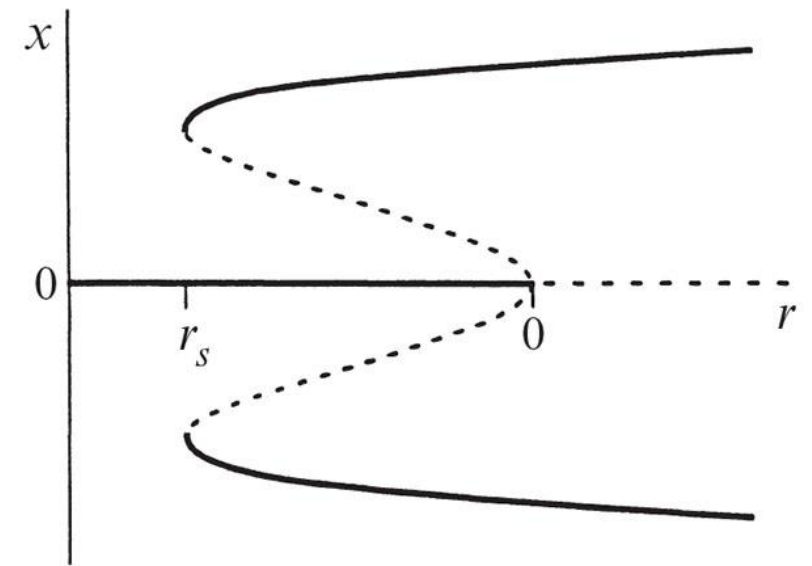
Pitchfork Bifurcation

► Subcritical Pitchfork Bifurcation

$$\dot{x} = rx + x^3$$

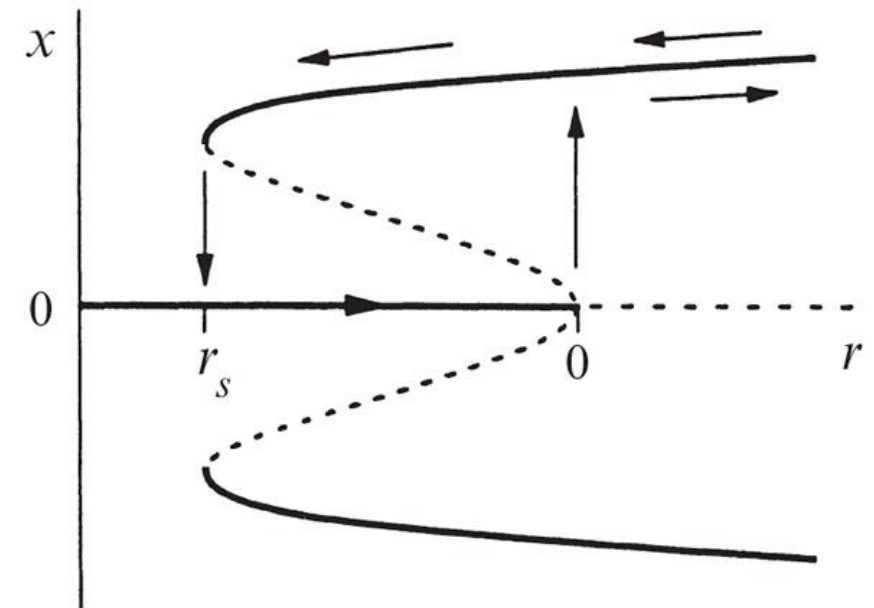


$$\dot{x} = rx + x^3 - x^5$$



Pitchfork Bifurcation

- In the range $r_s < r < 0$, two qualitatively different stable states coexist, namely the **origin** and the **large-amplitude** fixed points. The initial condition x_0 determines which fixed point is approached as $t \rightarrow \infty$.
- The existence of different stable states allows for the possibility of jumps and **hysteresis** as r is varied.
- The bifurcation at r_s is a **saddle-node** bifurcation.



Bifurcation in a Mechanical System

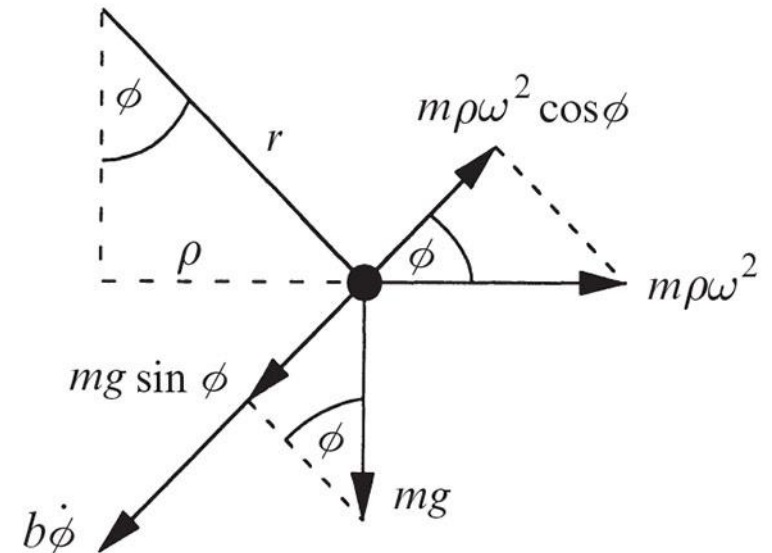
► Overdamped Bead on a Rotating Hoop

$$mr\ddot{\phi} = -b\dot{\phi} - mg \sin \phi + mr\omega^2 \sin \phi \cos \phi.$$

we would like to find some conditions under which we can safely **neglect** $mr\ddot{\phi}$ term.

Then

$$\begin{aligned} b\dot{\phi} &= -mg \sin \phi + mr\omega^2 \sin \phi \cos \phi \\ &= mg \sin \phi \left(\frac{r\omega^2}{g} \cos \phi - 1 \right). \end{aligned}$$



Bifurcation in a Mechanical System

► Overdamped Bead on a Rotating Hoop

Dimensional Analysis and Scaling

$$\tau = \frac{t}{T}$$

where T is a characteristic time scale

then

$$\ddot{\phi} = \frac{1}{T^2} \frac{d^2\phi}{d\tau^2}.$$

And finally,

$$\left(\frac{r}{gT^2} \right) \frac{d^2\phi}{d\tau^2} = - \left(\frac{b}{mgT} \right) \frac{d\phi}{d\tau} - \sin\phi + \left(\frac{r\omega^2}{g} \right) \sin\phi \cos\phi.$$

Each of the terms in parentheses is a dimensionless group.

Bifurcation in a Mechanical System

► Overdamped Bead on a Rotating Hoop

Dimensional Analysis and Scaling

$$\left(\frac{r}{gT^2}\right)\frac{d^2\phi}{d\tau^2} = -\left(\frac{b}{mgT}\right)\frac{d\phi}{d\tau} - \sin\phi + \left(\frac{r\omega^2}{g}\right)\sin\phi\cos\phi.$$

$$\boxed{\frac{b}{mgT} \approx O(1)}, \text{ and } \boxed{\frac{r}{gT^2} \ll 1}.$$

$$T = \frac{b}{mg}.$$

$$b^2 \gg m^2gr.$$

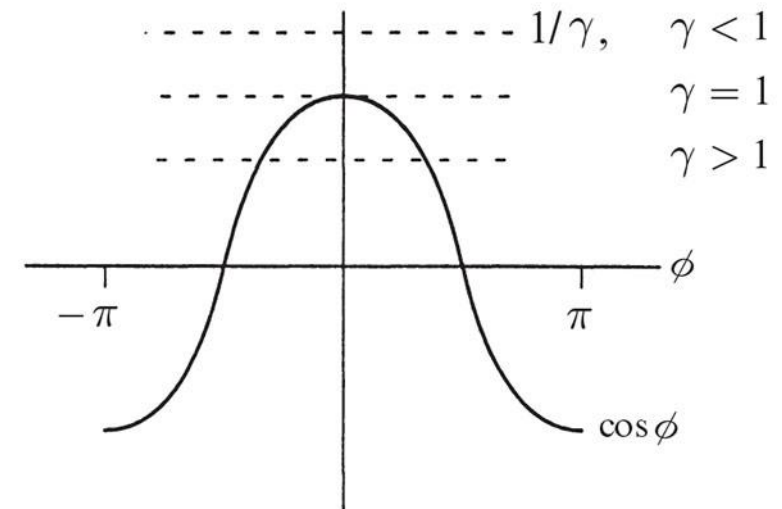
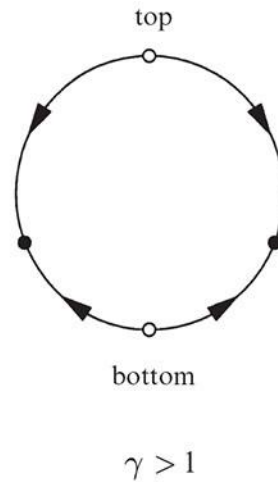
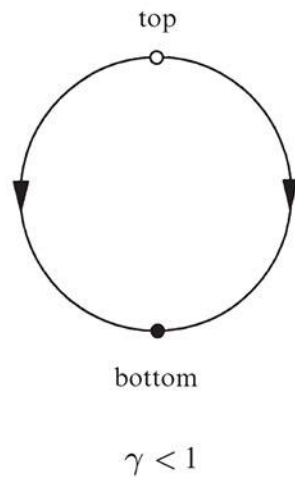
$$\varepsilon \frac{d^2\phi}{d\tau^2} = -\frac{d\phi}{d\tau} - \sin\phi + \gamma \sin\phi\cos\phi.$$

Bifurcation in a Mechanical System

► Overdamped Bead on a Rotating Hoop

Dimensional Analysis and Scaling

$$\gamma = \frac{r\omega^2}{g}$$



Bifurcation in a Mechanical System

► Overdamped Bead on a Rotating Hoop

Phase Plane Analysis

First-order system



Vector field

Second-order system



Phase plane

- The plane is spanned by two axes, one for the angle ϕ and one for the angular velocity.

$$\Omega = \phi' \equiv d\phi / d\tau$$

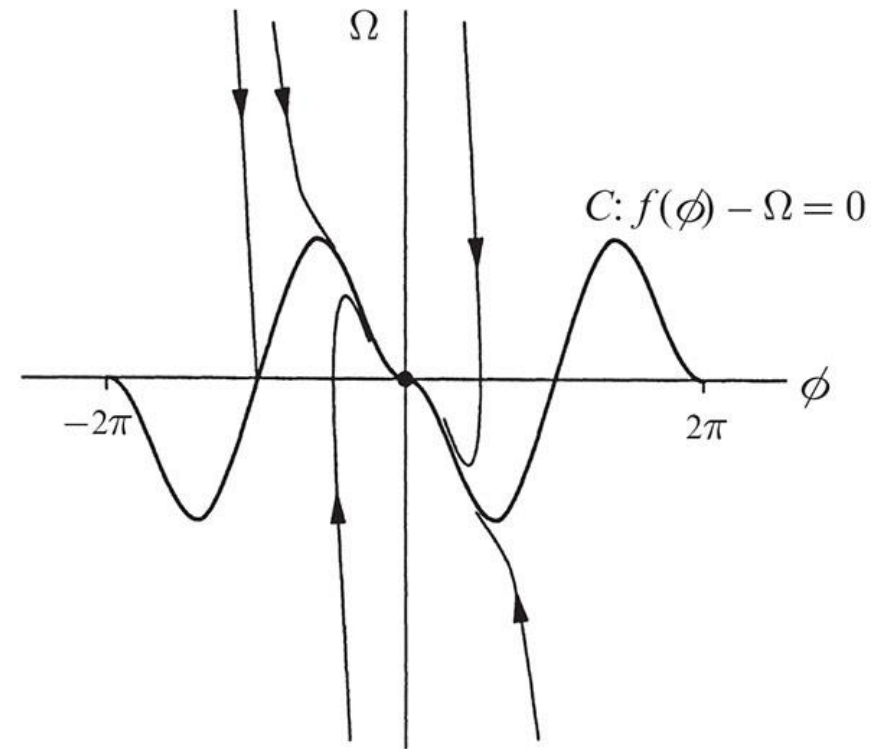
$$\Omega' = \frac{1}{\varepsilon}(f(\phi) - \Omega).$$

Bifurcation in a Mechanical System

► Overdamped Bead on a Rotating Hoop

Phase Plane Analysis

All trajectories slam straight up or down onto the curve C defined $f(\phi) = \Omega$ by, and then slowly ooze along this curve until they reach a fixed point.

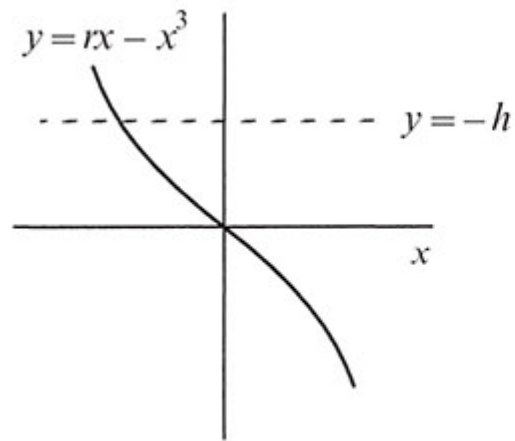


Imperfect Bifurcations

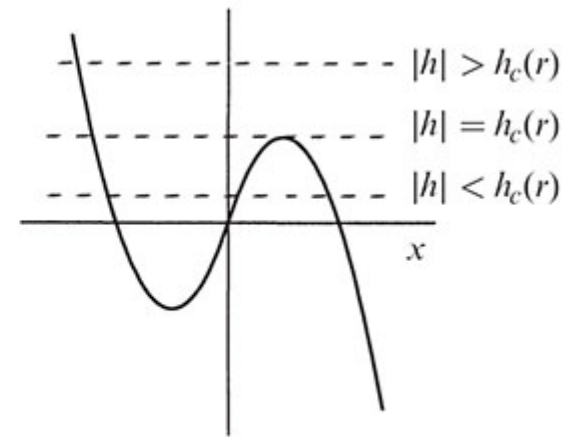
- In many real-world circumstances, the **symmetry** is only approximate, an imperfection leads to a slight difference between left and right.

$$\dot{x} = h + rx - x^3$$

h as an **imperfection parameter**.



(a) $r \leq 0$



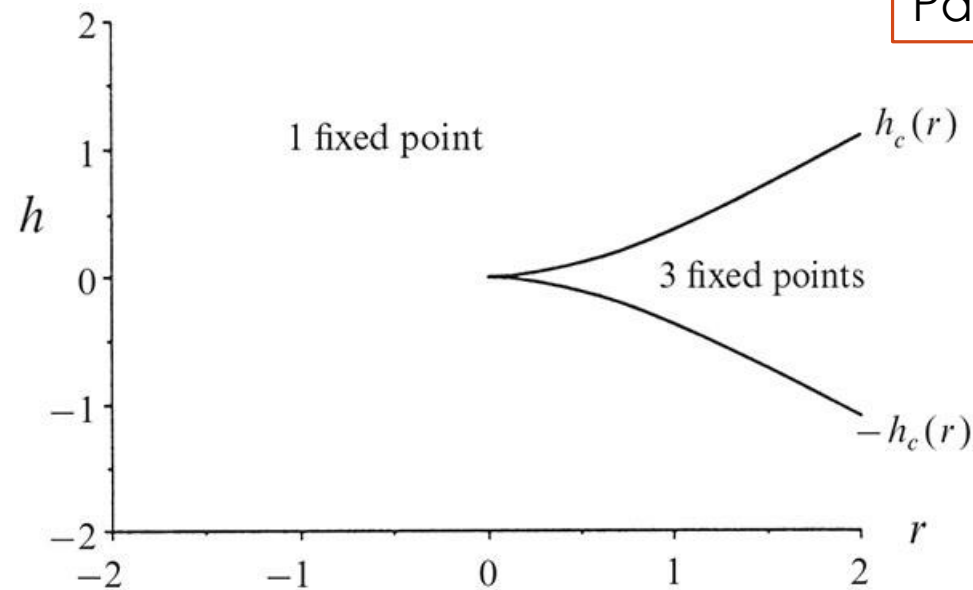
(b) $r > 0$

Imperfect Bifurcations

- The critical case occurs when the horizontal line is just tangent to either the local minimum or maximum of the cubic; then we have a saddle-node bifurcation.

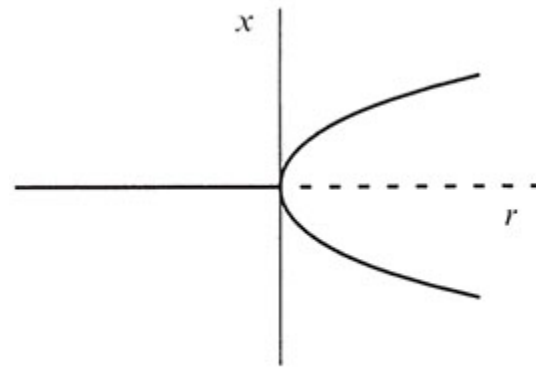
Saddle-node bifurcations occur when $h = \pm h_c(r)$, where

$$h_c(r) = \frac{2r}{2} \sqrt{\frac{r}{3}}.$$

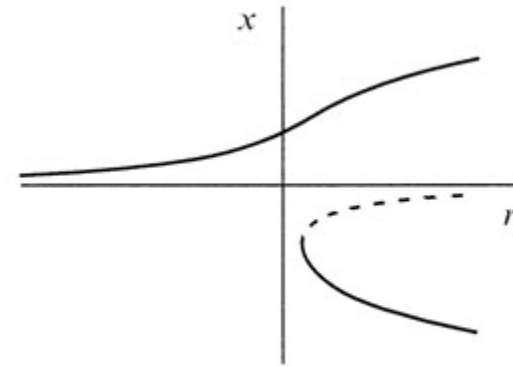


Imperfect Bifurcations

- The bifurcation diagram of X^* vs. r , for fixed h



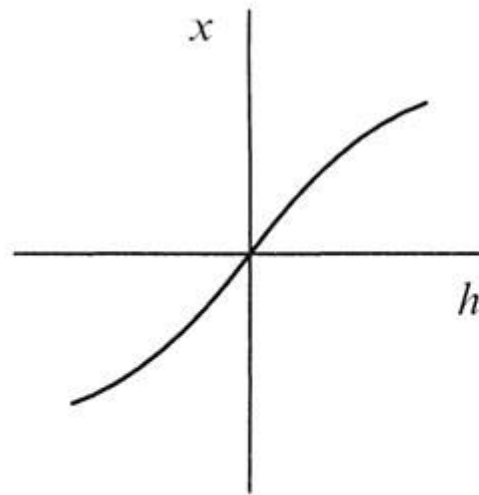
(a) $h = 0$



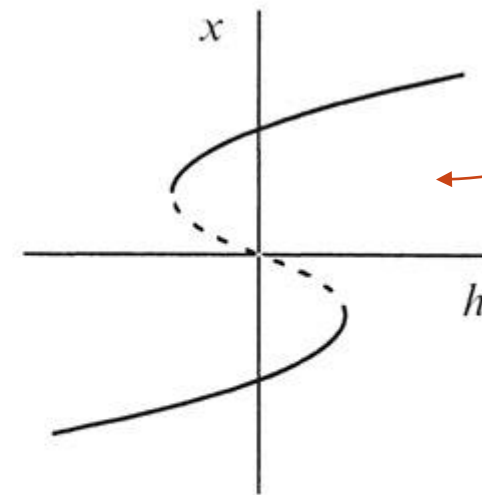
(b) $h \neq 0$

Imperfect Bifurcations

- ▶ The bifurcation diagram of x^* vs. h , for fixed r



(a) $r \leq 0$



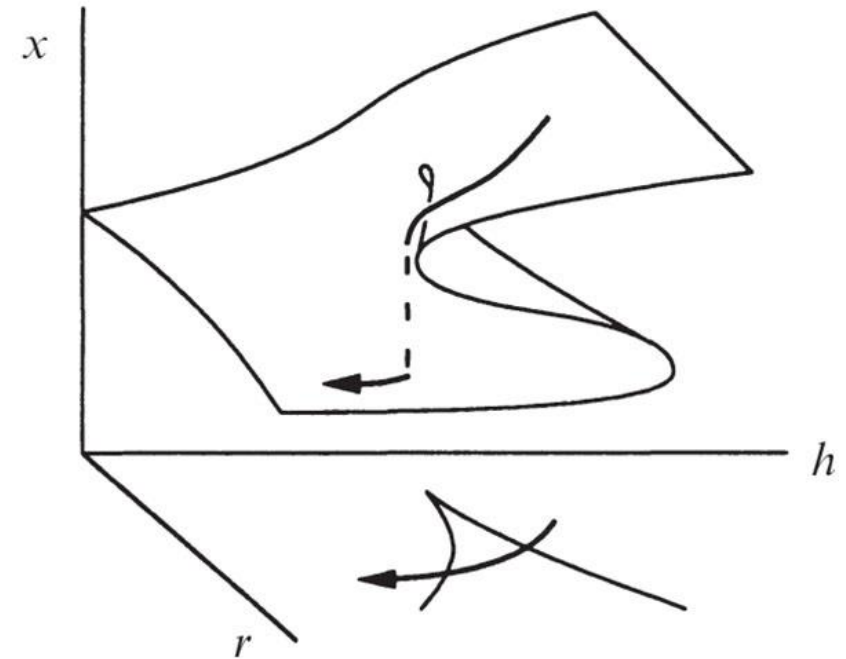
(b) $r > 0$

Hysteresis

Imperfect Bifurcations

- If we plot the fixed points X^* above the (r, h) plane, we get the **cusp catastrophe surface**.

The term **catastrophe** is motivated by the fact that as parameters change, the state of the system can be carried over the edge of the upper surface, after which it drops **discontinuously** to the lower surface.

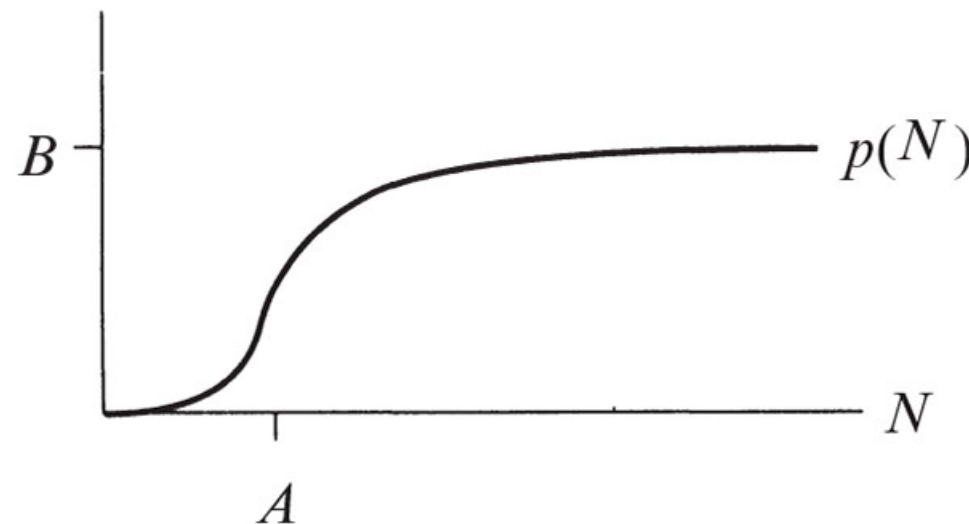


Insect Outbreak

- The proposed model for the budworm population dynamics is

$$\dot{N} = RN \left(1 - \frac{N}{K} \right) - \frac{BN^2}{A^2 + N^2}.$$

The term $p(N)$ represents the **death rate** due to predation.



$$p(N) = \frac{BN^2}{A^2 + N^2}$$

Insect Outbreak

- To get rid of the parameters:

$$x = N/A, \quad \longrightarrow \quad \frac{A}{B} \frac{dx}{dt} = \frac{R}{B} Ax \left(1 - \frac{Ax}{K} \right) - \frac{x^2}{1+x^2}.$$

Then

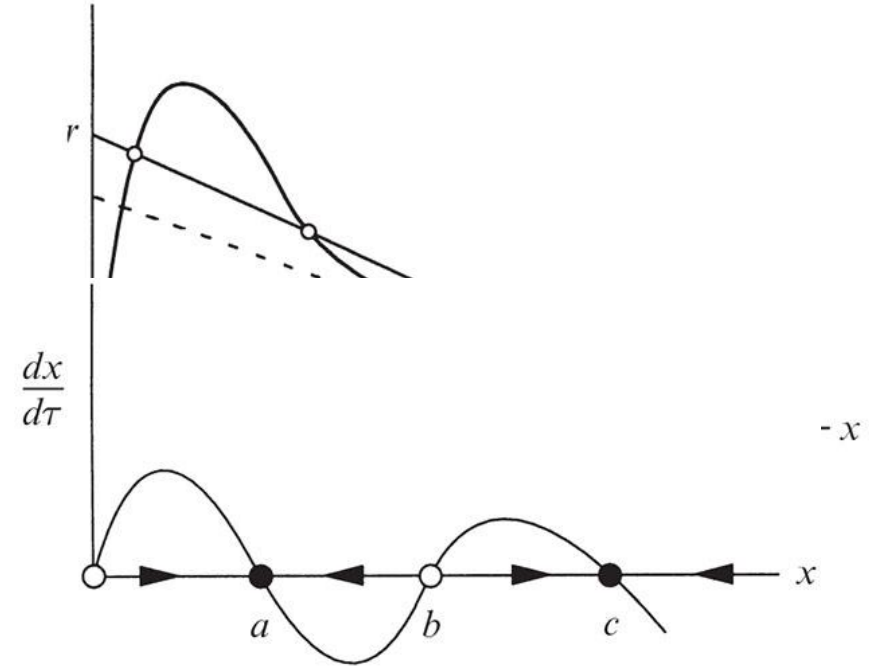
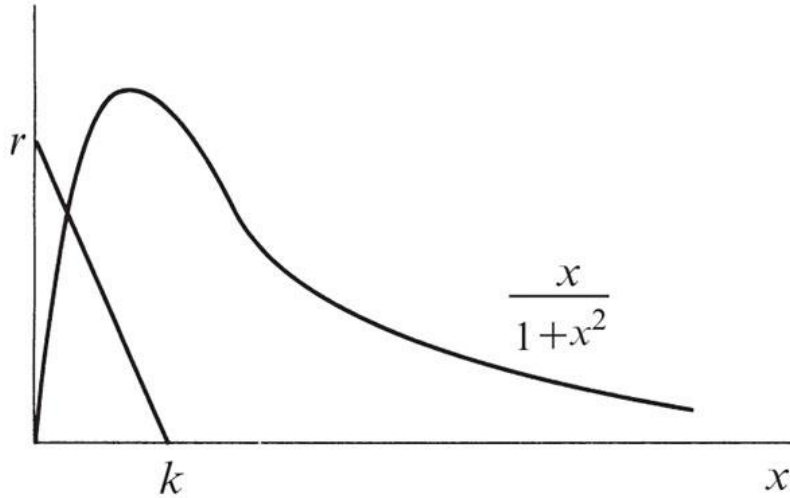
$$\tau = \frac{Bt}{A}, \quad r = \frac{RA}{B}, \quad k = \frac{K}{A}.$$

And finally

$$\frac{dx}{d\tau} = rx \left(1 - \frac{x}{k} \right) - \frac{x^2}{1+x^2},$$

Insect Outbreak

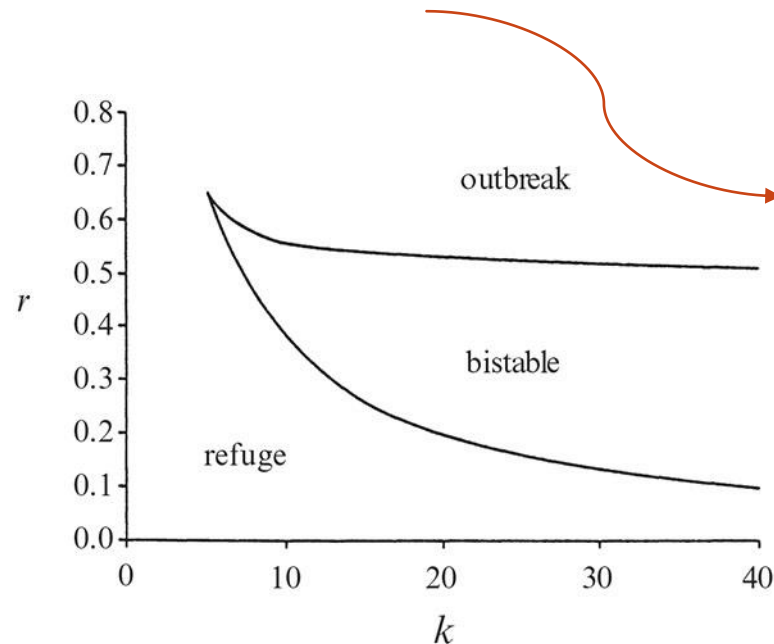
$$r\left(1 - \frac{x}{k}\right) = \frac{x}{1+x^2}.$$



Insect Outbreak

Calculating the Bifurcation Curves

$$r\left(1 - \frac{x}{k}\right) = \frac{x}{1+x^2} \longrightarrow \frac{d}{dx}\left[r\left(1 - \frac{x}{k}\right)\right] = \frac{d}{dx}\left[\frac{x}{1+x^2}\right] \longrightarrow -\frac{r}{k} = \frac{1-x^2}{(1+x^2)^2}.$$



$$r = \frac{2x^3}{(1+x^2)^2}.$$

$$k = \frac{2x^3}{x^2 - 1}.$$

Insect Outbreak

► Calculating the Bifurcation Curves

The **refuge** level a is the only stable state for low r , and the **outbreak** level c is the only stable state for large r . In the **bistable** region, both stable states exist.

