# PART 7 Ordinary Differential Equations ODEs

Part 7

 Equations which are composed of an unknown function and its derivatives are called differential equations.

$$\frac{dv}{dt} = g - \frac{c}{m}v$$

*v* - dependent variable

*t* - independent variable

 Differential equations play a fundamental role in engineering because many physical phenomena are best formulated mathematically in terms of their rate of change.

• When a function involves one dependent variable, the equation is called an ordinary differential equation (ODE).

•A partial differential equation (PDE) involves two or more independent variables.

# Differential equations are also classified as to their order:

1. A first order equation includes a first derivative as its highest derivative.

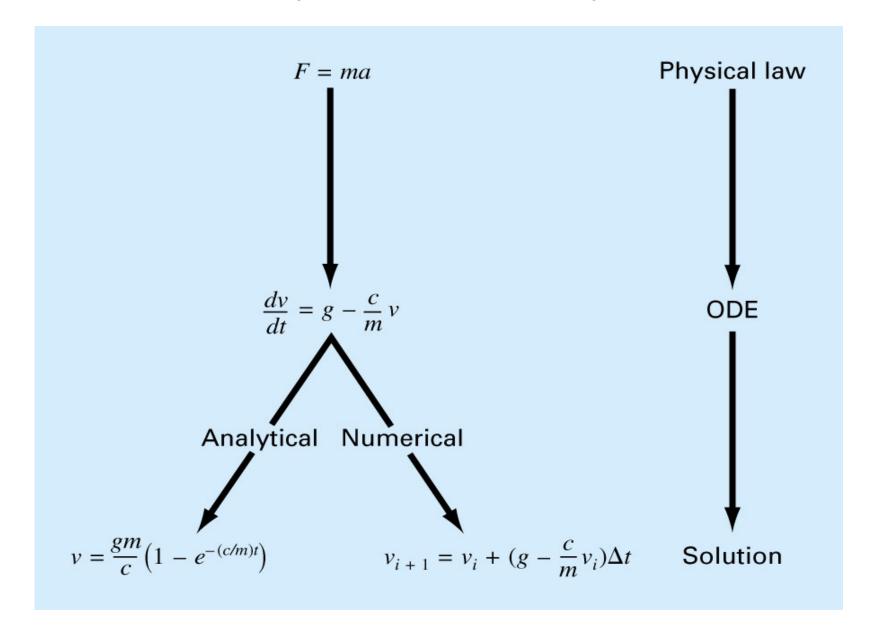
- Linear 1<sup>st</sup> order ODE 
$$\frac{dy}{dx} + \alpha \cdot y = f(x)$$

- Non-Linear 1<sup>st</sup> order ODE 
$$\frac{dy}{dx} = f(x, y)$$
  
Where  $f(x,y)$  is nonlinear

- 2. A second order equation includes a second derivative.
- Linear 2<sup>nd</sup> order ODE  $\frac{d^2y}{dx^2} + p\frac{dy}{dx} + Qy = f(x)$
- Non-Linear 2nd order ODE

$$\frac{d^2y}{dx^2} + p(x, y)\frac{dy}{dx} + Q(x, y) \cdot y = f(x)$$

 Higher order equations can be reduced to a system of first order equations, by redefining a variable.



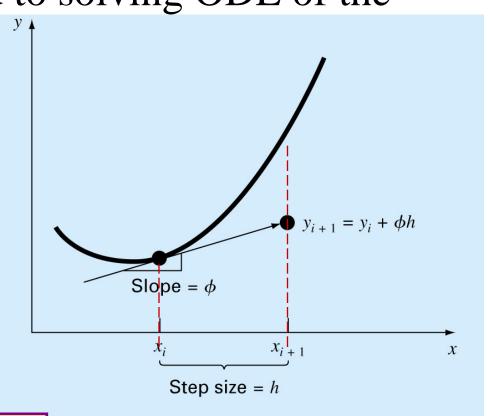
This chapter is devoted to solving ODE of the

form:

$$\frac{dy}{dx} = f(x, y)$$

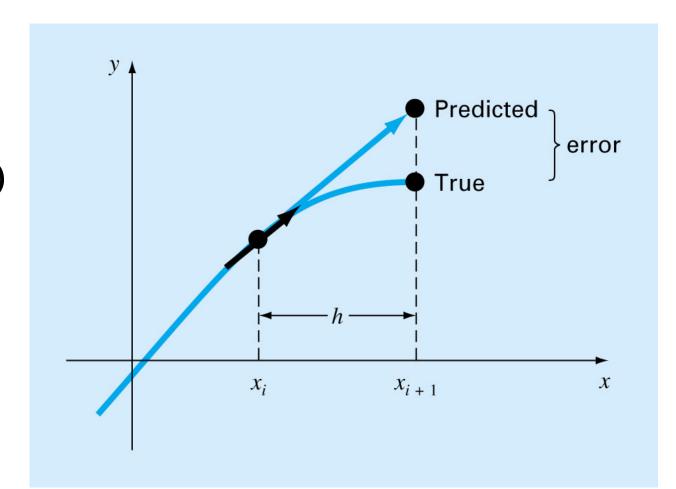
Euler's Method

$$\frac{dy}{dx} = f(x, y)$$
solution



$$y_{i+1} = y_i + f(x_i, y_i) \cdot h$$

$$\frac{dy}{dx} = f(x, y)$$



$$y_{i+1} = y_i + f(x_i, y_i) \cdot h$$

# Euler's Method: Example

Obtain a solution between x = 0 to x = 4

with a step size of 0.5 for: 
$$\frac{dy}{dx} = -2x^3 + 12x^2 - 20x + 8.5$$

Initial conditions are: x = 0 to y = 1

Solution: 
$$y_{i+1} = y_i + f(x_i, y_i) \cdot h$$

$$y(0.5) = y(0) + f(0,1).(0.5)$$

$$= 1.0 + 8.5 \times 0.5 = 5.25$$

$$y(1.0) = y(0.5) + f(0.5,5.25).(0.5)$$

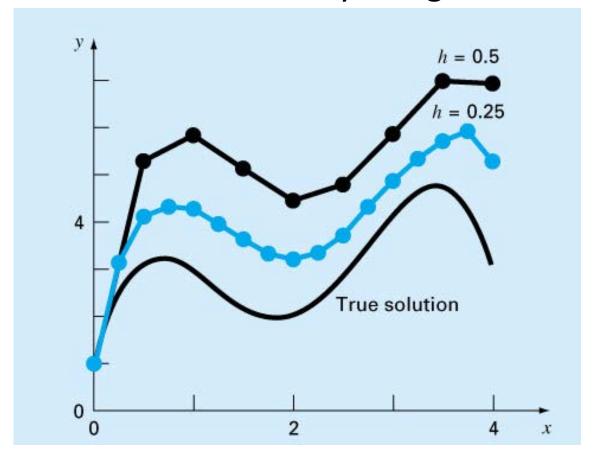
$$= 5.25 + (-2(0.5)^3 + 12(0.5)^2 - 20(0.5) + 8.5).(0.5) = 5.875$$

$$y(20) = y(1.0) + f(1.0,5.875).(0.5)$$

$$= 5.25 + (-2(1.0)^3 + 12(1.0)^2 - 20(1.0) + 8.5).(0.5) = 5.125$$

#### Euler's Method: Example

- Although the computation captures the general trend solution, the error is considerable.
- This error can be reduced by using a smaller step size.



# Improvements of Euler's method

 A fundamental source of error in Euler's method is that the derivative at the beginning of the interval is assumed to apply across the entire interval.

- Simple modifications are available:
  - Heun's Method
  - The Midpoint Method
  - Ralston's Method

 Runge-Kutta methods achieve the accuracy of a Taylor series approach without requiring the calculation of higher derivatives.

$$y_{i+1} = y_i + \phi(x_i, y_i, h)h$$

$$\phi = a_1k_1 + a_2k_2 + \dots + a_nk_n$$
(representative slope
$$a's = \text{constants}$$

$$k_1 = f(x_i, y_i)$$

$$k_2 = f(x_i + p_1h, y_i + q_{11}k_1h)$$

$$k_3 = f(x_i + p_3h, y_i + q_{21}k_1h + q_{22}k_2h)$$

$$\vdots$$

$$k_n = f(x_i + p_{n-1}h, y_i + q_{n-1}k_1h + q_{n-1,2}k_2h + \dots + q_{n-1,n-1}k_{n-1}h)$$

$$p's \text{ and } q's \text{ are constants}$$

- Various types of RK methods can be devised by employing different number of terms in the increment function as specified by n.
- **1.** First order RK method with n=1 is Euler's method.
  - Error is proportional to O(h)
- 2. Second order RK methods:
  - Error is proportional to O(h<sup>2</sup>)

$$y_{i+1} = y_i + (a_1k_1 + a_2k_2)h$$

$$k_1 = f(x_i, y_i)$$

$$k_2 = f(x_i + p_1h, y_i + q_{11}k_1h)$$

 Values of a<sub>1</sub>, a<sub>2</sub>, p<sub>1</sub>, and q<sub>11</sub> are evaluated by setting the second order equation to Taylor series expansion to the second order term.

• Three equations to evaluate the four unknown constants are derived:

$$a_1 + a_2 = 1$$

$$a_2 p_1 = \frac{1}{2}$$

$$a_2 q_{11} = \frac{1}{2}$$

 $a_1 + a_2 = 1$   $a_2 p_1 = \frac{1}{2}$ A value is assumed for one of the unknowns to solve for the other three.

$$a_1 + a_2 = 1$$
,  $a_2 p_1 = \frac{1}{2}$ ,  $a_2 q_{11} = \frac{1}{2}$ 

- We can choose an infinite number of values for  $a_2$ , there are an infinite number of second-order RK methods.
- Every version would yield exactly **the same results** if the solution to ODE were **quadratic**, **linear**, or **a constant**.
- However, they yield different results if the solution is more complicated (typically the case).

#### Three of the most commonly used methods are:

$$y_{i+1} = y_i + (a_1k_1 + a_2k_2)h$$
  $k_1 = f(x_i, y_i)$ 

• Huen Method with a Single Corrector  $(a_2=1/2)$ 

$$y_{i+1} = y_i + (\frac{1}{2}k_1 + \frac{1}{2}k_2) \cdot h \quad k_2 = f((x_i + h), (y_i + k_1 h))$$

• The Midpoint Method  $(a_2 = 1)$ 

$$y_{i+1} = y_i + k_2 \cdot h$$
  $k_2 = f(x_i + \frac{1}{2}h, y_i + \frac{1}{2}k_1h)$ 

• Raltson's Method  $(a_2 = 2/3)$ 

$$y_{i+1} = y_i + (\frac{1}{3}k_1 + \frac{2}{3}k_2) \cdot h$$

$$k_2 = f(x_i + \frac{3}{4}h, y_i + \frac{3}{4}k_1h)$$

$$k_2 = f(x_i + \frac{3}{4}h, y_i + \frac{3}{4}k_Ih)$$

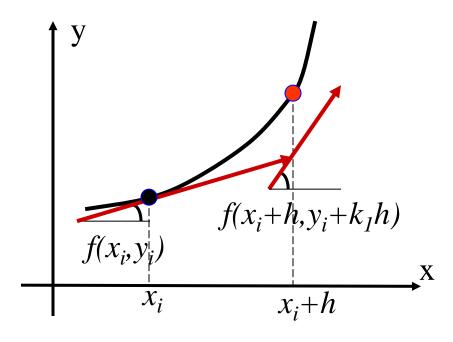
#### Heun's Method:

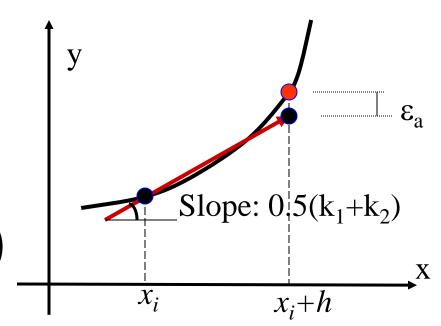
Involves the determination of two derivatives for the interval at the initial point and the end point.

$$y_{i+1} = y_i + (\frac{1}{2}k_1 + \frac{1}{2}k_2) \cdot h$$

$$k_1 = f(x_i, y_i)$$
  

$$k_2 = f((x_i + h), (y_i + k_l h))$$





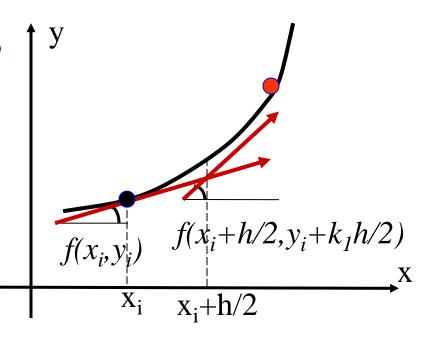
#### • Midpoint Method:

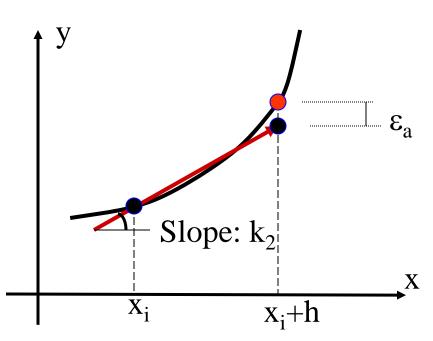
Uses Euler's method to predict a value of y at the midpoint of the interval:

$$y_{i+1} = y_i + k_2 \cdot h$$

$$k_i = f(x_i, y_i)$$

$$k_2 = f(x_i + \frac{1}{2}h, y_i + \frac{1}{2}k_1h)$$



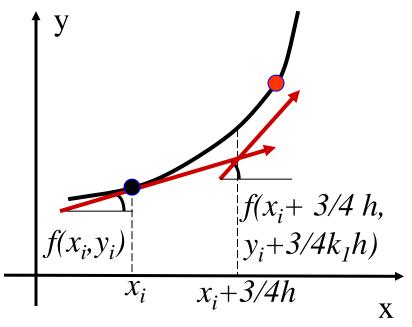


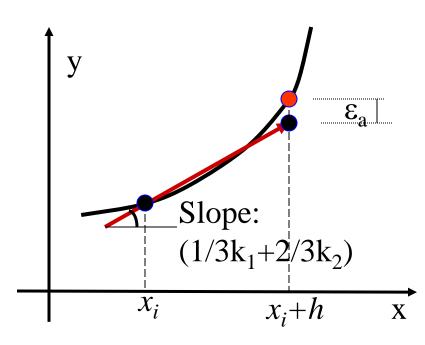
#### • Ralston's Method:

$$y_{i+1} = y_i + (\frac{1}{3}k_1 + \frac{2}{3}k_2) \cdot h$$

$$k_1 = f(x_i, y_i)$$

$$k_2 = f(x_i + \frac{3}{4}h, y_i + \frac{3}{4}k_Ih)$$





#### EXAMPLE 25.6 Comparison of Various Second-Order RK Schemes

Problem Statement. Use the midpoint method [Eq. (25.37)] and Ralston's method [Eq. (25.38)] to numerically integrate Eq. (PT7.13)

$$f(x, y) = -2x^3 + 12x^2 - 20x + 8.5$$

from x = 0 to x = 4 using a step size of 0.5. The initial condition at x = 0 is y = 1. Compare the results with the values obtained using another second-order RK algorithm, that is, the Heun method

Solution. The first step in the midpoint method is to use Eq. (25.37a) to compute

$$k_1 = -2(0)^3 + 12(0)^2 - 20(0) + 8.5 = 8.5$$

However, because the ODE is a function of x only, this result has no bearing on the second step—the use of Eq. (25.37b) to compute

$$k_2 = -2(0.25)^3 + 12(0.25)^2 - 20(0.25) + 8.5 = 4.21875$$

Notice that this estimate of the slope is much closer to the average value for the interval (4.4375) than the slope at the beginning of the interval (8.5) that would have been used for Euler's approach. The slope at the midpoint can then be substituted into Eq. (25.37) to predict

$$y(0.5) = 1 + 4.21875(0.5) = 3.109375$$
  $\varepsilon_t = 3.4\%$ 

The computation is repeated, and the results are summarized in Fig. 25.14 and Table 25.3.

For Ralston's method,  $k_1$  for the first interval also equals 8.5 and [Eq. (25.38b)]

$$k_2 = -2(0.375)^3 + 12(0.375)^2 - 20(0.375) + 8.5 = 2.58203125$$

The average slope is computed by

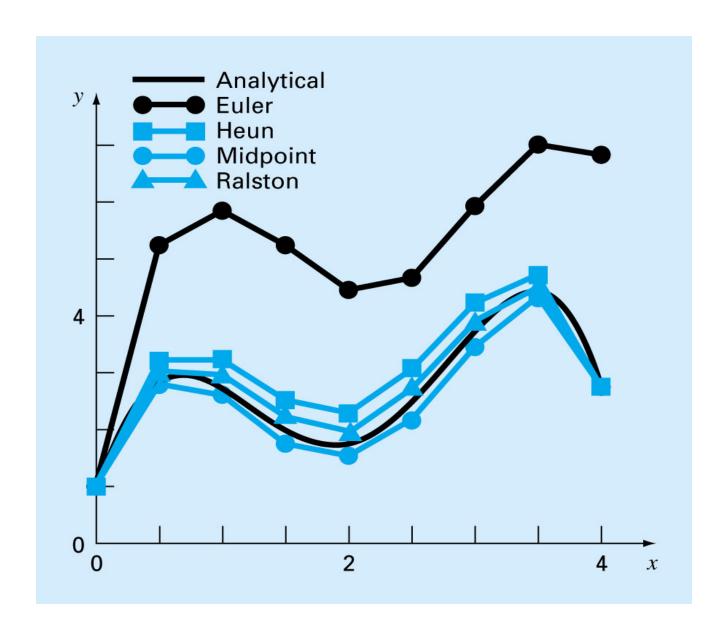
$$\phi = \frac{1}{3}(8.5) + \frac{2}{3}(2.58203125) = 4.5546875$$

which can be used to predict

$$y(0.5) = 1 + 4.5546875(0.5) = 3.27734375$$
  $\varepsilon_t = -1.82\%$ 

The computation is repeated, and the results are summarized in Fig. 25.14 and Table 25.3 Notice how all the second-order RK methods are superior to Euler's method.

x	Ytrue	Heun		Midpoint		Second-Order Ralston RK	
		y	lε, I (%)	y	18,1 (%)	y	lest
0.0	1.00000	1.00000	0	1.00000	0	1.00000	N
0.5	3.21875	3.43750	6.8	3.109375	3.4	3.277344	100
1.0	3.00000	3.37500	12.5	2.81250	6.3	3.101563	7.0
1.5	2.21875	2.68750	2}.1	1.984375	10.6	2.347656	4 0
2.0	2.00000	2.50000	25.0	1.75	12.5	2.140625	20
2.5	2.71875	3.18750	17.2	2.484375	8.6	2.855469	50
3.0	4.00000	4.37500	9.4	3.81250	4.7	4.117188	20
3.5	4.71875	4.93750	4.6	4.609375	2.3	4.800781	1.7
4.0	3.00000	3.00000	0	3	0	3.031250	1.0



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#### 3. Third order RK methods

$$y_{i+1} = y_i + \frac{1}{6}(k_1 + 4k_2 + k_3)h$$

$$k_{1} = f(x_{i}, y_{i})$$

$$k_{2} = f(x_{i} + \frac{1}{2}h, y_{i} + \frac{1}{2}k_{1}h)$$

$$k_{3} = f(x_{i} + h, y_{i} - k_{1}h + 2k_{2}h)$$

#### 4. Fourth order RK methods

$$y_{i+1} = y_i + \frac{1}{6}(k_1 + 2k_2 + 2k_3 + k_4)h$$

where

$$k_{1} = f(x_{i}, y_{i})$$

$$k_{2} = f(x_{i} + \frac{1}{2}h, y_{i} + \frac{1}{2}k_{1}h)$$

$$k_{3} = f(x_{i} + \frac{1}{2}h, y_{i} + \frac{1}{2}k_{2}h)$$

$$k_{3} = f(x_{i} + h, y_{i} + k_{3}h)$$

#### Comparison of Runge-Kutta Methods

Use first to fourth order RK methods to solve the equation from x = 0 to x = 4

Initial condition y(0) = 2, exact answer of y(4) = 75.33896

$$f(x, y) = 4e^{0.8x} - 0.5y$$