# Digital Signal Processing

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## Part I

Discrete Fourier Transform (DFT)



## Comparison of DFT and DTFT

- **DTFT:** infinite, aperiodic, discrete signals x[n]
- DTFT output: continuous, complex, periodic spectrum  $X(e^{j\omega})$  (period  $2\pi$ )
- **DFT:** infinite, periodic, discrete signals  $\tilde{x}[n]$
- In practice: the computation is performed on a single period x[n] (of duration N samples) of the periodic signal  $\tilde{x}[n]$
- DFT output: discete, complex, periodic spectrum  $\tilde{X}[k]$  (period N)
- In practice: only single period X[k] (N-point DFT) of the periodic spectrum  $\tilde{X}[k]$  is computed
- The values of the *DFT spectrum* can be obtained by sampling of DTFT spectrum at frequencies  $\omega = \frac{2\pi k}{N}, k = 0, 1, \dots N-1$
- The distance between frequency samples  $\Delta \omega = \frac{2\pi}{N}$  is called frequency resolution



# DFT properties I

• **Linearity:** Let signals  $x_1[n]$  and  $x_2[n]$  have spectrum  $X_1[k]$  and  $X_2[k]$ . Then it holds

$$ax_1[n] + bx_2[n] \stackrel{DFT}{\Longleftrightarrow} aX_1[k] + bX_2[k] \tag{1}$$

- Sequences must have equal duration, if not, the shorter one is zero-padded
- **Symmetry:** If  $x[n] \in \mathcal{R}$ , then X[k] is conjugate symmetric:

$$X[k] = X^*[-k] = X^*[N-k]_N$$
 (2)

• If x[n] is imaginary, then X[k] is conjugate antisymmetric:

$$X[k] = -X^*[-k] = -X^*[N-k]_N$$
 (3)

• EXAMPLE: DFT symmetry



## DFT properties II

#### Simplified notation:

$$W_N \stackrel{\text{def.}}{=} e^{-j2\pi/N} \tag{4}$$

$$W_N^{nk} \stackrel{\text{def.}}{=} e^{-j2\pi kn/N} \tag{5}$$

• Circular shift: Circular shift by  $n_0$  samples is defined by

$$(x[n-n_0])_N R_N[n] = \tilde{x}[n-n_0] R_N[n]$$
 (6)

where  $R_N[n]$  is rectangular window of length N

- EXAMPLE: Circular shift
- Circular shift in the time domain causes in the frequency domain a change of the phase spectrum

$$(x[n-n_0])_N R_N[n] \stackrel{DFT}{\Longleftrightarrow} W_N^{n_0k} X[k]$$



### DFT properties III

• Circular convolution: Let x[n] and h[n] be two finite sequences with N-point DFTs X[k] and H[k], then sequence with DFT equal to Y[k] = H[k]X[k] is given by a formula

$$y[n] = x[n] \circledast h[n] = \left[ \sum_{k=0}^{N-1} h[k] \tilde{x}[n-k] \right] R_N[n]$$
 (8)

- This is a convolution of h[n] with periodical  $\tilde{x}[n]$ , evaluated using only single period of  $\tilde{x}[n]$
- Circular convolution is generally not equal to linear convolution (filtering), even lengths of these two operations differ.
- Using suitable zero-padding, both operations coincide (give the same result).
- Then, the circular convolution can be used for fact computation of linear convolution (using Fast Fourier Transform - FFT)



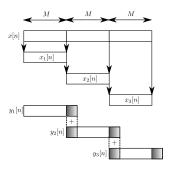
## Computation of linear convolution via the circular one

- DFT and circular convolution can be used for effective computation of linear convolution
- Having two finite sequences h[n] and x[n] with lengths  $N_1$  and  $N_2$ , respectively, the linear convolution can be computed as follows:
  - **1** Zero-padding of h[n] and x[n] to length  $N \ge N_1 + N_2 1$
  - **2** Computation of *N*-point DFT of sequences h[n] and x[n]
  - **3** Multiplication Y[k] = H[k]X[k]
  - 4 Inverse DFT of Y[k]
- This procedure becomes much less computationally demanding then the definition formula of convolution, when FFT is used to compute the DFT.
- Unlike the definition formula, this procedure is not suitable for very long sequences x[n]
  - It requires the knowledge of the whole x[n] (which disables real-time processing)
  - h[n] is usually much shorter than x[n] (a lot of zero-padding)
- These negatives are mitigated using block-wise computation of convolution



# Overlap-Add (Block-wise processing)

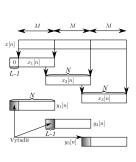
- Overlap-Add (OA,OLA) is an efficient approach to compute convolution of a long signal x[n] with impulse response of a FIR filter h[n] (length L)
  - Signal x[n] is split to non-overlapping sequences  $x_i[n]$  of length M
  - Output signal y[n] can be expressed as a sum of partial convolutions  $y_i[n] = x_i[n] * h[n]$
  - The partial convolutions  $y_i[n]$  have lengths N = L + M 1 and are added with shift M (L 1 samples of  $y_i[n]$  and  $y_{i-1}[n]$  thus overlap)
  - Computation of y<sub>i</sub>[n] is performed via zero-padded circular convolution using FFT





# Overlap-Save (Block-wise processing)

- Overlap-Save: is an alternative to Overlap-Add, it efficiently computes convolution of a long signal x[n] with impulse response of a FIR filter h[n] (length L)
- x[n] is split (with overlap of L-1 samples) into subsequences  $x_i[n]$  of length N
- Overlap-Save computes the classing convolution via suitable concatenation of parts of circular convolutions involving subsequences x<sub>i</sub>[n].
- PRINCIPLE: Considering the circular convolution  $x_1[n]@h[n]$ , the first L-1 samples differ from  $x_1[n]*h[n]$ , the remaining M=N-L+1 samples are equal.
- These M samples constitute one interval of the output y[n]



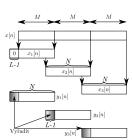


# Overlap-Save II - Algorithm

**1** Formation of the sequence  $x_1[n]$ 

$$x_1[n] = \begin{cases} 0 & 0 \le n < L - 1 \\ x[n - L + 1] & L - 1 \le n \le N - 1 \end{cases}$$
 (9)

- ② Computation of  $x_1[n]@h[n]$  using DFT. L-1 samples differ from linear convolution. Last M=N-L+1 values of  $x_1[n]@h[n]$  are the first samples of y[n]
- **3** Formation of subsequence  $x_2[n]$ , where first L-1 samples overlap with the last samples of  $x_1[n]$
- **③** Computation of  $x_2[n]$ ®h[n] using DFT. L-1 samples differ from the linear convolution. Last M=N-L+1 values form the second interval of y[n]
- Steps 3. and 4. are repeated until the whole linear convolution is evaluated





# Part II

Fast Fourier Transform (FFT)



### Fast Fourier Transform

- Fast Fourier Transform is a group of algorithms allowing optimized computation of DFT and IDFT
- DFT transforms finite (or infinite periodic) sequence of time-domain samples into finite sequence of frequency components
- Computational complexity od DFT computed by definition is  $O(N^2)$
- FFT is able to compute the same result in O(N log(N)) operations
- ullet The difference in computational complexity becomes apparent for growing N
- Due to FFT, the DFT algorithm is used into many scientific areas (signal processing, image processing, solution of differential equations etc.)



### Fast Fourier Transform II

- Many FFT algorithms stem from factorization of the sample number N
- The *N*-point DFT of x[n] is computed via several transforms applied to subsequences of x[n]
- However, even implementations suitable for prime N have been discovered
- The FFT algorithm can easily compute the IDFT (which differs by a sign in the exponent and normalization)
- Comparison of FFT and DFT:
- Evaluation of DFT by definition requires  $N^2$  complex multiplications and N(N-1) complex summations
- The most famous FFT version radix-2 Cooley-Tukey is suitable for N equals power of 2
- It requires  $(N/2)\log_2(N)$  complex multiplications and  $N\log_2(N)$  complex summations



### Fast Fourier Transform III

- Radix-2 Cooley-Tukey FFT: Algorithm designed for sequences of length  $N = 2^k$ ,  $k \in \mathcal{Z}$
- Computational savings are achieved due to periodicity of the complex exponentials and the possibility to compute N-point DFT using two N/2-point DFTs
- The algorithm is recursive but can be computed non-recursively, if the input samples are suitably permuted
- Details: Radix-2 Cooley-Tukey FFT



# Thank you for attention!

