Chapter 4: Classification & Prediction

- 4.1 Basic Concepts of Classification and Prediction
- 4.2 Decision Tree Induction
 - 4.2.1 The Algorithm
 - 4.2.2 Attribute Selection Measures
 - 4.2.3 Tree Pruning
 - 4.2.4 Scalability and Decision Tree Induction
- 4.3 Bayes Classification Methods
 - 2.3.1 Naïve Bayesian Classification
 - 2.3.2 Note on Bayesian Belief Networks
- 4.4 Rule Based Classification
- 4.5 Lazy Learners
- ▶ 4.6 Prediction
- 4.7 How to Evaluate and Improve Classification

4.3 Bayes Classification Methods

What are Bayesian Classifiers?

- → Statistical classifiers
- Predict class membership probabilities: probability of a given tuple belonging to a particular class
- → Based on Bayes' Theorem

Characteristics?

 Comparable performance with decision tree and selected neural network classifiers

Bayesian Classifiers

- → Naïve Bayesian Classifiers
 - Assume independency between the effect of a given attribute on a given class and the other values of other attributes
- → Bayesian Belief Networks
 - Graphical models
 - Allow the representation of dependencies among subsets of attributes

- X is a data tuple. In Bayesian term it is considered "evidence"
- ▶ H is some hypothesis that X belongs to a specified class C

$$P(H \mid X) = \frac{P(X \mid H)P(H)}{P(X)}$$

- P(H|X) is the posterior probability of H conditioned on X
 Example: predict whether a costumer will buy a computer or not
 - → Costumers are described by two attributes: **age** and **income**
 - → X is a 35 years-old costumer with an income of 40k
 - → **H** is the hypothesis that the costumer will buy a computer
 - → P(H|X) reflects the probability that costumer X will buy a computer given that we know the costumers' age and income

- X is a data tuple. In Bayesian term it is considered "evidence"
- H is some hypothesis that X belongs to a specified class C

$$P(H \mid X) = \frac{P(X \mid H)P(H)}{P(X)}$$

- P(X|H) is the posterior probability of X conditioned on H
 Example: predict whether a costumer will buy a computer or not
 - → Costumers are described by two attributes: age and income
 - → X is a 35 years-old costumer with an income of 40k
 - → **H** is the hypothesis that the costumer will buy a computer
 - → P(X | H) reflects the probability that costumer X, is 35 years-old and earns 40k, given that we know that the costumer will buy a computer

- X is a data tuple. In Bayesian term it is considered "evidence"
- H is some hypothesis that X belongs to a specified class C

$$P(H \mid X) = \frac{P(X \mid H)P(H)}{P(X)}$$

P(H) is the prior probability of H

Example: predict whether a costumer will buy a computer or not

- → **H** is the hypothesis that the costumer will buy a computer
- → The prior probability of H is the probability that a costumer will buy a computer, regardless of age, income, or any other information for that matter
- → The posterior probability P(H|X) is based on more information than the prior probability P(H) which is independent from X

- X is a data tuple. In Bayesian term it is considered "evidence"
- H is some hypothesis that X belongs to a specified class C

$$P(H \mid X) = \frac{P(X \mid H)P(H)}{P(X)}$$

P(X) is the prior probability of X

Example: predict whether a costumer will buy a computer or not

- → Costumers are described by two attributes: **age** and **income**
- → X is a 35 years-old costumer with an income of 40k
- → **P(X)** is the probability that a person from our set of costumers is 35 years-old and earns 40k

Naïve Bayesian Classification

D: A training set of tuples and their associated class labels Each tuple is represented by n-dimensional vector $X(x_1,...,x_n)$, n measurements of n attributes $A_1,...,A_n$

Classes: suppose there are m classes $C_1,...,C_m$

Principle

- Given a tuple X, the classifier will predict that X belongs to the class having the **highest posterior probability** conditioned on X
- Predict that tuple X belongs to the class C_i if and only if

$$P(C_i \mid X) > P(C_j \mid X)$$
 for $1 \le j \le m, j \ne i$

Maximize P(C_i | X): find the maximum posteriori hypothesis

$$P(C_i \mid X) = \frac{P(X \mid C_i)P(C_i)}{P(X)}$$

P(X) is constant for all classes, thus, maximize P(X | C_i)P(C_i)

Naïve Bayesian Classification

- To maximize P(X | Ci)P(Ci), we need to know class prior probabilities
 - → If the probabilities are not known, assume that $P(C_1)=P(C_2)=...=P$ (C_m) \Rightarrow maximize $P(X | C_i)$
 - \rightarrow Class prior probabilities can be estimated by $P(C_i) = |C_{i,D}|/|D|$
- Assume Class Conditional Independence to reduce computational cost of P(X | C_i)
 - \rightarrow given $X(x_1,...,x_n)$, $P(X \mid C_i)$ is:

$$P(X \mid C_i) = \prod_{k=1}^n P(x_k \mid C_i)$$

$$= P(x_1 \mid C_i) \times P(x_2 \mid C_i) \times ... \times P(x_n \mid C_i)$$

→ The probabilities $P(x_1 | C_i)$, ... $P(x_n | C_i)$ can be estimated from the training tuples

Estimating $P(x_i | C_i)$

Categorical Attributes

- \rightarrow Recall that $\mathbf{x_k}$ refers to the value of attribute A_k for tuple X
- \rightarrow X is of the form $X(x_1,...,x_n)$
- \rightarrow **P**($\mathbf{x_k} | \mathbf{C_i}$) is the number of tuples of class $\mathbf{C_i}$ in D having the value $\mathbf{x_k}$ for $\mathbf{A_k}$, divided by $|\mathbf{C_{i,D}}|$, the number of tuples of class $\mathbf{C_i}$ in D
- → Example
 - 8 costumers in class C_{ves} (costumer will buy a computer)
 - 3 costumers among the 8 costumers have high income
 - P(income=high | C_{yes}) the probability of a costumer having a high income knowing that he belongs to class C_{yes} is 3/8

Continuous-Valued Attributes

 \rightarrow A continuous-valued attribute is assumed to have a **Gaussian** (Normal) distribution with mean μ and standard deviation σ

$$g(x,\mu,\sigma) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$$

Estimating $P(x_i | C_i)$

Continuous-Valued Attributes

 \rightarrow The probability $P(x_k | C_i)$ is given by:

$$P(x_k \mid C_i) = g(x_k, \mu_{Ci}, \sigma_{Ci})$$

 \rightarrow Estimate μ_{Ci} and σ_{Ci} the mean and standard variation of the values of attribute A_k for training tuples of class C_i

→ Example

- X a 35 years-old costumer with an income of 40k (age, income)
- Assume the age attribute is continuous-valued
- Consider class C_{ves} (the costumer will buy a computer)
- We find that in D, the costumers who will buy a computer are 38 ± 12 years of age $\Rightarrow \mu_{\text{Cves}}$ =38 and σ_{Cves} =12

$$P(age = 35 \mid C_{ves}) = g(35,38,12)$$

RID	age	income	student	credit-rating	class:buy_computer
1	youth	high	no	fair	no
2	youth	high	no	excellent	no
3	middle-aged	high	no	fair	yes
4	senior	medium	no	fair	yes
5	senior	low	yes	fair	yes
6	senior	low	yes	excellent	no
7	middle-aged	low	yes	excellent	yes
8	youth	medium	no	fair	no
9	youth	low	yes	fair	yes
10	senior	medium	yes	fair	yes
11	youth	medium	yes	excellent	yes
12	middle-aged	medium	no	excellent	yes
13	middle-aged	high	yes	fair	yes
14	senior	medium	no	excellent	no

Tuple to classify is

X (age=youth, income=medium, student=yes, credit=fair)

Maximize $P(X | C_i)P(C_i)$, for i=1,2

Given X (age=youth, income=medium, student=yes, credit=fair)

Maximize $P(X | C_i)P(C_i)$, for i=1,2

First step: Compute $P(C_i)$. The prior probability of each class can be computed based on the training tuples:

P(buys_computer=yes)=9/14=0.643

P(buys_computer=no)=5/14=0.357

Second step: compute $P(X \mid C_i)$ using the following conditional prob.

P(age=youth | buys_computer=yes)=0.222

P(age=youth | buys_computer=no)=3/5=0.666

P(income=medium | buys_computer=yes)=0.444

P(income=medium | buys_computer=no)=2/5=0.400

P(student=yes|buys_computer=yes)=6/9=0.667

P(tudent=yes | buys_computer=no)=1/5=0.200

P(credit_rating=fair | buys_computer=yes)=6/9=0.667

P(credit_rating=fair | buys_computer=no)=2/5=0.400

```
P(X | buys_computer=yes) = P(age=youth | buys_computer=yes) x
                           P(income=medium | buys_computer=yes) x
                            P(student=yes|buys_computer=yes) x
                            P(credit_rating=fair | buys_computer=yes)
                          = 0.044
P(X | buys_computer=no) = P(age=youth | buys_computer=no) ×
                           P(income=medium | buys_computer=no) x
                            P(student=yes | buys_computer=no) x
                            P(credit_rating=fair | buys_computer=no)
                            = 0.019
Third step: compute P(X \mid C_i)P(C_i) for each class
P(X \mid buys\_computer=yes)P(buys\_computer=yes)=0.044 \times 0.643=0.028
P(X \mid buys\_computer=no)P(buys\_computer=no)=0.019 \times 0.357=0.007
```

The naïve Bayesian Classifier predicts buys_computer=yes for tuple X

Avoiding the 0-Probability Problem

Naïve Bayesian prediction requires each conditional prob. be non-zero. Otherwise, the predicted prob. will be zero

$$P(X \mid C_i) = \prod_{k=1}^{n} P(x_k \mid C_i)$$

- Ex. Suppose a dataset with 1000 tuples, income=low (0), income=medium (990), and income = high (10),
- Use Laplacian correction (or Laplacian estimator)
 - → Adding 1 to each case

 Prob(income = low) = 1/1003

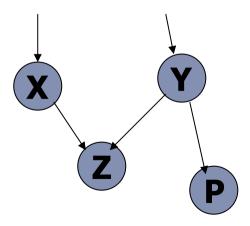
 Prob(income = medium) = 991/1003
 - Prob(income = high) = 11/1003
 - → The "corrected" prob. estimates are close to their "uncorrected" counterparts

Summary of Section 4.3

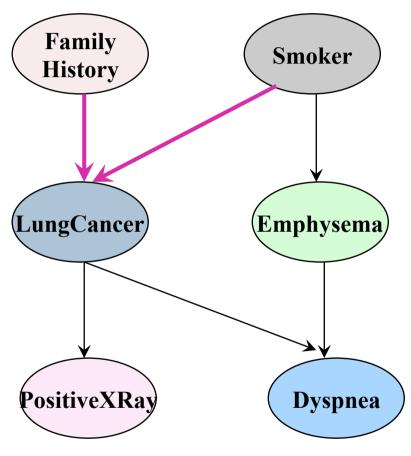
- Advantages
 - → Easy to implement
 - → Good results obtained in most of the cases
- Disadvantages
 - Assumption: class conditional independence, therefore loss of accuracy
 - → Practically, dependencies exist among variables
 - E.g., hospitals: patients: Profile: age, family history, etc.
 - Symptoms: fever, cough etc., Disease: lung cancer, diabetes, etc.
 - Dependencies among these cannot be modeled by Naïve Bayesian Classifier
- How to deal with these dependencies?
 - → Bayesian Belief Networks

4.3.2 Bayesian Belief Networks

- Bayesian belief network allows a subset of the variables conditionally independent
- A graphical model of causal relationships
 - → Represents <u>dependency</u> among the variables
 - → Gives a specification of joint probability distribution



- → Nodes: random variables
- → Links: dependency
- \rightarrow X and Y are the parents of Z, and Y is the parent of P
- → No dependency between Z and P
- → Has no loops or cycles



The **conditional probability table** (**CPT**) for variable LungCancer:

	(FH, S)	(FH, ~S)	(~FH, S)	(~FH, ~S)
LC	0.8	0.5	0.7	0.1
~LC	0.2	0.5	0.3	0.9

CPT shows the conditional probability for each possible combination of its parents

Derivation of the probability of a particular combination of values of **X**, from CPT:

$$P(x_1,...,x_n) = \prod_{i=1}^{n} P(x_i | Parents(Y_i))$$

Training Bayesian Networks

- Several scenarios:
 - Given both the network structure and all variables observable: learn only the CPTs
 - → Network structure known, some hidden variables: gradient descent (greedy hill-climbing) method, analogous to neural network learning
 - Network structure unknown, all variables observable: search through the model space to reconstruct network topology
 - → Unknown structure, all hidden variables: No good algorithms known for this purpose

Summary of Section 4.3

- Bayesian Classifiers are statistical classifiers
- They provide good accuracy
- Naïve Bayesian classifier assumes independency between attributes
- Causal relations are captured by Bayesian Belief Networks