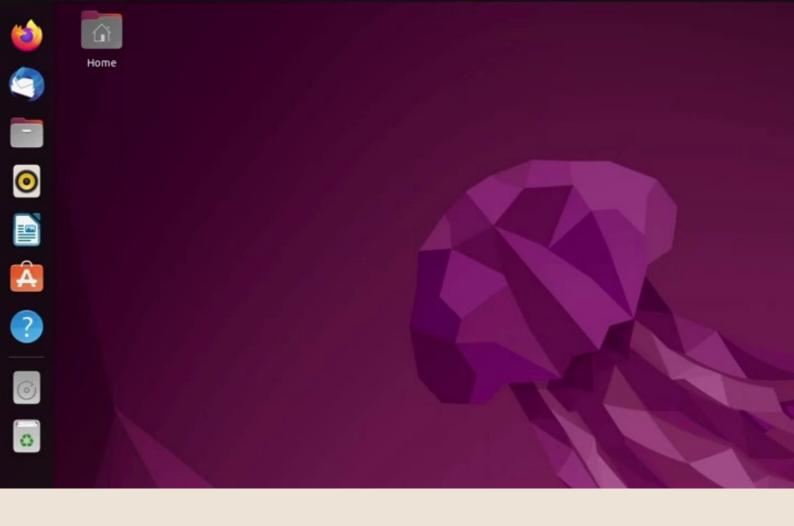
## خطوات تثبیت ROS on Jetson nano

مسار الروبوت والذكاء الاصطناعي

## تنفيذ الطالبات :

صفيه القرشي ، شهد الجعيد



## Steps:

step 1: Install VirtualBox

step 2: Download Ubuntu version 16.04 LTS

step 3: Create a new Virtual Machine for Ros OS

step4: Click on start button then select the Ubuntu

drive & wait for loading to end

step 5: Copy the required commands from Smart Methos web & paste the commands in the Ubuntu

**Terminal**