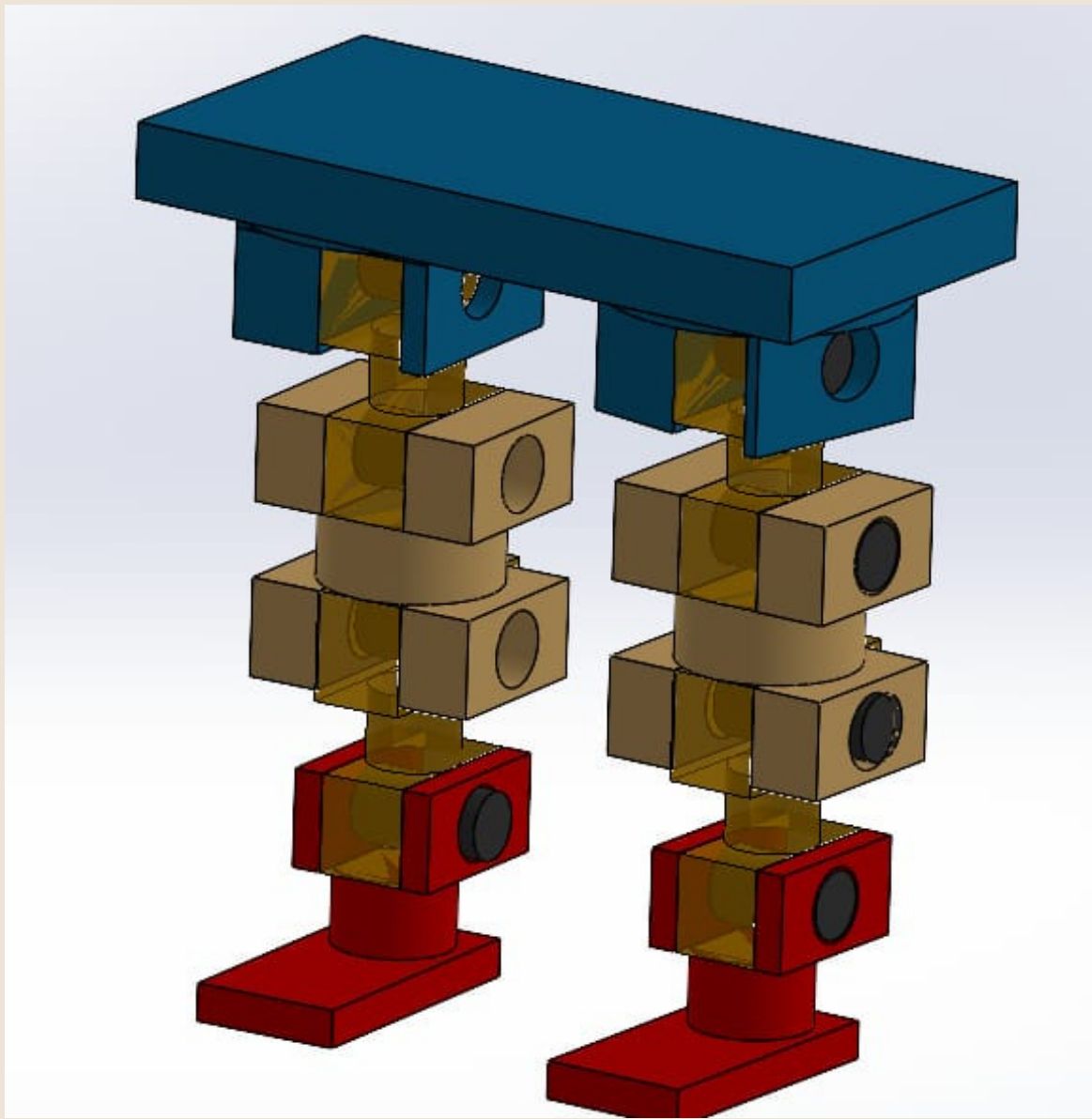


# تصميم أرجل الروبوت باستخدام برامج التصميم الثلثي الأبعاد “Cinema 4D”

مسار الهندسة الميكانيكية

تنفيذ الطالبة :  
صفية القرشي



The legs of the robot are designed using cinema 4D software. As we can see the legs of the robot are flat and rectangular from the bottom, and then the weight is distributed on them evenly using this design shown in the picture. The design facilitates the ease and flexibility of the robot's movement and improves the outward appearance of the way it travels.

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