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## SDA - Sheelo - Exercise 2

Linear Regression Problem.

$$y = XB + \epsilon$$
 with  $\epsilon_1 \sim N(0, \sigma^2)$ 

(I)

LS - estimator: 
$$\hat{\beta} = (X^T \times)^{-1} \times T_y$$

 $(\pi)$ 

Some useful equations / rules grom our lacture:

(III)

$$\hat{\epsilon} = y - \hat{y} = y - X\hat{\beta}$$

(III)

$$H = \times (x^T \times)^{-1} \times^T$$

 $(\pi)$ 

 $(\Pi)$ 

$$\hat{\epsilon} \stackrel{\text{(II)}}{=} y - \hat{y} \stackrel{\text{(III)}}{=} y - Hy = (T_n - H) y$$

(UI)

# 1. Task

Show that E[E] = O.

(1) = E[y] - E[ŷ]

- (1) linearity of expectation
- (2) In sheet 05 we have proven: E[is] = (3

The result  $\mathbb{E}[\hat{\mathbf{e}}] = 0$  does lit our linding in the lecture that the residuals are zero on average:

$$\hat{\mathbf{E}} = \frac{1}{n} \sum_{i=1}^{n} \hat{\mathbf{E}}_{i} = 0 \tag{1}$$

I [ê] = O alone does not imply (III), but it proves a necessary condition for (III) to hold:

Because  $\mathbb{E}[\mathbf{e}] = 0$ , it holds:  $\mathbb{E}[\mathbf{e}] = \mathbb{E}[\hat{\mathbf{e}}]$ , i.e.  $\mathbb{E}[\mathbf{e}] = \mathbb{E}[\hat{\mathbf{e}}]$ Thus, we could see  $\hat{\mathbf{e}}$ ; as an noise residual estimator for the error  $\mathbf{e}$ ;

(AIL)

### 2. Task

Determine (ou(ê)

$$=$$
  $(I_n - H) Cov(y) (I_n - H)^T$ 

$$= (\mathbf{I}_{n} - \mathbf{H}) \quad \sigma^{2} \mathbf{I}_{n} \quad (\mathbf{I}_{n} - \mathbf{H})^{T}$$

$$= \sigma^2 \left( \mathbf{I}_0 - \mathbf{H} \right) \left( \mathbf{I}_0 - \mathbf{H} \right)^{\mathsf{T}}$$

(3) It generally holds: Let  $X \in \mathbb{R}^n$  be a multivariate RV and  $A \in \mathbb{R}^{m \times n}$  a matrix of constants. Then, it holds:  $Cov(AX) = A(ov(X)A^T)$ 

Here A is given by 
$$(I_n-H)$$
 with  $H:=\times(X^TX)^{-1}X^T$   
  $\times$  is given by  $Y$ 

(4) We have seen in the Oechure that  $(\mathbf{I}_n-\mathbf{H})$  is symmetric and idempotent.

$$\Rightarrow (\mathbf{T}^{\prime} - \mathbf{H})(\mathbf{T}^{\prime} - \mathbf{H})^{\perp} = (\mathbf{T}^{\prime} - \mathbf{H})(\mathbf{T}^{\prime} - \mathbf{H}) = (\mathbf{T}^{\prime} - \mathbf{H})$$

(Prove of this can be found on the next page)

$$Cov(\hat{\epsilon}) = \sigma^2(I_n - H)$$

## Interpretation/Comments:

• In contrast to the error term  $\in$  for which the covariance matrix is a diagonal matrix:  $\sigma I_n$ , i.e.  $cov(\epsilon_i, \epsilon_i) = 0$  if  $i \neq j$ , i.e. each error term  $\epsilon_i$  is independent, here we have dependencies

The matrix  $Cov(\hat{\boldsymbol{\varepsilon}})$  is not a diagonal matrix and  $cov(\boldsymbol{\varepsilon}_i, \boldsymbol{\varepsilon}_j) \neq 0$  in general (not necessarily though).

- · De know that  $H = X(X^TX)^{-1}X^T$ , this means  $Cov(\hat{\epsilon})$  depends on  $\sigma^2$  and X, not on Y.
- · For the variance of each residual ê; it holds:

$$Vax(\hat{e}_i) = \sigma^2(1-R_{ii})$$

2 entry in H in column i and row;

It can be shown that  $\frac{1}{n} \leq R_{ii} \leq 1$ 

https://stats.stackexchange.com/questions/61924/diagonal-elements-of-the-projection-matrix

This implies:

$$Var(\hat{\epsilon}_i) \leq \sigma^2 = Var(\epsilon_i)$$

The variance of each residual term  $\hat{\epsilon}_i$  is smaller our equal to the variance of our noise/error terms  $\epsilon_i$ .

Extra: Prace that (In-H) is symmetric and idempotent

$$H := \times (\times^{T} \times)^{-1} \times^{T}$$

$$H^{\top} = (\times(\times^{\top}\times)^{-1}\times^{\top})^{\top} = \times((\times^{\top}\times)^{-1})^{\top}\times^{\top} = \times(\times^{\top}\times)^{-1}\times^{\top} = H$$
 $\rightarrow H$  is symmetric

$$HH = \times (X^{T}X)^{-1}X^{T}X(X^{T}X)^{-1}X^{T} = XI_{p}(X^{T}X)^{-1}X^{T}$$

$$= \times (X^{T}X)^{-1}X^{T} = H$$

→ H is idempotent

$$(\mathbf{I}_{n}-\mathbf{H})^{\mathsf{T}}=\mathbf{I}_{n}^{\mathsf{T}}-\mathbf{H}^{\mathsf{T}}=\mathbf{I}_{n}-\mathbf{H}$$
  
 $\rightarrow (\mathbf{I}_{n}-\mathbf{H})$  is symmetric

$$(I_n - H)(I_n - H) = I_n I_n - I_n H - H I_n + H H = I_n - 2H + H$$