New exercise 4 (2):

Kalman filter:

$$2n = 0.99 2n-3 + En-2 \rightarrow N(0,0.5)$$

 $20 \sim N(0,0.5)$
 $3n = 2n + N_1 \rightarrow N(0,0.5)$

mo = 0, Co = 0.5, R= 0.5, A= 0.99, B= 0.5

1st Iteration:

$$\hat{m}_{1} = Am_{0} = 0.99 \times 0 = 0$$

$$\hat{C}_{1} = A^{2}C_{0} + B = 0.99 \times 0.5 + 0.5$$

$$K = \frac{0.99005}{0.5 + 0.99005} = 0.6644$$

$$m_{1} = \hat{m}_{1} - K(\hat{m}_{1} - 1.51.64.644)$$

$$= 0 - 0.6644(0 - 0.39894)$$

$$= 0 - 0.6644(0 - 0.39894)$$

$$= 0.26507$$

$$C_{1} = \hat{C}_{1} - K(\hat{m}_{1} - 1.51.64.644)$$

- 0'33226

2nd Iteration:

$$\hat{m}_{2}$$
 = Am₁ = 0.99 x 0.26507 = 0.262421
 \hat{c}_{2} = A² c₁ + B = 0.825609
 $K = \frac{\hat{c}_{2}}{R + \hat{c}_{2}} = 0.6228149$
 $m_{2} = \hat{m}_{2} - \kappa (\hat{m}_{1} - 2nd obsdata)$
= 0.6205702
 $c_{2} = \hat{c}_{2} - \kappa \hat{c}_{2}$
= 0.3114074659

3nd Iteration:

$$\hat{m}_3 = Am_2 = 0.6143645$$
 $\hat{c}_3 = A^3 c_2 + B = 0.805210457$
 $K = \frac{\hat{c}_3}{R + \hat{c}_3} = 0.61692001$
 $m_3 = \hat{m}_3 - K(\hat{m}_3 - 3\pi d \text{ obs-data})$
 $= 0.136162346$
 $c_3 = \hat{c}_3 - K\hat{c}_3$
 $= 0.30846$

m = 0, 0.265072, 0.6205702127, 0.136162396Ref-value = 0.15127, 0.7171, 0.18423, -0.6281.

$$MSE = (0.15127 - 0)^{2} + (0.7171 - 0.265072)^{2} + (0.18423 - 0.6205702127)^{2} + (-0.6281 - 0.136162346)^{2}$$

Mean MSE =
$$\frac{1.00170164}{9} = 0.25042540809$$
.

For MSE, the lower the value the better and 0 means the model is perfect.

Prwof (Extra):

$$\hat{\xi} = \frac{1 - \kappa^2 x^2}{\kappa^2 x^2} = \frac{1 - \kappa^2$$

$$\mathbb{E}[\hat{\xi}] = \mathbb{E}[\mathcal{A} - \mathcal{H}_{\mathcal{I}}]$$

$$= \times \beta - \times (x^{T}x)^{-1}x^{T}x \beta$$

$$= Q_{\rho} ((\Delta^{\nu} - H) \Delta A \Delta (\Delta^{\nu} - H) \Delta)$$

$$= Q_{\rho} ((\Delta^{\nu} - H) \Delta) (\Delta^{\nu} - H) \Delta)_{\Delta}$$

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$$= Q_{\rho} ((\Delta^{\nu} - H) \Delta) (\Delta^{\nu} - H) \Delta)_{\Delta}$$

 $= \sigma^{2} (I_{n}-H) I_{n} (I_{n}-H)^{T}$

= 0 (In-H)

[(In-H) (In-H) = (In-H) (In-H)
= (In-H)]