

Recap:

① Sufficient statistic

② Factorization theorem.

Theorem (Factorization theorem)

Let \underline{X} have joint p.d.f. (p.m.f) $f_{\theta}(\underline{x})$, where θ is the unknown parameter. A statistic $T(\underline{x})$ is called sufficient statistic for θ if and only if

$$f_{\theta}(\underline{x}) = g(T(\underline{x}), \theta) h(\underline{x})$$

pf: only if part

$$P(\underline{X} = \underline{x}) = \sum_t P(\underline{X} = \underline{x} | T(\underline{X}) = t) P(T(\underline{X}) = t)$$

only one of these summands is nonzero.

$$= P(\underline{X} = \underline{x} | T(\underline{X}) = T(\underline{x})) P(T(\underline{X}) = T(\underline{x}))$$

By the definition of sufficient statistic, $\underline{X} | T(\underline{X})$ is free of $\theta \Rightarrow P(\underline{X} = \underline{x} | T(\underline{X}) = T(\underline{x}))$ is free of θ

$$P(\underline{X} = \underline{x} | T(\underline{X}) = T(\underline{x})) = h(\underline{x})$$

$$\text{also I call } P(T(\underline{X}) = T(\underline{x})) = g(T(\underline{x}), \theta)$$

$$\textcircled{1} P(\underline{X} = \underline{x}) = f_{\theta}(\underline{x}) = g(T(\underline{x}), \theta) h(\underline{x})$$

if part

We are given $f_{\theta}(\underline{x}) = g(T(\underline{x}), \theta) h(\underline{x})$

We need to prove that $T(\underline{x})$ is sufficient stat.

$$P(T(\underline{X}) = t) = P(\{\underline{x} : T(\underline{x}) = t\}) = \sum_{\underline{x} : T(\underline{x}) = t} f_{\theta}(\underline{x})$$

$$= \sum_{\underline{x} : T(\underline{x}) = t} g(T(\underline{x}), \theta) h(\underline{x}) = g(t, \theta) \sum_{\underline{x} : T(\underline{x}) = t} h(\underline{x})$$

$$P(\underline{X} = \underline{x} \mid T(\underline{X}) = t) = \frac{P(\underline{X} = \underline{x}, T(\underline{X}) = t)}{P(T(\underline{X}) = t)}$$

$$= 0 \quad \text{if } \cancel{T(\underline{x}) = t} \cdot t \neq T(\underline{x})$$

$$= \frac{P(\underline{X} = \underline{x})}{P(T(\underline{X}) = t)} \quad t = T(\underline{x})$$

$$= \frac{g(T(\underline{x}), \theta) h(\underline{x})}{g(t, \theta) \sum_{\underline{x} : T(\underline{x}) = t} h(\underline{x})} = \frac{\cancel{g(t, \theta)} h(\underline{x})}{\cancel{g(t, \theta)} \sum_{\underline{x} : T(\underline{x}) = t} h(\underline{x})}$$

thus $\underline{X} \mid T(\underline{X})$ is free of θ .

$\Rightarrow T(\underline{X})$ is sufficient stat.

Some Important Facts:

(1) $T(\underline{X}) = (X_1, \dots, X_n)$ is trivially a sufficient stat.

(2) If $X_1, \dots, X_n \stackrel{iid}{\sim} f_{\theta}(\underline{x})$ then $(X_{(1)}, \dots, X_{(n)})$ is also a sufficient statistic.

(3) Any one to one function of a sufficient statistic is also a sufficient statistic.

- $X_1, \dots, X_n \stackrel{iid}{\sim} N(\mu, \sigma^2)$ where σ^2 is known.

We have seen that $\sum_{i=1}^n X_i$ is a sufficient stat.

$\Rightarrow \bar{X} = \frac{1}{n} \sum_{i=1}^n X_i$ is also a sufficient stat.

- $X_1, \dots, X_n \stackrel{iid}{\sim} N(\mu, \sigma^2)$ both μ and σ^2 are unknown.

We have seen that $(\sum_{i=1}^n X_i, \sum_{i=1}^n X_i^2)$ is sufficient.

Define a function $K(z_1, z_2) = (z_1/n, \frac{z_2}{n} - \frac{z_1^2}{n^2})$

$$K(z_1, z_2) = (h_1, h_2), \quad h_1 = \frac{z_1}{n}, \quad h_2 = \frac{z_2}{n} - \frac{z_1^2}{n^2}$$

$$\Rightarrow z_1 = n h_1, \quad h_2 = \frac{z_2}{n} - \frac{n^2 h_1^2}{n^2} \Rightarrow z_2 = (h_2 + h_1^2) n$$

~~$K(z_1, z_2)$~~ $K(\cdot, \cdot)$ is a one-one function.

$$K\left(\sum_{i=1}^n X_i, \sum_{i=1}^n X_i^2\right) = \left(\bar{X}, \frac{\sum_{i=1}^n X_i^2}{n} - \frac{(n\bar{X})^2}{n^2}\right)$$

$$= \left(\bar{X}, \frac{1}{n} \sum_{i=1}^n X_i^2 - \bar{X}^2\right) = \left(\bar{X}, \frac{1}{n} \sum_{i=1}^n (X_i - \bar{X})^2\right)$$

thus mean and variance together become sufficient for (μ, σ^2) .

$$X_1, X_2, X_3 \stackrel{\text{iid}}{\sim} \text{Ber}(p)$$

$$f_p(\underline{x}) = p^{\sum_{i=1}^3 x_i} (1-p)^{3 - \sum_{i=1}^3 x_i}$$

We have seen $T(\underline{x}) = \sum_{i=1}^3 x_i$

now, $(\sum_{i=1}^2 x_i, x_3)$ is also a sufficient statistic by factorization theorem.

and (x_1, x_2, x_3) is trivially sufficient.

How far we can go in terms of summarizing without losing any information on the parameter. We describe a concept known as the minimal sufficiency which answers this.

Definition (Minimal sufficiency)

A statistic $T(\underline{x})$ is minimal sufficient if
 (a) it is sufficient (b) it is a function of every other sufficient statistic.

$$\text{eg } H\left(\sum_{i=1}^2 x_i, x_3\right) = \sum_{i=1}^3 x_i \leftarrow H(z_1, z_2) = z_1 + z_2 \text{ then}$$

Question: How to find the minimal sufficient stat.

⊕

Theorem: Let $f_\theta(\underline{x})$ be the p.d.f. (or p.m.f.) of \underline{x} .

Suppose there exists a statistic $T(\underline{x})$ s.t.

for any two realizations $\underline{x}, \underline{y}$ of the sample \underline{x} ,

$T(\underline{x}) = T(\underline{y})$ if and only if $\frac{f_\theta(\underline{x})}{f_\theta(\underline{y})} = k$, where

k is a fixed constant independent of θ .

Then $T(\underline{x})$ is minimal sufficient for θ .

Example: $x_1, x_2, x_3 \stackrel{iid}{\sim} \text{Ber}(p)$

$$f_p(\underline{x}) = p^{\sum_{i=1}^3 x_i} (1-p)^{3 - \sum_{i=1}^3 x_i}, \quad f_p(\underline{y}) = p^{\sum_{i=1}^3 y_i} (1-p)^{3 - \sum_{i=1}^3 y_i}$$

$$\frac{f_p(\underline{x})}{f_p(\underline{y})} = \frac{p^{\sum_{i=1}^3 x_i} (1-p)^{3 - \sum_{i=1}^3 x_i}}{p^{\sum_{i=1}^3 y_i} (1-p)^{3 - \sum_{i=1}^3 y_i}} = \left(\frac{p}{1-p}\right)^{\sum_{i=1}^3 x_i - \sum_{i=1}^3 y_i}$$

this ratio is constant as a function of parameter p , if and only if $\sum_{i=1}^3 x_i = \sum_{i=1}^3 y_i$. Thus by

applying the theorem, $T(\underline{x}) = x_1 + x_2 + x_3$

~~$T_1(\underline{x}) = (x_1 + x_2, x_3)$~~

$$\frac{f_p(\underline{x})}{f_p(\underline{y})} = \left(\frac{p}{1-p}\right)^{\sum_{i=1}^3 x_i - \sum_{i=1}^3 y_i}$$

~~$T_1(\underline{x}) = T_1(\underline{y})$~~

if $T_1(\underline{x}) = T_1(\underline{y})$ then the ratio is constant.

But the only if part is not as we can have (x_1, x_2, x_3) and (y_1, y_2, y_3) s.t.

$$x_1 + x_2 \neq y_1 + y_2, \quad x_3 \neq y_3 \quad \text{but} \quad x_1 + x_2 + x_3 = y_1 + y_2 + y_3$$

then $\frac{f_p(\underline{x})}{f_p(\underline{y})}$ is constant but $T_1(\underline{x}) \neq T_1(\underline{y})$

Example: $x_1, \dots, x_n \stackrel{iid}{\sim} N(\mu, \sigma^2)$, μ, σ^2 are unknown.

$$\frac{f_{\mu, \sigma^2}(\underline{x})}{f_{\mu, \sigma^2}(\underline{y})} = \frac{\left(\frac{1}{\sqrt{2\pi\sigma^2}}\right)^n \exp\left\{-\frac{1}{2\sigma^2} \left[\sum_{i=1}^n (x_i - \mu)^2\right]\right\}}{\left(\frac{1}{\sqrt{2\pi\sigma^2}}\right)^n \exp\left\{-\frac{1}{2\sigma^2} \left[\sum_{i=1}^n (y_i - \mu)^2\right]\right\}}$$

$$= \frac{\exp\left\{-\frac{1}{2\sigma^2} \left[\sum_{i=1}^n x_i^2 - 2\mu \sum_{i=1}^n x_i + n\mu^2\right]\right\}}{\exp\left\{-\frac{1}{2\sigma^2} \left[\sum_{i=1}^n y_i^2 - 2\mu \sum_{i=1}^n y_i + n\mu^2\right]\right\}}$$

$$= \frac{\exp\left\{-\frac{1}{2\sigma^2} \left[\sum_{i=1}^n x_i^2 - 2\mu \sum_{i=1}^n x_i + n\mu^2\right]\right\}}{\exp\left\{-\frac{1}{2\sigma^2} \left[\sum_{i=1}^n y_i^2 - 2\mu \sum_{i=1}^n y_i + n\mu^2\right]\right\}}$$

$$= \exp\left(-\frac{1}{2\sigma^2} \left[\left(\sum_{i=1}^n x_i^2 - \sum_{i=1}^n y_i^2\right) - 2\mu \left(\sum_{i=1}^n x_i - \sum_{i=1}^n y_i\right)\right]\right)$$

this ratio is a fixed constant if and only if

$$\sum_{i=1}^n x_i = \sum_{i=1}^n y_i \text{ and } \sum_{i=1}^n x_i^2 = \sum_{i=1}^n y_i^2$$

thus $T(\underline{x}) = \left(\sum_{i=1}^n x_i, \sum_{i=1}^n x_i^2\right)$ is minimal sufficient.

Example: $x_1, \dots, x_n \stackrel{iid}{\sim} U(0, \theta+1)$, $-\infty < \theta < \infty$.

$$\frac{f_{\theta}(\underline{x})}{f_{\theta}(\underline{y})} = \frac{\mathbb{I}(x_{(1)} > \theta, x_{(n)} - 1 < \theta)}{\mathbb{I}(y_{(1)} > \theta, y_{(n)} - 1 < \theta)}$$

$$\frac{f_{\theta}(\underline{x})}{f_{\theta}(\underline{y})} = \frac{\mathbb{I}(x_{(1)} > \theta, x_{(n)} - 1 < \theta)}{\mathbb{I}(y_{(1)} > \theta, y_{(n)} - 1 < \theta)}$$

in different ranges of θ this ratio takes the value 0, 1 or ∞ .

the ratio can be made fixed if and only if $x_{(1)} = y_{(1)}$ and $x_{(n)} = y_{(n)}$.

thus $T(\underline{x}) = (x_{(1)}, x_{(n)})$ is minimal sufficient.

if $x_{(1)} = y_{(1)}$ but $x_{(n)} \neq y_{(n)}$

$x_{(n)} < y_{(n)}$ or $x_{(n)} > y_{(n)}$

when $x_{(n)} < y_{(n)}$

$$\frac{f_{\theta}(x)}{f_{\theta}(y)} = \frac{I(x_{(1)} > \theta, x_{(n)} - 1 < \theta)}{I(y_{(1)} > \theta, y_{(n)} - 1 < \theta)}$$

$\theta > x_{(n)} - 1$ but $\theta < y_{(n)} - 1$ then $\frac{f_{\theta}(x)}{f_{\theta}(y)} = \infty$

when $\theta > x_{(n)} - 1$ and $\theta > y_{(n)} - 1$ then $\frac{f_{\theta}(x)}{f_{\theta}(y)} = 1$

thus only using $x_{(1)}$ is not minimal sufficient.

Property: Any one-to-one function of a minimal sufficient statistic is also minimal sufficient.
thus minimal sufficient statistic is not unique.

Recap: ① Minimal sufficient

② Examples of how to ~~compute~~ find a minimal sufficient statistic.

Ancillary Statistic

A statistic whose distribution does not depend on the unknown parameter θ is known as an ancillary statistic.

It seems that ancillary statistic has a distribution free of θ . Then why are we interested? We will discuss it later.

Finding ancillary statistics

Let $X_1, \dots, X_n \stackrel{i.i.d}{\sim} f(x-\theta)$, $-\infty < \theta < \infty$.

$$X \sim N(\mu, 1) \Rightarrow f(x|\mu) = \frac{1}{\sqrt{2\pi}} \exp\left\{-\frac{(x-\mu)^2}{2}\right\} = g(x-\mu)$$

$$\text{If } X_i \sim f(x-\theta), \quad Z_i = X_i - \theta$$

$$\text{If } X_i \sim N(\mu+5, 1) \Rightarrow Z_i \sim N(5, 1)$$

$$X_i \sim f(x-\theta) \Rightarrow Z_i = X_i - \theta \sim f(x)$$

$$P(Z_i \leq z) = P(X_i - \theta \leq z) = P(X_i \leq \theta + z) = \int_{-\infty}^{\theta+z} f(x-\theta) dx$$

$$\text{Let } h = x - \theta$$

$$= \int_{-\infty}^z f(h) dh$$

$$\Rightarrow f_{Z_i}(z) = f(z)$$

$$R = X_{(n)} - X_{(1)} \rightarrow \text{Range statistic}$$

$$\begin{aligned}
 P(R \leq \kappa) &= P\left(\max_{1 \leq i \leq n} X_i - \min_{1 \leq i \leq n} X_i \leq \kappa\right) \\
 &= P\left(\max_{1 \leq i \leq n} (Z_i + \theta) - \min_{1 \leq i \leq n} (Z_i + \theta) \leq \kappa\right) \\
 &= P\left(\max_{1 \leq i \leq n} Z_i + \cancel{\theta} - \cancel{\theta} - \min_{1 \leq i \leq n} Z_i \leq \kappa\right) \\
 &= P(Z_{(n)} - Z_{(1)} \leq \kappa)
 \end{aligned}$$

Since $Z_1, \dots, Z_n \stackrel{iid}{\sim} f(x)$ free of θ
 Thus $Z_{(n)}$ and $Z_{(1)}$ have distributions free of θ
 Thus $P(Z_{(n)} - Z_{(1)} \leq \kappa)$ is free of θ
 \Rightarrow The distribution of $X_{(n)} - X_{(1)}$ is free of θ .
 $\Rightarrow X_{(n)} - X_{(1)}$ is an ancillary statistic.

Other ancillary statistics

$Z_i = X_i - \theta$ thus $X_i - X_j = Z_i + \theta - Z_j - \theta = Z_i - Z_j$
 $\Rightarrow X_i - X_j$ has a distribution free of θ
 $\Rightarrow X_i - X_j$ for any $i \neq j$ is ancillary.

Example: $X_1, \dots, X_n \stackrel{iid}{\sim} U(\theta, \theta+1)$

$\Rightarrow Z_i = X_i - \theta \sim U(0, 1)$ hence $R = X_{(n)} - X_{(1)}$ is an ancillary statistic.

Scale family of distributions

Let $X_1, \dots, X_n \stackrel{iid}{\sim} f\left(\frac{x}{\tau}\right) \frac{1}{\tau}, \tau > 0$.

this is called the scale family of distributions.

Example: $x_1, \dots, x_n \stackrel{iid}{\sim} N(0, \sigma^2)$

$$g(x|\sigma^2) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left\{-\frac{x^2}{2\sigma^2}\right\} = \frac{1}{\sigma} f\left(\frac{x}{\sigma}\right)$$

$$\text{where } f(x) = \exp\left\{-\frac{x^2}{2}\right\} \frac{1}{\sqrt{2\pi}}$$

this is a scale family of distributions.

When $x_1, \dots, x_n \stackrel{iid}{\sim} \frac{1}{\sigma} f\left(\frac{x}{\sigma}\right)$, $\sigma > 0$

$$z_i = \frac{x_i}{\sigma} \sim f(x) \quad \text{Thus } z_1, \dots, z_n \stackrel{iid}{\sim} f(x)$$

$$\text{Take any } \frac{x_i}{x_j} = \frac{x_i/\sigma}{x_j/\sigma} = \frac{z_i}{z_j}$$

thus $\frac{z_i}{z_j}$ and hence $\frac{x_i}{x_j}$ has a density free of σ .

$\Rightarrow \frac{x_i}{x_j}$ is an ancillary statistic.

Example: $x_1, \dots, x_n \stackrel{iid}{\sim} U(0, \theta+1)$

The minimal sufficient statistic is $(x_{(1)}, x_{(n)})$.

$\Rightarrow \left(x_{(n)} - x_{(1)}, \frac{x_{(n)} + x_{(1)}}{2}\right)$ being a one to one function of $(x_{(1)}, x_{(n)})$ is also a minimal sufficient statistic.

this is a location family and hence $x_{(n)} - x_{(1)}$ is an ancillary statistic.

Thus ancillary statistic together with some other statistic contains all the information about θ .

Example: ~~x_1, x_2~~ x_1, x_2 are i.i.d drawn from the following discrete distribution

$$P(\textcircled{X} = \theta) = P(X = \theta+1) = P(X = \theta+2) = \frac{1}{3} \quad \forall \theta.$$

$$Z = X - \theta \quad \textcircled{Z}, \quad P(Z=0) = P(Z=1) = P(Z=2) = \frac{1}{3}$$

thus this is also a location family and Hence $X_{(2)} - X_{(1)}$ is an ancillary statistic.

~~the~~ $(X_{(1)}, X_{(2)})$ is a minimal sufficient statistic.

$\Rightarrow (X_{(2)} - X_{(1)}, \frac{X_{(2)} + X_{(1)}}{2})$ is minimal sufficient.

● If I observe from the data the value for $\frac{X_{(1)} + X_{(2)}}{2} = m$, then what are the possible values of θ ?

● ● there are 9 possible cases

$$\bullet X_1 = \theta+2, \quad X_2 = \theta+2 \Rightarrow \frac{X_{(1)} + X_{(2)}}{2} = \theta+2 = m \Rightarrow \theta = m-2$$

$$\text{if } X_1 = \theta, \quad X_2 = \theta+2 \Rightarrow \frac{X_{(1)} + X_{(2)}}{2} = \theta+1 = m \Rightarrow \theta = m-1$$

$$\text{if } X_1 = \theta, \quad X_2 = \theta \Rightarrow \frac{X_{(1)} + X_{(2)}}{2} = \theta = m \Rightarrow \theta = m$$

If I am given an additional information $X_{(2)} - X_{(1)} = 2$ then ~~one~~ one of them has to be θ and the other has to be $\theta+2$

$$\Rightarrow \frac{X_{(1)} + X_{(2)}}{2} = \theta+1 = m \Rightarrow \theta = m-1$$

clearly minimal sufficient statistic is not independent of ancillary statistic although one of them contains all information about θ and the other has a distribution free of θ . It appears that we need to put extra restriction on ~~the~~ minimal sufficient stat.

Def: (Complete statistic)

Let $f_\theta(t)$ be a family of p.d.f.s (or p.m.f.s) for a statistic $T(\underline{x})$. The family of distributions is called complete if $E_\theta[g(T(\underline{x}))] = 0 \quad \forall \theta$ implies $P_\theta(g(T(\underline{x})) = 0) = 1 \quad \forall \theta$.

Example: $X_1, \dots, X_n \stackrel{iid}{\sim} \text{Ber}(p)$

then $T(\underline{x}) = \sum_{i=1}^n X_i \sim \text{Bin}(n, p)$

Let g be a function s.t. $E_p[g(T(\underline{x}))] = 0 \quad \forall p$

$$E_p[g(T(\underline{x}))] = \sum_{t=0}^n g(t) \binom{n}{t} p^t (1-p)^{n-t} = 0 \quad \forall p$$

$$\bullet E_p[g(T(\underline{x}))] = 0 \quad \forall p$$

$$\Rightarrow \sum_{t=0}^n g(t) \binom{n}{t} p^t (1-p)^{n-t} = 0 \quad \forall p$$

$$\Rightarrow \sum_{t=0}^n g(t) \binom{n}{t} \left(\frac{p}{1-p}\right)^t = 0 \quad \forall p$$

$$f(x) = a_0 + a_1 x + \dots + a_n x^n = 0 \quad \forall x$$

$$\Rightarrow a_0 = a_1 = \dots = a_n = 0$$

$\sum_{t=0}^n g(t) \binom{n}{t} \left(\frac{p}{1-p}\right)^t$ is a polynomial w.r.t. $\frac{p}{1-p}$ and this polynomial is $=0$ for all values of $\frac{p}{1-p}$.

$$\Rightarrow g(0) \binom{n}{0} = g(1) \binom{n}{1} = \dots = g(n) \binom{n}{n} = 0$$

$$\Rightarrow g(0) = \dots = g(n) = 0$$

$$P_p(g(T(X)) = 0) = 1 \quad \forall p$$

example: $X_1, \dots, X_n \stackrel{iid}{\sim} U(0, \theta)$.

$T(X) = \max_{1 \leq i \leq n} X_i$ $f_\theta(t)$ is the density of $T(X)$

$$\text{then } f_\theta(t) = n \frac{t^{n-1}}{\theta^n}, \quad 0 < t < \theta$$

If there is a g s.t.

$$E_\theta[g(T(X))] = 0 \quad \forall \theta > 0$$

$$\Rightarrow E_\theta[g(T(X))] = \int_0^\theta g(t) n \frac{t^{n-1}}{\theta^n} dt = 0 \quad \forall \theta > 0$$

$$\Rightarrow \int_0^\theta g(t) t^{n-1} dt = 0 \quad \forall \theta$$

$$\Rightarrow \frac{d}{d\theta} \int_0^\theta g(t) t^{n-1} dt = 0 \quad \forall \theta \Rightarrow g(\theta) \theta^{n-1} = 0 \quad \forall \theta > 0$$

$$\Rightarrow g(\theta) = 0 \quad \forall \theta > 0$$

$$\Rightarrow P_\theta[g(T(X)) = 0] = 1$$

$\Rightarrow \max_{1 \leq i \leq n} X_i$ is a complete statistic.

Recap: ① Complete statistic.

Def: Let $f_\theta(t)$ be a family of pdfs (or pmfs) for a statistic $T(\underline{x})$. The family of dists. is called complete if $E_\theta[g(T(\underline{x}))] = 0 \forall \theta$ implies $P_\theta(g(T(\underline{x})) = 0) = 1 \forall \theta$. $T(\underline{x})$ is called a complete statistic.

$X_1, X_2, X_3 \stackrel{iid}{\sim} \text{Ber}(p)$ $T(\underline{x}) = X_1 - X_2$.

$$E[X_1 - X_2] = 0 \quad \forall p \quad \text{if } g(t) = t$$

$$\Rightarrow E[g(T(\underline{x}))] = 0 \quad \forall p \quad \text{but } g \neq 0$$

$X_1 - X_2$ is not a complete statistic.

Theorem: If a minimal sufficient statistic exists, then any complete ^{sufficient} statistic is also a minimal sufficient statistic.

pf: Let $T(\underline{x})$ be a complete sufficient statistic and ~~some~~ $S(\underline{x})$ be a minimal sufficient statistic. Then $S(\underline{x})$ is a function of $T(\underline{x})$.

$$\text{Now } E[T(\underline{x}) | S(\underline{x})] = g(S(\underline{x}))$$

$$\Rightarrow E[(T(\underline{x}) - g(S(\underline{x}))) | S(\underline{x})] = 0$$

$$\Rightarrow E[T(\underline{x}) - g(S(\underline{x}))] = 0$$

$$\text{If } S(\underline{x}) = g_1(T(\underline{x})) \Rightarrow E[T(\underline{x}) - g(g_1(T(\underline{x})))] = 0$$

By the definition of completeness of $T(\underline{x})$,

$$T(\underline{x}) = g(g_1(T(\underline{x}))) = g(S(\underline{x}))$$

$\Rightarrow T(\underline{x})$ is also minimal sufficient.

Basu's theorem: If $T(\underline{x})$ is a complete and sufficient statistic, then $T(\underline{x})$ is independent of any ancillary statistic.

Pf: (Only in the discrete case)

Let $S(\underline{x})$ be any ancillary statistic. Then

$P_\theta(S(\underline{x})=s)$ does not depend on θ . Since

$T(\underline{x})$ is a sufficient statistic

$P_\theta(S(\underline{x})=s | T(\underline{x})=t)$ is ~~independent~~ free of θ .

Now,

$$P_\theta(S(\underline{x})=s) = \sum_t P_\theta(S(\underline{x})=s | T(\underline{x})=t) P_\theta(T(\underline{x})=t) \quad \dots (*)$$

Furthermore,

$$P_\theta(S(\underline{x})=s) = \sum_t P_\theta(S(\underline{x})=s | T(\underline{x})=t) P_\theta(T(\underline{x})=t) \quad \dots (**)$$

$$\sum_t P_\theta(T(\underline{x})=t) = 1$$

From (*) and (**)

$$\sum_t P_\theta(S(\underline{x})=s | T(\underline{x})=t) P_\theta(T(\underline{x})=t) = \sum_t P_\theta(S(\underline{x})=s) P_\theta(T(\underline{x})=t)$$

$$\Rightarrow \sum_t \{ P_\theta(S(\underline{x})=s | T(\underline{x})=t) - P_\theta(S(\underline{x})=s) \} P_\theta(T(\underline{x})=t) = 0 \quad \forall \theta$$

$$g(T(x)) = P_0(S(x) | T(x)) - P_0$$

$$g(t) = P_0(S(x)=s | T(x)=t) - P_0(S(x)=s)$$

$$\Rightarrow E[g(T(x))] = 0 \quad \forall \theta$$

Since $T(x)$ is a complete statistic,

$$P_0(g(T(x))=0) = 1 \quad \forall \theta$$

$$\Rightarrow P_0(S(x)=s | T(x)=t) = P_0(S(x)=s) \quad \forall \theta$$

$\Rightarrow S(x)$ and $T(x)$ are independent.

Example: let $x_1, \dots, x_n \stackrel{iid}{\sim} \text{Exp}(\theta)$.

$$\text{Find } E_\theta \left[\frac{x_n}{\sum_{i=1}^n x_i} \right] ?$$

$$f_\theta(x) = \frac{1}{\theta} \exp\left(-\frac{x}{\theta}\right)$$

this is a scale family of distributions.

$$\frac{x_n}{\sum_{i=1}^n x_i} = \frac{1}{\sum_{i=1}^n \frac{x_i}{x_n}} \quad \text{Now, we have seen that}$$

for scale families $\frac{x_i}{x_n} \forall i$ are ancillary statistic.

Thus $\frac{x_n}{\sum_{i=1}^n x_i}$ is also an ancillary statistic.

$f_{\theta}(x_1, \dots, x_n) = \frac{1}{\theta^n} \exp\left(-\sum_{i=1}^n \frac{x_i}{\theta}\right)$ is the joint density.
thus by factorization theorem $\sum_{i=1}^n x_i$ is a sufficient statistic.

$\sum_{i=1}^n x_i$ is also a complete statistic (as we will show with a general result)

thus $\sum_{i=1}^n x_i$ is a complete sufficient statistic.

thus $g(\underline{x}) = \frac{x_n}{\sum_{i=1}^n x_i}$ and $T(\underline{x}) = \sum_{i=1}^n x_i$ are independent by Basu's theorem

$$E[g(\underline{x}) T(\underline{x})] = E[g(\underline{x})] E[T(\underline{x})]$$

$$\Rightarrow E[x_n] = E\left[\frac{x_n}{\sum_{i=1}^n x_i}\right] E\left[\sum_{i=1}^n x_i\right]$$

$$\Rightarrow \theta = E\left[\frac{x_n}{\sum_{i=1}^n x_i}\right] n \theta$$

$$\Rightarrow E\left[\frac{x_n}{\sum_{i=1}^n x_i}\right] = \frac{1}{n}$$

Exponential family of distributions

A one parameter exponential family density is given by $f_{\theta}(x) = h(x) c(\theta) \exp(\omega(\theta) + t(\theta)x)$, where $h(\cdot)$, $c(\cdot)$, $\omega(\cdot)$, $t(\cdot)$ are some functions

Example: $X \sim \text{Ber}(p)$

$$f_p(x) = p^x (1-p)^{1-x} = \left(\frac{p}{1-p}\right)^x (1-p)$$

$$= \exp\left\{x \log \frac{p}{1-p}\right\} (1-p)$$

So Bernoulli density belongs to the exponential family with $t(x) = x$, $\omega(\theta) = \log \frac{p}{1-p}$, $c(\theta) = (1-p)$ and $h(x) = 1$

Example: $X \sim \text{Pois}(\lambda)$

$$f_{\lambda}(x) = \exp(-\lambda) \frac{\lambda^x}{x!} = \exp(-\lambda) \exp(x \log \lambda) \frac{1}{x!}$$

$$h(x) = \frac{1}{x!}, \quad c(\theta) = \exp(-\lambda), \quad \omega(\theta) = \log \lambda \quad \text{and} \quad t(x) = x.$$

You can express Exponential, Normal, Gamma, Inverse gamma all as exponential family of densities.

$$\int_{\mathcal{X}} f_{\theta}(x) dx = 1$$

$$\Rightarrow \int_{\mathcal{X}} h(x) c(\theta) \exp(\omega(\theta) + t(x)) dx = 1$$

$$\Rightarrow \frac{d}{d\theta} \int_{\mathcal{X}} h(x) c(\theta) \exp(\omega(\theta) + t(x)) dx = 0$$

$$\Rightarrow \int_{\mathcal{X}} \frac{d}{d\theta} [h(x) c(\theta) \exp(\omega(\theta) + t(x))] dx = 0$$

$$\Rightarrow \int_{\mathcal{X}} [h(x) c'(\theta) \exp(\omega(\theta) + t(x)) + h(x) c(\theta) \omega'(\theta) + t(x) \exp(\omega(\theta) + t(x))] dx = 0$$

$$\Rightarrow \int_{\mathcal{X}} h(x) c'(\theta) \exp(\omega(\theta) + t(x)) dx = - \int_{\mathcal{X}} h(x) c(\theta) \omega'(\theta) + t(x) \exp(\omega(\theta) + t(x)) dx$$

$$\Rightarrow \frac{c'(\theta)}{c(\theta)} \int_{\mathcal{X}} h(x) c(\theta) \exp(\omega(\theta) + t(x)) dx = - \omega'(\theta) \int_{\mathcal{X}} h(x) c(\theta) + t(x) \exp(\omega(\theta) + t(x)) dx$$

$$\Rightarrow \frac{c'(\theta)}{c(\theta)} \int_{\mathcal{X}} f_{\theta}(x) dx = - \omega'(\theta) \int_{\mathcal{X}} t(x) f_{\theta}(x) dx$$

$$\Rightarrow \frac{c'(\theta)}{c(\theta)} = - \omega'(\theta) E[\cancel{t(x)} t(x)]$$

$$\Rightarrow E[t(x)] = \frac{-c'(\theta)}{c(\theta) \omega'(\theta)}$$

By taking second derivative you can find closed form expressions for $E[t(x)]$ and $\text{Var}(t(x))$.

Similar to the one parameter exponential family, a multi-parameter exponential family has density

$$f_{\underline{\theta}}(x) = h(x) c(\underline{\theta}) \exp\left(\sum_{i=1}^k w_i(\underline{\theta}) t_i(x)\right)$$

check: $N(\mu, \sigma^2)$ with μ, σ^2 both unknown parameters can be written in the above form.

If x_1, \dots, x_n i.i.d $f_{\underline{\theta}}(x)$ where $f_{\underline{\theta}}(x)$ is from a multiparameter exponential family

$$f_{\underline{\theta}}(x_1, \dots, x_n) = \prod_{i=1}^n f_{\underline{\theta}}(x_i)$$

$$= \left[\prod_{i=1}^n h(x_i)\right] [c(\underline{\theta})]^n \exp\left\{\sum_{j=1}^k w_j(\underline{\theta}) \sum_{i=1}^n t_j(x_i)\right\}$$

By factorization theorem

$\left(\sum_{i=1}^n t_1(x_i), \sum_{i=1}^n t_2(x_i), \dots, \sum_{i=1}^n t_k(x_i)\right)$ is a sufficient statistic for $\underline{\theta}$.