

## 1 The $\ell_2$ Support Vector Machine [20pts]

In class, we discussed that if our data is not linearly separable, then we need to modify our optimization problem to include slack variables. The formulation that was used is known as the  $\ell_1$ -norm soft margin SVM. Now consider the formulation of the  $\ell_2$ -norm soft margin SVM, which squares the slack variables within the sum. Notice that non-negativity of the slack variables has been removed.

$$\begin{aligned} \arg \min_{\mathbf{w}, b, \xi} & \frac{1}{2} \|\mathbf{w}\|^2 + \frac{C}{2} \sum_{i=1}^n \xi_i^2 \\ \text{s.t. } & y_i(\mathbf{w}^T \mathbf{x}_i + b) \geq 1 - \xi_i \quad \forall i \in [n] \end{aligned}$$

Derive the dual form expression along with any constraints. Work must be shown. *Hints:* Refer to the methodology that was used in class to derive the dual form. The solution is given by:

$$\begin{aligned} \arg \max_{\alpha} & \sum_{i=1}^n \alpha_i - \frac{1}{2} \sum_{i=1}^n \sum_{j=1}^n \alpha_i \alpha_j y_i y_j \mathbf{x}_i^T \mathbf{x}_j - \frac{1}{2C} \sum_{i=1}^n \alpha_i^2 \\ \text{s.t. } & \alpha_i \geq 0 \quad \forall i \in [n] \quad \text{and} \quad \sum_{i=1}^n \alpha_i y_i = 0 \end{aligned}$$

*Solution:*

- Form the Lagrangian function:

$$L(w, b, \alpha) = \frac{1}{2} \|w\|^2 + \frac{C}{2} \sum_{i=1}^n \xi_i^2 - \sum_{i=1}^n \alpha_i [y_i(w^T x_i + b) - 1 + \xi_i]$$

$$\frac{\partial L}{\partial w} = w - \sum_{i=1}^n \alpha_i y_i x_i = 0$$

$$\Rightarrow w = \sum_{i=1}^n \alpha_i y_i x_i$$

$$\frac{\partial L}{\partial b} = \sum_{i=1}^n \alpha_i y_i = 0$$

$$w^T w = \sum_{i=1}^n \alpha_i y_i^T x_i^T$$

$$\frac{\partial L}{\partial \xi_i} = C \xi_i - \alpha_i = 0$$

$$\Rightarrow \xi_i = \frac{\alpha_i}{C}$$

$$\begin{aligned} L(w, b, \xi) &= \frac{1}{2} \sum_{i=1}^n \sum_{j=1}^n \alpha_i \alpha_j y_i y_j x_i^T x_j + \frac{C}{2} \sum_{i=1}^n \frac{\alpha_i^2}{C^2} \\ &\quad - \sum_{i=1}^n [\alpha_i y_i w^T x_i + \alpha_i y_i b - \alpha_i + \alpha_i \xi_i] \end{aligned}$$

$$\begin{aligned} &= \frac{1}{2} \sum_{i=1}^n \sum_{j=1}^n \alpha_i \alpha_j y_i y_j x_i^T x_j + \frac{1}{2C} \sum_{i=1}^n \alpha_i^2 \\ &\quad - \sum_{i=1}^n \sum_{j=1}^n \alpha_i \alpha_j y_i y_j x_i^T x_j + \sum_{i=1}^n \alpha_i - \frac{\sum_{i=1}^n \alpha_i^2}{2C} \end{aligned}$$

$$-\sum_{i=1}^n \sum_{j=1}^n \alpha_i \alpha_j y_i y_j x_i^T x_j + \sum_{i=1}^n \alpha_i - \frac{1}{2C} \sum_{i=1}^n \alpha_i^2$$

$$L(\alpha) = \sum_{i=1}^n \alpha_i - \frac{1}{2} \sum_{i=1}^n \sum_{j=1}^n \alpha_i \alpha_j y_i y_j x_i^T x_j - \frac{1}{2C} \sum_{i=1}^n \alpha_i^2$$

$$\text{s.t. } \alpha_i \geq 0 \Rightarrow \sum_{i=1}^n \alpha_i y_i = 0$$

$$\alpha_i = C \epsilon_i$$

## 2 Domain Adaptation Support Vector Machines [20pts]

We now look at a different type of SVM that is designed for domain adaptation and optimizes the hyperplanes given by  $\mathbf{w}_S$  (source hyperplane) before optimizing  $\mathbf{w}_T$  (target hyperplane). The process begins by training a support vector machine on source data then once data from the target are available, train a new SVM using the hyperplane from the first SVM and the data from the target to solve for a new "domain adaptation" SVM.

The primal optimization problem is given by

$$\begin{aligned} \arg \min_{\mathbf{w}_T, \xi} \quad & \frac{1}{2} \|\mathbf{w}_T\|^2 + C \sum_{i=1}^n \xi_i - B \mathbf{w}_T^T \mathbf{w}_S \\ \text{s.t.} \quad & y_i (\mathbf{w}_T^T \mathbf{x}_i + b) \geq 1 - \xi_i \quad \forall i \in \{1, \dots, n\} \\ & \xi_i \geq 0 \quad \forall i \in \{1, \dots, n\} \end{aligned}$$

where  $\mathbf{w}_S$  is hyperplane trained on the source data (assumed to be known),  $\mathbf{w}_T$  is hyperplane for the target,  $y_i \in \{\pm 1\}$  is the label for instance  $\mathbf{x}_i$ ,  $C$  &  $B$  are regularization parameters defined by the user and  $\xi_i$  is a slack variable for instance  $\mathbf{x}_i$ . The problem becomes finding a hyperplane,  $\mathbf{w}_T$ , that minimizes the above objective function subject to the constraints. Solve/derive the dual optimization problem.

Note: I will give the class the solution to this problem prior to the due date because Problem #3 requires that you implement this algorithm in code.

$$L(\mathbf{w}_T, b, \xi_i) = \frac{1}{2} \|\mathbf{w}_T\|^2 + C \sum_{i=1}^n \xi_i - B \mathbf{w}_T^T \mathbf{w}_S - \sum_{i=1}^n \alpha_i [y_i (\mathbf{w}_T^T \mathbf{x}_i + b) - 1 + \xi_i] - \sum_{i=1}^n \mu_i \xi_i$$

$$\frac{\partial L}{\partial \mathbf{w}_T} = \mathbf{w}_T - B \mathbf{w}_S - \sum_{i=1}^n \alpha_i y_i \mathbf{x}_i = 0$$

$$\Rightarrow \mathbf{w}_T = B \mathbf{w}_S + \sum_{i=1}^n \alpha_i y_i \mathbf{x}_i$$

$$\frac{\partial L}{\partial b} = \sum_{i=1}^n \alpha_i y_i = 0$$

$$\begin{aligned} \frac{\partial L}{\partial \xi_i} &= C - \alpha_i - \mu_i = 0 \\ \Rightarrow C &= \alpha_i + \mu_i \quad \therefore 0 \leq \alpha_i \leq C \end{aligned}$$

$$\begin{aligned}
L &= \frac{1}{2} \|W_T\|^2 + C \sum_{i=1}^n \epsilon_i - B W_T^T W_S - \sum_{i=1}^n \alpha_i [y_i (W_T^T x_i + b) - 1 + \epsilon_i] \\
&\quad - \sum_{i=1}^n \mu_i \epsilon_i \\
&= \frac{1}{2} \left[ B W_S^T + \sum_{i=1}^n \alpha_i y_i x_i^T \right] \cdot \left[ B W_S + \sum_{i=1}^n \alpha_i y_i x_i \right] \\
&= \frac{1}{2} \left[ B^2 W_S^T W_S + B W_S^T \sum_{i=1}^n \alpha_i y_i x_i + (\sum_{i=1}^n \alpha_i y_i x_i^T) B W_S \right. \\
&\quad \left. + \sum_{i=1}^n \sum_{j=1}^n \alpha_i \alpha_j y_i y_j x_i^T x_j \right] \\
&\quad + C \sum_{i=1}^n \epsilon_i - B \left[ B W_S^T + \sum_{i=1}^n \alpha_i y_i x_i^T \right] W_S \\
&\quad - \sum_{i=1}^n \alpha_i y_i B W_S^T - \sum_{i=1}^n \sum_{j=1}^n \alpha_i \alpha_j y_i y_j x_i^T x_j + \sum_{i=1}^n \alpha_i - \sum_{i=1}^n \alpha_i \epsilon_i - \sum_{i=1}^n \mu_i \epsilon_i
\end{aligned}$$

$$\begin{aligned}
&= \sum_{i=1}^n \alpha_i - \frac{1}{2} \sum_{i=1}^n \sum_{j=1}^n \alpha_i \alpha_j y_i y_j x_i^T x_j - \frac{1}{2} B^2 W_S^T W_S \\
&\quad + \frac{1}{2} B W_S^T \sum_{i=1}^n \alpha_i y_i x_i - \frac{1}{2} (\sum_{i=1}^n \alpha_i y_i x_i^T) B W_S
\end{aligned}$$

s.t.  $\sum_{i=1}^n \alpha_i y_i = 0$

$C > \alpha_i \geq 0$

Since  $\frac{1}{2} B^2 W_S^T W_S$  is constant w.r.t. the optimization

the equation reduces to

$$L = \frac{1}{2} \sum_{i=1}^n \alpha_i - \frac{1}{2} \sum_{i=1}^n \sum_{j=1}^n \alpha_i \alpha_j y_i y_j x_i^T x_j - \sum_{i=1}^n B \alpha_i y_i W_S^T x_i$$

s.t.  $\sum_{i=1}^n \alpha_i y_i = 0$

$C > \alpha_i \geq 0$

### 3 Density Estimation (Code) [20pts]

Implement the domain adaptation SVM from Problem #2. A data set for the source and target domains (both training and testing) have been uploaded to D2L. There are several ways to implement this algorithm. If I were doing this for an assignment, I would implement the SVM (both the domain adaptation SVM and normal SVM) directly using quadratic programming. You do not need to build the classifier (i.e., solve for the bias term); however, you will need to find  $\mathbf{w}_T$  and  $\mathbf{w}_S$ . To find the weight vectors, you will need to solve a quadratic programming problem and look through the documentation to learn how to solve this optimization task. The following Python packages are recommended:

- CVXOPT (<https://cvxopt.org/>)
- PyCVX (<https://www.cvxpy.org/install/>)

*Note: Your solution can use any of the packages above.*

## Domain adaptation SVM

```
In [1]: import numpy as np
import pandas as pd
from sklearn.model_selection import train_test_split
import matplotlib.pyplot as plt
from matplotlib import cm
import matplotlib.mlab as ml
from scipy.interpolate import griddata
import numpy as np
import cvxopt
```

```
In [2]: source_train = '/home/safwan/Downloads/source_train.csv'
target_train = '/home/safwan/Downloads/target_train.csv'
```

```
In [3]: source_t_pd = pd.read_csv(source_train, header=None)
```

```
In [4]: target_t_pd = pd.read_csv(target_train, header=None)
# target_t_pd
```

```
In [5]: #seperating the features and labels.
X_s = source_t_pd.iloc[:, 0:-1]
y_s = source_t_pd.iloc[:, -1]
#converting to array
X_s = X_s.values
y_s = y_s.values
```

```
In [6]: #seperating the features and labels.
X_t = target_t_pd.iloc[:, 0:-1]
y_t = target_t_pd.iloc[:, -1]
#converting to array
X_t = X_t.values
y_t = y_t.values
```

```
In [7]: s=y_s.reshape(1,-1)
s.shape
```

```
Out[7]: (1, 200)
```

```
In [8]: def linear_kernel(x_i, x_j):
    return np.matmul(x_i,x_j.T)
```

Need to write SVM first to find the Ws.

$$\max_{\lambda \geq 0} -\frac{1}{2} \sum_i \sum_j \lambda_i \lambda_j y_i y_j x^{(i)T} x^{(j)} + \sum_i \lambda_i$$

such that

$$\sum_i \lambda_i y_i = 0$$

$$c \geq \lambda_i \geq 0, \text{ for all } i$$

$$\begin{aligned} & \text{minimize} && (1/2)x^T Px + q^T x \\ & \text{subject to} && Gx \leq h \\ & && Ax = b \end{aligned}$$

In [9]:

```
def svm(X_s, y_s, C):
    n = len(X_s)
    #using the kernal trick
    K = linear_kernel(X_s, X_s)
    #finding the P matrix
    P = cvxopt.matrix(np.matmul(y_s, y_s.T) * K)
    #finding the q matrix
    q = cvxopt.matrix (-1 * np.ones((len(X_s),1)))
    # alpha <= C and -alpha <= 0
    temp1 = np.diag(-np.ones(n))
    temp2 = np.identity(n)
    G = cvxopt.matrix(np.vstack((temp1, temp2)))
    temp1 = np.zeros(n)
    temp2 = np.ones(n) * C
    h = cvxopt.matrix(np.hstack((temp1, temp2)))
    A = cvxopt.matrix(y_s.reshape(1,-1),(1, n),'d')
    b = cvxopt.matrix(0.0)
    #solving for alpha
    a = cvxopt.solvers.qp(P, q, G, h, A, b)
    a = np.array(a['x'])
    #finding the weights
    w = np.array([[0 , 0]])
    for i in range(len(a)):
        w = w + a[i] + y_s[i] + X_s[i]

    return w
```

In [10]:

```
w_s = svm(X_s, y_s, 10)
w_s
```

pcost	dcost	gap	pres	dres
-------	-------	-----	------	------

```

0: -1.0002e+03 -9.7814e+03 9e+03 4e-14 1e-11
1: -1.1318e+03 -1.8739e+03 7e+02 2e-15 8e-12
2: -1.15433e+03 -1.7047e+03 2e+02 9e-14 1e-11
3: -1.16043e+03 -1.6448e+03 4e+01 7e-14 1e-11
4: -1.16154e+03 -1.6336e+03 2e+01 2e-14 1e-11
5: -1.16214e+03 -1.6280e+03 7e+00 7e-15 1e-11
6: -1.16243e+03 -1.6252e+03 9e-01 3e-14 2e-11
7: -1.16246e+03 -1.6248e+03 2e-01 1e-14 1e-11
8: -1.16247e+03 -1.6247e+03 3e-02 2e-16 1e-11
9: -1.16247e+03 -1.6247e+03 3e-04 2e-16 1e-11
Optimal solution found.

```

```
Out[10]: array([[1659.75153226, 1652.55403706]])
```

## Now we can find DA-SVM

```
In [11]: def da_svm(X_t, y_t, C, B, w_s):
    n = len(X_t)
    #using the kernal trick
    K = linear_kernel(X_t, X_t)

    #finding the P matrix
    P = cvxopt.matrix(np.matmul(y_t,y_t.T) * K)
    #finding the q matrix
    #Adjusting the q matrix for da-svm
    temp3 = np.matmul(w_s, X_t.T)
    temp4 = np.matmul(B * np.vstack(y_t), temp3)
    temp5 = - (1 - np.diagonal(temp4))
    q = cvxopt.matrix(np.vstack(temp5))

    # alpha <= C and -alpha <= 0
    temp1 = np.diag(-(np.ones(n)))
    temp2 = np.identity(n)
    G = cvxopt.matrix(np.vstack((temp1, temp2)))
    temp1 = np.zeros(n)
    temp2 = np.ones(n) * C
    h = cvxopt.matrix(np.hstack((temp1, temp2)))
    A = cvxopt.matrix(y_t.reshape(1,-1),(1, n),'d')
    b = cvxopt.matrix(0.0)
    #solving for alpha
    a = cvxopt.solvers.qp(P, q, G, h, A, b)
    a = np.array(a['x'])
    #finding the weights
    w = np.array([[0 , 0]])

    for i in range(len(a)):
        w = w + a[i] + y_t[i] + X_t[i]
        w = B * w_s + w

    return w
```

```
In [12]: da_svm(X_t, y_t, 10 , 1, w_s)
```

	pconst	dconst	gap	pres	dres
0:	-2.5868e+08	-1.7333e+06	2e+09	7e+02	1e-13
1:	-2.6673e+06	-1.7282e+06	2e+07	7e+00	3e-13
2:	-1.7172e+04	-1.3750e+06	3e+06	5e-01	1e-12

```
3: 1.1707e+05 -1.4545e+05 3e+05 2e-15 1e-15
4: 2.0034e+04 -2.0933e+04 4e+04 9e-16 4e-16
5: 2.1743e+03 -2.3440e+03 5e+03 8e-16 3e-16
6: 1.0083e+02 -8.0851e+01 2e+02 5e-16 5e-16
7: 2.8074e+00 -6.1000e+00 9e+00 2e-16 4e-16
8: -1.3106e+00 -1.9276e+00 6e-01 2e-16 3e-16
9: -1.4032e+00 -1.4218e+00 2e-02 2e-16 4e-16
10: -1.4041e+00 -1.4043e+00 2e-04 2e-16 3e-16
11: -1.4041e+00 -1.4041e+00 2e-06 2e-16 4e-16
12: -1.4041e+00 -1.4041e+00 2e-08 2e-16 2e-16
Optimal solution found.
```

```
Out[12]: array([[82983.35581857, 82654.23975857]])
```

In [ ]: