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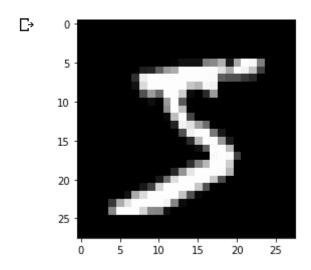
In this problem we will train a neural network from scratch using numpy. In practice, you will never need to do this (you'd just use TensorFlow or PyTorch). But hopefully this will give us a sense of what's happening under the hood.

For training/testing, we will use the standard MNIST benchmark consisting of images of handwritten images.

```
import tensorflow as tf
import matplotlib.pyplot as plt

(x_train, y_train), (x_test, y_test) = tf.keras.datasets.mnist.load_data(path="mnist.r

plt.imshow(x_train[0],cmap='gray');
```



Loading MNIST is the only place where we will use TensorFlow; the rest of the code will be pure numpy.

Let us now set up a few helper functions. We will use sigmoid activations for neurons, the softmax activation for the last layer, and the cross entropy loss.

```
import numpy as np

def sigmoid(x):
    # Numerically stable sigmoid function based on
    # http://timvieira.github.io/blog/post/2014/02/11/exp-normalize-trick/
    x = np.clip(x, -500, 500) # We get an overflow warning without this
```

```
return np.where(
    x >= 0,
    1 / (1 + np.exp(-x)),
    np.exp(x) / (1 + np.exp(x))
  )
def dsigmoid(x): # Derivative of sigmoid
  return sigmoid(x) * (1 - sigmoid(x))
def softmax(x):
  # Numerically stable softmax based on (same source as sigmoid)
  # http://timvieira.github.io/blog/post/2014/02/11/exp-normalize-trick/
  b = x.max()
  y = np.exp(x - b)
  return y / y.sum()
def cross_entropy_loss(y, yHat):
  return -np.sum(y * np.log(yHat))
def integer to one hot(x, max):
  # x: integer to convert to one hot encoding
  # max: the size of the one hot encoded array
  result = np.zeros(10)
  result[x] = 1
  return result
```

OK, we are now ready to build and train our model. The input is an image of size 28x28, and the output is one of 10 classes. So, first:

Q1. Initialize a 2-hidden layer neural network with 32 neurons in each hidden layer, i.e., your layer sizes should be:

```
784 -> 32 -> 32 -> 10
```

If the layer is  $n_{in} \times n_{out}$  your layer weights should be initialized by sampling from a normal distribution with mean zero and variance  $1/\max(n_{in}, n_{out})$ .

```
import math

# Initialize weights of each layer with a normal distribution of mean 0 and
# standard deviation 1/sqrt(n), where n is the number of inputs.
# This means the weighted input will be a random variable itself with mean
# 0 and standard deviation close to 1 (if biases are initialized as 0, standard
# deviation will be exactly 1)

from numpy.random import default_rng

rng = default_rng(80085)

# Q1. Fill initialization code here.
```

Next, we will set up the forward pass. We will implement this by looping over the layers and successively computing the activations of each layer.

Q2. Implement the forward pass for a single sample, and for the entire dataset.

Right now, your network weights should be random, so doing a forward pass with the data should not give you any meaningful information. Therefore, in the last line, when you calculate test accuracy, it should be somewhere around 1/10 (i.e., a random guess).

```
def feed_forward_sample(sample, y):
    """ Forward pass through the neural network.
    Inputs:
        sample: 1D numpy array. The input sample (an MNIST digit).
        label: An integer from 0 to 9.

    Returns: the cross entropy loss andmost likely class of "sample"
    """

# Q2. Fill code here.
# ...
L1 = sigmoid(np.dot(sample, weights[0]) + biases[0])
L2 = sigmoid(np.dot(L1, weights[1]) + biases[1])
    output = softmax(np.dot(L2, weights[2]) + biases[2])
    one_hot_guess = integer_to_one_hot(np.argmax(output), 10)

y = integer_to_one_hot(y, 10)
    loss = cross_entropy_loss(y, output)
    return_loss_one_hot_guess
```

```
def feed_forward_dataset(x, y):
  losses = np.empty(x.shape[0])
  one_hot_guesses = np.empty((x.shape[0], 10))
  # ...
  # Q2. Fill code here to calculate losses, one hot guesses
  # ...
  x = x.reshape(-1, 784)
  for i in range(len(x)):
    l, h = feed_forward_sample(x[i], y[i])
    losses[i] = 1
    one_hot_guesses[i] = h
  y one hot = np.zeros((y.size, 10))
  y_one_hot[np.arange(y.size), y] = 1
  correct_guesses = np.sum(y_one_hot * one_hot_guesses)
  correct guess percent = format((correct guesses / y.shape[0]) * 100, ".2f")
  print("\nAverage loss:", np.round(np.average(losses), decimals=2))
  print("Accuracy (# of correct guesses):", correct_guesses, "/", y.shape[0], "(", correct_guesses, "/", y.shape[0], "(", correct_guesses)
def feed forward_training_data():
  print("Feeding forward all training data...")
  feed forward dataset(x train, y train)
  print("")
def feed forward_test_data():
  print("Feeding forward all test data...")
  feed forward dataset(x test, y test)
  print("")
feed forward test data()
    Feeding forward all test data...
    Average loss: 1.0
    Accuracy (# of correct quesses): 1132.0 / 10000 ( 11.32 %)
```

OK, now we will implement the backward pass using backpropagation. We will keep it simple and just do training sample-by-sample (no minibatching, no randomness).

Q3: Compute the gradient of all the weights and biases by backpropagating derivatives all the way from the output to the first layer.

```
a = sample.flatten()
# We will store each layer's activations to calculate gradient
activations = []
# Forward pass
# Q3. This should be the same as what you did in feed forward sample above.
# ...
A1 = np.dot(a, weights[0]) + biases[0]
Z1 = sigmoid(A1)
A2 = np.dot(Z1,weights[1])+biases[1]
Z2 = sigmoid(A2)
A3 = np.dot(Z2,weights[2])+biases[2]
Z3 = softmax(A3)
one hot guess = integer to one hot(np.argmax(Z3),10)
y = integer_to_one_hot(y,10)
loss = cross_entropy_loss(y,Z3)
activations.append(Z1)
activations.append(Z2)
activations.append(Z3)
# Backward pass
# Q3. Implement backpropagation by backward-stepping gradients through each layer.
# You may need to be careful to make sure your Jacobian matrices are the right shape
# At the end, you should get two vectors: weight gradients and bias gradients.
dZ3 = -1 * (one hot guess - (one hot guess*Z3))
Z2 = Z2.reshape(1,32)
dZ3 = dZ3.reshape(1,10)
dW3 = np.dot(Z2.T, dZ3)
dB3 = dZ3
dZ2 = dsigmoid(Z2)*np.dot(dZ3,Z3.T)
A1 = A1.reshape(1,32)
dZ2 = dZ2.reshape(1,32)
dW2 = np.dot(A1.T, dZ2)
dB2 = dZ2
dZ1 = dsigmoid(Z1)*np.dot(dZ2,Z2.T)
a = a.reshape(1,784)
dZ1 = dZ1.reshape(1,32)
dW1 = np.dot(a.T, dZ1)
dB1 = dZ1
weight gradients = [dW1,dW2,dW3]
```

```
plas_gradients = [dB1,dB2,dB3]
for i in range(0,3):
    # Update weights & biases based on your calculated gradient
    weights[i] -= weight_gradients[i] * learning_rate
    biases[i] -= bias_gradients[i].flatten() * learning_rate
```

Finally, train for 3 epochs by looping over the entire training dataset 3 times.

Q4. Train your model for 3 epochs.

```
def train_one_epoch(learning_rate=0.003):
  print("Training for one epoch over the training dataset...")
 # Q4. Write the training loop over the epoch here.
  # ...
  for i in range(len(x_train)):
    train_one_sample(x_train[i],y_train[i])
  print("Finished training.\n")
feed forward test data()
def test_and_train():
  train one epoch()
  feed forward_test_data()
for i in range(3):
  print('Epoch ', i)
  test and train()
    Feeding forward all test data...
    Average loss: 1.0
    Accuracy (# of correct guesses): 1010.0 / 10000 ( 10.10 %)
    Training for one epoch over the training dataset...
    Finished training.
    Feeding forward all test data...
    Average loss: 1.0
    Accuracy (# of correct guesses): 1010.0 / 10000 ( 10.10 %)
    Epoch
    Training for one epoch over the training dataset...
    Finished training.
    Feeding forward all test data...
    Average loss: 1.0
```

```
Accuracy (# of correct guesses): 1010.0 / 10000 ( 10.10 %)

Epoch 2

Training for one epoch over the training dataset...

Finished training.

Feeding forward all test data...

Average loss: 1.0

Accuracy (# of correct guesses): 1010.0 / 10000 ( 10.10 %)
```

## That's it!

Your code is probably very time- and memory-inefficient; that's ok. There is a ton of optimization under the hood in professional deep learning frameworks which we won't get into.

If everything is working well, you should be able to raise the accuracy from  $\sim$ 10% to  $\sim$ 85% accuracy after 3 epochs.