



# *Introduction To OSEK OS*

*Sarea  
Alhariri*

# *Introduction To OSEK OS*

## ***Prerequisites:***

- **Basics of C programming**
- **Simple background in MCU programming**
- **Simple background in RTOS concepts**



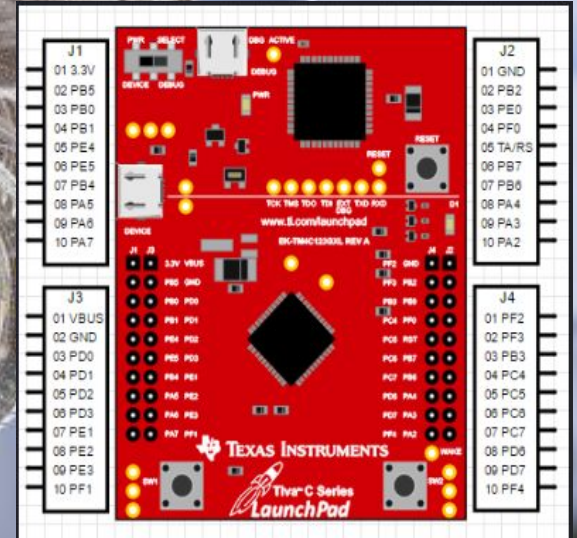


# Introduction To OSEK OS



## Hardware & Tools:

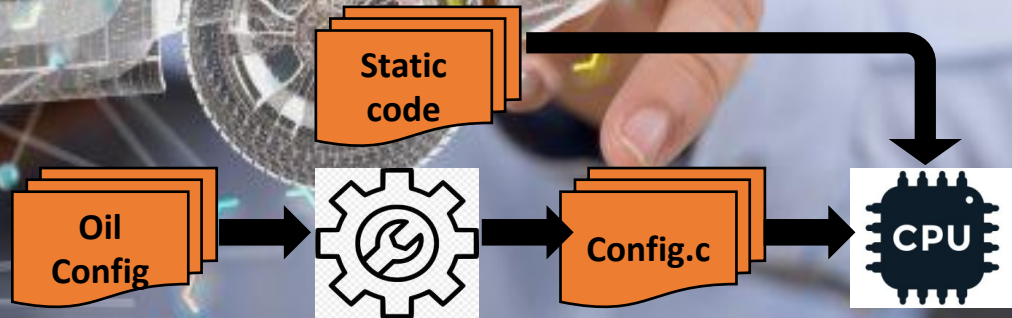
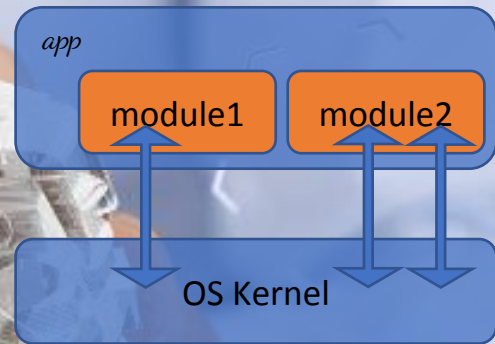
- Keil Uvision 5
- Tiva C Launchpad
- VSCode or Notepad++ for code editing



# Introduction To OSEK OS

## What is OSEK?

- **small, scalable RTOS.**
- **Standard interfaces** between the app and the OS.
- Different **conformance classes**, various **scheduling mechanisms**
- **Statically scaled/configured** at the system generation time





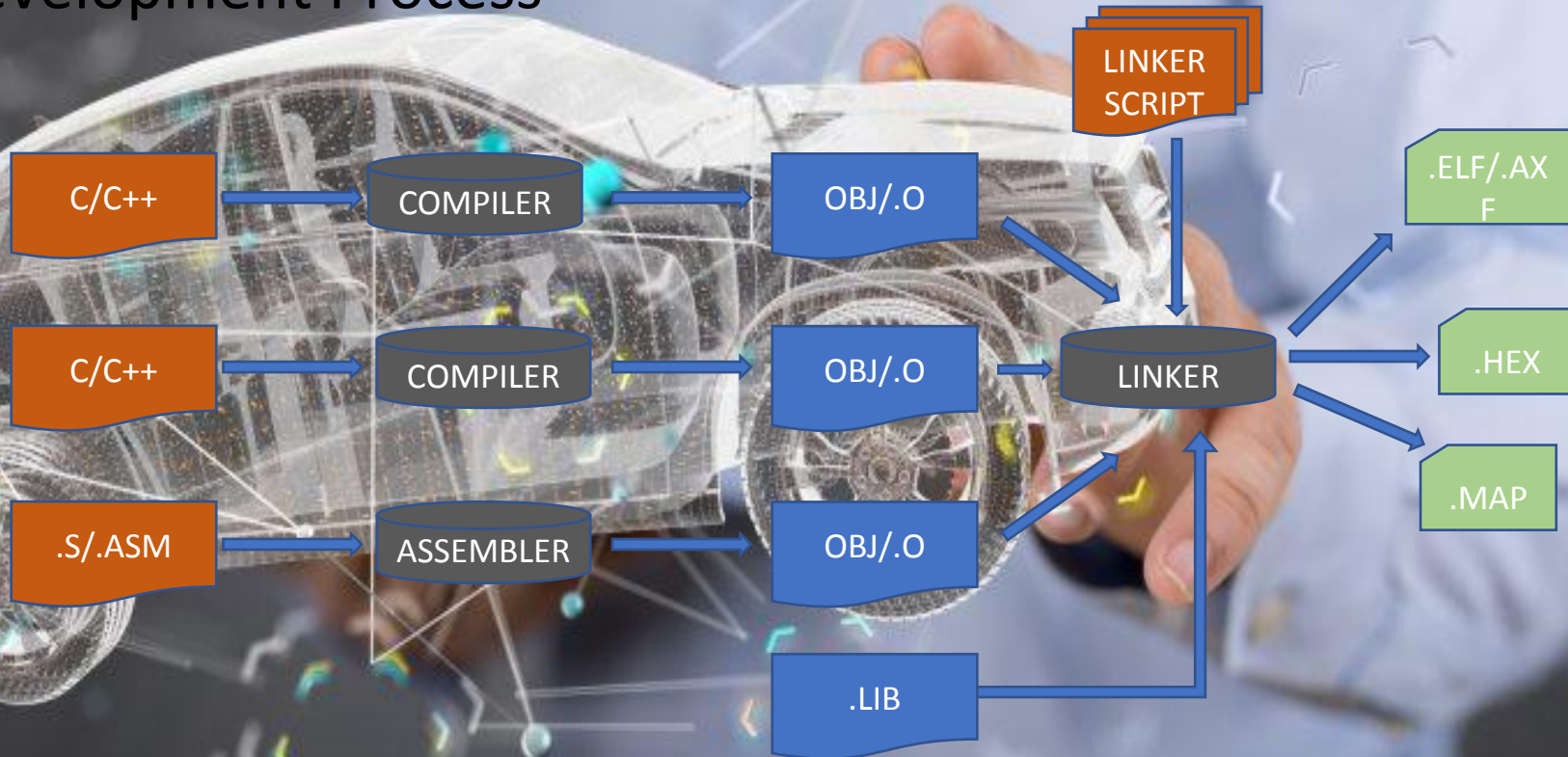
# *Introduction To OSEK OS*

## OSEK Features



# *Introduction To OSEK OS*

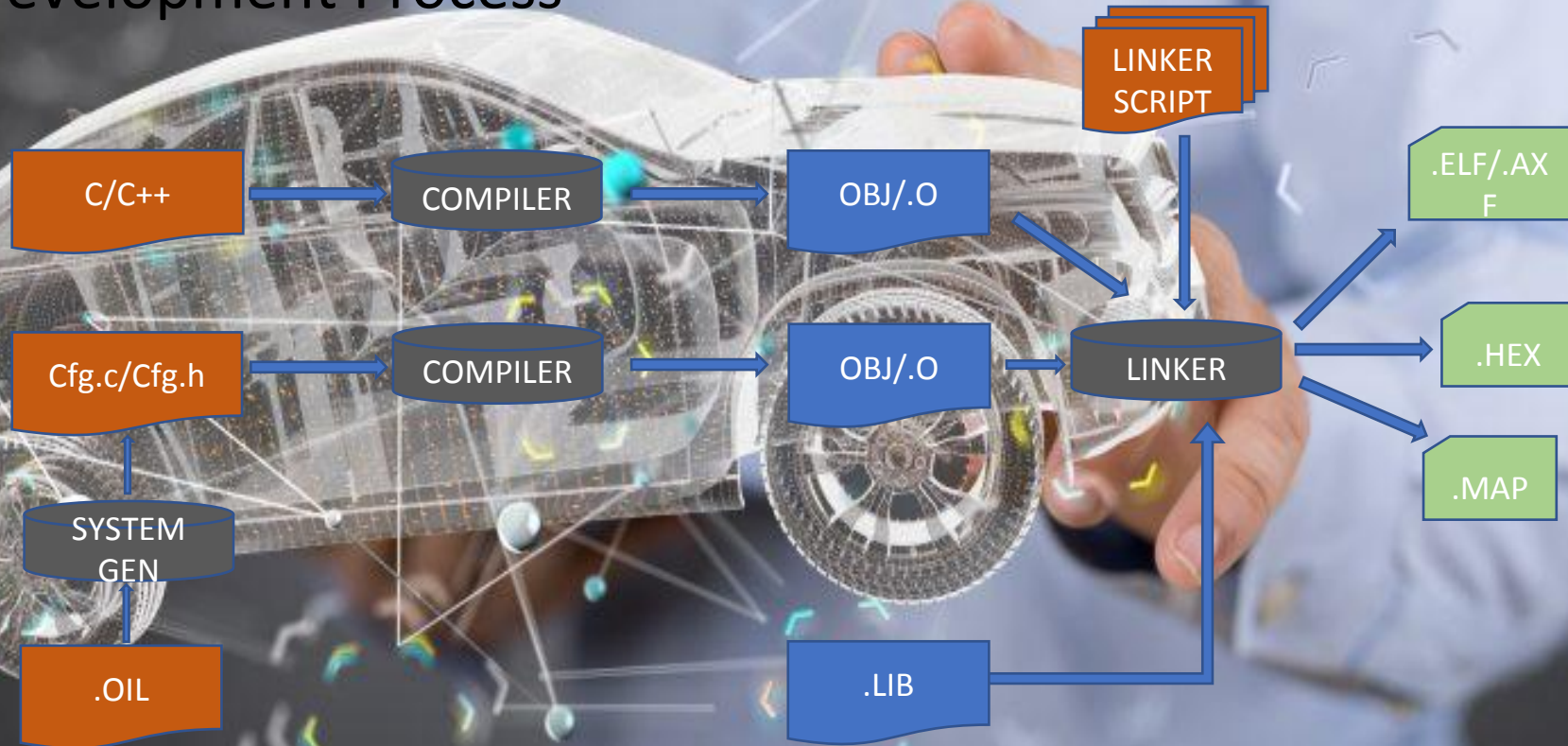
## OSEK Development Process





# *Introduction To OSEK OS*

## OSEK Development Process



# *Introduction To OSEK OS*

## OSEK Implementation Language (OIL)

```
CPU CORTEX-M4 {  
  OS OSEKOS {  
    STATUS = EXTENDED ;  
    ...  
  };  
  TASK MyTask{  
    PRIORITY = 45;  
    SCHEDULE = NON;  
    ...  
  }  
  RESOURCE ResourceExample{  
    RESOURCEPROPERTY = STANDARD;  
  }  
  ...  
  ...  
}
```

Hand  
written or  
generated

Input of  
system  
generator

Configure  
the SW  
inside a  
CPU

Oil  
Description

Attributes  
for each  
obj

Compose  
d of  
Objects



# *Introduction To OSEK OS*

## OSEK Implementation Language (OIL)

```
CPU CORTEX-M4 {
```

```
  OS OSEKOS {
```

```
    STATUS = EXTENDED ;
```

```
    STARTUPHOOK = FALSE;
```

```
    ERRORHOOK = FALSE;
```

```
    STACKOVERFLOWHOOK = TRUE;
```

```
    SHUTDOWNHOOK = FALSE;
```

```
    PRETASKHOOK = TRUE;
```

```
    POSTTASKHOOK = TRUE;
```

```
    USEGETSERVICEID = FALSE;
```

```
    USEPARAMETERACCESS = FALSE;
```

```
    USERESSCHEDULER = FALSE;
```

```
    SYSTEMTICKMS = 10
```

```
  };
```

```
TASK TaskA {
```

```
  PRIORITY = 10;
```

```
  SCHEDULE = FULL;
```

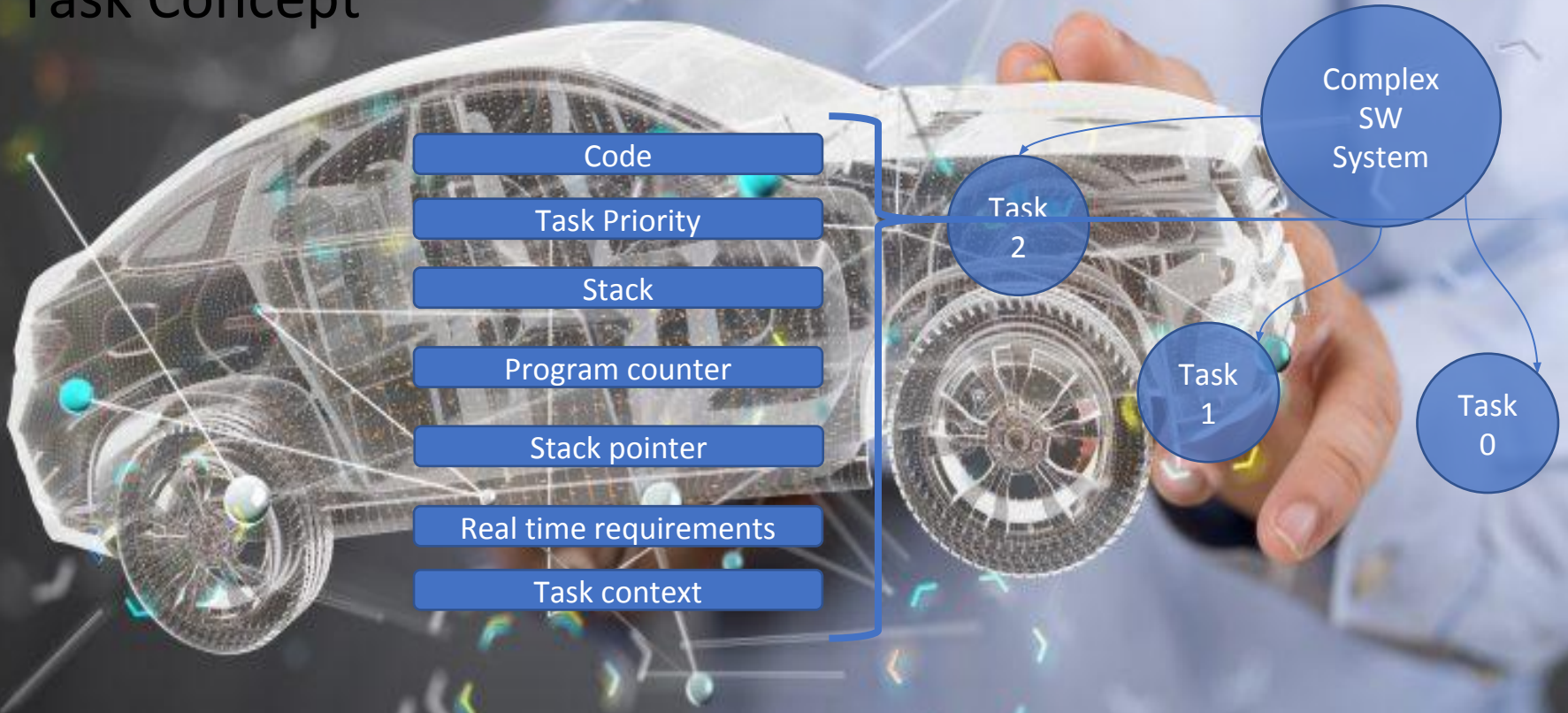
```
  ACTIVATION = 1;
```

```
  AUTOSTART = TRUE {APPMODE = AppMode1;;
```

```
  STACKSIZE = 50;
```

# *Introduction To OSEK OS*

## Task Concept





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## OSEK Task Management

TASK ShapeUpdate{

**PRIORITY = 10;**

**SCHEDULE = FULL/NON;**

Task A Running

Task B Running

OS

Time

Static priority

Preemption

Context

Tas  
k

Code

Stack

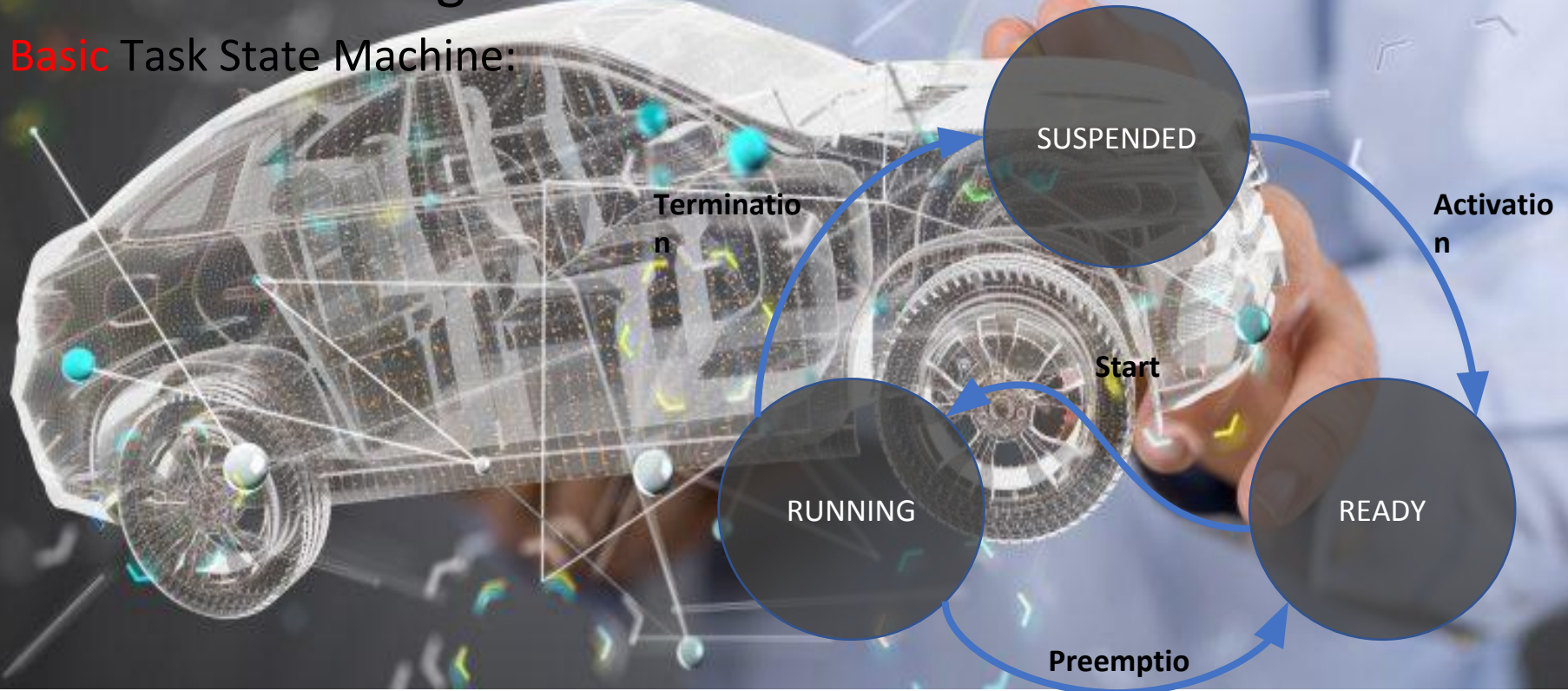
Real time  
requirements



# *Introduction To OSEK OS*

## OSEK Task Management

**Basic** Task State Machine:

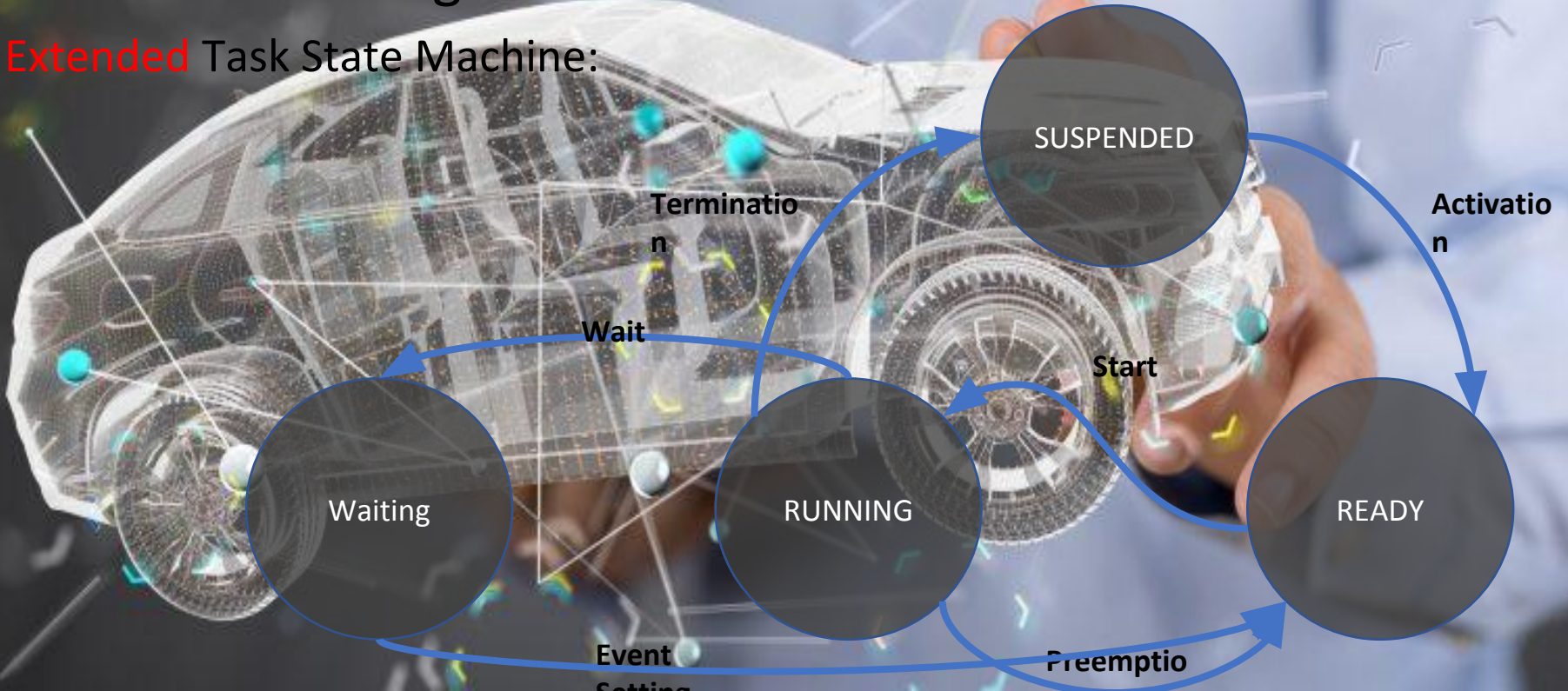




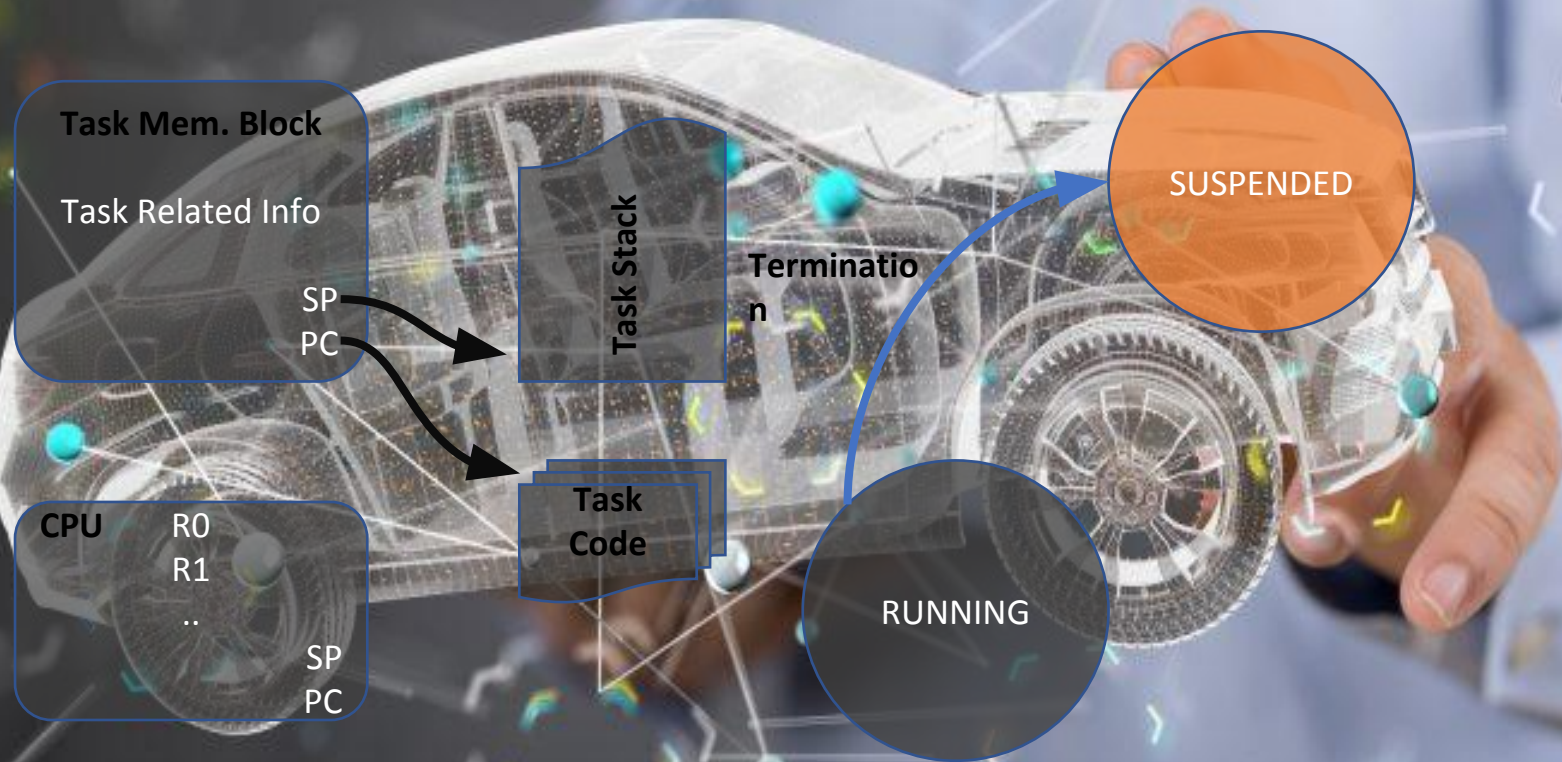
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## OSEK Task Management

**Extended** Task State Machine:

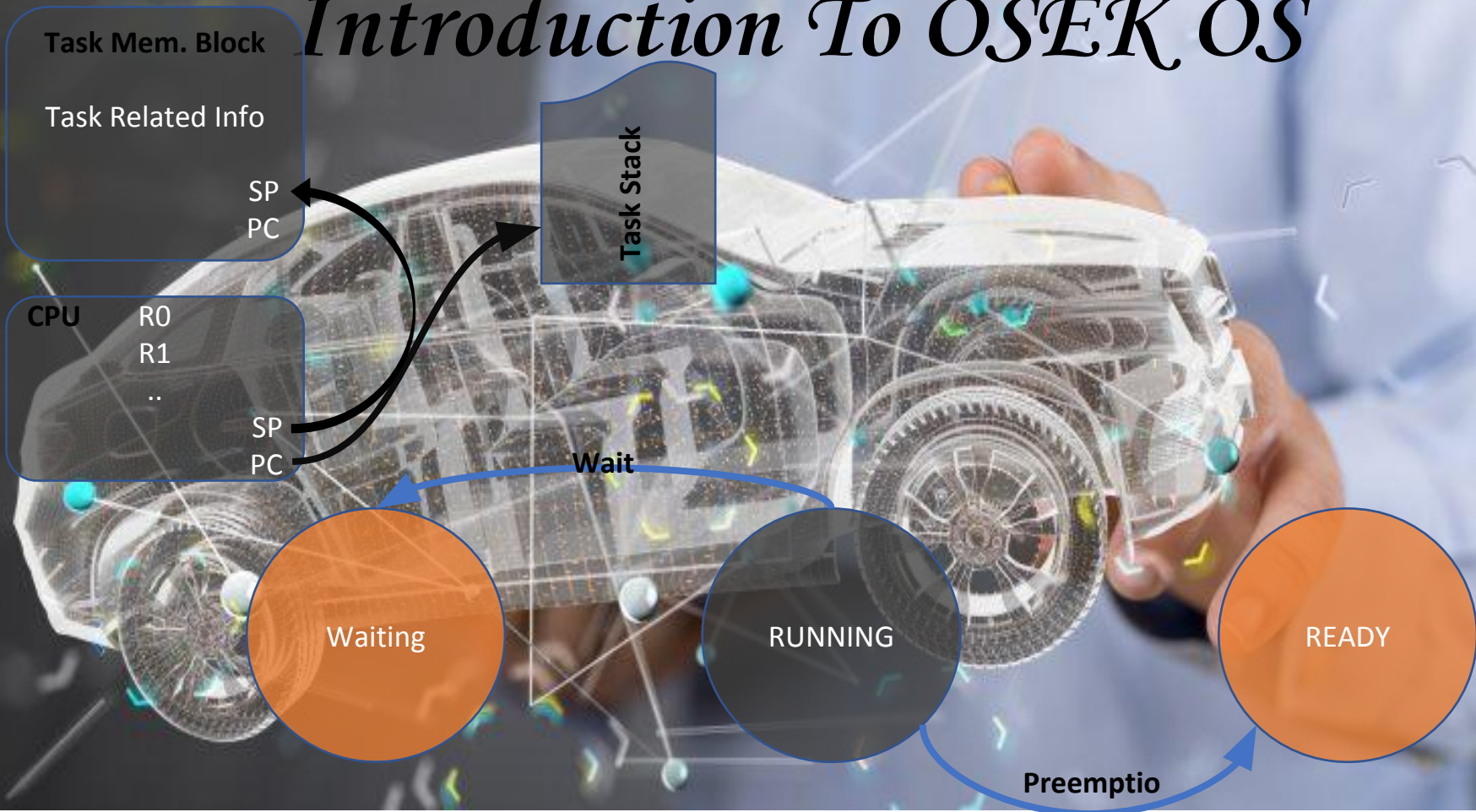


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# *Introduction To OSEK OS*



# *Introduction To OSEK OS*

Task Mem. Block

Task Related Info

SP  
PC

Task Stack

CPU R0  
R1  
..

SP  
PC

SUSPENDED

Activation

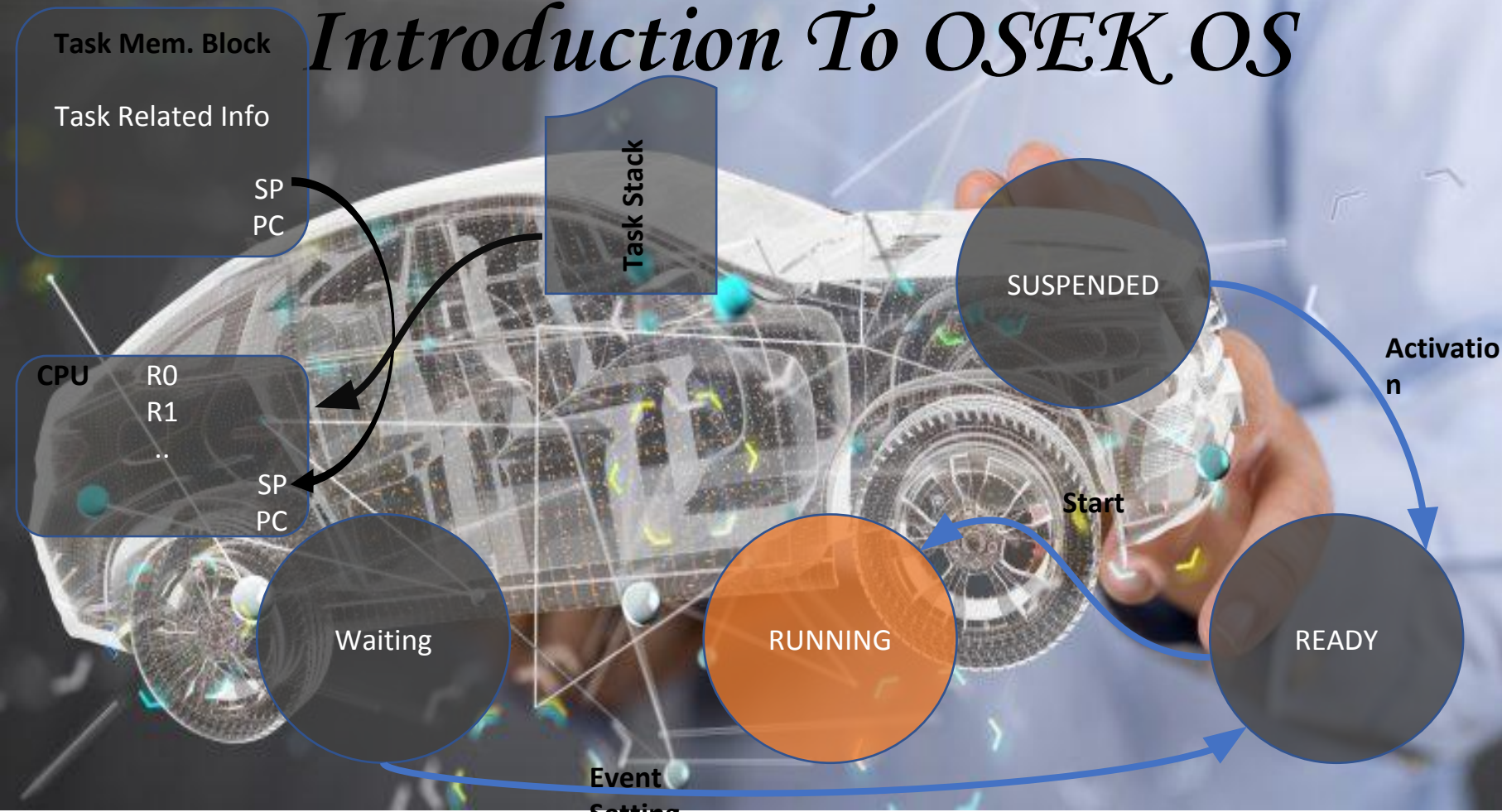
Start

Waiting

RUNNING

READY


Event  
Setting





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## Conformance Classes

- **4 conformance classes** to satisfy different requirements
  - The conformance class is determined based on the following:
    - **Multiple activation** request of task
    - **Task types**
    - Number of **tasks per priority** level
- 

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## Conformance Classes

### **ECC 1:**

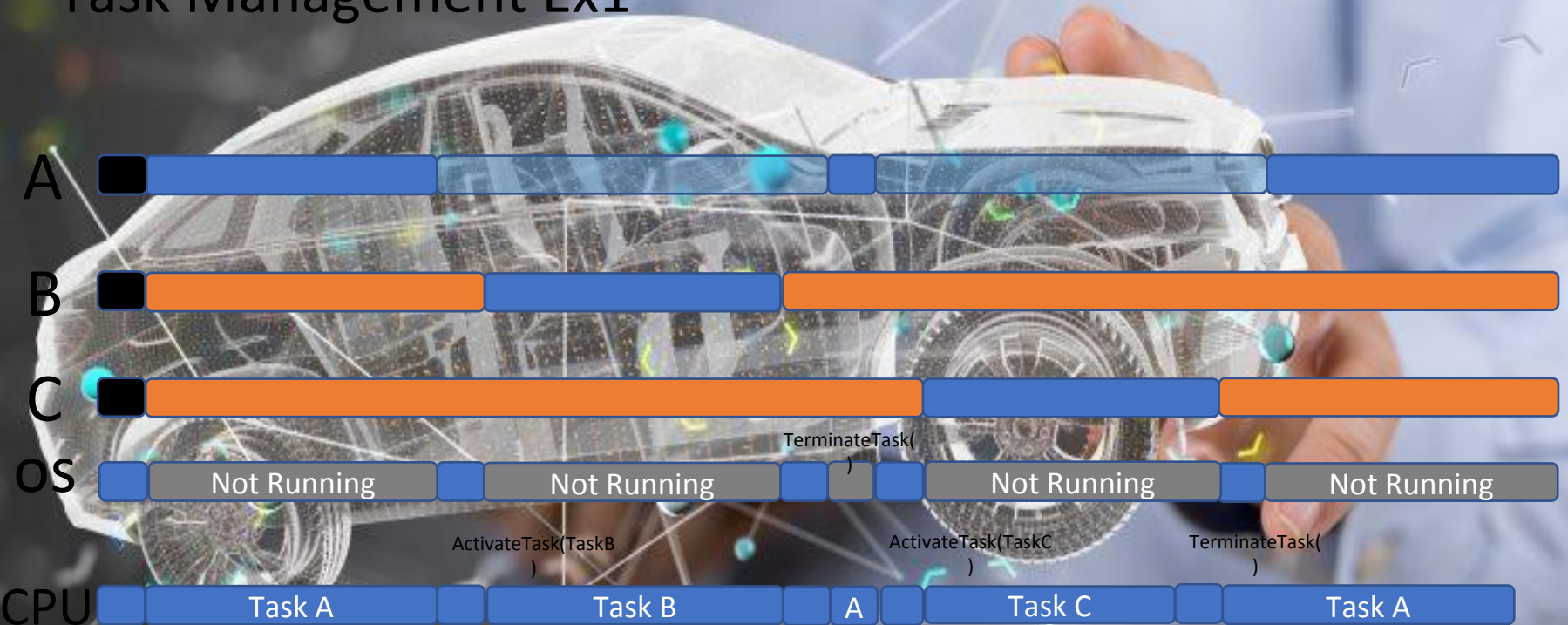
- Basic / extended tasks are supported
- One task per priority Level
- No multiple activation

	Basic task only	Basic& extended task
One Task/Priority No multiple activation	<i>BCC 1</i>	<i>ECC 1</i>
Many Task/Priority Multiple activation	<i>BCC 2</i>	<i>ECC 2</i>



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## Task Management Ex1



# *Introduction To OSEK OS*

## Task Management Ex1

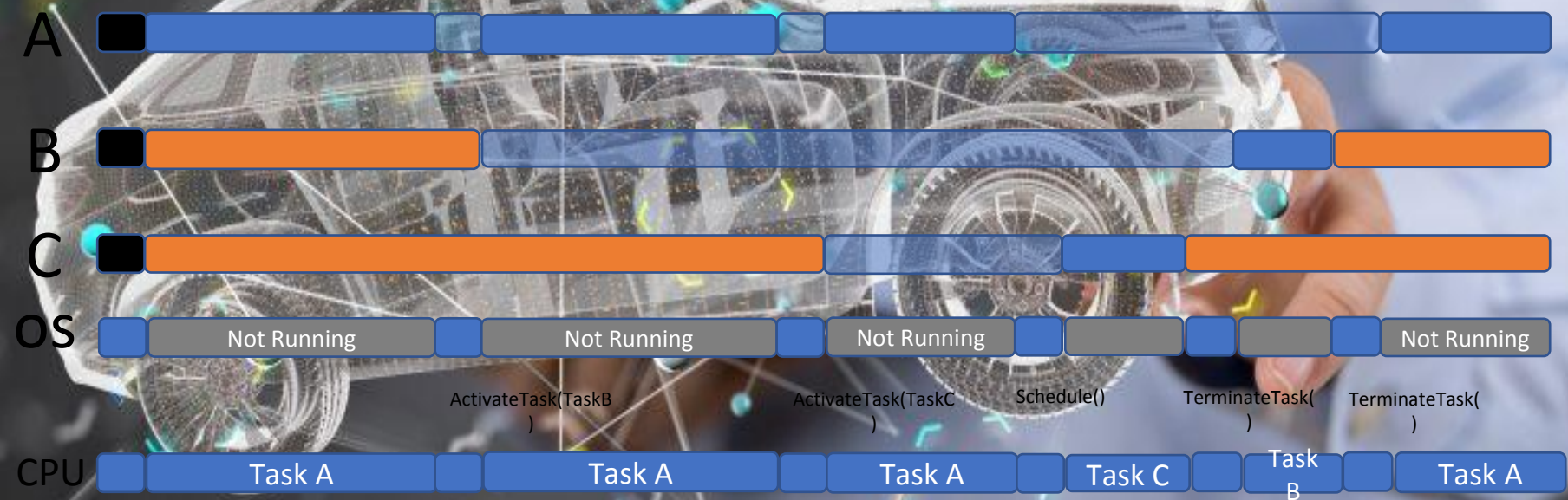
- 
- Oil description understand
  - Code understanding
  - Run/debug



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## Task Management Ex2

Preemptible /non preemptible Task : OSEK provides “**preemptability**” as a task attribute



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Task Management Ex2



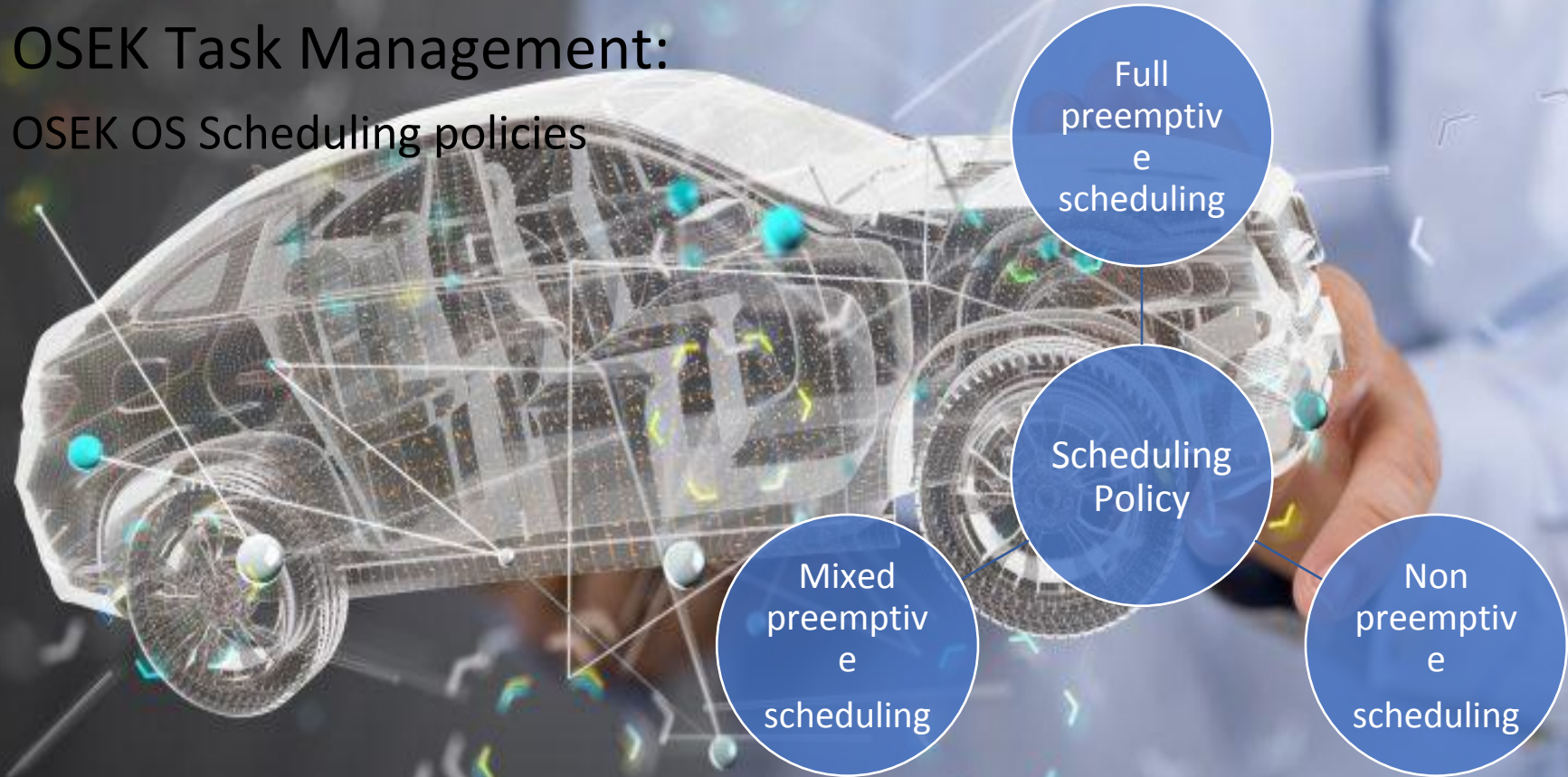
Oil description understand  
Code understanding  
Run/debug



# *Introduction To OSEK OS*

OSEK Task Management:

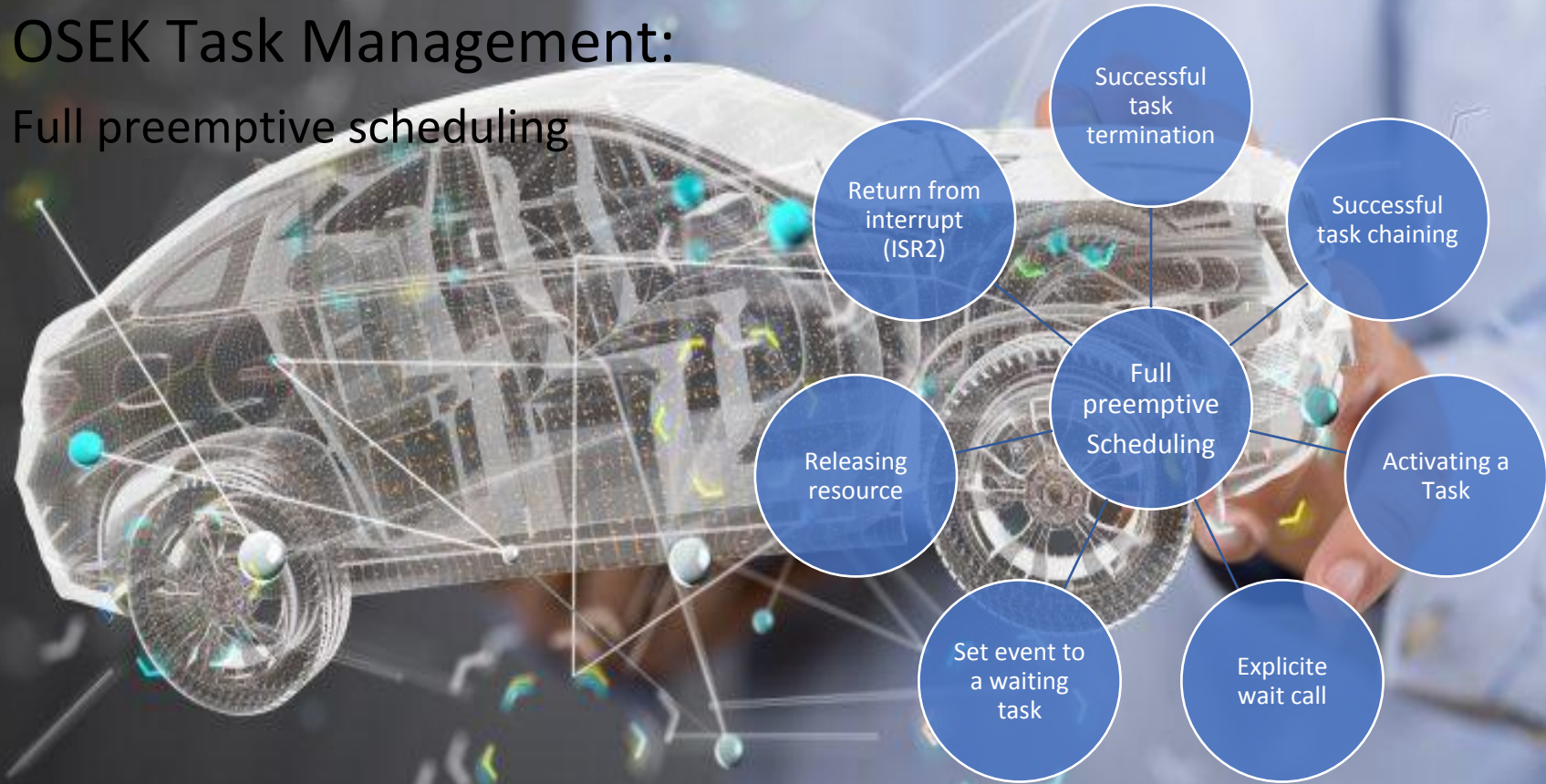
OSEK OS Scheduling policies



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## OSEK Task Management:

Full preemptive scheduling

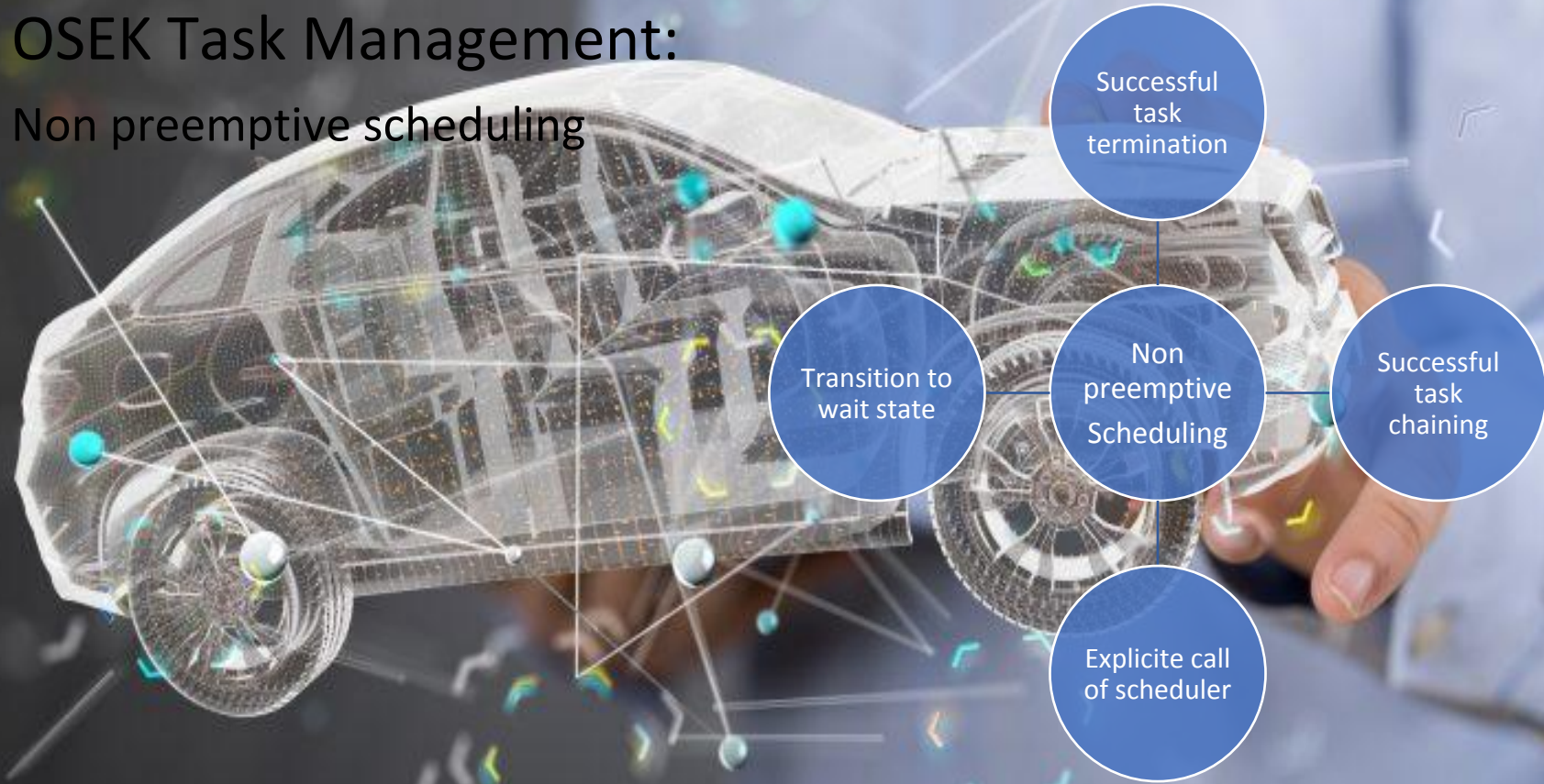




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OSEK Task Management:

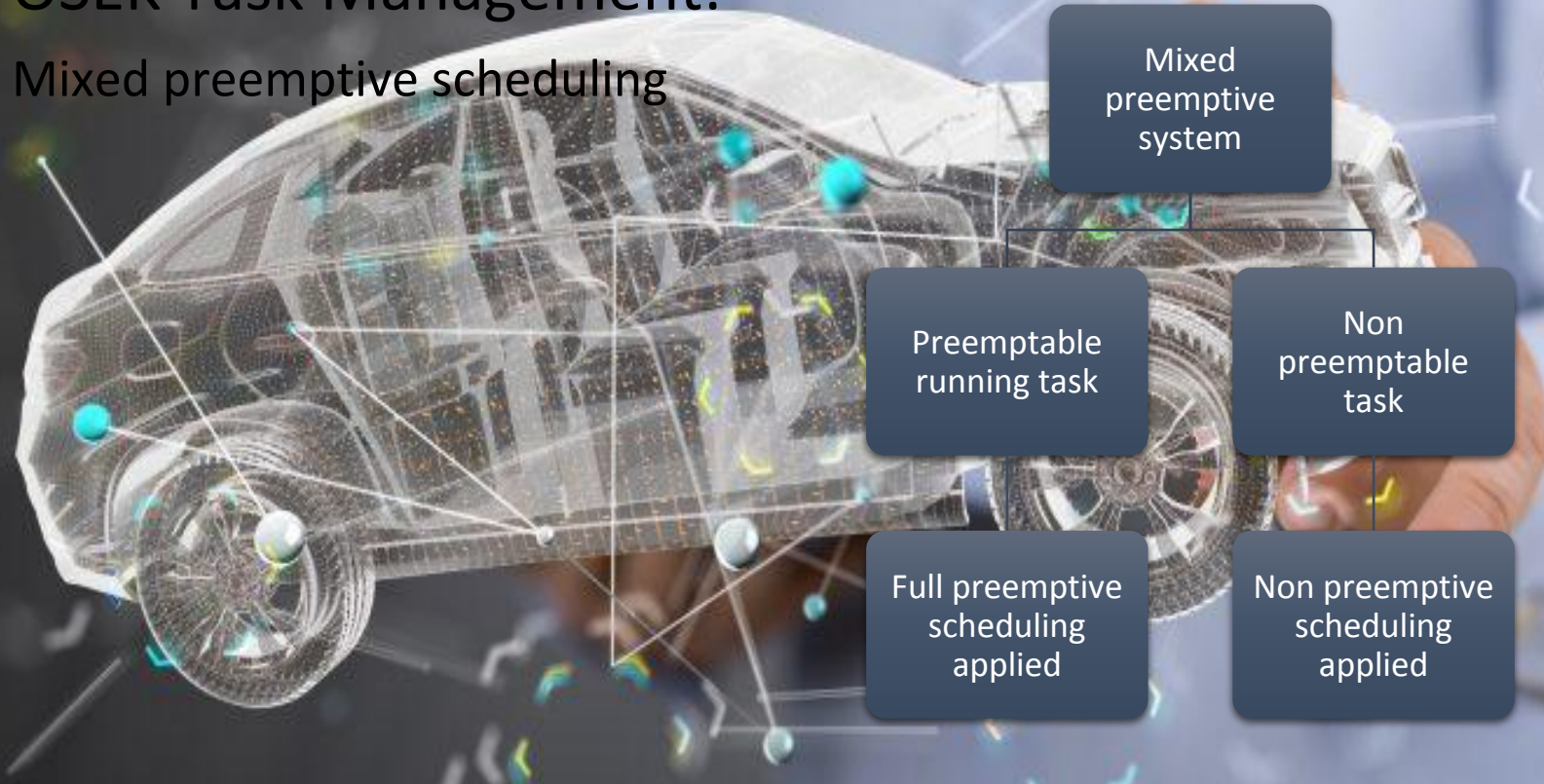
Non preemptive scheduling



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## OSEK Task Management:

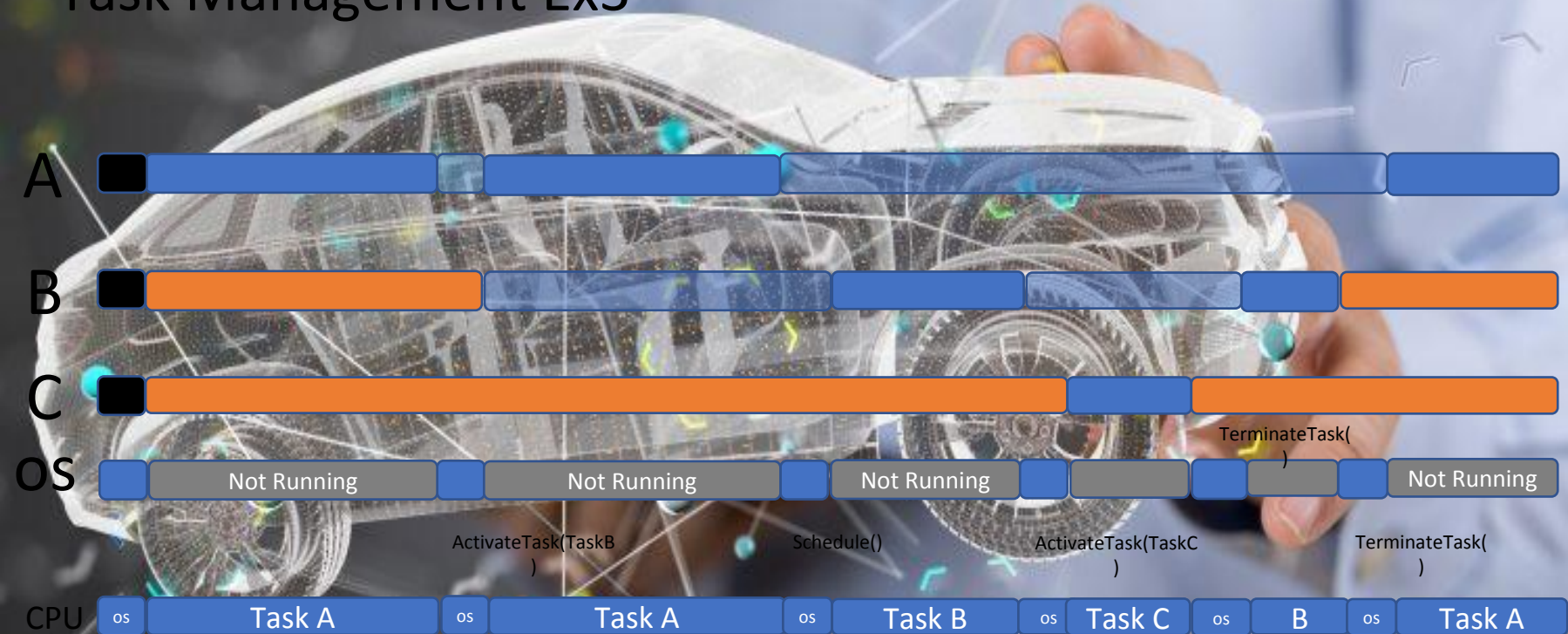
Mixed preemptive scheduling





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## Task Management Ex3



# *Introduction To OSEK OS*

Task Management Ex3

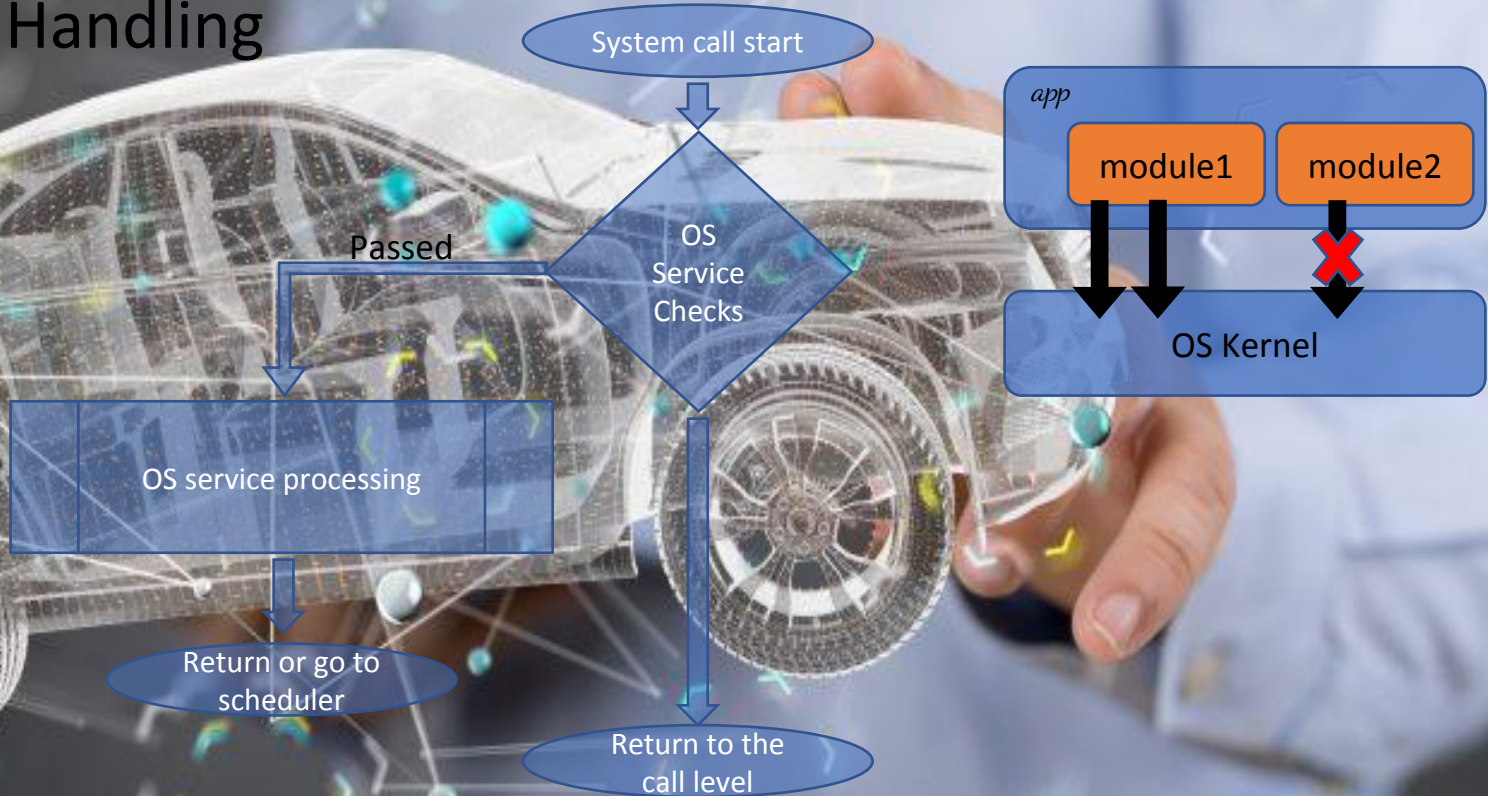


Oil description understand  
Code understanding  
Run/debug



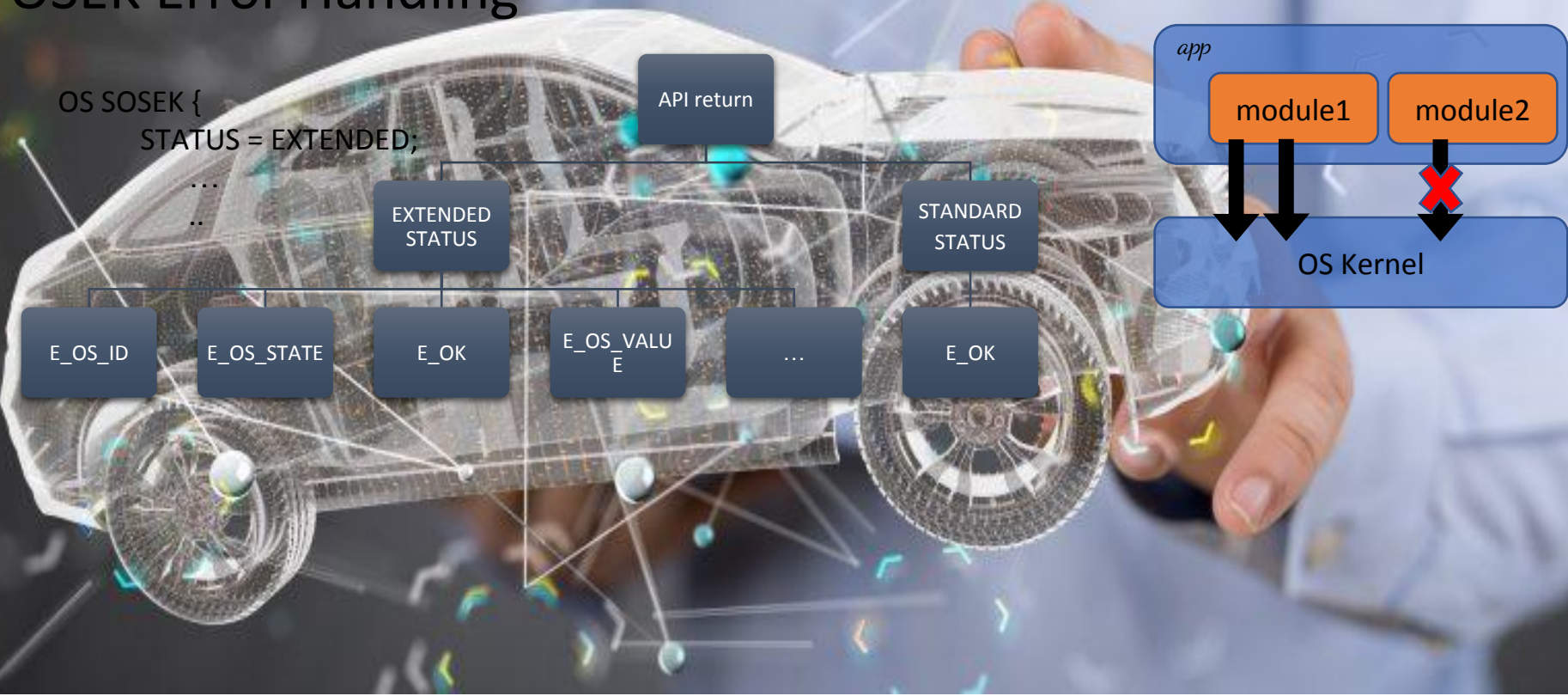
# *Introduction To OSEK OS*

## OSEK Error Handling



# *Introduction To OSEK OS*

## OSEK Error Handling





# *Introduction To OSEK OS*

## OSEK Task Management:

Task management  
services:

StatusType ActivateTask(TaskType Task)

E\_OS\_LIMIT

E\_OS\_ID

E\_OK

# *Introduction To OSEK OS*

## OSEK Task Management:

Task management  
services:

StatusType TerminateTask(void)

E\_OS\_RESOURCE

E\_OS\_CALLLEVEL

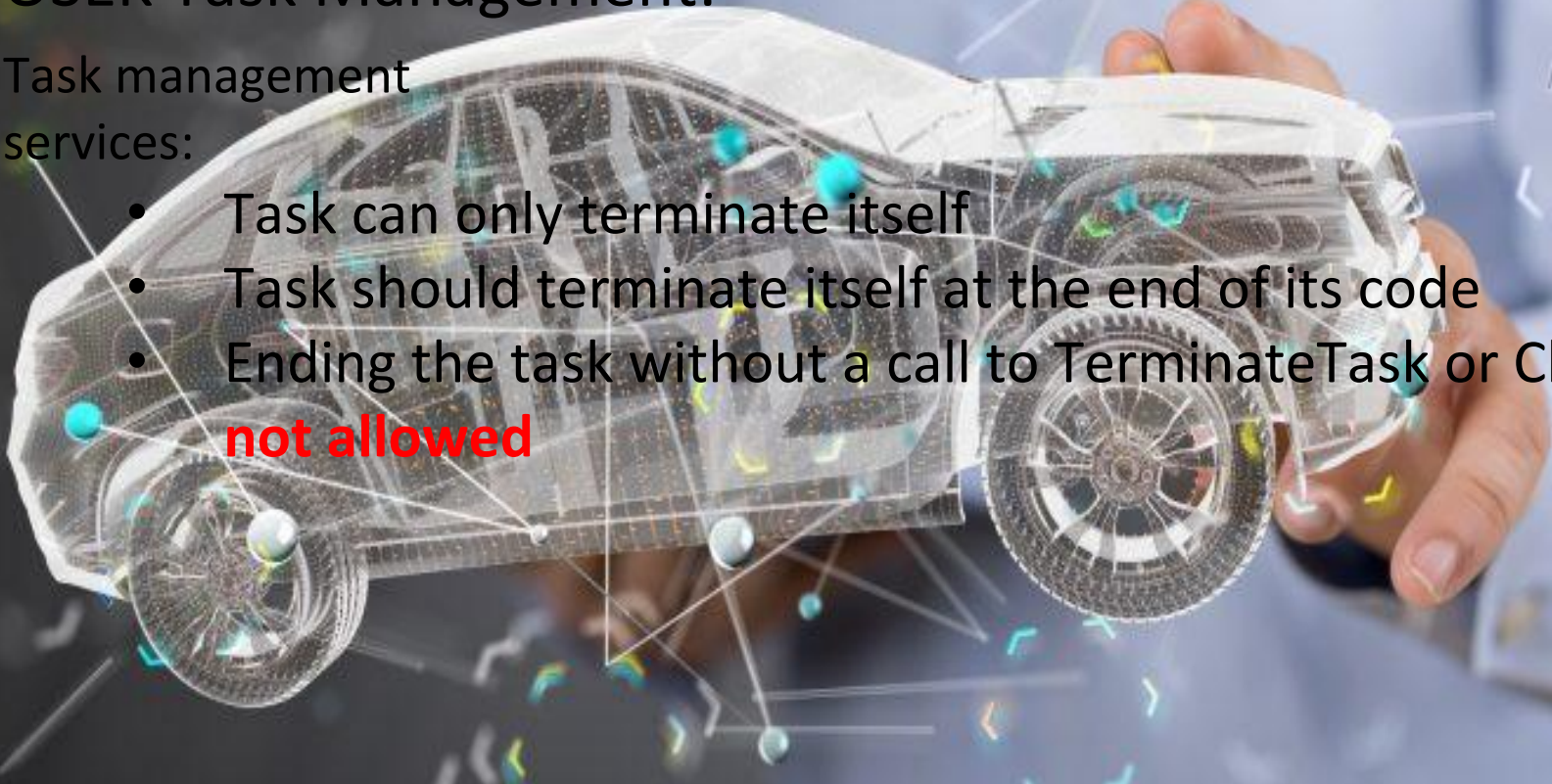


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## OSEK Task Management:

Task management  
services:

- Task can only terminate itself
- Task should terminate itself at the end of its code
- Ending the task without a call to TerminateTask or ChainTask **is not allowed**



# *Introduction To OSEK OS*

## OSEK Task Management:

Task management  
services:

StatusType ChainTask(TaskType TaskID)

E\_OS\_LIMIT

E\_OS\_ID

E\_OS\_RESOURCE

E\_OS\_CALLEVEL



# *Introduction To OSEK OS*

## OSEK Task Management:

Task management  
services:

StatusType Schedule(void)

E\_OS\_CALLEVEL

E\_OK

E\_OS\_RESOURCE

# *Introduction To OSEK OS*

## OSEK Task Management:

Task management services:

- Checks for the **highest priority ready** task
- The system return to the caller only when **ALL higher priority** tasks are done
- Schedule() service has **no effect** on the preemptable tasks



# *Introduction To OSEK OS*

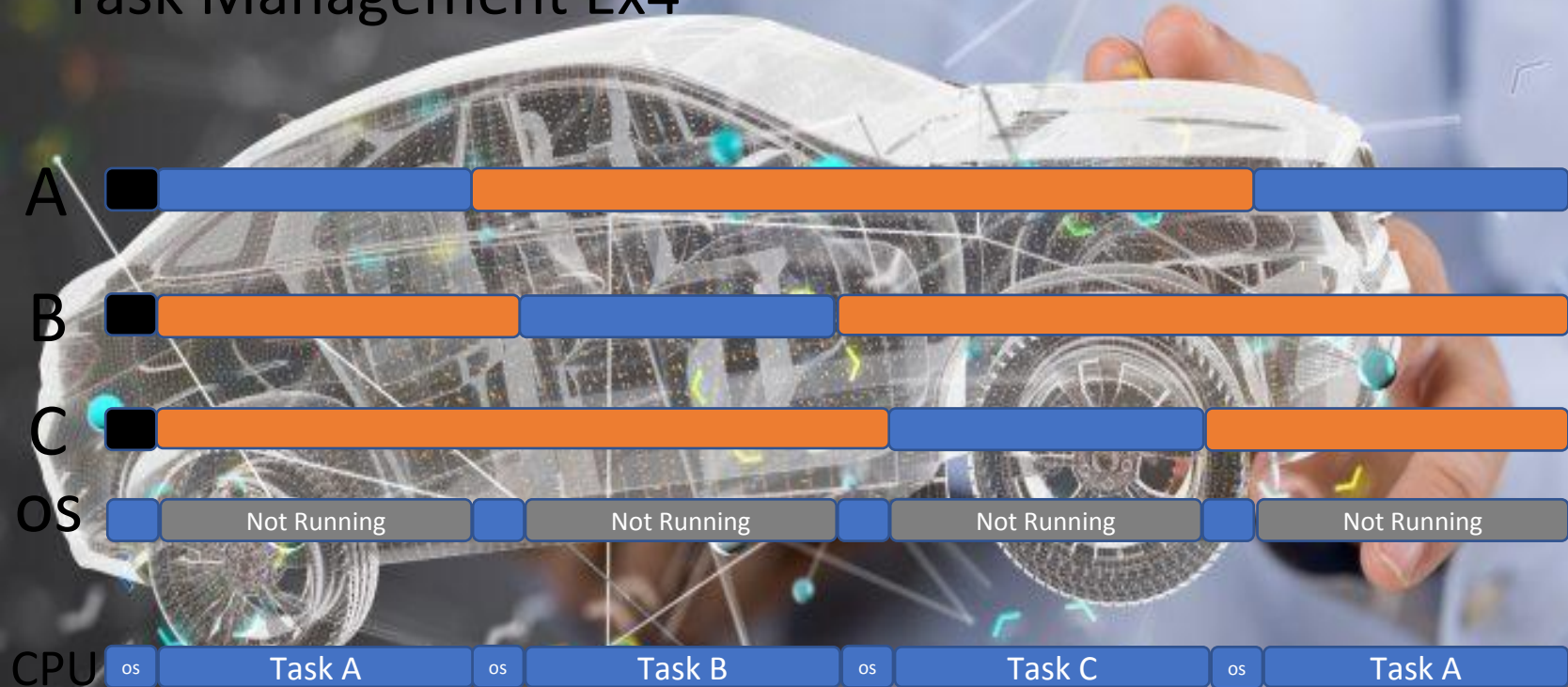
## OSEK Task Management:

Task management  
services:

- `StatusType GetTaskID(TaskRefType TaskID)`
- `StatusType GetTaskState(TaskType TaskID, TaskStateRefType State)`
- `DeclareTask(TaskIdentifier)`
- `TASK(TaskID)`

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## Task Management Ex4





# *Introduction To OSEK OS*

Task Management Ex4



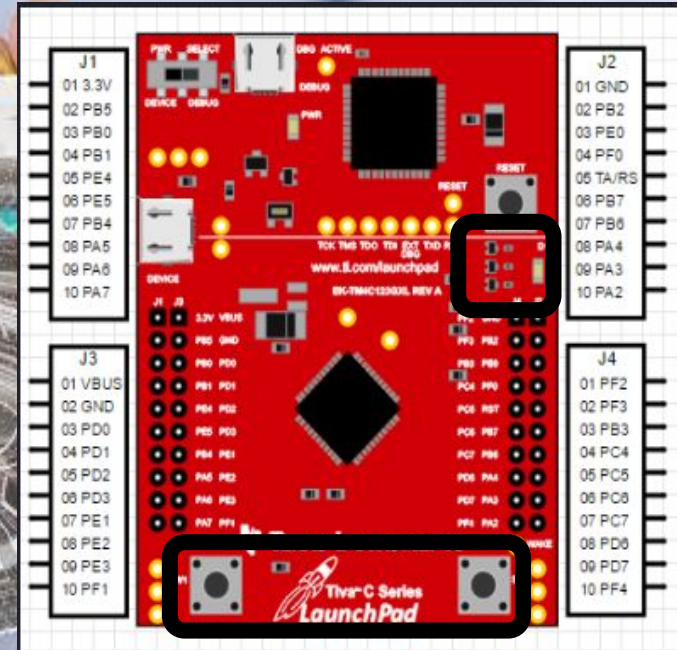
Oil description understand  
Code understanding  
Run/debug

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## Task Management Ex5

### LED simple state machine:

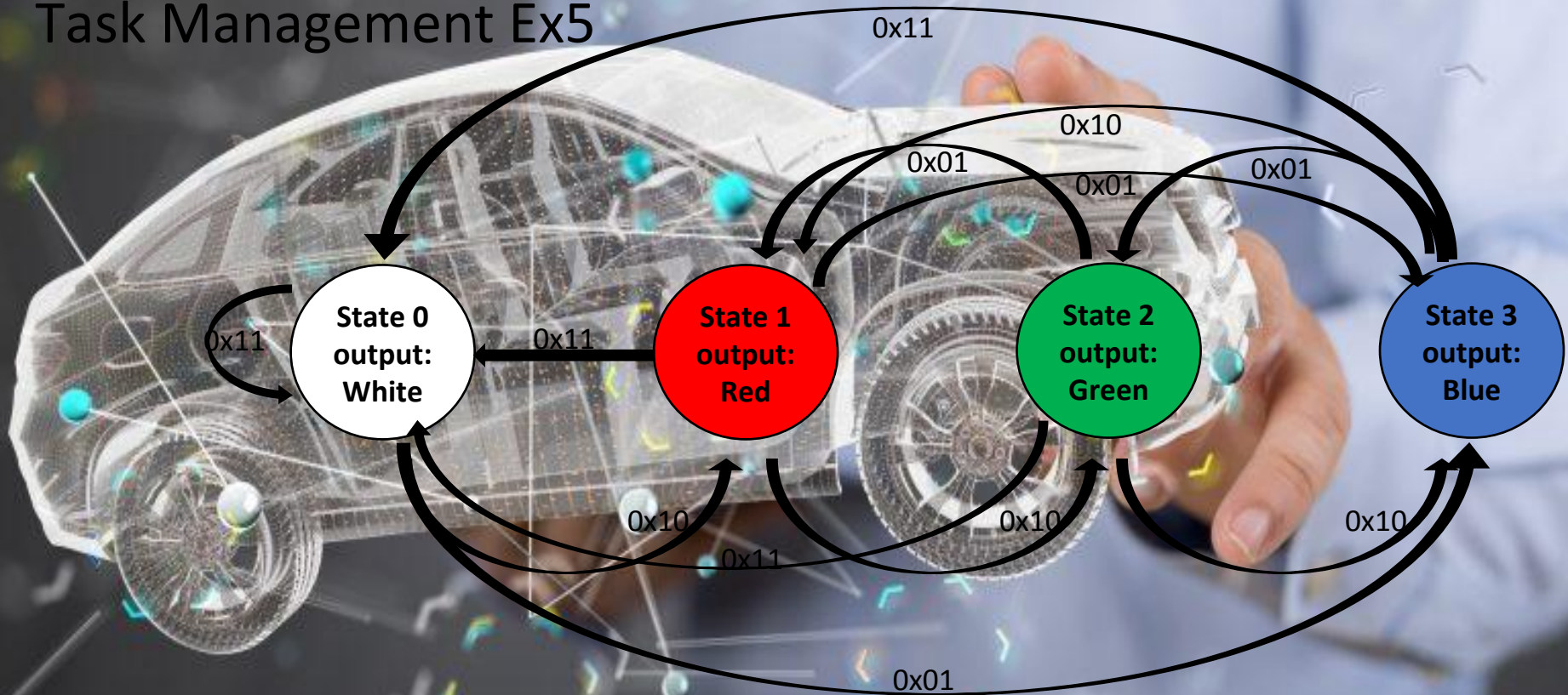
- Input: 2 onboard switches
- Output: 3 LEDs
- Possible state: 4 States





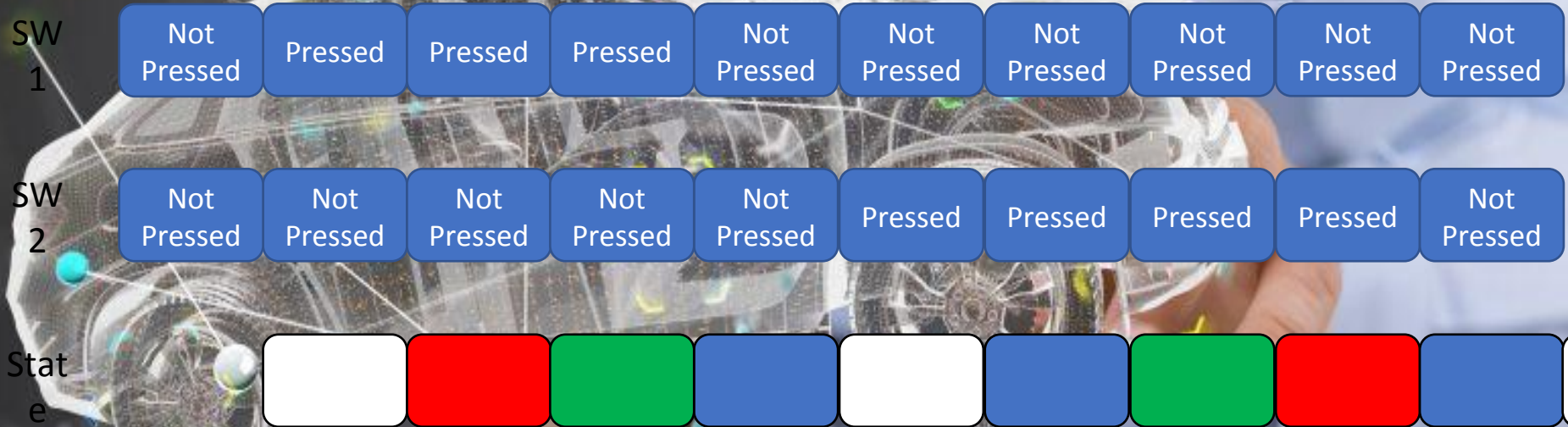
# *Introduction To OSEK OS*

## Task Management Ex5



# *Introduction To OSEK OS*

## Task Management Ex5





# *Introduction To OSEK OS*

Task Management Ex5

A hand in a light blue shirt holds a transparent car model. Overlaid on the car is a complex network diagram with nodes and connecting lines. The nodes are represented by small spheres in cyan, yellow, and white. The lines are thin and grey, creating a web-like structure across the car's body. The background is a blurred image of the same hand and shirt.

LED State Machine Flow  
chart

# *Introduction To OSEK OS*

Task Management Ex5



Oil description understand  
Code understanding  
Run/debug

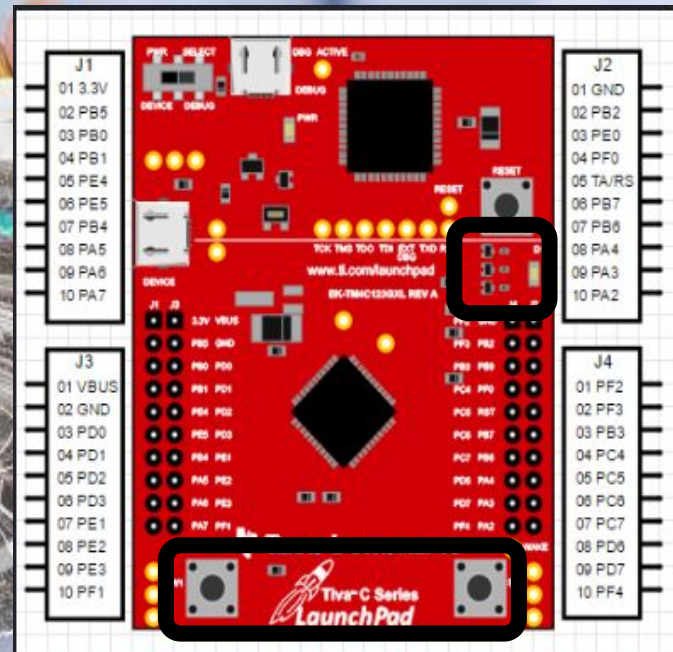


# *Introduction To OSEK OS*

## Task Management Assignment

### LED sequence state machine:

- Input: 2 onboard switches
- Output: 3 LEDs
- Four Tasks shall be implemented:
  - Task\_Init
  - Task\_BasicState
  - Task\_RGB
  - Task\_BGR



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Task Management Ex5

LED Sequence State Machine Flow  
chart

A hand in a light blue shirt holds a transparent car model. Overlaid on the car is a complex network diagram with nodes and connecting lines. The nodes are represented by small spheres in cyan, yellow, and white. The lines are thin and grey, creating a web-like structure across the car's body. The background is a blurred image of the same hand and shirt.



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## Task Management Assignment 2

### High level problem statement

- Alarm should be triggered if at least one of the doors is not closed
- Alarm should not be triggered if both of the doors are closed

### Assumptions

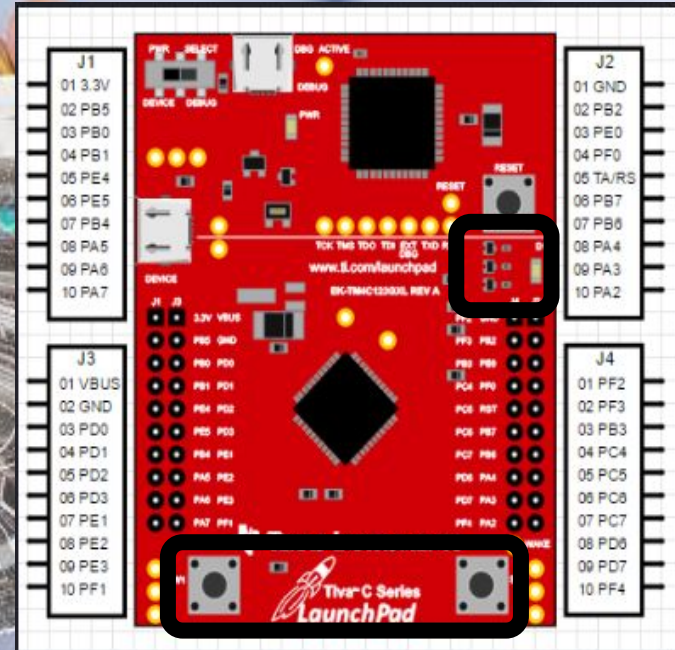
- The system is composed of 2 doors and 1 alarm
- No timing requirements

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## Task Management Assignment 2

### Simplify the problem

- We will assume the sensors and alarm are on the same ECU
- We will use the **on board switches** to represent the door sensors
- We will use the **on board red LED** to represent the alarm activation

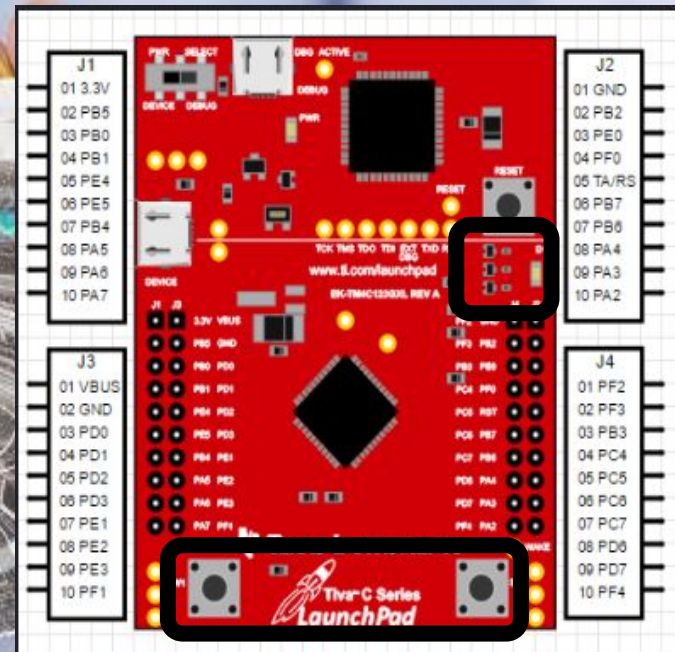




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## Task Management Assignment 2

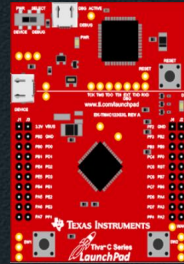
- Write your **own oil description** file
- Use a **different threads** to achieve the whole functionality
- Try to **re-use** from the previous examples(oil/code.. etc.).



```
string sInput;  
int iLength, iN;  
double dblTemp;  
bool again = true;
```

## Intro to OSEK RTOS I

```
while (again) {  
    iN = -1;  
    again = false;  
    getline(cin, sInput);  
    system("cls");  
    stringstream(sInput) >> dblTemp;  
    iLength = sInput.length();  
    if (iLength < 4) {  
        again = true;  
        continue;  
    } else if (sInput[iLength - 3] != '.') {  
        again = true;  
        continue;  
    } while (++iN < iLength) {  
        if (isdigit(sInput[iN])) {  
            continue;  
        } else if (iN == (iLength - 3) ) {  
            continue;  
        }  
    }  
}
```





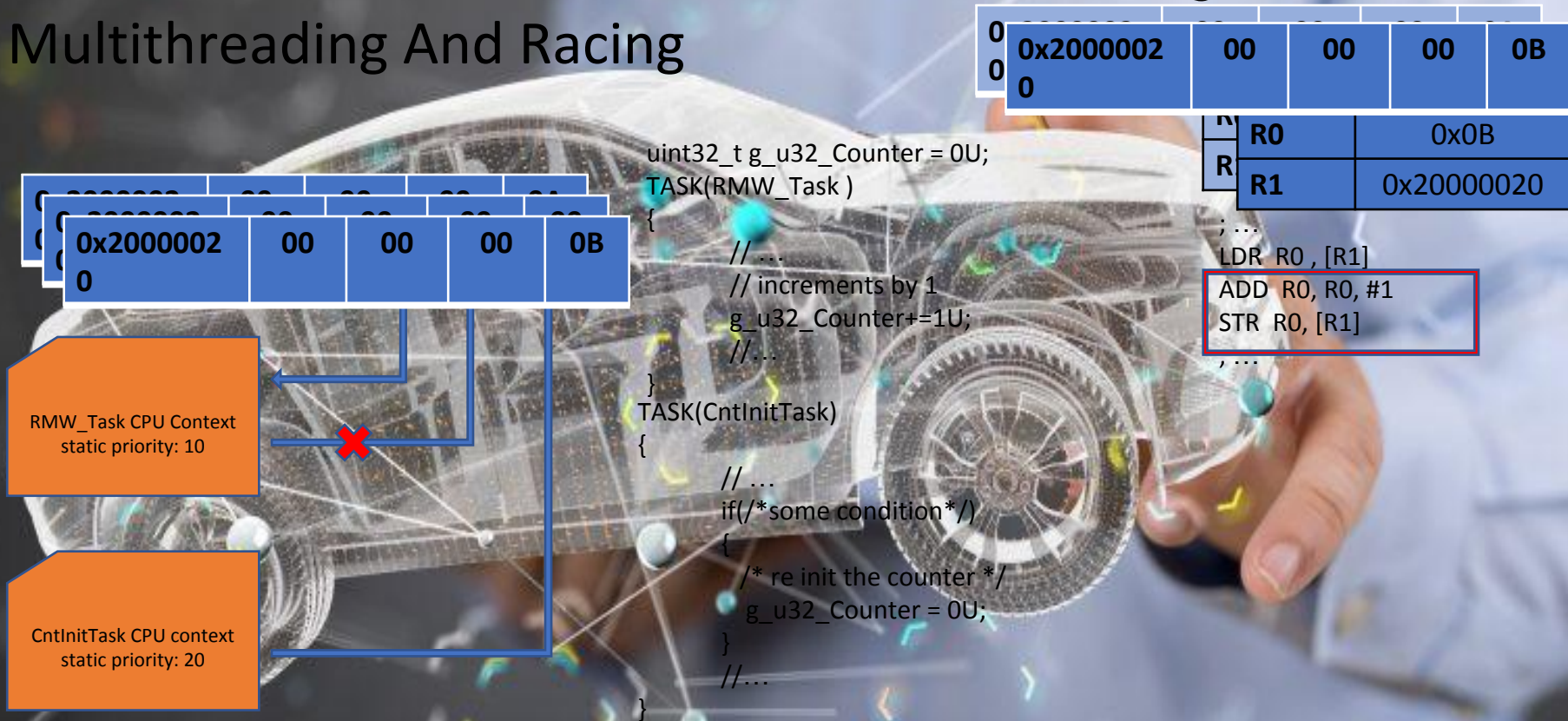
# *Introduction To OSEK OS*

Multithreading and concurrent access



# Introduction To OSEK OS

## Multithreading And Racing





# Introduction To OSEK OS

## Multithreading And Racing

0x2000002	00	00	00	F1
0				

Bit0\_Task CPU Context  
static priority: 10

Bit1\_Task CPU context  
static priority: 20

```
uint8_t EnableMask= 0x00U;  
TASK(Bit0_Task )  
{  
    // ...  
    // EnableMask is 0xF0  
    //Enable bit 0  
    EnableMask |= 0x01  
    //...  
}  
  
TASK(Bit1_Task)  
{  
    // ...  
    if(/*some condition*/)  
    {  
        //Enable bit 1  
        EnableMask |= 0x02;  
    }  
    //...  
}
```

0	0x2000002	00	00	00	F1
0	0				

R0	0xF1
R1	0x20000020

```
;...  
LDRB R0, [R1]  
ORR R0, R0, #1  
STRB R0, [R1]  
;...
```

<b>Correct EnableMask</b>	<b>0xF3</b>	<b>0b1111 0011</b>
<b>Actual EnableMask</b>	<b>0xF1</b>	<b>0b1111 0001</b>

# Introduction To OSEK OS

## Multithreading And Data Inconsistency

Producer Task  
static priority: 10  
Period: 10 ms

Time Stamp	99929.2123
ID	Client _0x01
Data[0]	0x3A
Data[1]	0xB0
...	...
Data[n]	...

Consumer Task  
static priority: 15

- Time stamp: 9960.323
- ID: 0x04
- Data[0..n] = 0x2F, 0x43, 0x8E...etc.

- Time stamp: 9970.397
- ID: 0x02
- Data[0..n] = 0x2F, 0x43, 0x8E...etc.

Producer

Producer

Producer

Producer



# *Introduction To OSEK OS*

Resource Example

- 
- Oil description understand
  - Code understanding
  - Run/debug

# *Introduction To OSEK OS*

## Semaphore, Mutex or Resource

```
uint32_t g_u32_Counter = 0U;  
TASK(Task1)
```

```
{  
    // ...  
    //GetSemaphoreAPI()  
  
    g_u32_Counter+=1U;  
    //..  
    // Accessing the shared  
    // Resource  
  
    //GiveSemaphoreAPI()  
}
```

```
TASK(Task2)
```

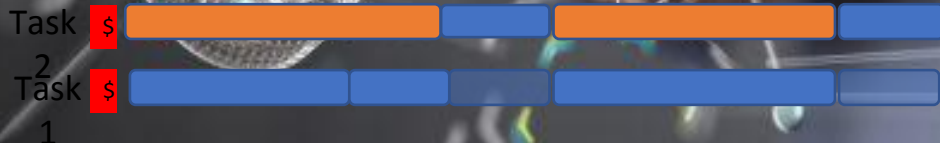
```
{  
    // ...  
    //GetSemaphoreAPI()  
    //..  
    g_u32_Counter = 0U;  
    //..  
    // Accessing the shared  
    // Resource  
  
    //GiveSemaphoreAPI()  
}
```

Task 2 \$  
static priority:  
20

Task 1 \$  
static priority:  
10

Shared Buffer or  
HW Area

Only one task at a time





# *Introduction To OSEK OS*

## Priority inversion problem

- **Higher** priority task is blocked by **lower** priority task(s)

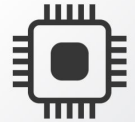


Task 1

static priority:

20

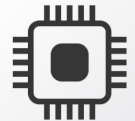
Ready



Task 2

static priority:

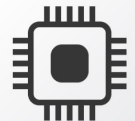
15



Task 3

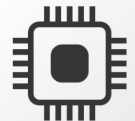
static priority:

10



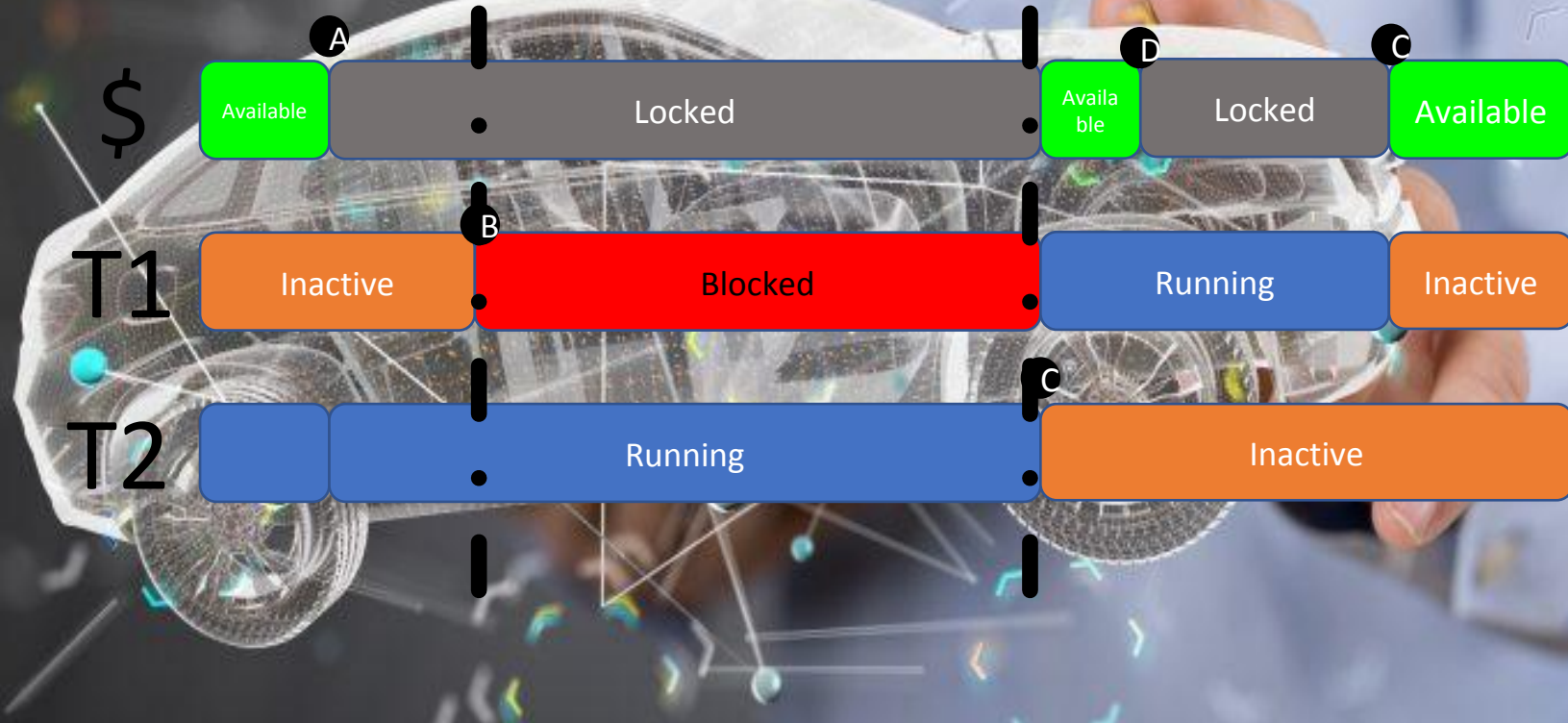
Task 4

static priority: 5



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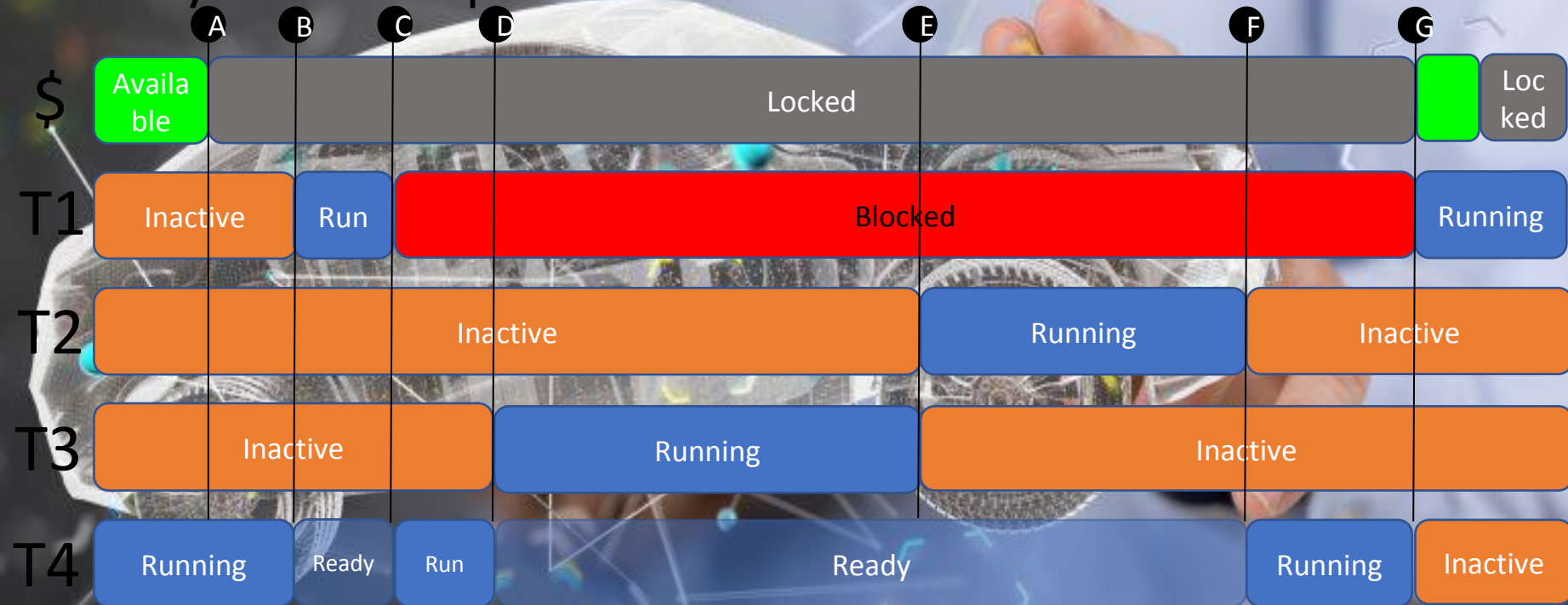
## Priority inversion problem





# *Introduction To OSEK OS*

## Priority inversion problem



# *Introduction To OSEK OS*

## Deadlock problem

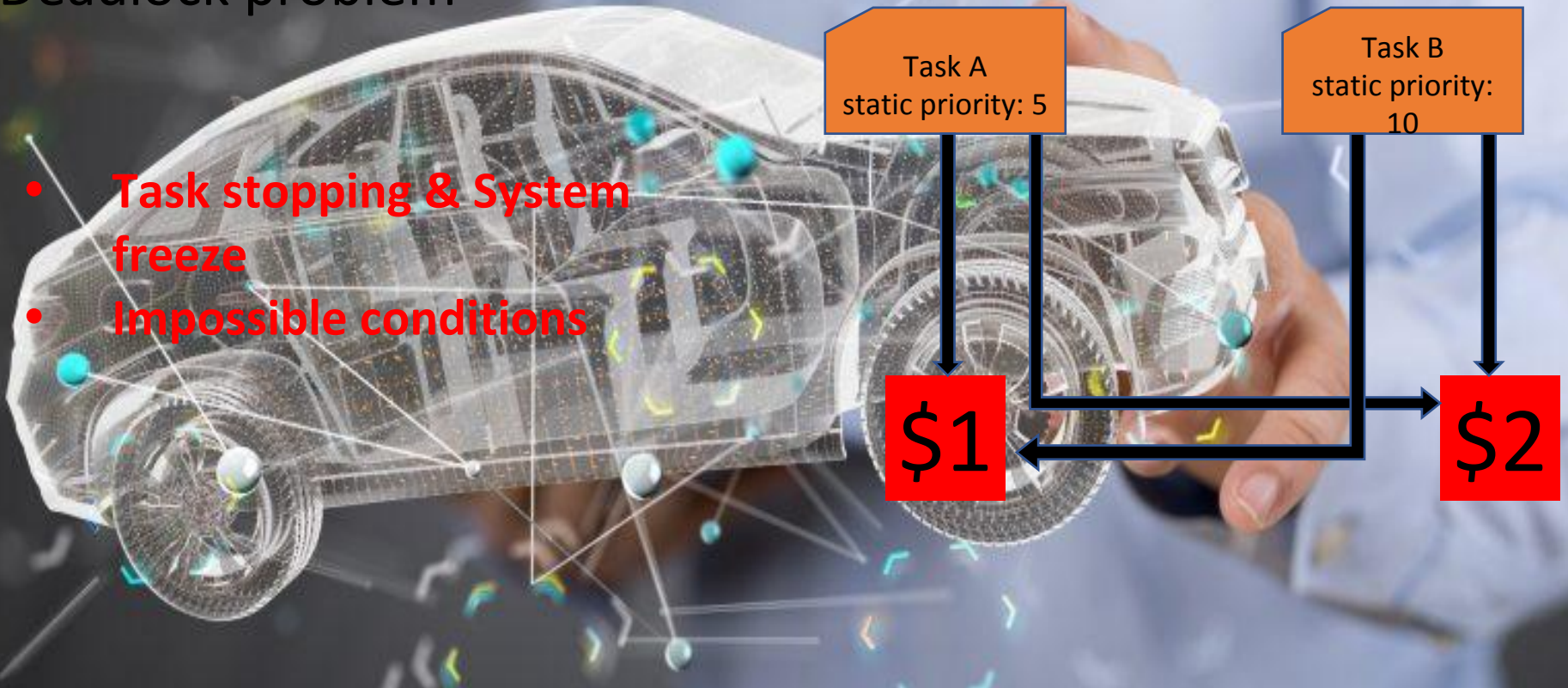
- Task stopping & System freeze
- Impossible conditions

Task A  
static priority: 5

Task B  
static priority: 10

\$1

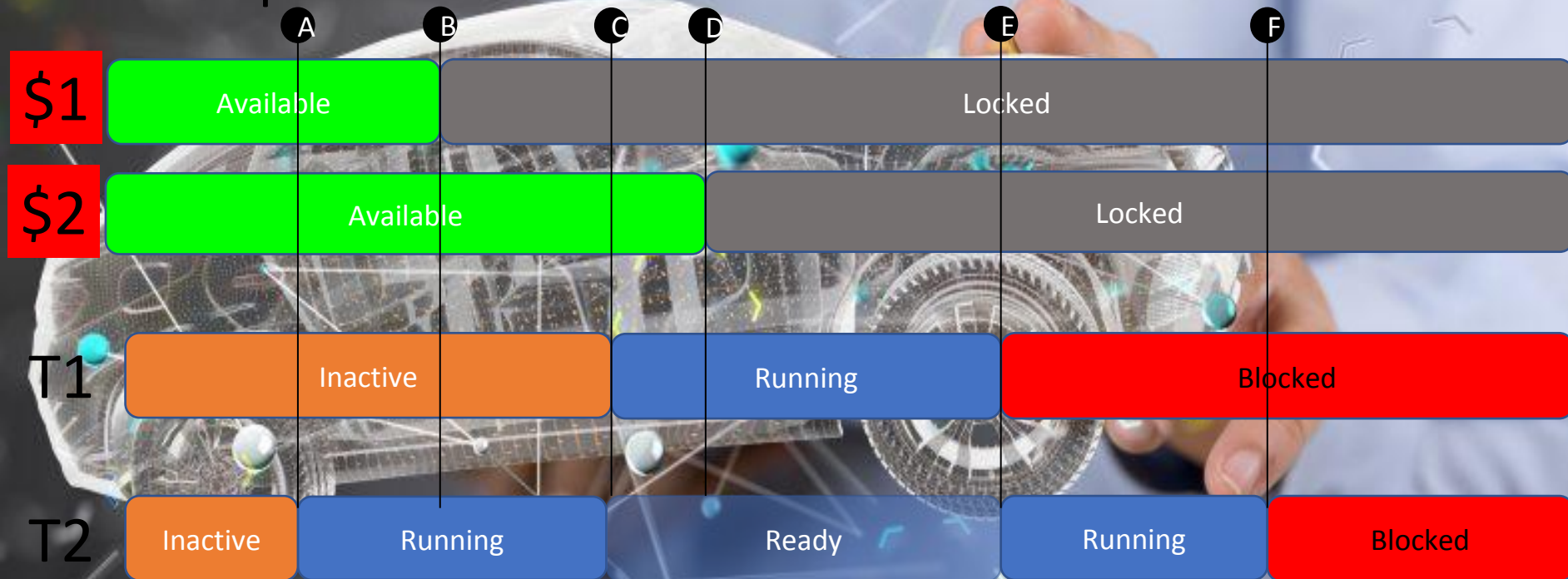
\$2





# *Introduction To OSEK OS*

## Deadlock problem



# *Introduction To OSEK OS*

## OSEK resource management

### **Priority Ceiling Pattern:**

To avoid deadlocks and priority inversion

Co-ordinate  
concurrent  
access

No resource  
based  
blocking  
state

One task  
occupy a  
resource at  
a time

Resource  
Management

No priority  
inversion

No  
deadlock



# Introduction To OSEK OS

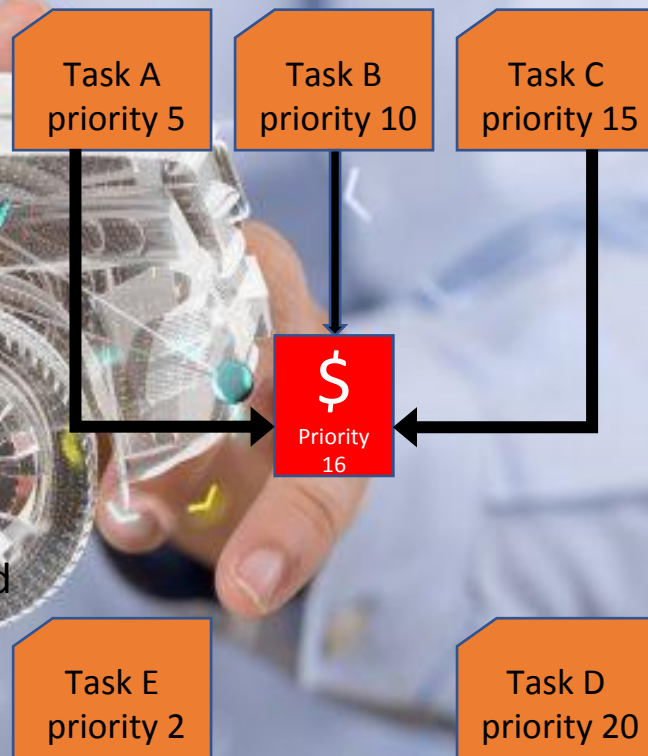
## OSEK priority ceiling protocol

- **At generation/compilation time**

1. Every  $\$$  Priority level (the ceiling priority)
2. Priority level  $>$  max user task priority
3. Priority level  $<$  min non user task priority (if higher than the highest user)

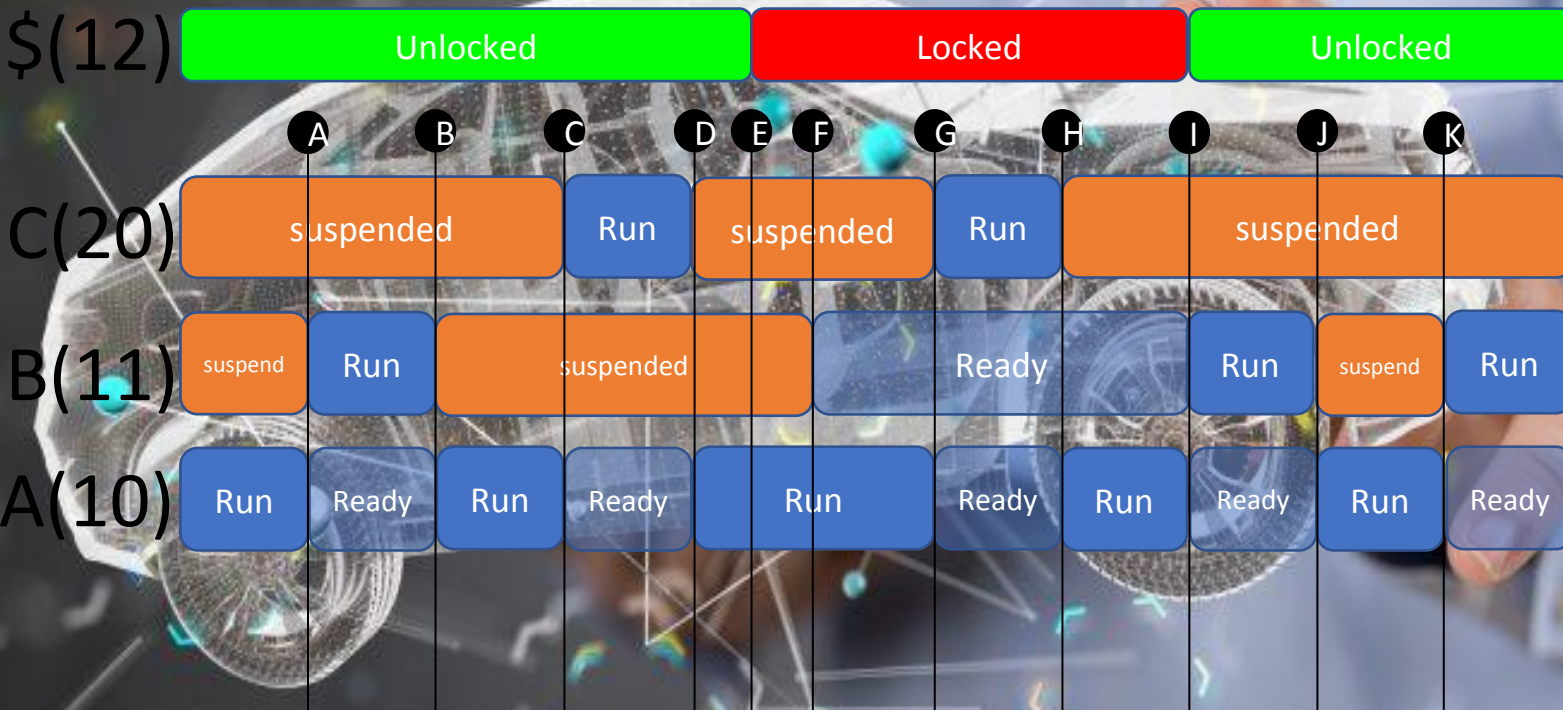
- **Run time behavior**

1. Requiring a resource  $\square$  execute at the ceiling priority level
2. Releasing a resource  $\square$  back to the nominal priority level
- $\square$  Scheduling point if preemptable thread



# *Introduction To OSEK OS*

## Resource Management Example 1





# *Introduction To OSEK OS*

Resource Example

- 
- Oil description understand
  - Code understanding
  - Run/debug

# *Introduction To OSEK OS*

## OSEK resources APIs

***StatusType GetResource ( ResourceType <ResID> StatusType ReleaseResource ( ResourceType <ResID> )***

1. Entering the critical section
2. The Ceiling priority will be applied
3. The used error codes:

1. E\_OK
2. E\_OS\_ID
3. E\_OS\_ACCESS

1. Leave the critical section
2. The static priority will be applied
3. The used error codes:

1. E\_OK
2. E\_OS\_ID
3. E\_OS\_NOFUNC
4. E\_OS\_ACCESS



# *Introduction To OSEK OS*

OSEK resources APIs

## ***Usage restriction while holding resource***

- *TerminateTask* -> *E\_OS\_RESOURCE*
- *ChainTask* -> *E\_OS\_RESOURCE*
- *Schedule* -> *E\_OS\_RESOURCE*
- *WaitEvent* -> *E\_OS\_RESOURCE*

# *Introduction To OSEK OS*

## Resource Management Example 2

- 
- Oil description understand
  - Code understanding
  - Run/debug



```
string sInput;  
int iLength, iN;  
double dblTemp;  
bool again = true;
```

## Intro to OSEK RTOS I

```
while (again) {  
    iN = -1;  
    again = false;  
    getline(cin, sInput);  
    system("cls");  
    stringstream(sInput) >> dblTemp;  
    iLength = sInput.length();  
    if (iLength < 4) {  
        again = true;  
        continue;  
    } else if (sInput[iLength - 3] != '.') {  
        again = true;  
        continue;  
    } while (++iN < iLength) {  
        if (isdigit(sInput[iN])) {  
            continue;  
        } else if (iN == (iLength - 3) ) {  
            continue;  
        }  
    }  
}
```

