

PROJECT

Finding Lane Lines on the Road

A part of the Self-Driving Car Program

PROJECT REVIEW

NOTES

SHARE YOUR ACCOMPLISHMENT!  

Meets Specifications

Hello,

Good work overall, you did a good job with your pipeline, Keep this up 😊

Congratulations, on meeting all of the specifications and good luck with your Self Driving Car Nanodegree. 🙌

Required Files

The project submission includes all required files



Lane Finding Pipeline

The output video is an annotated version of the input video.



Well done providing an annotated output video!

In a rough sense, the left and right lane lines are accurately annotated throughout almost all of the video. Annotations can be segmented or solid lines



Your pipeline is pretty good, with resulting lines right on target. ✅



Visually, the left and right lane lines are accurately annotated by solid lines throughout most of the video.

- Single solid line ✓
- On target ✓

The left and right lane lines are accurately annotated throughout most of the video. Well done!!



Your parameter choice is awesome.

For further reading and references:

[link1](#)

[link2](#)

[link3](#) for optional video.

[link4](#)

Reflection



Reflection describes the current pipeline, identifies its potential shortcomings and suggests possible improvements. There is no minimum length. Writing in English is preferred but you may use any language.

- pipeline description ✓
- shortcomings: ✓ curved lane lines
- possible improvements: ✓ polynomial fitting