```
%Sage Herrin, Numerical Analysis 1, Prof. Coffey
clear all;close all;clc
```

Solutions to question 3.5, 1

```
%First solution
A = [1 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0; 1 \ 1 \ 1 \ 1 \ 0 \ 0 \ 0; 0; 0 \ 0 \ 0 \ 1 \ 0 \ 0; 0; 0 \ 0 \ 0 \ 1 \ 1 \ 1
     \begin{smallmatrix} 0 & 1 & 2 & 3 & 0 & -1 & 0 & 0; 0 & 0 & 2 & 6 & 0 & 0 & -2 & 0; 0 & 0 & 2 & 0 & 0 & 0; 0 & 0 & 0 & 0 & 0 & 2 \\ \end{smallmatrix}
 6];
b = [0 \ 1 \ 1 \ 2 \ 0 \ 0 \ 0]';
x = A b
%second solution
syms a0 b0 c0 d0 a1 b1 c1 d1
eqn1 = a0 == 0;
eqn2 = a0 + b0 + c0 + d0 == 1;
eqn3 = a1 == 1;
eqn4 = a1 + b1 + c1 + d1 == 2;
eqn5 = b0 + 2*c0 + 3*d0 - b1 == 0;
eqn6 = 2*c0 + 6*d0 - 2*c1 == 0;
eqn7 = 2*c0 == 0;
eqn8 = 2*c1 + 6*d1 == 0;
[s1 s2 s3 s4 s5 s6 s7 s8] = solve(eqn1, eqn2, eqn3, eqn4, eqn5, eqn6,
 eqn7, eqn8,a0, b0, c0, d0, a1, b1, c1, d1);
S = [s1 \ s2 \ s3 \ s4 \ s5 \ s6 \ s7 \ s8]
x =
      0
      1
      0
      1
      1
      0
S =
[ 0, 1, 0, 0, 1, 1, 0, 0]
```

Solution to written question

```
clear all;close all;clc
```

```
%define initial starting points of each function
y = -0.5;
x = 0.5;
xp1 = [];
yp1 = [];
%define given eqns to perfomr 2D NR on
for i = 1:15
    f1 = x + tan(y);
    f2 = y + 2*cos(x) - exp(x);
    %define Jacobian with respective partials
    J = det([1 sec(y)^2; -2*cos(x) - exp(x) 1]);
    %defind h and k matrices used to solve system
    h = (1/J)*det([-f1 sec(y)^2;-f2 1]);
    k = (1/J)*det([1 -f1;-2*sin(x) - exp(x) -f2]);
    %determine next iteration of X values
   xp1 = [xp1 x + h;];
    yp1 = [yp1 y + k];
    x = xp1(end);
    y = yp1(end);
end
xp1(end)
yp1(end)
ans =
  0.390315944920470
ans =
  -0.372130278535266
```

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