ML project

Me

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Reading the given training and test sets

```
knitr::opts_chunk$set(echo = TRUE)
library(caret)

## Loading required package: lattice

## Loading required package: ggplot2

library(ggplot2)

pml_training<- read.csv('pml-training.csv')
pml_testing<- read.csv('pml-testing.csv')</pre>
```

Having a quick look at our training and test sets

```
head(pml_training)
str(pml_training)
head(pml_testing)
str(pml_testing)
```

Cleaning the data

Step 1: Dealing with NA values

NA strategy: if a variable or column has more than 50% NA values then we will omit it from our dataset. Any variable that satisfies this condition and has less than or equal to 50% NA values will be kept. After that we will impute the remaining NA values and check if it will be a viable predictor for our model building or not

```
cond<- colSums(is.na(pml_training))<= (0.50*nrow(pml_training))
my_cleanset<- pml_training[, cond] #subsetting our training set to include only those variabl
es that satisfy cond i.e. we will only keep a variable or column that has 50% or lesser NA va
lues</pre>
```

We are now checking for any integer or numeric variables that are being stored in character format and convert them into numeric class. We will apply the same condition from before i.e. we will only keep a variable or column that has 50% or lesser NA values

```
character_variables<- my_cleanset[,sapply(my_cleanset, class)=='character']
str(character_variables)</pre>
```

We will now apply our NA strategy to see which variables to keep and which variables to remove. "" is the same as NA value in character format

```
cond2<- colSums(character_variables=="")<= (0.50*nrow(character_variables)) #we want to find
how many of the character variables can be converted into numeric class provided they have a
tleast 50% of the values i.e. we will tolerate maximum 50% NA values
cond2
character_variables_subset<- character_variables[,cond2] #subsetting character_variables so t
hat it satisfies our cond2 or the NA strategy
head(character_variables_subset) #so we don't need any of the columns aside from user_name, c
vtd_timestamp, new_window and classe as they did not satisfy cond2</pre>
```

Now doing the appropriate class conversions

```
library(dplyr)
## Attaching package: 'dplyr'
## The following objects are masked from 'package:stats':
##
##
       filter, lag
## The following objects are masked from 'package:base':
##
##
       intersect, setdiff, setequal, union
library(lubridate)
##
## Attaching package: 'lubridate'
## The following objects are masked from 'package:base':
##
       date, intersect, setdiff, union
##
character_variables_subset <- mutate(character_variables_subset, cvtd_timestamp= dmy_hm(cvtd_</pre>
timestamp))
str(character variables subset)
```

Now replacing the proper preprocessed columns in character_variables_subset to my_cleanset or our training set

```
my_cleanset2<- my_cleanset
my_cleanset2$cvtd_timestamp<- character_variables_subset$cvtd_timestamp
my_cleanset<- my_cleanset2</pre>
```

Now we are removing all the unnecessary character variables that did not satisfy cond2

```
char_var_to_be_removed<- names(character_variables[,!cond2])
my_cleanset<- select(my_cleanset, -char_var_to_be_removed)</pre>
```

```
## Note: Using an external vector in selections is ambiguous.
## i Use `all_of(char_var_to_be_removed)` instead of `char_var_to_be_removed` to silence this
message.
## i See <a href="https://tidyselect.r-lib.org/reference/faq-external-vector.html">https://tidyselect.r-lib.org/reference/faq-external-vector.html</a>.
## This message is displayed once per session.
```

Step 2: Data conversions and removing remaining unnecessary variables**

Converting classe and new_window into factor variables

```
my_cleanset$classe<- as.factor(my_cleanset$classe)
my_cleanset$new_window<- as.factor(my_cleanset$new_window)</pre>
```

We will use nearZeroVar() to find out the variables that have near zero variance and will omit them from our model building process

```
library(ISLR)
library(caret)
```

```
## Loading required package: lattice
```

```
## Loading required package: ggplot2
```

nearZeroVar(my_cleanset, saveMetrics = TRUE) #so the variable new_window has near zero varian ce. So it won't be a good predictor for our model.

```
##
                         freqRatio percentUnique zeroVar
## X
                                     100.00000000
                          1.000000
                                                    FALSE FALSE
## user_name
                          1.100679
                                       0.03057792
                                                    FALSE FALSE
## raw_timestamp_part_1
                          1.000000
                                       4.26562022
                                                    FALSE FALSE
## raw_timestamp_part_2
                          1.000000
                                      85.53154622
                                                    FALSE FALSE
## cvtd_timestamp
                          1.000668
                                       0.10192641
                                                    FALSE FALSE
## new_window
                         47.330049
                                       0.01019264
                                                    FALSE TRUE
## num_window
                                       4.37264295
                                                    FALSE FALSE
                          1.000000
## roll_belt
                          1.101904
                                       6.77810621
                                                    FALSE FALSE
## pitch belt
                          1.036082
                                       9.37722964
                                                    FALSE FALSE
## yaw_belt
                          1.058480
                                       9.97349913
                                                    FALSE FALSE
## total accel belt
                          1.063160
                                       0.14779329
                                                    FALSE FALSE
## gyros belt x
                          1.058651
                                       0.71348486
                                                    FALSE FALSE
## gyros_belt_y
                          1.144000
                                       0.35164611
                                                    FALSE FALSE
## gyros_belt_z
                          1.066214
                                       0.86127816
                                                    FALSE FALSE
## accel belt x
                          1.055412
                                       0.83579655
                                                    FALSE FALSE
## accel belt y
                          1.113725
                                       0.72877383
                                                    FALSE FALSE
## accel belt z
                          1.078767
                                       1.52379982
                                                    FALSE FALSE
## magnet_belt_x
                          1.090141
                                       1.66649679
                                                    FALSE FALSE
                          1.099688
                                                    FALSE FALSE
## magnet_belt_y
                                       1.51870350
## magnet belt z
                          1.006369
                                       2.32901845
                                                    FALSE FALSE
## roll arm
                         52.338462
                                      13.52563449
                                                    FALSE FALSE
## pitch_arm
                         87.256410
                                      15.73234125
                                                    FALSE FALSE
## yaw_arm
                         33.029126
                                      14.65701763
                                                    FALSE FALSE
## total_accel_arm
                          1.024526
                                       0.33635715
                                                    FALSE FALSE
## gyros_arm_x
                          1.015504
                                       3.27693405
                                                    FALSE FALSE
                          1.454369
                                                    FALSE FALSE
## gyros_arm_y
                                       1.91621649
## gyros_arm_z
                          1.110687
                                       1.26388747
                                                    FALSE FALSE
## accel arm x
                          1.017341
                                       3.95984099
                                                    FALSE FALSE
## accel_arm_y
                          1.140187
                                       2.73672409
                                                    FALSE FALSE
## accel_arm_z
                                                    FALSE FALSE
                          1,128000
                                       4.03628580
## magnet_arm_x
                          1.000000
                                       6.82397309
                                                    FALSE FALSE
## magnet arm y
                          1.056818
                                       4.44399144
                                                    FALSE FALSE
## magnet_arm_z
                          1.036364
                                       6.44684538
                                                    FALSE FALSE
## roll_dumbbell
                                                    FALSE FALSE
                          1.022388
                                      84.20650290
## pitch_dumbbell
                                      81.74498012
                                                    FALSE FALSE
                          2.277372
## yaw_dumbbell
                          1.132231
                                      83.48282540
                                                    FALSE FALSE
## total accel dumbbell
                          1.072634
                                       0.21914178
                                                    FALSE FALSE
## gyros_dumbbell_x
                          1.003268
                                       1.22821323
                                                    FALSE FALSE
                          1.264957
                                                    FALSE FALSE
  gyros_dumbbell_y
                                       1.41677709
## gyros_dumbbell_z
                                       1.04984201
                                                    FALSE FALSE
                          1.060100
## accel dumbbell x
                          1.018018
                                       2.16593619
                                                    FALSE FALSE
## accel dumbbell y
                          1.053061
                                       2.37488533
                                                    FALSE FALSE
## accel dumbbell z
                          1.133333
                                       2.08949139
                                                    FALSE FALSE
## magnet_dumbbell_x
                          1.098266
                                       5.74864948
                                                    FALSE FALSE
## magnet dumbbell y
                          1.197740
                                      4.30129447
                                                    FALSE FALSE
## magnet_dumbbell_z
                          1.020833
                                       3.44511263
                                                    FALSE FALSE
## roll_forearm
                         11.589286
                                      11.08959331
                                                    FALSE FALSE
## pitch forearm
                         65.983051
                                      14.85577413
                                                    FALSE FALSE
## yaw forearm
                         15.322835
                                      10.14677403
                                                    FALSE FALSE
## total accel forearm
                                       0.35674243
                                                    FALSE FALSE
                          1.128928
## gyros_forearm_x
                          1.059273
                                       1.51870350
                                                    FALSE FALSE
## gyros_forearm_y
                          1.036554
                                       3.77637346
                                                    FALSE FALSE
## gyros forearm z
                          1.122917
                                       1.56457038
                                                    FALSE FALSE
## accel forearm x
                          1.126437
                                       4.04647844
                                                    FALSE FALSE
## accel forearm y
                          1.059406
                                       5.11160942
                                                    FALSE FALSE
## accel_forearm_z
                          1.006250
                                       2.95586586
                                                    FALSE FALSE
```

#We also no that the variable X contains just the serial numbers so we won't need it.

so removing X and new_window from our train set

```
my_cleanset_updated<- select(my_cleanset, -c(X, new_window))
str(my_cleanset_updated) #this is the final cleaned and formatted train set</pre>
```

```
## 'data.frame':
                 19622 obs. of 58 variables:
                       : chr "carlitos" "carlitos" "carlitos" ...
## $ user_name
## $ raw_timestamp_part_1: int 1323084231 1323084231 1323084232 1323084232 1323084232
84232 1323084232 1323084232 1323084232 1323084232 ...
  $ raw_timestamp_part_2: int 788290 808298 820366 120339 196328 304277 368296 440390 4843
23 484434 ...
## $ cvtd_timestamp
                       : POSIXct, format: "2011-12-05 11:23:00" "2011-12-05 11:23:00" ...
## $ num window
                       : int 11 11 11 12 12 12 12 12 12 12 ...
## $ roll belt
                       : num 1.41 1.41 1.42 1.48 1.48 1.45 1.42 1.42 1.43 1.45 ...
                            8.07 8.07 8.07 8.05 8.07 8.06 8.09 8.13 8.16 8.17 ...
## $ pitch belt
                       : num
## $ yaw_belt
                       : num
                             -94.4 -94.4 -94.4 -94.4 -94.4 -94.4 -94.4 -94.4 -94.4
## $ total accel belt
                       : int
                            3 3 3 3 3 3 3 3 3 ...
                       ##
  $ gyros_belt_x
## $ gyros belt y
                       : num 00000.0200000...
## $ gyros belt z
                       : num
                             -0.02 -0.02 -0.02 -0.03 -0.02 -0.02 -0.02 -0.02 -0.02 0 ...
## $ accel belt x
                       : int
                             -21 -22 -20 -22 -21 -21 -22 -22 -20 -21 ...
## $ accel belt y
                       : int
                            4 4 5 3 2 4 3 4 2 4 ...
## $ accel_belt_z
                       : int 22 22 23 21 24 21 21 21 24 22 ...
## $ magnet_belt_x
                       : int
                             -3 -7 -2 -6 -6 0 -4 -2 1 -3 ...
## $ magnet belt y
                       : int 599 608 600 604 600 603 599 603 602 609 ...
## $ magnet belt z
                       : int
                             -313 -311 -305 -310 -302 -312 -311 -313 -312 -308 ...
                             ## $ roll arm
                       : num
                       : num 22.5 22.5 22.5 22.1 22.1 22 21.9 21.8 21.7 21.6 ...
## $ pitch_arm
## $ yaw arm
                       : num
                             $ total_accel_arm
##
                       : int 34 34 34 34 34 34 34 34 34 ...
                             ## $ gyros arm x
                       : num
##
  $ gyros_arm_y
                       : num
                             0 -0.02 -0.02 -0.03 -0.03 -0.03 -0.03 -0.02 -0.03 -0.03 ...
## $ gyros arm z
                       : num
                             -0.02 -0.02 -0.02 0.02 0 0 0 0 -0.02 -0.02 ...
                       : int
                             -288 -290 -289 -289 -289 -289 -289 -288 -288 ...
## $ accel_arm_x
## $ accel_arm_y
                       : int 109 110 110 111 111 111 111 111 109 110 ...
## $ accel_arm_z
                       : int
                             -123 -125 -126 -123 -123 -122 -125 -124 -122 -124 ...
##
   $ magnet arm x
                       : int
                             -368 -369 -368 -372 -374 -369 -373 -372 -369 -376 ...
## $ magnet arm y
                       : int 337 337 344 344 337 342 336 338 341 334 ...
## $ magnet_arm_z
                       : int
                             516 513 513 512 506 513 509 510 518 516 ...
## $ roll_dumbbell
                            13.1 13.1 12.9 13.4 13.4 ...
                       : num
## $ pitch_dumbbell
                       : num
                             -70.5 -70.6 -70.3 -70.4 -70.4 ...
   $ yaw dumbbell
                             -84.9 -84.7 -85.1 -84.9 -84.9 ...
##
                       : num
## $ total_accel_dumbbell: int
                            37 37 37 37 37 37 37 37 37 37 ...
## $ gyros_dumbbell_x
                       : num 0000000000...
## $ gyros_dumbbell_y
                             -0.02 -0.02 -0.02 -0.02 -0.02 -0.02 -0.02 -0.02 -0.02
                       : num
. . .
   $ gyros dumbbell z
                             0 0 0 -0.02 0 0 0 0 0 0 ...
##
                       : num
## $ accel dumbbell x
                       : int
                             -234 -233 -232 -232 -233 -234 -232 -234 -232 -235 ...
## $ accel dumbbell y
                       : int 47 47 46 48 48 48 47 46 47 48 ...
## $ accel dumbbell z
                            -271 -269 -270 -269 -270 -269 -270 -272 -269 -270 ...
                       : int
  $ magnet dumbbell x
                       : int
                             -559 -555 -561 -552 -554 -558 -551 -555 -549 -558 ...
##
##
   $ magnet dumbbell y
                       : int
                             293 296 298 303 292 294 295 300 292 291 ...
  $ magnet dumbbell z
                       : num
                             -65 -64 -63 -60 -68 -66 -70 -74 -65 -69 ...
                             28.4 28.3 28.3 28.1 28 27.9 27.9 27.8 27.7 27.7 ...
##
  $ roll forearm
                       : num
## $ pitch forearm
                             -63.9 -63.9 -63.9 -63.9 -63.9 -63.9 -63.8 -63.8 -63.8
                       : num
## $ yaw_forearm
                       : num
                             -153 -153 -152 -152 -152 -152 -152 -152 -152 ·...
## $ total_accel_forearm : int
                             36 36 36 36 36 36 36 36 36 ...
  $ gyros forearm x
                       : num
                             $ gyros_forearm_y
##
                       : num
                             0 0 -0.02 -0.02 0 -0.02 0 -0.02 0 0 ...
   $ gyros_forearm_z
                       : num
                             -0.02 -0.02 0 0 -0.02 -0.03 -0.02 0 -0.02 -0.02 ...
```

Building a model with classe as our outcome variable and random forest as our prediction method

Algorithm: We will use random forest here as our outcome variable classe is a categorical variable and random forests are good with non linear data

Now dividing the train set further into a smaller train (70%) and validation set(30%). We will then building a model with random forest method

```
set.seed(100)
project_train<- createDataPartition(my_cleanset_updated$classe, p=0.70, list = FALSE)
my_cleanset_training<- my_cleanset_updated[project_train,]
my_cleanset_validation<- my_cleanset_updated[-project_train,]</pre>
```

Usiing parallel processing for improving the processing time of random forest

```
#Step 1: Configure parallel processing
library(parallel)
library(doParallel)
```

```
## Loading required package: foreach
```

```
## Loading required package: iterators
```

```
cluster <- makeCluster(detectCores() - 1) # convention to leave 1 core for OS
registerDoParallel(cluster)

#Configuring trainControl object.We will be doing cross validation with 10 folds

modControl<- trainControl(method = 'cv', number = 5, verboseIter = TRUE, allowParallel = TRUE)

#Finally, building a model with random forest method

set.seed(100)
system.time(model_RF<- train(classe~., data= my_cleanset_training, method= 'rf', trControl= m odControl))</pre>
```

```
## Aggregating results
## Selecting tuning parameters
## Fitting mtry = 31 on full training set
```

```
## user system elapsed
## 39.51 1.74 576.51
```

```
#Step 4: De-register parallel processing cluster
stopCluster(cluster)
registerDoSEQ()
```

Now evaluating the accuracy on our validation set

```
set.seed(100)
modelRF_predictions<- predict(model_RF, my_cleanset_validation)
confusionMatrix(my_cleanset_validation$classe, modelRF_predictions)</pre>
```

```
## Confusion Matrix and Statistics
##
##
            Reference
## Prediction A
                     В
                         C
                                   Ε
           A 1674
                    0
##
##
           B 0 1139
                    2 1024 0
           C
##
                0
           D
                0
                    0
                       1 963
##
##
           Е
                0 0
                         0
                              0 1082
##
## Overall Statistics
##
##
                 Accuracy : 0.9995
##
                   95% CI: (0.9985, 0.9999)
##
      No Information Rate: 0.2845
      P-Value [Acc > NIR] : < 2.2e-16
##
##
                    Kappa: 0.9994
##
##
##
   Mcnemar's Test P-Value : NA
##
## Statistics by Class:
##
##
                       Class: A Class: B Class: C Class: D Class: E
## Sensitivity
                        1.0000 0.9982
                                          0.9990
                                                  1.0000
                                                           1,0000
## Specificity
                        1.0000 1.0000
                                          0.9996
                                                  0.9998
                                                           1.0000
## Pos Pred Value
                        1.0000
                                 1.0000
                                          0.9981
                                                  0.9990
                                                           1.0000
## Neg Pred Value
                        1.0000
                                 0.9996
                                          0.9998
                                                  1.0000
                                                           1.0000
## Prevalence
                        0.2845
                                 0.1939
                                          0.1742
                                                  0.1636
                                                           0.1839
                                          0.1740
## Detection Rate
                        0.2845
                                 0.1935
                                                  0.1636
                                                           0.1839
## Detection Prevalence 0.2845
                                 0.1935
                                          0.1743
                                                  0.1638
                                                           0.1839
                        1.0000
                                 0.9991
                                          0.9993
                                                  0.9999
                                                           1.0000
## Balanced Accuracy
```

Conclusion

So we are getting an accuracy of 0.9985 or near 100% accuracy (approximately). So we can conclude that using a random forest model is giving us near perfect accuracy on our validation set

Prediciting on the test data set now

```
pml_testing_updated<- pml_testing[,-160] #removing problem ID from test set
#cleaning the test set
pml_testing_updated<- select(pml_testing_updated, names(my_cleanset_updated)[-58]) #selecting
only the variables in our final cleaned train set and removing classe as it does not exist th
e test set

pml_testing_updated<- mutate(pml_testing_updated, cvtd_timestamp= dmy_hm(cvtd_timestamp))
set.seed(100)
#now predicting on the test set
testing_predictions<- predict(model_RF, pml_testing_updated)
testing_predictions</pre>
```

[1] B A B A A E D B A A B C B A E E A B B B ## Levels: A B C D E