Boundary Area

Saha Kuljit Shantanu

1905119

We need to know

Handling Boundary edges

When partitioning a problem space (such as a geometric space or a graph), the elements near the boundaries of partitions may interact with elements in neighboring partitions. These interactions can create edge effects, where the behavior near the boundary is different from that in the interior.

Decomposing Global Problems

For some problems, the **global structure** is more important than the local details. By studying the boundaries, you can better understand how to decompose the global problem into manageable subproblems **without losing essential connections** or interactions between different parts of the problem.

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We need to know

Dominating Set

A dominating set for a graph G = (V, E) is a subset $D \subseteq V$ such that every vertex not in D is adjacent to at least one vertex in D.

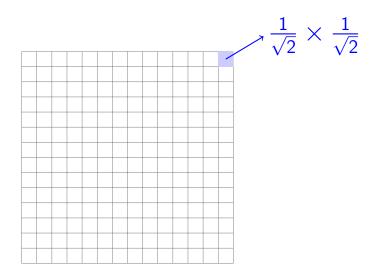
Unit Disk Graph

A unit disk graph is a graph where each vertex represents a disk of unit diameter in the Euclidean plane. There is an edge between two points u and v if and only if the two unit disks centered at u and v have a nonempty intersection.

CDS-UDG Problem

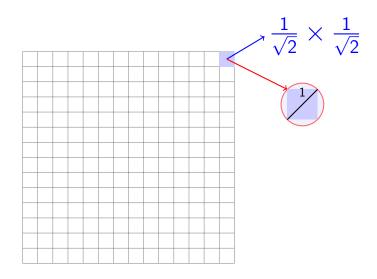
The Connected Dominating Set (CDS) problem in Unit Disk Graphs (UDGs) is to find a connected dominating set with minimum cardinality for the graph.

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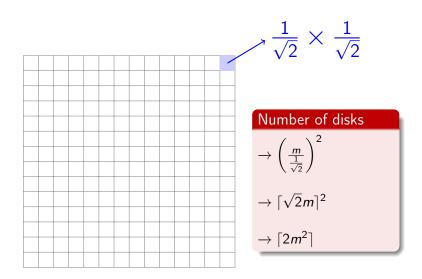


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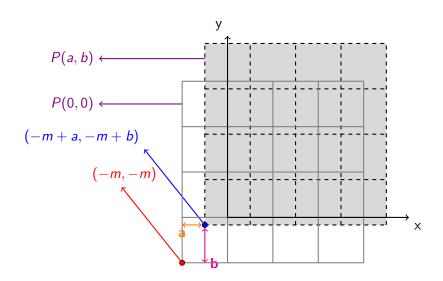
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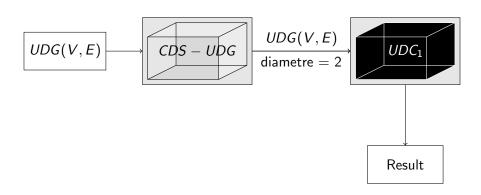
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Theorem 4.4

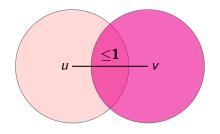
For any $\varepsilon>0$, there is a $(1+\varepsilon)$ -approximation for the minimum dominating set problem in unit disk graphs that runs in time $n^{O(1/\varepsilon^2)}$.

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Theorem 4.4

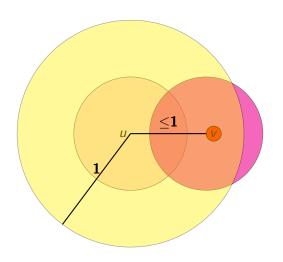


Theorem 4.4 contd...



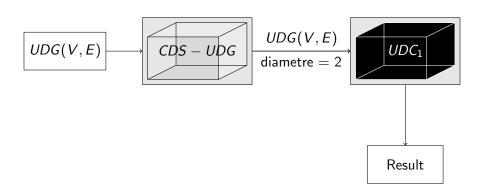
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Theorem 4.4 contd...



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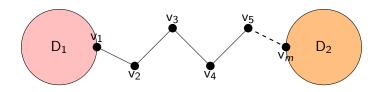
Theorem 4.4 contd...



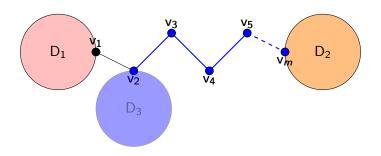
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If a Dominating set D of some graph G is not connected, then the number of its connected components can be reduced by adding at most two vertices to D

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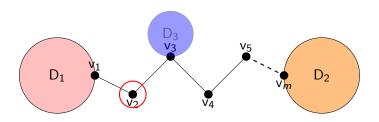
 D_1 and D_2 are the two connected components of the entire dominating set of vertices D of some graph G that are connected with the shortest possible path among connecting components $\{v_1, v_2, v_3, \ldots, v_m\}$ where $v_1 \in D_1$ and $v_m \in D_2$.



Now v_2 cannot be a part of the Dominating set D of the graph G as this will give a shorter path $\{v_2, v_3, v_4, \ldots, v_m\}$ contradicting to our assumption.

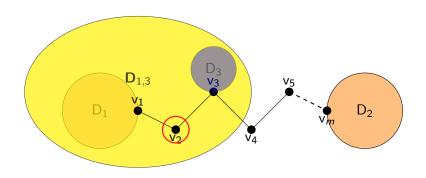
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If $v_3 \in D$, v_2 can be included in D in order to reduce the number of connected components.

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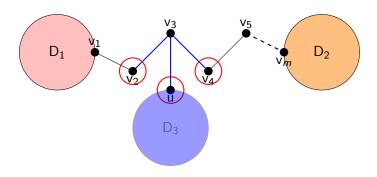


 D_1 and D_3 are merged upon joining v_2 hence number of connected components reduced.

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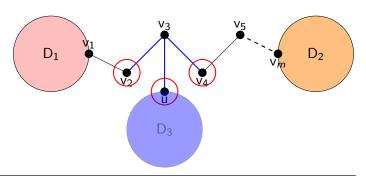


If $v_3 \notin D$, then v_3 must be dominated by one of its neighbours $\{v_2, v_4, u\}$

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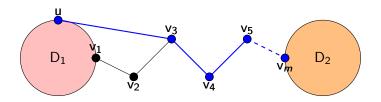
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- \rightarrow We already know $v_2 \notin D$
- \rightarrow If $v_4 \in D$ or some $u \in D_3$ ($D_3 \neq D_1$), then v_2 and v_3 are added to reduce a component

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Again $u \notin D_1$ as this will give yet another shorter path $\{u, v_3, v_4, \dots, v_m\}$ contradicting to our assumption.

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Theorem 4.5

There is a polynomial-time 4-approximation for CDS-UDG.

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Theorem 4.5 contd...

- Suppose the approximated Dominating set of a Unit Disk Graph G(V,E), $D \subseteq V$ is a (4/3)-approximation for the minimum connected Dominating set D^* $|D| \le 4|D^*|/3$
- Our claim is that D is not connected
- We have already proved that, If a Dominating set D of some graph G is not connected, then the number of its connected components can be reduced by adding at most two vertices to D
- Hence, as per our claim, we need to add at most 2(c-1) vertices to D to get a connected dominating set, where c is the number of connected components in D.

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Theorem 4.5 contd...

Calculation for 4-approximation

Clearly, $c - 1 < c \le |D|$

$$\rightarrow 2(c-1) < 2|D|$$

$$\rightarrow |D| + 2(c-1) < 3|D|$$

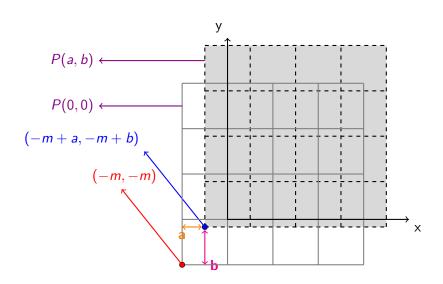
$$\rightarrow |C| < 3|D|$$

$$\rightarrow |C| < 3(4|D^*|/3)$$

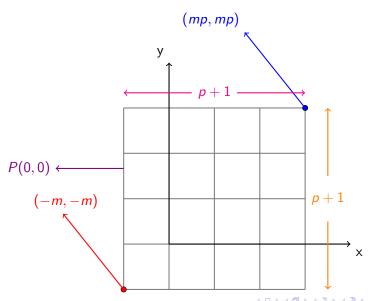
$$\rightarrow |C| < 4|D^*|$$

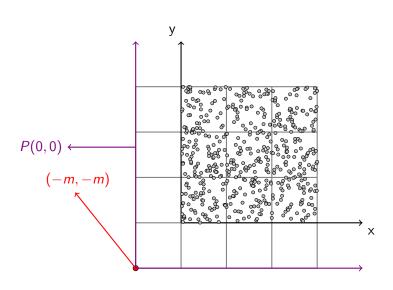
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We need to know more

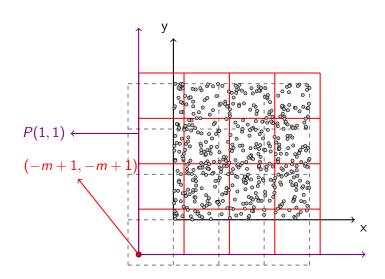


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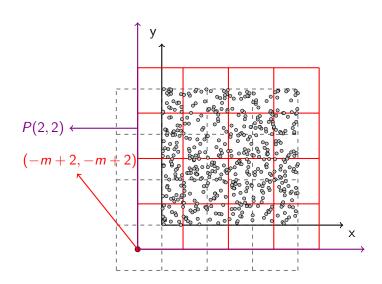




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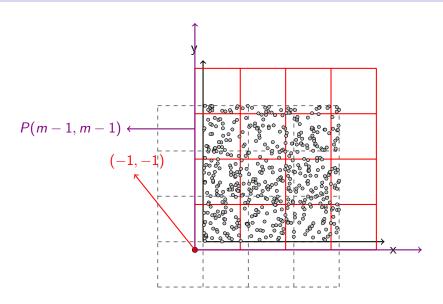


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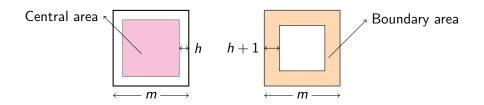


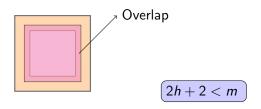
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Central Area and Boundary Area

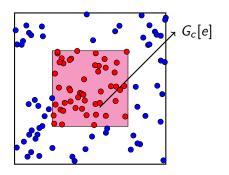




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Central Area and Boundary Area



- \rightarrow One of the (p+1)*(p+1) cells is considered e
- ightarrow For each connected component H of $G_c[e]$, the subgraph of G induced by C[e] has a connected component dominating H

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Theorem 4.6

For each cell e in a partition P(a,a), the set C[e] can be computed in time $n_e^{O(m^2)}$, where n_e is the number of vertices in e

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Theorem 4.6

- We have already known that that each cell can be covered with $2m^2$ unit disks without considering boundaries, hence there are at most $2m^2$ dominating vertices in C[e]
- ② We have already proved that, If a Dominating set D of some graph G is not connected, then the number of its connected components can be reduced by adding at most two vertices to D, hence for making the set connected we add at most $2*2m^2=4m^2$ more vertices to C[e]
- **3** Hence, as per our claim, there at most $6m^2$ vertices in C[e] to get a connected dominating set, which are selected from n_e vertices in cell e

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Theorem 4.6 contd...

Calculation for C[e]

At most $6m^2$ vertices are exhaustively selected from n_e vertices.

$$\rightarrow \binom{n_e}{1} + \binom{n_e}{2} + \binom{n_e}{3} + \ldots + \binom{n_e}{6m^2}$$

$$\to \sum_{k=1}^{6m^2} \binom{n_e}{k}$$

$$\rightarrow n_e^{O(m^2)}$$

Whether C[e] dominates each connected dominating set H in subgraph $G_c[e]$ can be determine in linear time. So C[e] is calculated in time $n_e^{O(m^2)}$

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PTAS for CDS-UDG

Algorithm 4.B PTAS for CDS-UDG

Input: A unit disk graph G = (V, E), with all vertices lying in square Q. **Output:** An approximate connected dominating set A_{a^*} .

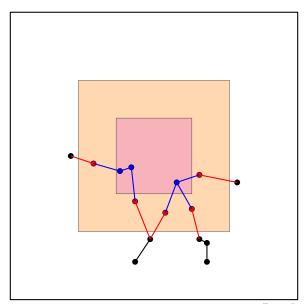
- 1: Let $h \leftarrow 3$ and $m \leftarrow \lceil 160/\epsilon \rceil$.
- 2: Let $D \subseteq V$ be a 4-approximation to the minimum connected dominating set for G (obtained by the algorithm of Corollary 4.5).
- 3: **for** $a \leftarrow 0$ to m-1 **do**
- 4: Let $D_a \leftarrow \{v \in D \mid v \text{ lies in the boundary area of } P(a, a)\}.$
- 5: **for** each cell e of P(a, a) **do**
- 6: Compute set C[e] (by exhaustive search of Lemma 4.6).
- 7: end for

8: Let
$$A_a \leftarrow D_a \cup \left(\bigcup_{e \in P(a,a)} C[e]\right)$$
.

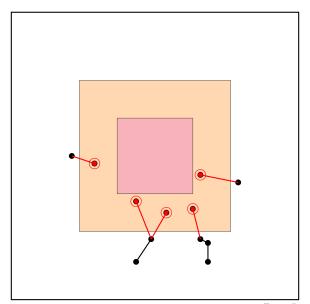
- 9: end for
- 10: Let $a^* \leftarrow \arg\min_{0 \le a \le m} |A_a|$.
- 11: Return A_{a^*} .

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And we need to know again

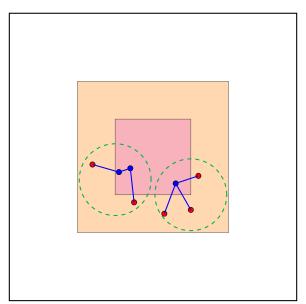


How do we achieve D_a ?



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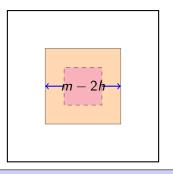
How do we achieve $G_c[e]$?



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For each $a \in \{0, 1, ..., m-1\}$, set A_a computed by Algorithm 4.B in step (8) is a connected dominating set for input unit disk graph G.

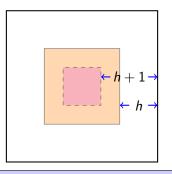
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The area within the white boundary, that is the Central Area of dimension(m-2h)*(m-2h) is dominated by C[e] as per the condition of C[e], where e denotes the cell

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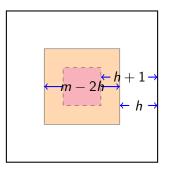
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The white boundary, that denotes the area within h unit of the boundary of cell e is dominated by the boundary area as the boundary area is 1 unit wider from each side

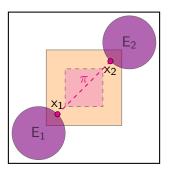
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Thus the set A_a is a Dominating set

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Both x_1 and x_2 are inside the central area, hence are dominated by some connected component C' of the subgraph of G induced by C[e] as per the condition of C[e], where e denotes the cell

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Algorithm 4.B is a PTAS

Runtime of C[e] computation for each cell e in partition P(a, a)

$$\sum_{e \in P(a,a)} n_e^{O(m^2)} \le \left(\sum_{e \in P(a,a)} n_e\right)^{O(m^2)} = n^{O(m^2)} \tag{1}$$

Runtime of algorithm 4.B

for
$$a \leftarrow 0$$
 to $m-1$ do $\rightarrow O(m)$

 $D_a \leftarrow \{v \in D \mid v \text{ lies in the boundary area of } P(a, a)\} \rightarrow O(n)$

Compute
$$\bigcup_{e \in P(a,a)} C[e] \rightarrow n^{O(m^2)}$$

Runtime =
$$O(mn) + m \cdot n^{O(m^2)}$$

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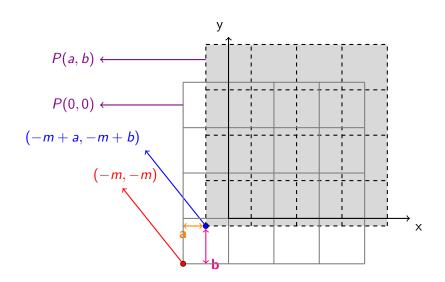
Theorem 4.8

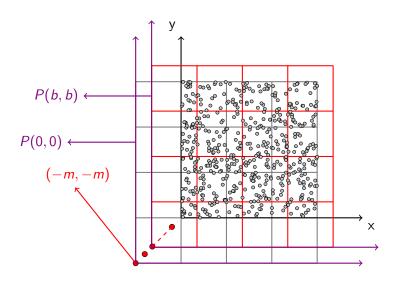
Output A_a^* of algorithm 4.B is a $(1+\varepsilon)$ – approximation for CDS-UDG with computation time $n^{O(1/\varepsilon^2)}$.

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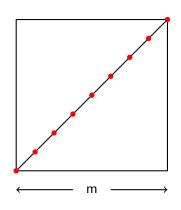
Theorem 4.8







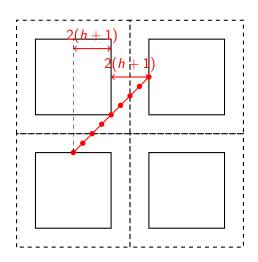
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 \rightarrow The slope of the line created by the change of the position of points is 1

 \rightarrow There are m possible positions for a point in a cell for partition transition, each of them are consecutively spaced by $\sqrt{2}$ unit

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Claim

$$6 \cdot |D_b^*| + |D_b| \le \varepsilon \cdot |D^*| \tag{2}$$

For any vertex v in D^* , it belongs to at most 4(h+1) of the sets $D_0^*, D_1^*, ..., D_{m-1}^*$. Therefore, by the pigeonhole principle, we have

$$\sum_{a=0}^{m-1} |D_a^*| \le 4(h+1)|D^*| \tag{3}$$

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For any vertex v in D, it belongs to at most 4(h+1) of the sets $D_0, D_1, ..., D_{m-1}$. Therefore, by the pigeonhole principle, we have

$$\sum_{a=0}^{m-1} |D_a| \le 4(h+1)|D| \le 16(h+1)|D^*| \tag{4}$$

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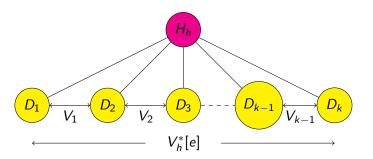
Adding 6 * (3) and (4)

$$6 \cdot \sum_{a=0}^{m-1} |D_a^*| + \sum_{a=0}^{m-1} |D_a| \le 40(h+1)|D^*| \tag{5}$$

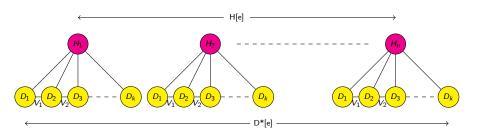
Therefore, again applying the pigeonhole principle, there must exist an integer $b \in \{0,1,...,m-1\}$ such that,

$$6 \cdot |D_b^*| + |D_b| \le \frac{40(h+1)}{m} |D^*| \le \varepsilon \cdot |D^*| \tag{6}$$

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For any cell e that has n connected components in central Area,

$$|V^*[e]| = \sum_{h=0}^n |V_h^*[e]| \le 2(k-1)n$$

$$|D'[e]| = |D^*[e]| + |V^*[e]| \le |D^*[e]| + 2(k-1)n$$

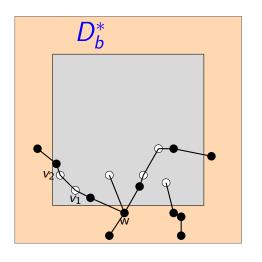
We define D' for some $b \in \{0, 1, 2, ..., m-1\}$,

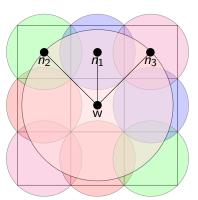
$$D' = D_b \cup \left(\bigcup_{e \in P(b,b)} D'[e]\right)$$

Clearly for each connected component H of central area $G_c[e]$, D' has a connected component dominating H. However, not necessarily with minimum number of vertices.

$$|A_b| \le |D'| \tag{7}$$

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Since vertex w in D_b^* can be charged only twice (by vertices $\{v_1,v_2\}$) for each connected component induced by independent neighbour in central Area, and in case of an unit disk graph vertex w can have at most 3 independent neighbours $\{n_1,n_2,n_3\}$, it implies that w can be charged 2*3=6 times. This phenomenon is only possible for vertices in D_b^* , hence,

$$|D'[e]| \le |D^*[e]| + 6 \cdot |D_b^*[e]|$$

$$|D'| \le |D_b| + \sum_{e \in P(b,b)} |D^*[e]| \le \sum_{e \in P(b,b)} (|D^*[e]| + 6 \cdot |D_b^*[e]|)$$

$$= |D_b| + |D^*| + 6 \cdot |D_b^*|$$

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Using our claim for equation (2), we conclude

$$|D_b| + |D^*| + 6 \cdot |D_b^*| \le |D^*| + \varepsilon \cdot |D^*|$$

$$|D'| \leq (1+\varepsilon) \cdot |D^*|$$

$$|A_b| \leq |D'| \leq (1+arepsilon) \cdot |D^*|$$

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