# GOVERNMENT COLLEGE OF ENGINEERINGERODE



# B.E Electronics and Communication Engineering NOISE POLLUTION MONITORING

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# **Department of Electronics and Communication Engineering**

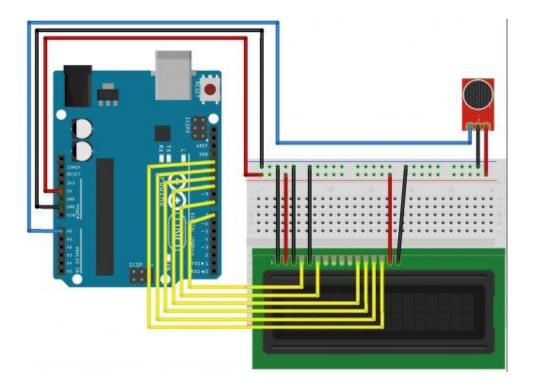
Government College of Engineering
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Chennai.

#### **INTRODUCTION:**

Noise pollution is the propagation of noise with ranging impacts on theactivity of human or animal life, most of which are harmful to a degree. Large amount of increasing noise pollution has made human life proneto large number of diseases. Therefore, it has now become necessary to control the pollution to ensure healthy livelihood and better future.

#### **HARDWARE APPROACH:**

#### **CIRCUIT DIAGRAM:**



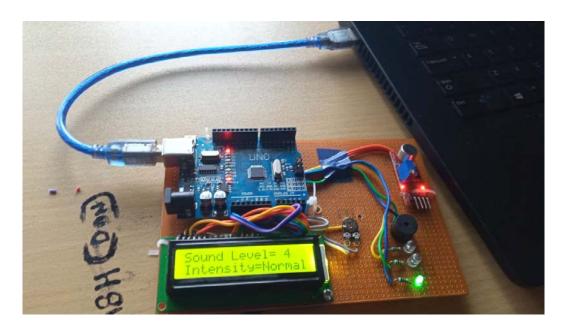
## **PROGRAM:**

```
#include <LiquidCrystal.h>
LiquidCrystal lcd(7,8,10,11,12,13);
int num_Measure = 128; // Set the number of measurements
int pinSignal = A0; // pin connected to pin O module sound sensor
int greenLed = 4;
int blueLed = 5;
int redLed = 6;
int buzzer = 3;
long Sound_signal; // Store the value read Sound Sensor
long sum = 0; // Store the total value of n measurements
```

```
long level = 0; // Store the average value
int soundlow = 40;
int soundmedium = 200;
void setup ()
 pinMode (pinSignal, INPUT); // Set the signal pin as input
 pinMode (greenLed,OUTPUT);
 pinMode (blueLed,OUTPUT);
 pinMode (redLed,OUTPUT);
 pinMode (buzzer,OUTPUT);
 Serial.begin (9600);
 lcd.begin(16,2);
 lcd.print("Noise Detector");
 delay(1000);
void loop ()
{
 // Performs 128 signal readings
 for (int i = 0; i < num Measure; i ++)
 Sound signal = analogRead (pinSignal);
  sum =sum + Sound signal;
 level = sum / num Measure; // Calculate the average value
 Serial.print("Sound Level: ");
 lcd.print("Sound Level= ");
 Serial.println (level-33);
 lcd.print(level-33);
 if(level-33<soundlow)
  lcd.setCursor(0,2);
  lcd.print("Intensity=Normal");
   digitalWrite(greenLed,HIGH);
   digitalWrite(blueLed,LOW);
    digitalWrite(redLed,LOW);
    digitalWrite(buzzer, LOW);
    delay(500);
 if(level-33>soundlow && level-33<soundmedium)
  lcd.setCursor(0,2);
  lcd.print("Intensity=Medium");
   digitalWrite(blueLed,HIGH);
   digitalWrite(redLed,LOW);
```

```
digitalWrite(greenLed,LOW);
    digitalWrite(buzzer, LOW);
    delay(500);
}
if(level-33>soundmedium)
{
    lcd.setCursor(0,2);
    lcd.print("Intensity= High");
    digitalWrite(redLed,HIGH);
    digitalWrite(greenLed,LOW);
    digitalWrite(blueLed,LOW);
    digitalWrite(blueLed,LOW);
    digitalWrite(buzzer, HIGH);
}
sum = 0; // Reset the sum of the measurement values delay(200);
lcd.clear();
}
```

#### **IMPLEMENTATION:**

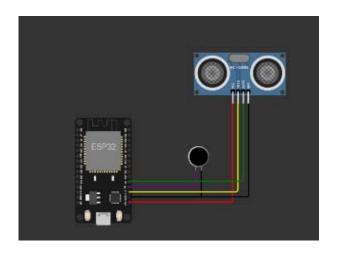


#### **CONDITION:**

- If sound level is less than 40dB, Green LED turns on, which denotes normal sound intensity.
- If sound level is in between 40-200dB, Blue LED turns on, which denotes medium noise intensity.
- If sound level is >200dB, Red LED turns on, which indicates very high level of noise.

#### **SOFTWARE APPROACH:**

## **CIRCUIT DIAGRAM:**



### **PROGRAM:**

import machine import time import urequests import ujson import network import math

# Define your Wi-Fi credentials
wifi\_ssid = 'Wokwi-GUEST'
wifi\_password = " # Replace with the actual Wi-Fi password
# Connect to Wi-Fi
wifi = network.WLAN(network.STA\_IF)
wifi.active(True)

# Wait for Wi-Fi connection while not wifi.isconnected(): pass

wifi.connect(wifi ssid, wifi password)

# Define ultrasonic sensor pins (Trig and Echo pins) ultrasonic\_trig = machine.Pin(15, machine.Pin.OUT) ultrasonic\_echo = machine.Pin(4, machine.Pin.IN)

# Define microphone pin microphone = machine.ADC(2)

```
calibration constant = 2.0
noise threshold = 60 # Set your desired noise threshold in dB
# Firebase Realtime Database URL and secret
firebase url = 'https://noise-pollution-monitori-9196a-default-rtdb.asia-
southeast1.firebasedatabase.app/
firebase secret = 'aANDKcKQEK3ky7G38Uuq5WDdvPP5OUmtBxsSMN2C'
def measure distance():
  # Trigger the ultrasonic sensor
  ultrasonic trig.value(1)
  time.sleep us(10)
  ultrasonic trig.value(0)
  # Measure the pulse width of the echo signal
  pulse time = machine.time pulse us(ultrasonic echo, 1, 30000)
  # Calculate distance in centimeters
  distance cm = (pulse time / 2) / 29.1
  return distance cm
def measure noise level():
  # Read analog value from the microphone
  noise level = microphone.read()
  noise level db = 20 * math.log10(noise level / calibration constant)
  return noise level, noise level db
# Function to send data to Firebase
def send data to firebase(distance, noise level db):
  data = {
    "Distance": distance,
    "NoiseLevelDB": noise level db
  url = f'{firebase url}/sensor data.json?auth={firebase secret}'
  try:
    response = urequests.patch(url, json=data) # Use 'patch' instead of 'put'
    if response.status code == 200:
       print("Data sent to Firebase")
    else:
       print(f'Failed to send data to Firebase. Status code:
{response.status code}")
  except Exception as e:
    print(f"Error sending data to Firebase: {str(e)}")
```

```
try:
    while True:
        distance = measure_distance()
        noise_level, noise_level_db = measure_noise_level()

    print("Distance: {} cm, Noise Level: {:.2f} dB".format(distance, noise_level_db))

    if noise_level_db > noise_threshold:
        print("Warning: Noise pollution exceeds threshold!")

# Send data to Firebase
    send_data_to_firebase(distance, noise_level_db)

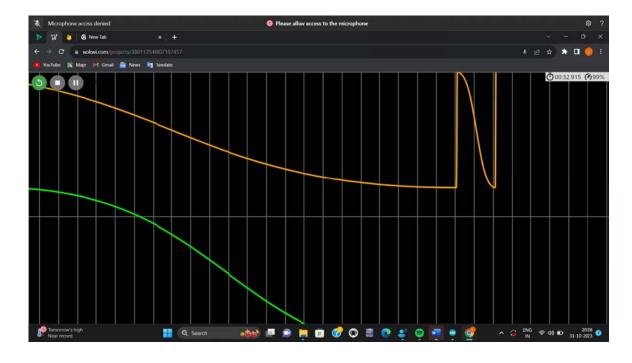
    time.sleep(1) # Adjust the sleep duration as needed

except KeyboardInterrupt:
    print("Monitoring stopped")
```

#### **WORKING:**

The circuit is simulated using wokwi. The real time data base is created in firebase whose URL and secret ID is added to this program. Real time noise data measured using sensor is sent to the firebase for data storage.

#### **SIMULATED OUTPUT:**



# **CONCLUSION:**

A low-budget smart sensor unit for environmental noise level measurement is designed using IoT. I ensure that my project will perform efficiently. With some advanced developments in this project, we can create smart cities and a healthy environment.