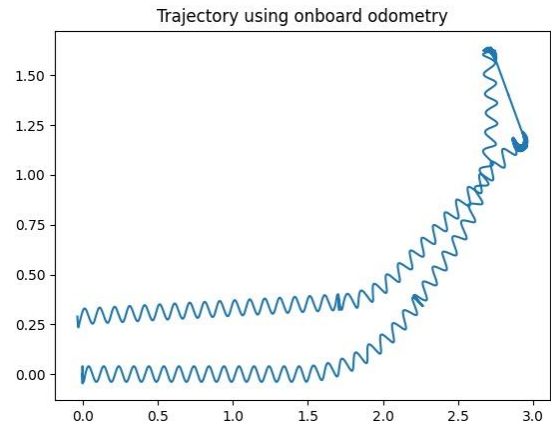
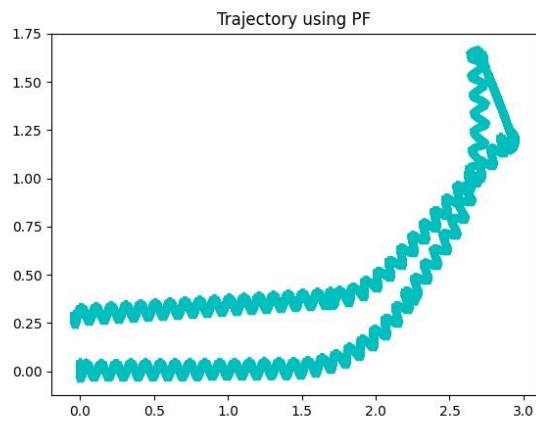
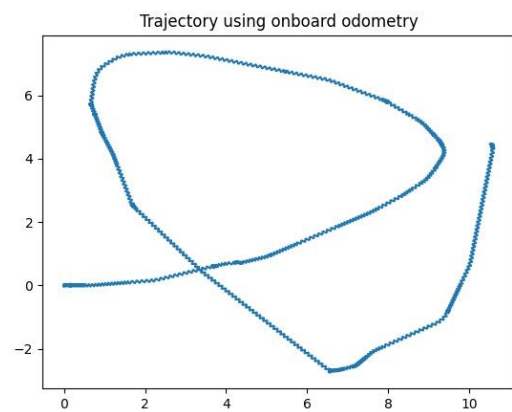
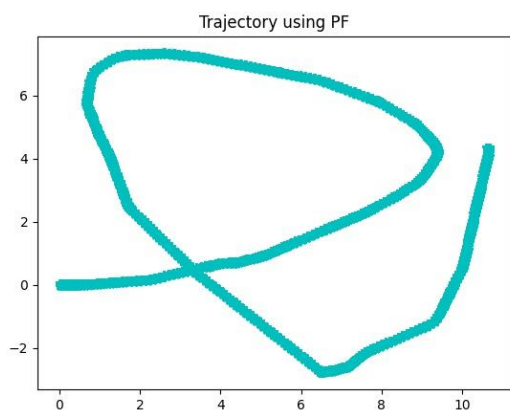


2. (c – Dynamics step)

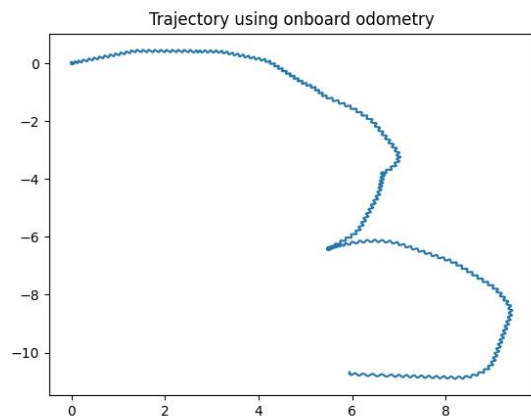
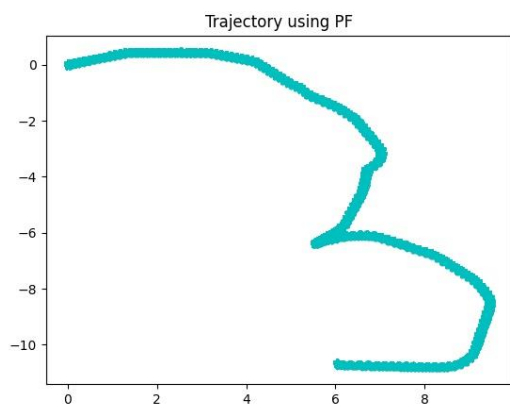
Map0



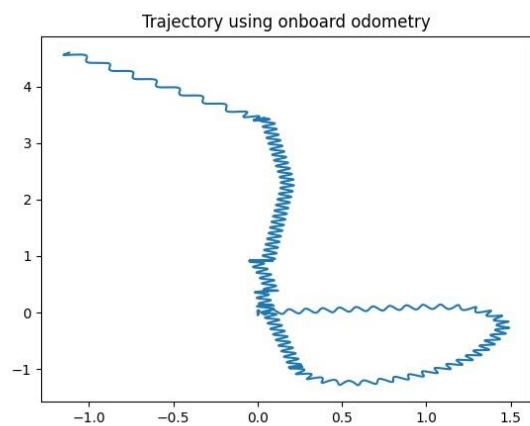
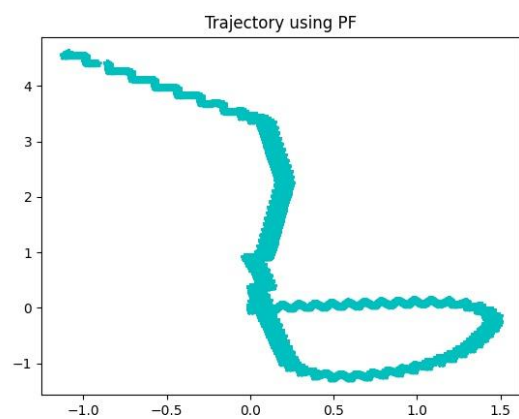
Map1



Map2



Map3



2. (e – SLAM)

