```
In [66]:
          # Author : Sahil Chitnis
          # Dataset : https://drive.google.com/drive/folders/1s1-174qlu ekiKcGXeutP5tvr
In [ ]:
         # Install some libraries/packages required for Google Collab
          #!pip install noisereduce
          #!pip install torchaudio
          #!apt install libasound2-dev portaudio19-dev libportaudio2 libportaudiocpp0 f
          #!pip install pyaudio
In [142...
         # Step0: Import all libraries required for this project
          import librosa
          import os
          import numpy as np
          import noisereduce as nr
          import torchaudio
          import tensorflow
          import numpy
          import torch
          import random
          from sklearn.preprocessing import LabelEncoder
          import pandas as pd
          import numpy as np
          import os
          from sklearn import metrics
          import keras
          from keras.models import Sequential
          from keras.layers import Convolution2D, MaxPooling2D,MaxPooling1D,Conv1D
          from keras.layers import Dense, Dropout, Activation, Flatten, LSTM, TimeDistrib
          from keras.optimizers import Adam, SGD
          from keras.utils import np utils
          from keras.callbacks import EarlyStopping, ModelCheckpoint
          import random
          from keras import optimizers
          import datetime
          import matplotlib.pyplot as plt
          import noisereduce as nr
          from keras.models import model from json
          from sklearn.preprocessing import LabelEncoder
          import IPython
          import os
          import pyaudio
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In [143... #!unzip ./Dataset_audio.zip
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In [144...
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# Step1 : Data Cleaning and Feature extraction step
# Step1.a) Data augmentation - Shift the signal to left/right by some %
           This step is needed to increase samples
def time shift(aud, shift limit):
  sig, sr = aud
  _, sig_len = sig.shape
  shift amt = int(random.random() * shift limit * sig len)
  return (sig.roll(shift amt), sr)
# Step1.b) Transform data and extract features :
# a) Data Augmentation
# b) Noise reduction
# c) Data Trimming
# d) Perform Short-time Fourier transform to extract features
# e) Save features for future use
def compute and save transform(file, name, activity, subject):
    # read the audio data
    audio data, sample rate = librosa.load(file)
    #aud = torchaudio.load(file)
    #data = []
    # Performing data augmentation
    #aud1 = time shift(aud, 1)
    #for elem in aud1[0][0]:
    # data.append(elem)
    #audio data = np.array(data)
    # Perform noise reduction
    noise audio = audio data[0:35000]
    noise removed audio = nr.reduce noise(audio clip=audio data, noise clip=n
    # Trim the silence in the data by setting silence threshold to 20DB,
    # 512 samples per frame and 128 number of samples between analysis frames
    trimmed audio, index = librosa.effects.trim(noise removed audio, top db=2
    # Perform Short-time Fourier transform to extract features
    stft_feat = np.abs(librosa.stft(trimmed_audio, n_fft=512, hop_length=256,
    # Save the features to folder "Transformed Audio Features"
    np.save("Transformed_Audio_Features/" + subject + "_" + name[:-4] + "_" +
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In [146...
          # Step2) Split Activities1,2,3 of each sample as per
                   sample in 3 buckets into Training, Test, Validation based on
          # Taking 12 Training samples
          train samples = ['s07', 's16', 's09', 's13', 's04', 's11', 's15', 's01', 's12
          # Taking 2 validation samples
          validation_samples = ['s02', 's03']
          # Taking 4 test samples
          test samples = ['s05', 's17']
          def Split data(path,sampleSize):
              Activities1 = ['Drinking', 'Eating', 'LyingDown', 'OpeningPillContainer',
                                     'PickingObject', 'Reading', 'SitStill', 'Sitting',
                                     'StandUp', 'UseLaptop', 'UsingPhone', 'WakeUp', 'Wa
                                     'WaterPouring', 'Writing']
              Activities2 = ['Calling', 'Clapping', 'Falling', 'Sweeping', 'WashingHand
              Activities3 = ['Entering', 'Exiting']
              X train = []
              Y_train = []
              X_{\text{test}} = []
              Y test = []
              X validation = []
              Y validation = []
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# Split data into Training, Validation, Test
for file in os.listdir(path):
   if int(file.split("__")[1].split("_")[0])!=1:
      a = (np.load(path + file)).T
      activityLabel = file.split('__')[-1].split(".")[0]
      # Split data from Activities2
      if(activityLabel in Activities2):
            if file.split("_")[0] in train_samples:
              X_train.append(np.mean(a,axis=0))
              Y train.append(activityLabel)
            elif file.split("_")[0] in validation_samples:
              X validation.append(np.mean(a,axis=0))
              Y validation.append(activityLabel)
            else:
              X test.append(np.mean(a,axis=0))
              Y test.append(activityLabel)
      # Split data from Activities3
      elif(activityLabel in Activities3):
            activityLabel = "Activities3"
            if file.split("_")[0] in train_samples:
              X_train.append(np.mean(a,axis=0))
              Y train.append(activityLabel)
            elif file.split("_")[0] in validation_samples:
              X_validation.append(np.mean(a,axis=0))
              Y validation.append(activityLabel)
            else:
              X test.append(np.mean(a,axis=0))
              Y test.append(activityLabel)
      # Split from remaining activities
      else:
            activityLabel = "other"
            if file.split("_")[0] in train_samples:
              X train.append(np.mean(a,axis=0))
              Y train.append(activityLabel)
            elif file.split("_")[0] in validation_samples:
              X_validation.append(np.mean(a,axis=0))
              Y_validation.append(activityLabel)
            else:
              X test.append(np.mean(a,axis=0))
              Y test.append(activityLabel)
# Change lists to numpy arrays
X train = np.array(X train)
Y train = np.array(Y train)
X test = np.array(X test)
Y test = np.array(Y test)
X validation = np.array(X validation)
Y_validation = np.array(Y_validation)
return X_train, Y_train, X_validation, Y_validation, X_test, Y_test
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*** | ** | # Step3) Functions to print output/data
          # Re-sample the data
          def reSample(data, samples):
              r = len(data)/samples #re-sampling ratio
              newdata = []
              for i in range(0, samples):
                  newdata.append(data[int(i*r)])
              return np.array(newdata)
          # Print ConfMatrix
          def print activity data1(confMatrix):
                  s = "ACTIVITY Confusion Matrix:\n"
                  for i in range(len(confMatrix)):
                      s += lb.inverse_transform([i])[0] + "\t|"
                  print(s[:-1])
                  for i in range(len(confMatrix)):
                      s = ""
                      for j in range(len(confMatrix)):
                          s += str(confMatrix[i][j])
                          s += "\t|"
                      print(lb.inverse transform([i])[0],"\t|", s[:-1])
                  print()
          def print_activity_data2(confMatrix):
                  s = "ACTIVITY Matrix:\n"
                  for i in range(len(confMatrix)):
                      s += lb.inverse transform([i])[0] + "\t|"
                  print(s[:-1])
                  for i in range(len(confMatrix)):
                      s = ""
                      for j in range(len(confMatrix)):
                          val = confMatrix[i][j]/float(sum(confMatrix[i]))
                          s += str(round(val,2))
                          s += "\t|"
                      print(lb.inverse_transform([i])[0],"\t|", s[:-1])
                  print()
          # Display the result
          def DisplayResult():
            predictions = [np.argmax(y) for y in result]
            expected = [np.argmax(y) for y in y test]
            confMatrix = []
            num labels=y test[0].shape[0]
            for i in range(num_labels):
                r = []
                for j in range(num labels):
                    r.append(0)
                confMatrix.append(r)
            n_tests = len(predictions)
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for i in range(n_tests):
    confMatrix[expected[i]][predictions[i]] += 1

# Print activity data
print_activity_data1(confMatrix)
print_activity_data2(confMatrix)
```

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featuresPath = "Transformed_Audio_Features/"

# Split data into Train, Validation, Test
X_train,Y_train,X_validation,Y_validation,X_test,Y_test = Split_data(feature)
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In [149...
          n samples = len(Y train)
          print("Number of training samples: " + str(n_samples))
          order = np.array(range(n samples))
          # Shuffle Training data
          np.random.shuffle(order)
          X train = X train[order]
          Y_train = Y_train[order]
          # Step4) Encode the labels for Y train, Y test and Y validation
          # Encode the labels
          lb = LabelEncoder()
          # Fit label encoder on Y train, Y test and Y validation
          y train = np utils.to categorical(lb.fit transform(Y train))
          y test = np utils.to categorical(lb.fit transform(Y test))
          y validation = np utils.to categorical(lb.fit transform(Y validation))
          num labels = y train.shape[1]
```

Number of training samples: 880

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In [161...
# Step5.1) Build Model:
# a) 1st layer: Dense with o/p = 256 neurons, i/p = 257and RELU acti
# b) 2nd layer: Dense with o/p = 256 neurons and RELU activation
# c) 3rd layer: Dense with o/p = 128 neurons and RELU activation
# d) 4th layer: Dense with o/p = 128 neurons, RELU activation and Dr
# d) 5th layer: Dense with o/p = 128 neurons, RELU activation and Dr
# e) 6th layer: Dense with o/p = 8 neurons (ie = num_labels), Softma

num_labels = y_train.shape[1]
filter_size = 20

# Build Sequential model
model = Sequential()
#Layer1
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model.add(Dense(256, input shape=(257,)))
model.add(Activation('relu'))
#Layer2
model.add(Dense(256))
model.add(Activation('relu'))
#Layer3
model.add(Dense(128))
model.add(Activation('relu'))
#Layer4
model.add(Dense(128))
model.add(Activation('relu'))
model.add(Dropout(0.5))
#Layer5
model.add(Dense(128))
model.add(Activation('relu'))
model.add(Dropout(0.5))
#Layer6
model.add(Dense(num labels))
model.add(Activation('softmax'))
model.summary()
# Step5.2) Compile Model:
         a) Loss is categorical crossentropy
          b) Optimizer is Adam optimizer
\#1r \ rates = [2e-3, 3e-1, 3e-2, 3e-3]
# Step5.3) Fit the Model:
          a) Batch size is 10
#
          b) Epoch's is 100
lr_rate = 3e-3
opt = keras.optimizers.Adam(learning rate=lr rate)
model.compile(loss='categorical_crossentropy', metrics=['accuracy'], optimize
model.fit(X train, y train, batch size=10, epochs=100, validation data=(X val
     result = model.predict(X test)
```

Model: "sequential\_32"

Layer (type)	Output Shape	Param #
dense_137 (Dense)	(None, 256)	66048
activation_137 (Activation)	(None, 256)	0
dense_138 (Dense)	(None, 256)	65792
activation_138 (Activation)	(None, 256)	0

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dense 139 (Dense)
                    (None, 128)
                                       32896
activation_139 (Activation)
                    (None, 128)
dense 140 (Dense)
                    (None, 128)
                                       16512
activation 140 (Activation)
                    (None, 128)
                                       0
dropout 46 (Dropout)
                    (None, 128)
                                       16512
dense 141 (Dense)
                    (None, 128)
                    (None, 128)
activation 141 (Activation)
dropout 47 (Dropout)
                    (None, 128)
                                       n
dense 142 (Dense)
                    (None, 8)
                                       1032
activation 142 (Activation) (None, 8)
_____
Total params: 198,792
Trainable params: 198,792
Non-trainable params: 0
Train on 880 samples, validate on 146 samples
Epoch 1/100
880/880 [=============] - 2s 2ms/step - loss: 1.1108 - accura
cy: 0.7091 - val loss: 0.7038 - val accuracy: 0.8014
Epoch 2/100
racy: 0.7557 - val_loss: 0.6278 - val accuracy: 0.7808
Epoch 3/100
racy: 0.7636 - val loss: 0.6095 - val accuracy: 0.8082
Epoch 4/100
880/880 [============] - 1s 867us/step - loss: 0.8441 - accu
racy: 0.7614 - val loss: 0.5670 - val accuracy: 0.8082
Epoch 5/100
racy: 0.7693 - val loss: 0.5642 - val accuracy: 0.8082
Epoch 6/100
880/880 [=============] - 1s 869us/step - loss: 0.7501 - accu
racy: 0.7739 - val_loss: 0.5632 - val_accuracy: 0.8151
Epoch 7/100
880/880 [=============] - 1s 865us/step - loss: 0.7306 - accu
racy: 0.7773 - val loss: 0.6151 - val accuracy: 0.8151
Epoch 8/100
racy: 0.7784 - val loss: 0.5905 - val accuracy: 0.8082
Epoch 9/100
racy: 0.7636 - val loss: 0.6070 - val accuracy: 0.8151
Epoch 10/100
racy: 0.7682 - val loss: 0.5265 - val accuracy: 0.8219
Epoch 11/100
```

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880/880 [============] - 1s 871us/step - loss: 0.7531 - accu
racy: 0.7841 - val loss: 0.5150 - val accuracy: 0.8082
Epoch 12/100
880/880 [============] - 1s 875us/step - loss: 0.7327 - accu
racy: 0.7852 - val loss: 0.5331 - val accuracy: 0.8151
Epoch 13/100
880/880 [=============] - 1s 868us/step - loss: 0.7291 - accu
racy: 0.7852 - val loss: 0.5423 - val accuracy: 0.8288
Epoch 14/100
880/880 [=============] - 1s 883us/step - loss: 0.7254 - accu
racy: 0.7852 - val loss: 0.5186 - val accuracy: 0.8151
Epoch 15/100
racy: 0.7898 - val loss: 0.5140 - val_accuracy: 0.8151
Epoch 16/100
racy: 0.7932 - val loss: 0.4793 - val accuracy: 0.8356
Epoch 17/100
racy: 0.8023 - val loss: 0.4179 - val accuracy: 0.8288
Epoch 18/100
racy: 0.8068 - val loss: 0.3927 - val accuracy: 0.8562
Epoch 19/100
racy: 0.8182 - val loss: 0.4904 - val accuracy: 0.8219
Epoch 20/100
880/880 [=============] - 1s 860us/step - loss: 0.7376 - accu
racy: 0.7977 - val loss: 0.4909 - val accuracy: 0.8014
Epoch 21/100
racy: 0.8000 - val loss: 0.3955 - val accuracy: 0.8904
Epoch 22/100
880/880 [=============] - 1s 911us/step - loss: 0.5630 - accu
racy: 0.8273 - val loss: 0.3790 - val accuracy: 0.8425
Epoch 23/100
880/880 [============] - 1s 873us/step - loss: 0.6345 - accu
racy: 0.8068 - val loss: 0.4693 - val accuracy: 0.8219
Epoch 24/100
880/880 [=============] - 1s 871us/step - loss: 0.5351 - accu
racy: 0.8364 - val loss: 0.3512 - val accuracy: 0.8767
Epoch 25/100
880/880 [=============] - 1s 884us/step - loss: 0.5365 - accu
racy: 0.8386 - val loss: 0.3620 - val accuracy: 0.8836
Epoch 26/100
880/880 [============] - 1s 876us/step - loss: 0.5240 - accu
racy: 0.8523 - val loss: 0.3337 - val accuracy: 0.8973
Epoch 27/100
racy: 0.8534 - val loss: 0.4294 - val accuracy: 0.8630
Epoch 28/100
racy: 0.8409 - val loss: 0.4014 - val accuracy: 0.8699
Epoch 29/100
racy: 0.8443 - val loss: 0.3879 - val accuracy: 0.8767
Epoch 30/100
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880/880 [============] - 1s 863us/step - loss: 0.5022 - accu
racy: 0.8682 - val loss: 0.2903 - val accuracy: 0.9041
Epoch 31/100
880/880 [=============] - 1s 876us/step - loss: 0.4557 - accu
racy: 0.8705 - val loss: 0.3571 - val accuracy: 0.8836
Epoch 32/100
racy: 0.8648 - val loss: 0.3619 - val accuracy: 0.8767
Epoch 33/100
880/880 [=============] - 1s 874us/step - loss: 0.4495 - accu
racy: 0.8636 - val loss: 0.3686 - val accuracy: 0.8767
Epoch 34/100
racy: 0.8784 - val loss: 0.4533 - val accuracy: 0.8767
Epoch 35/100
racy: 0.8477 - val loss: 0.4869 - val accuracy: 0.8493
Epoch 36/100
racy: 0.8477 - val loss: 0.3672 - val accuracy: 0.8904
Epoch 37/100
racy: 0.8648 - val loss: 0.3399 - val accuracy: 0.9041
Epoch 38/100
racy: 0.8636 - val loss: 0.3387 - val accuracy: 0.8973
Epoch 39/100
cy: 0.8739 - val loss: 0.4116 - val accuracy: 0.8630
Epoch 40/100
racy: 0.8784 - val loss: 0.2869 - val accuracy: 0.8836
Epoch 41/100
880/880 [=============] - 1s 962us/step - loss: 0.3893 - accu
racy: 0.8818 - val loss: 0.4090 - val accuracy: 0.8767
Epoch 42/100
880/880 [=============] - 1s 989us/step - loss: 0.4027 - accu
racy: 0.8852 - val loss: 0.4162 - val accuracy: 0.8904
Epoch 43/100
880/880 [=============] - 1s 937us/step - loss: 0.4272 - accu
racy: 0.8795 - val loss: 0.4390 - val accuracy: 0.8630
Epoch 44/100
880/880 [=============] - 1s 930us/step - loss: 0.4030 - accu
racy: 0.8886 - val loss: 0.4076 - val accuracy: 0.8836
Epoch 45/100
racy: 0.8909 - val loss: 0.4038 - val accuracy: 0.8904
Epoch 46/100
racy: 0.8955 - val loss: 0.4328 - val accuracy: 0.8767
Epoch 47/100
racy: 0.8875 - val loss: 0.4349 - val accuracy: 0.8699
Epoch 48/100
racy: 0.8886 - val loss: 0.3450 - val accuracy: 0.8836
Epoch 49/100
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880/880 [============] - 1s 873us/step - loss: 0.3584 - accu
racy: 0.8898 - val loss: 0.3311 - val accuracy: 0.8904
Epoch 50/100
880/880 [=============] - 1s 869us/step - loss: 0.3372 - accu
racy: 0.9102 - val loss: 0.4090 - val accuracy: 0.8630
Epoch 51/100
racy: 0.8943 - val loss: 0.3034 - val accuracy: 0.8973
Epoch 52/100
880/880 [=============] - 1s 976us/step - loss: 0.3744 - accu
racy: 0.8966 - val loss: 0.5100 - val accuracy: 0.8630
Epoch 53/100
racy: 0.8830 - val loss: 0.4451 - val_accuracy: 0.8904
Epoch 54/100
racy: 0.8807 - val_loss: 0.4881 - val_accuracy: 0.8562
Epoch 55/100
racy: 0.8705 - val loss: 0.3268 - val accuracy: 0.9041
Epoch 56/100
racy: 0.8989 - val loss: 0.4202 - val accuracy: 0.9041
Epoch 57/100
racy: 0.9068 - val loss: 0.5139 - val accuracy: 0.8699
Epoch 58/100
880/880 [=============] - 1s 890us/step - loss: 0.3393 - accu
racy: 0.9000 - val loss: 0.5292 - val accuracy: 0.8699
Epoch 59/100
racy: 0.9057 - val loss: 0.5160 - val accuracy: 0.9041
Epoch 60/100
880/880 [=============] - 1s 918us/step - loss: 0.5519 - accu
racy: 0.8670 - val loss: 0.3971 - val accuracy: 0.8699
Epoch 61/100
880/880 [=============] - 1s 890us/step - loss: 0.4464 - accu
racy: 0.8795 - val loss: 0.3483 - val accuracy: 0.8904
Epoch 62/100
880/880 [=============] - 1s 899us/step - loss: 0.4299 - accu
racy: 0.8898 - val loss: 0.3617 - val accuracy: 0.8973
Epoch 63/100
880/880 [=============] - 1s 892us/step - loss: 0.3654 - accu
racy: 0.9000 - val loss: 0.3087 - val accuracy: 0.9041
Epoch 64/100
880/880 [============] - 1s 887us/step - loss: 0.3370 - accu
racy: 0.8920 - val loss: 0.3969 - val accuracy: 0.8767
Epoch 65/100
racy: 0.9068 - val loss: 0.4493 - val accuracy: 0.8904
Epoch 66/100
racy: 0.9159 - val loss: 0.3979 - val accuracy: 0.8904
Epoch 67/100
racy: 0.9182 - val loss: 0.3697 - val accuracy: 0.9110
Epoch 68/100
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880/880 [============] - 1s 917us/step - loss: 0.3157 - accu
racy: 0.9045 - val loss: 0.4778 - val accuracy: 0.8767
Epoch 69/100
racy: 0.9239 - val loss: 0.4622 - val accuracy: 0.8904
Epoch 70/100
880/880 [=============] - 1s 903us/step - loss: 0.2707 - accu
racy: 0.9170 - val loss: 0.4896 - val accuracy: 0.8630
Epoch 71/100
880/880 [=============] - 1s 889us/step - loss: 0.3144 - accu
racy: 0.9068 - val loss: 0.4358 - val accuracy: 0.8904
Epoch 72/100
racy: 0.9057 - val loss: 0.5584 - val_accuracy: 0.8904
Epoch 73/100
racy: 0.9068 - val loss: 0.4943 - val accuracy: 0.8904
Epoch 74/100
racy: 0.9125 - val loss: 0.5915 - val accuracy: 0.8699
Epoch 75/100
racy: 0.9261 - val loss: 0.4829 - val accuracy: 0.8904
Epoch 76/100
racy: 0.8943 - val loss: 0.4993 - val accuracy: 0.8904
Epoch 77/100
racy: 0.8841 - val loss: 0.5316 - val accuracy: 0.8973
Epoch 78/100
cy: 0.9080 - val loss: 0.5781 - val accuracy: 0.8836
Epoch 79/100
880/880 [=============] - 1s 1ms/step - loss: 0.2886 - accura
cy: 0.9227 - val loss: 0.6791 - val accuracy: 0.8493
Epoch 80/100
880/880 [============] - 1s 1ms/step - loss: 0.3143 - accura
cy: 0.8989 - val loss: 0.5002 - val accuracy: 0.8767
Epoch 81/100
cy: 0.9261 - val loss: 0.6536 - val accuracy: 0.8425
Epoch 82/100
880/880 [=============] - 1s 922us/step - loss: 0.2936 - accu
racy: 0.9136 - val loss: 0.5697 - val accuracy: 0.9110
Epoch 83/100
880/880 [============] - 1s 935us/step - loss: 0.2644 - accu
racy: 0.9216 - val loss: 0.5580 - val accuracy: 0.8973
Epoch 84/100
racy: 0.9216 - val loss: 0.5092 - val accuracy: 0.8836
Epoch 85/100
racy: 0.9227 - val loss: 0.5464 - val accuracy: 0.8973
Epoch 86/100
racy: 0.9080 - val loss: 0.5612 - val accuracy: 0.9041
Epoch 87/100
```

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racy: 0.9227 - val loss: 0.4365 - val accuracy: 0.8904
Epoch 88/100
880/880 [=============] - 1s 910us/step - loss: 0.2858 - accu
racy: 0.9261 - val loss: 0.4951 - val accuracy: 0.8836
Epoch 89/100
racy: 0.9034 - val loss: 0.5078 - val accuracy: 0.8630
Epoch 90/100
880/880 [==============] - 1s 957us/step - loss: 0.2987 - accu
racy: 0.9205 - val loss: 0.9739 - val accuracy: 0.8630
Epoch 91/100
racy: 0.9227 - val loss: 0.6721 - val accuracy: 0.8904
Epoch 92/100
racy: 0.9170 - val loss: 0.7108 - val accuracy: 0.8836
Epoch 93/100
racy: 0.9284 - val loss: 0.7413 - val accuracy: 0.9110
Epoch 94/100
racy: 0.9295 - val loss: 0.8465 - val accuracy: 0.9178
Epoch 95/100
racy: 0.9170 - val loss: 0.5542 - val accuracy: 0.9041
Epoch 96/100
880/880 [=============] - 1s 954us/step - loss: 0.2511 - accu
racy: 0.9307 - val loss: 0.5453 - val accuracy: 0.8904
Epoch 97/100
racy: 0.9284 - val loss: 0.3941 - val accuracy: 0.9041
Epoch 98/100
racy: 0.8875 - val loss: 0.4598 - val accuracy: 0.8699
Epoch 99/100
880/880 [============= ] - 1s 891us/step - loss: 0.3520 - accu
racy: 0.8932 - val loss: 0.5015 - val accuracy: 0.8836
Epoch 100/100
880/880 [=============] - 1s 887us/step - loss: 0.3386 - accu
racy: 0.8898 - val loss: 0.3184 - val accuracy: 0.9178
```

Out[161... <keras.callbacks.callbacks.History at 0x7f932376dfd0>

```
In [162...
```

```
# Step5.4) Predict on test data using above Model
result = model.predict(X_test)

# Step5.5) Calculate accuracy
cnt = 0
for i in range(len(Y_test)):
    if(np.amax(result[i]) < 0.5):
        pred = np.argmax(result[i])
    else:
        pred = np.argmax(result[i])
    if np.argmax(y_test[i]) == pred:
        cnt+=1

acc = str(round( cnt*100 / float(len(Y_test)),2))
print("Accuracy: " + acc + "%")

# Step5.6) Display accuracy and ConfMatrix
DisplayResult()</pre>
```

## Accuracy: 91.28%

## **ACTIVITY Confusion Matrix:**

Activitie		Calling		Clapping		Falling		Sweeping	
WashingH	and	WatchingTV		other					
Activitie	s3	14	0	0	0	0	0	0	0
Calling		0	6	0	2	0	0	0	4
Clapping		0	0	12	0	0	0	0	0
Falling		0	0	0	11	1	0	0	0
Sweeping		0	0	0	0	6	0	0	0
WashingHa	nd	0	0	0	0	0	4	0	2
WatchingTV		0	0	0	0	1	0	1	4
other	0	0	0	2	3	0	0	145	

## **ACTIVITY** Matrix:

Activitie	es3	Calling		Clapping		Falling		Sweeping	
Washing	land	WatchingTV		other					
Activitie	es3	1.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0
Calling		0.0	0.5	0.0	0.17	0.0	0.0	0.0	0.33
Clapping		0.0	0.0	1.0	0.0	0.0	0.0	0.0	0.0
Falling		0.0	0.0	0.0	0.92	0.08	0.0	0.0	0.0
Sweeping		0.0	0.0	0.0	0.0	1.0	0.0	0.0	0.0
WashingHa	and	0.0	0.0	0.0	0.0	0.0	0.67	0.0	0.33
Watching	ľV	0.0	0.0	0.0	0.0	0.17	0.0	0.17	0.67
other	0.0	0.0	0.0	0.01	0.02	0.0	0.0	0.97	

odel/ as audio CNN model.h5

In []: