

203 S. Sixth Street | Champaign, IL 61820 | Room 102 smodi9@illinois.edu | (847) 890-3506

EDUCATION

University of Illinois at Urbana-Champaign

College of Engineering: Computer Science

Courses: Discrete Math, Linear Algebra, Data Structures, Computer Architecture

May 2021

GPA | 4.00/4.00 James Scholar Honors

PROFESSIONAL EXPERIENCE

EarthSense, Undergraduate Research Assistant

Retrained a CNN that categorizes the heading of wheat into 3 classes with 90% accuracy

Trained a CNN on a 90-10 split dataset that classifies the lodging of wheat with 80% accuracy

Created visualizations of different datasets to determine data collection needs

Swarm Robotix, Software Engineering Intern

Worked in a team of 5 people to design software architecture for an autonomous swarm of robots

Collaborated with 2 people to develop vision algorithms with OpenCV that detected corner castings

Researched Convolutional Neural Networks to improve vision accuracy

Implemented SLAM with A* path planning for real-time navigation in the environment

Distributed Autonomous Systems Laboratory, Undergraduate Research Assistant

Improved a fully-autonomous robotic system that phenotypes a plot of crops (TerraSentia)

Wrote scripts to automatically update individual robots to the latest software

Developed a user-facing configuration page on Android that sets the data mode of the robot

Sep 2018 - Present Urbana, IL

May 2018 - Aug 2018

Naperville, IL

Jan 2018 - May 2018

Urbana, IL

PROJECT HIGHLIGHTS

CU-Recycle | PYGHacks 2018: 2nd Place

Determines if an item is recyclable in Urbana-Champaign

- CNN recognizes item in a photo and determines recyclability
- Neural Network was trained on Keras & TensorFlow
- Android App launched on the Play Store

FaceTunes | Lead Developer

iRobotics MRDC | 2017 - 2018

Subsystem Lead, Software Team

An app that plays a song based on current mood

- Machine learning detects emotions in an image
- Strongest emotion picked to play a song
- Spotify integration with specific mood playlists

Designed and built the robot's intake system

Developed code to control various subsystems

LEADERSHIP DEVELOPMENT

ACM SIGBot | 2017 – Present

Software Team

- Used ROS with vision to recognize game objects
- Researched KCF and other tracking algorithms

Engineering Freshmen Council | 2017 – 2018

IT Chair, 2017 - Present

Redesigned the EFC main website

SKILLS

Proficient Intermediate **Beginner**

C++, Python, Java, ROS, Android Development

OpenCV, Keras, Neural Nets, CAD (Autodesk, SolidWorks)

TensorFlow



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