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## MCT Project - 4

### Exercise 1.

Process Model :-

$$x_{t+1} = x_t + \delta t (\dot{x}_t \cos \varphi_t - \dot{y}_t \sin \varphi_t) + w_t^x$$

$$y_{t+1} = y_t + \delta t (\dot{x}_t \sin \varphi_t + \dot{y}_t \cos \varphi_t) + w_t^y$$

$$\varphi_{t+1} = \varphi_t + \delta t \dot{\varphi}_t + w_t^\varphi$$

$$\therefore x_{t+1} = f(x_t, u_t) + w_t$$

$$\therefore f = x_t + \delta t \dot{x}_t$$

$$= \begin{bmatrix} x_t \\ y_t \\ \varphi_t \\ m_x \\ m_y \\ \vdots \\ n_x \\ n_y \end{bmatrix} + \delta t \begin{bmatrix} \dot{x}_t \\ \dot{y}_t \\ \dot{\varphi}_t \\ 0 \\ \vdots \\ 0 \end{bmatrix}$$

$$f = \begin{bmatrix} x_t + \delta_t (\dot{x}_t \cos \varphi_t - \dot{y}_t \sin \varphi_t) \\ y_t + \delta_t (\dot{x}_t \sin \varphi_t + \dot{y}_t \cos \varphi_t) \\ \varphi_t + \delta_t \dot{\varphi}_t \\ m_x' \\ m_y' \\ \vdots \\ m_x^n \\ m_y^n \end{bmatrix}$$

$$\therefore F = \frac{df}{d\mathbf{x}}$$

$$F_t = \begin{bmatrix} 1 & 0 & -\delta_t (\dot{x}_t \sin \varphi_t + \dot{y}_t \cos \varphi_t) & 0 & \dots & 0 \\ 0 & 1 & \delta_t (\dot{x}_t \cos \varphi_t - \dot{y}_t \sin \varphi_t) & 0 & \dots & 0 \\ 0 & 0 & 1 & 0 & \dots & 0 \\ 0 & 0 & 0 & 1 & 0 & \dots & 0 \\ 0 & 0 & 0 & 0 & 1 & \dots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & 0 & \dots & 0 & 1 \end{bmatrix}$$

$\underbrace{\hspace{10em}}_3$ 
 $\underbrace{\hspace{10em}}_{2n}$

## Measurement Model :-

$$y_t = \begin{bmatrix} \left[ (m'_x - x_t)^2 + (m'_y - y_t)^2 \right]^{1/2} \\ \left[ (m^2_x - x_t)^2 + (m^2_y - y_t)^2 \right]^{1/2} \\ \vdots \\ \text{atan2}(m'_y - y_t, m'_x - x_t) - 4\pi \\ \text{atan2}(m^2_y - y_t, m^2_x - x_t) - 4\pi \end{bmatrix} + v_t$$

$2n \times 1$

$\swarrow$   
 $h(x_t)$

$$J = \frac{\partial h}{\partial x}$$

$$J = \begin{bmatrix} \underbrace{\frac{(m'_x - x_t)}{\|m' - p_t\|} \quad \frac{(m'_y - y_t)}{\|m' - p_t\|}}_{n} \quad \underbrace{0 \quad \frac{m'_x - x_t}{\|m' - p_t\|} \quad \frac{m'_y - y_t}{\|m' - p_t\|} \quad 0 \dots 0}_{2n} \\ \underbrace{\frac{(m^2_x - x_t)}{\|m^2 - p_t\|} \quad \frac{(m^2_y - y_t)}{\|m^2 - p_t\|}}_{n} \quad \underbrace{0 \quad 0 \quad 0 \quad \frac{m^2_x - x_t}{\|m^2 - p_t\|} \quad \frac{m^2_y - y_t}{\|m^2 - p_t\|} \quad 0 \dots 0}_{2n} \\ \vdots \\ \underbrace{\frac{m'_y - y_t}{\|m' - p_t\|^2} \quad \frac{x_t - m'_x}{\|m' - p_t\|^2} \quad -1}_{n} \quad \underbrace{\frac{y_t - m'_y}{\|m' - p_t\|^2} \quad \frac{m'_x - x_t}{\|m' - p_t\|^2} \quad 0 \dots 0}_{2n} \\ \vdots \end{bmatrix}$$

Rough work :-

wekt  $x_t$

$$\tan^{-1} \left[ \frac{m_y - y_t}{m_x - x_t} \right]$$
$$= \frac{m_y - y_t}{(x_t - m_x)^2 \left[ \frac{(y_t - m_y)^2}{(x_t - m_x)^2} + 1 \right]}$$

$$= \frac{m_y - y_t}{(y_t - m_y)^2 + (x_t - m_x)^2}$$

wekt  $y_t$

$$= \frac{1}{(x_t - m_x) \left[ \frac{(y_t - m_y)^2}{(x_t - m_x)^2} + 1 \right]}$$
$$= \frac{(y_t - m_y)^2}{x_t - m_x} + x_t - m_x$$

$$= \frac{\|m' - \mu_t\|^2}{x_t - m_n}$$

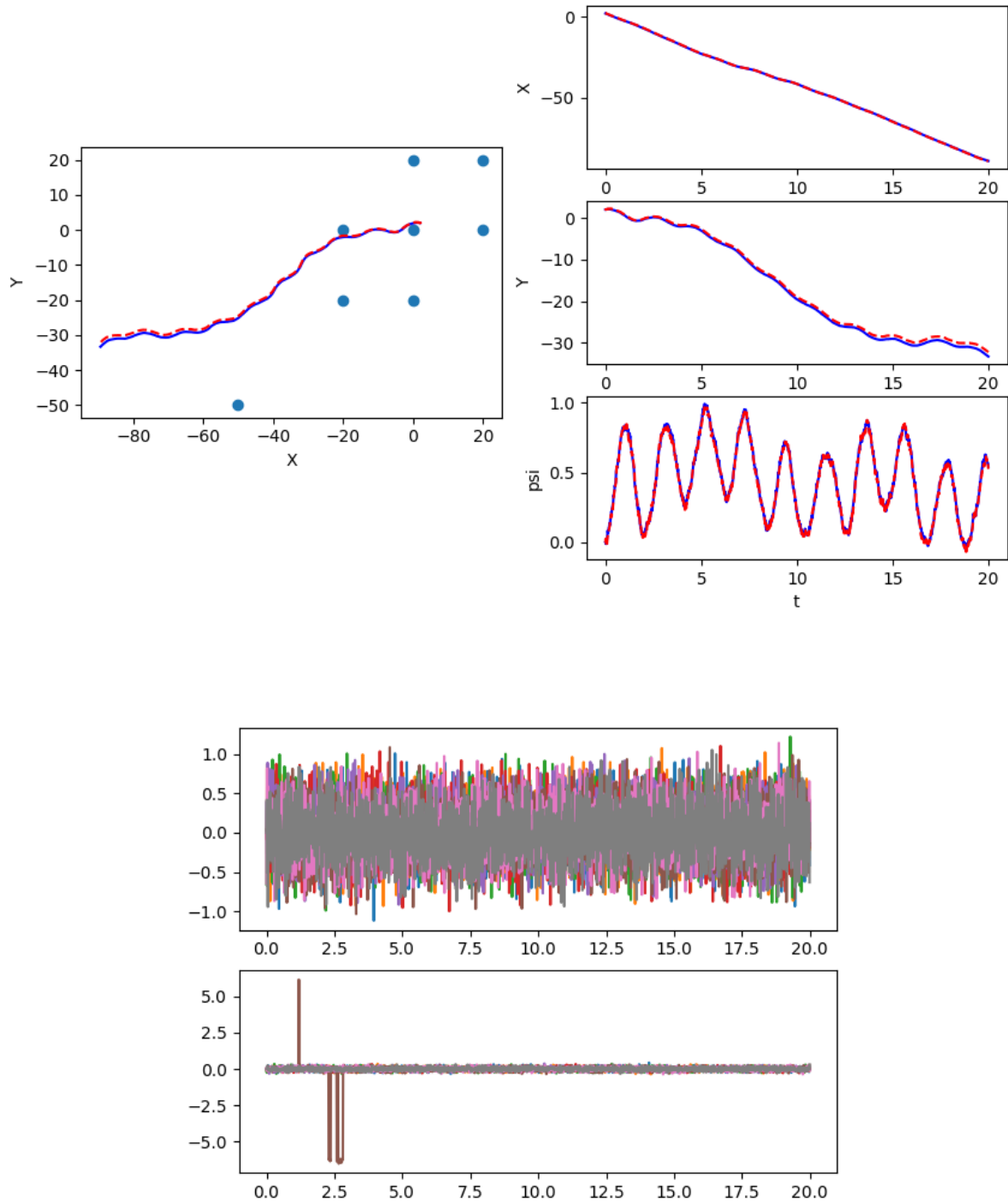
$$2(\text{row}) + 3$$

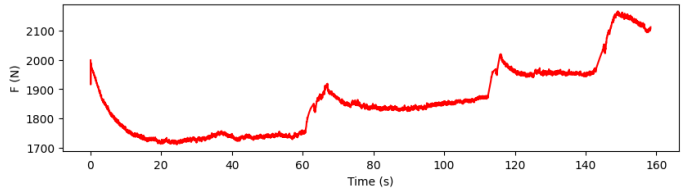
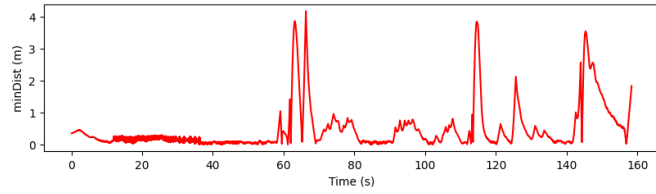
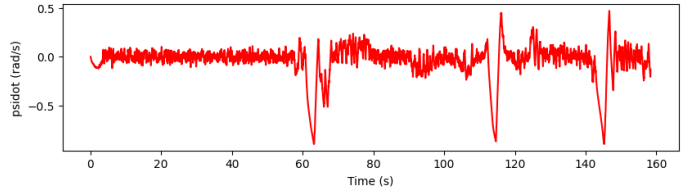
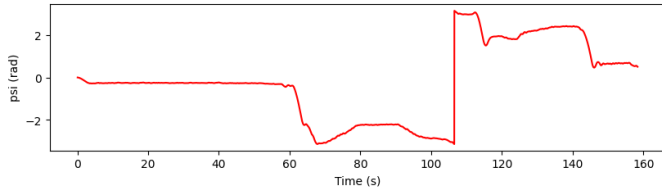
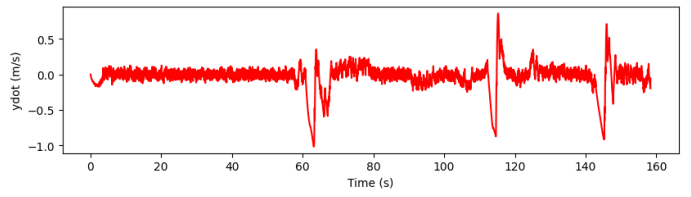
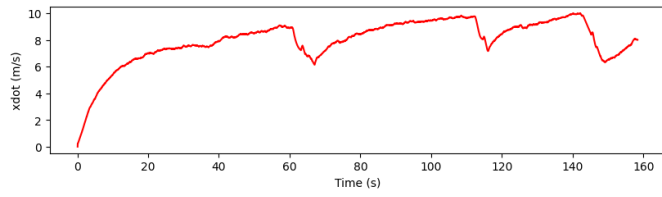
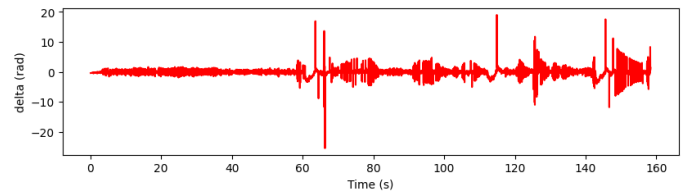
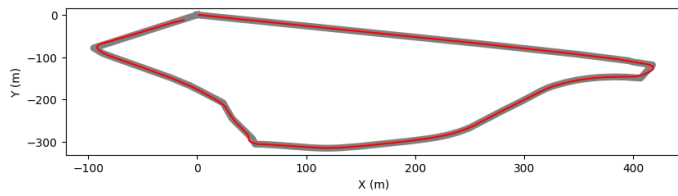
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## **PROJECT-4**

### **Exercise 2.**





#### Console - All

```
Score for completing the loop: 30.0/30.0
Score for average distance: 30.0/30.0
Score for maximum distance: 30.0/30.0
Your time is 158.368
Your total score is : 100.0/100.0
total steps: 158368
maxMinDist: 4.171348433108599
avgMinDist: 0.48647716041721717
INFO: 'main' controller exited successfully.
```