

SAHIL T CHAUDHARY

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EDUCATION

Carnegie Mellon University

Pittsburgh, PA

Master of Science in Mechanical Engineering – Research | GPA: 4.0/4.0

May 2025

- **Relevant coursework:** Planning and Decision-making, Introduction to Robot Learning, Optimal Control and Reinforcement Learning, Robot Localization and Mapping, Modern Control Theory, Machine Learning, Robot Dynamics and Analysis
- **Scholarship:** Fully funded Master's student

Vellore Institute of Technology

Vellore, India

Bachelor of Technology in Mechanical Engineering | GPA: 9.05/10.0

May 2022

- **Relevant coursework:** Robotics, CAD/CAM, Design of Machine Elements

SKILLS

Programming Languages: C++, Python, MATLAB, Julia

Tools and Software: ROS, Git, Linux, Gazebo, Matplotlib, PyTorch, NumPy, SKLearn, Docker, SolidWorks, Ansys, Fusion 360

Knowledge Areas: Controls, Planning, SLAM, Robot Dynamics, Machine Learning, CAD, Mechanical Design, 3-D Printing

WORK EXPERIENCE

Biorobotics Lab, The Robotics Institute

Pittsburgh, PA

Graduate Research Assistant, **Supervisor:** Dr Matthew J. Travers

August 2023 – Present

- **Comms-Aware Planning:** Developed a novel algorithm to maintain communication fidelity among robots in a convoy, by formulating a modified Max-Min Spanning Tree, and validated the algorithm through successful deployment on robots using proprietary radios
- **Heterogeneous Convoy Framework:** Developed a decentralized convoy framework integrating RC cars and quadruped robots, and an algorithm enabling rendezvous at intersections and coordinated return as a convoy
- **Payload Redesign:** Engineered a modular, serviceable payload for RC cars and quadruped robots, achieving a 10% weight reduction and lowering the center of gravity while ensuring optimal sensor field-of-view and accessibility, and incorporating sensors such as LiDAR, IMU, cameras, onboard computer, motor controller, and circuit boards

Carnegie Mellon University's College of Engineering

Pittsburgh, PA

Course Assistant, **Supervisor:** Dr Levent Burak Kara

January 2024 – May 2024

- Assisted in teaching the Machine Learning and Artificial Intelligence for Engineers course to graduate students

ArcelorMittal Nippon Steel India Limited

Hazira, India

Graduate Engineer Trainee – Corex Operations, **Supervisor:** Mr Akhil Timani

June 2022 – March 2023

- Ensured the smooth running of different processes such as conveyors, skip charging, coal blending, coal drying, slag granulation plant, and machinery involved in all the areas within Material Handling and the Corex Process
- Collaborated with Field Engineers to troubleshoot problems such as malfunctioning, errors, or issues with the equipment and machinery, ensuring the safety and productivity of the Plant

PROJECTS

Quadruped Path Planner for Dynamic Environments [\[Website\]](#)

Pittsburgh, PA

Carnegie Mellon University – Course Project

September 2024 – November 2024

- Demonstrated a global path planner using C++ and ROS, that accounts for dynamic obstacles and the z-height of the robot
- Benchmarked Lazy-PRM with D-Star against KD-RRT-Connect, demonstrating lower-cost paths with comparable planning times

PinBot – Reinforcement Learning on a Pinball Machine [\[Website\]](#)

Pittsburgh, PA

Carnegie Mellon University – Course Project

September 2024 – November 2024

- Developed a Proximal Policy Optimization (PPO) agent using Unity ML-Agents to play a game of pinball, achieving performance comparable to an amateur human player
- Applied transfer learning to adapt the agent for a physical pinball machine (ongoing work)

Model Predictive Path Integral Control [\[Website\]](#)

Pittsburgh, PA

Carnegie Mellon University – Course Project

February 2024 – April 2024

- Implemented MPPI in C++ and ROS for aggressive driving, with obstacle avoidance using a Voxel Grid Costmap
- Benchmarked MPPI against an existing iLQR controller, demonstrating faster path generation of up to 20%

Point-LiDAR Inertial Odometry [\[Website\]](#)

Pittsburgh, PA

Carnegie Mellon University – Course Project

February 2024 – April 2024

- Implemented the Point-LIO algorithm using C++, ROS and GTSAM, addressing the limitations of scan-based LiDAR processing
- Improved state estimation with IMU saturation, by using an Extended Kalman Filter (EKF) framework