



Experiment 1.2

Aim: Write a program to assess various feature matching algorithms for object recognition.

Software Required: Matlab, Google Colab

Objective: The primary objective of this project is to create a program that successfully implements feature matching techniques for image classification. This program will systematically compare and match distinctive features extracted from images, enabling accurate and reliable image classification. By utilizing advanced feature matching algorithms, the project aims to enhance the precision and robustness of image classification processes, thereby contributing to the advancement of computer vision applications. The program's objective is to empower researchers, developers, and practitioners with a powerful tool for improving the efficiency and effectiveness of image classification tasks through the utilization of feature matching techniques.

Code:

```
import cv2
import numpy as np
import matplotlib.pyplot as plt
query_image = cv2.imread('/content/WhatsApp Image 2023-08-29 at 12.30.23.jpeg',
cv2.IMREAD_GRAYSCALE)
target_image = cv2.imread('/content/ytyg.jpeg', cv2.IMREAD_GRAYSCALE)
feature_extractors = {
  'SIFT': cv2.SIFT_create(),
  'ORB': cv2.ORB_create(),
  'AKAZE': cv2.AKAZE create(),
  'BRISK': cv2.BRISK_create()
}
matchers = {
  'BFMatcher': cv2.BFMatcher(),
  'FlannBasedMatcher': cv2.FlannBasedMatcher()
query_kp, query_des = feature_extractors['SIFT'].detectAndCompute(query_image, None)
target_kp, target_des = feature_extractors['SIFT'].detectAndCompute(target_image, None)
results = \{ \}
# Loop through feature extractors and matchers
```

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```
for extractor_name, extractor in feature_extractors.items():
  for matcher_name, matcher in matchers.items():
    # Skip AKAZE with FlannBasedMatcher due to compatibility issues
    if extractor name == 'AKAZE' and matcher name == 'FlannBasedMatcher':
       continue
    # Compute matches
    if matcher_name == 'BFMatcher':
       matches = matcher.knnMatch(query_des, target_des, k=2)
    else:
       matches = matcher.knnMatch(np.float32(query_des), np.float32(target_des), k=2)
    # Apply ratio test
    good_matches = []
    for m, n in matches:
       if m.distance < 0.75 * n.distance:
         good_matches.append(m)
    # Store match count in results
    match_count = len(good_matches)
    results[(extractor_name, matcher_name)] = match_count
# Print the results
for (extractor_name, matcher_name), match_count in results.items():
  print(f"{extractor_name} + {matcher_name}: {match_count} matches")
for (extractor_name, matcher_name), match_count in results.items():
  print(f"{extractor_name} + {matcher_name}: {match_count} matches")
# Plot the matches for the best combination
best_combination = max(results, key=results.get)
best_extractor = feature_extractors[best_combination[0]]
best matcher = matchers[best combination[1]]
if best_combination[1] == 'BFMatcher':
  matches = best_matcher.knnMatch(query_des, target_des, k=2)
else:
  matches = best_matcher.knnMatch(np.float32(query_des), np.float32(target_des), k=2)
good_matches = []
for m, n in matches:
  if m.distance < 0.75 * n.distance:
    good_matches.append(m)
result_image = cv2.drawMatches(query_image, query_kp, target_image, target_kp, good_matches, None,
flags=cv2.DrawMatchesFlags_NOT_DRAW_SINGLE_POINTS)
plt.figure(figsize=(10, 8))
plt.imshow(result_image)
plt.title(f"Best Combination: {best_combination[0]} + {best_combination[1]}")
plt.axis('off')
plt.show()
```



Implementation:

```
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Q
       import cv2
            import numpy as np
{x}
            import matplotlib.pyplot as plt
[ ] query_image = cv2.imread('/content/WhatsApp Image 2023-08-29 at 12.30.23.jpeg', cv2.IMREAD_GRAYSCALE)
           target_image = cv2.imread('/content/ytyg.jpeg', cv2.IMREAD_GRAYSCALE)
       [ ] feature_extractors = {
               'SIFT': cv2.SIFT_create(),
                'ORB': cv2.ORB_create(),
                'AKAZE': cv2.AKAZE_create(),
                'BRISK': cv2.BRISK_create()
                'BFMatcher': cv2.BFMatcher(),
                'FlannBasedMatcher': cv2.FlannBasedMatcher()
       [ ] query_kp, query_des = feature_extractors['SIFT'].detectAndCompute(query_image, None)
           target_kp, target_des = feature_extractors['SIFT'].detectAndCompute(target_image, None)
       [ ] results = {}
       [ ] # Loop through feature extractors and matchers
            for extractor_name, extractor in feature_extractors.items():
                for matcher_name, matcher in matchers.items():
                   # Skip AKAZE with FlannBasedMatcher due to compatibility issues
                   if extractor_name == 'AKAZE' and matcher_name == 'FlannBasedMatcher':
                        continue
                   # Compute matches
                    if matcher_name == 'BFMatcher':
                        matches = matcher.knnMatch(query_des, target_des, k=2)
                       matches = matcher.knnMatch(np.float32(query_des), np.float32(target_des), k=2)
                   # Apply ratio test
                    good_matches = []
()
                   for m, n in matches:
                       if m.distance < 0.75 * n.distance:
=
                           good_matches.append(m)
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                   # Store match count in results
```



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[ ] # Print the results
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                      for (extractor_name, matcher_name), match_count in results.items():
    print(f"(extractor_name) + (matcher_name): (match_count) matches")
\{x\}
                       SIFT + BFMatcher: 96 matches
                      SIFT + BFMatcher: 96 matches
SIFT + FlannBasedMatcher: 97 matches
ORB + BFMatcher: 96 matches
ORB + FlannBasedMatcher: 98 matches
AKAZE + BFMatcher: 96 matches
BRISK + BFMatcher: 96 matches
BRISK + FlannBasedMatcher: 101 matches
 [ ] # Print the results
                      for (extractor_name, matcher_name), match_count in results.items():
    print(f"{extractor_name} + {matcher_name}: {match_count} matches")
                      # Plot the matches for the best combination
                      best_combination = max(results, key=results.get)
best_extractor = feature_extractors[best_combination[0]]
best_matcher = matchers[best_combination[1]]
                      if best_combination[1] == 'BFMatcher':
    matches = best_matcher.knnMatch(query_des, target_des, k=2)
                             matches = best_matcher.knnMatch(np.float32(query_des), np.float32(target_des), k=2)
                      good_matches = []
                      for m, n in matches:
if m.distance < 0.75 * n.distance:
                                   good matches.append(m)
                      result_image = cv2.drawMatches(query_image, query_kp, target_image, target_kp, good_matches, None, flags=cv2.DrawMatchesFlags_NOT_DRAW_SINGLE_POINTS)
                      plt.figure(figsize=(10, 8))
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 <>
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