

# Principles of Programming Languages

Module M09: Denotational Semantics of Imperative Languages

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## Imperative Languages

Imperative Languages

## **Imperative Languages**



# Imperative Languages

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Applicative Most sequential programming languages use a Data Structure that exists independently
of any program in the language

- The data structure is not explicitly mentioned in the language's syntax, but it is possible to build phrases that access it and update it
- This data structure is called the *Store*, and languages that utilize stores are called *Imperative*
- Fundamental *Store*'s are:
  - Primary memory
  - o File stores, and
  - Databases



## Imperative Languages: Stores

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Languages with Context Block Structured Applicative Summary • The *Store* and a *Program* share an intimate relationship:

- The store is critical to the evaluation of a *Phrase* in a program
- A phrase is understood in terms of
  - ▷ how it handles the store, and
  - b the absence of a proper store makes the phrase non-executable
- The store serves as a means of communication between the different phrases in the program
  - Values computed by one phrase are deposited in the store so that another
     phrase may use them
  - ▶ The language's sequencing mechanism establishes the order of communication
- The store is an inherently large argument
- Only one copy of store exists at any point during the evaluation
- We use lifted domains to model the Store



# $\mathsf{Language} + \mathsf{Assignment}$

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## Language + Assignment



## Example Language with Assignment: Command

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Languages with Context Block Structured Applicative • A declaration-free Pascal subset

- A program in the language is a sequence of commands
- Stores belong to the domain *Store* and serve as arguments to the valuation function:

$$\mathbf{C}: \mathit{Command} \to \mathit{Store}_{\perp} \to \mathit{Store}_{\perp}$$

- The purpose of a command is to produce a new store from its store argument
- A command might not terminate its actions upon the store it can loop
- The looping of a command [[C]] with store s has semantics  $C[[C]]s = \bot$ 
  - Store is lifted to Store⊥
- Command Composition is:

$$C[[C_1; C_2]] = C[[C_2]] \circ C[[C_1]]$$



## Example Language with Assignment: Abstract Syntax

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#### **Abstract Syntax:**

• Consider the entities as:

 $P \in Program$ 

 $C \in Command$ 

 $E \in Expression$ 

 $B \in Boolean\_expr$ 

 $I \in Identifier$ 

*N* ∈ *Numeral* 

P ::= C.

 $C ::= C_1$ ;  $C_2 \mid \text{if } B \text{ then } C \mid \text{if } B \text{ then } C_1 \text{ else } C_2 \mid$ 

 $I := E \mid \mathbf{diverge}$ 

 $E ::= E_1 + E_2 \mid I \mid N$ 

 $B ::= E_1 = E_2 \mid \neg B$ 

diverge is a non-terminating command



## Example Language with Assignment: Semantic Algebras

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#### Semantic Algebras:

• Truth values

Domain:  $t \in Tr = B$ 

Operations:

true, false : Tr  $not : Tr \rightarrow Tr$ 

Identifiers

Domain:  $i \in Id = Identifier$ 

• Natural Numbers

Domain:  $n \in Nat = \mathcal{N}$ 

Operations:

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zero, one, ... : Nat

 $plus : Nat \times Nat \rightarrow Nat$  $equals : Nat \times Nat \rightarrow Tr$ 



## Example Language with Assignment: Semantic Algebras

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Store

Domain:  $s \in Store = Id \rightarrow Nat$ 

Operations:

 $newstore: Store \\ newstore = \lambda i.zero$ 

 $\textit{access}: \textit{Id} \rightarrow \textit{Store} \rightarrow \textit{Nat}$ 

 $access = \lambda i.\lambda s.s(i)$ 

 $\textit{update}: \textit{Id} \rightarrow \textit{Nat} \rightarrow \textit{Store} \rightarrow \textit{Store}$ 

 $update = \lambda i.\lambda n.\lambda s.[i \mapsto n]s$ 



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#### **Valuation Functions:**

•  $P : Program \rightarrow Nat \rightarrow Nat_{\perp}$  P[[P]] = P[[C.]] = ?where the input number n is associated

where the input number n is associated with identifier [[A]] in a new store. As the program body is evaluated, and the answer is extracted from the store at [[Z]]

• C :  $Command \rightarrow Store_{\perp} \rightarrow Store_{\perp}$ C[[ $C_1$ ;  $C_2$ ]] =? C[[if B then  $C_1$ ] =? C[[if B then  $C_1$  else  $C_2$ ]] =? C[[I := E]] =? C[[diverge]] =?



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Summary • The clauses of the C function are all strict in their use of the store

- Command composition works as discussed earlier
- The conditional commands are choice functions
- The expression (e<sub>1</sub> → e<sub>2</sub> [] e<sub>3</sub>) is non-strict in arguments e<sub>2</sub> and e<sub>3</sub> the value of C[[if B then C]]s is s when B[[B]]s is false, even if C[[C]]s = ⊥
- The assignment statement performs the expected *update*
- The [[diverge]] command causes non-termination



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• **E** : Expression → Store → Nat **E**[[E<sub>1</sub> + E<sub>2</sub>]] =? **E**[[/]] =? **E**[[N]] =?

• **B** : Boolean\_expr → Store → Tr **B**[[E<sub>1</sub> = E<sub>2</sub>]] =? **B**[[¬B]] =?

• N : Numeral  $\rightarrow$  Nat (maps numeral  $\mathcal N$  to corresponding  $n \in Nat$ )



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- The **E** function also needs a store argument, but the store is used in a *read only* mode
- E's functionality shows that an expression produces a number, not a new version of store; the store is not updated by an expression
- The equation for addition is stated so that the order of evaluation of  $[[E_1]]$  and  $[[E_2]]$  is not important to the final answer. Indeed, the two expressions might even be evaluated in parallel
- A strictness check of the store is not needed, because **C** has already verified that the store is proper prior to passing it to **E**



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#### **Valuation Functions:**

• **P** :  $Program \rightarrow Nat \rightarrow Nat_{\perp}$ 

$$P[[C.]] = \lambda n.let \ s = (update [[A]] \ n \ newstore) \ in$$
 $let \ s' = C[[C]]s \ in \ (access \ [[Z]] \ s')$ 

where the input number n is associated with identifier [A] in a new store. As the program body is evaluated, and the answer is extracted from the store at [Z]

• **C** :  $Command \rightarrow Store_{\perp} \rightarrow Store_{\perp}$  $\mathbf{C}[[C_1; C_2]] = \underline{\lambda}s.\mathbf{C}[[C_2]](\mathbf{C}[[C_1]]s)$ 

$$\mathbf{C}[[\mathbf{if} \ B \ \mathbf{then} \ C]] = \underline{\lambda} s. \mathbf{B}[[B]] s \to \mathbf{C}[[C]] s \ [] s$$

$$C[[if B then C_1 else C_2]] =$$

$$\underline{\lambda}s.\mathbf{B}[[B]]s \to \mathbf{C}[[C_1]]s [] \mathbf{C}[[C_2]]s$$

$$\mathbf{C}[[I := E]] = \underline{\lambda}s.update[[I]] \ (\mathbf{E}[[E]]s) \ s$$

$$C[[diverge]] = \underline{\lambda}s.\bot$$



Language + Assignment

• **E** : Expression  $\rightarrow$  Store  $\rightarrow$  Nat  $\mathbf{E}[[E_1 + E_2]] = \lambda s. \mathbf{E}[[E_1]] s \ plus \ \mathbf{E}[[E_2]] s$  $\mathbf{E}[[I]] = \lambda s.access [[I]] s$  $\mathbf{E}[[N]] = \lambda s. \mathbf{N}[[N]]$ 

• **B** : Boolean\_expr  $\rightarrow$  Store  $\rightarrow$  Tr  $\mathbf{B}[[E_1 = E_2]] = \lambda s. \mathbf{E}[[E_1]] s$  equals  $\mathbf{E}[[E_2]] s$  $\mathbf{B}[[\neg B]] = \lambda s.not(\mathbf{B}[[B]]s)$ 

• **N** : Numeral → Nat (omitted)



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• P[[Z := 1; if A = 0 then diverge; Z := 3.]](two)



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```
    P[[Z := 1; if A = 0 then diverge; Z := 3.]](two)
    = let s = (update [[A]] two newstore) in
    let s' = C[[Z := 1; if A = 0 then diverge; Z := 3]]s
    in (access [[Z]] s')
```

```
let s' = \mathbf{C}[[Z := 1; \mathbf{if} \ A = 0 \ \mathbf{then} \ \mathbf{diverge}; Z := 3]]([\ [[A]] \mapsto two] \ newstore) in access [[Z]] \ s'
```



let  $s' = \mathbb{C}[[Z := 1]; \text{ if } A = 0 \text{ then diverge}; Z := 3]]([[A]] \mapsto two] \text{ newstore})$ 

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```
    P[[Z := 1; if A = 0 then diverge; Z := 3.]](two)
    = let s = (update [[A]] two newstore) in
    let s' = C[[Z := 1; if A = 0 then diverge; Z := 3]]s
    in (access [[Z]] s')
```

in access [[Z]] s'



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```
• C[[Z := 1; if A = 0 then diverge; Z := 3]]s_1, s_1 = [[A]] \mapsto two] newstore
     = (\lambda s. \mathbf{C}[[\mathbf{if} \ A = 0 \ \mathbf{then} \ \mathbf{diverge}; Z := 3]](\mathbf{C}[[Z := 1]]s))s_1
   C[[if A = 0 then diverge; Z := 3]](C[[Z := 1]]s_1)
   C[[Z := 1]]s_1 = (\lambda s.update [[Z]] (E[[1]]s) s)s_1
     = update [[Z]] (\mathbf{E}[[1]]s_1)s_1 = update [[Z]] (\mathbf{N}[[1]])s_1 = update [[Z]] one s_1
     = [[Z]] \mapsto one[[A]] \mapsto two] newstore = s_2
   C[[if A = 0 then diverge; Z := 3]]s_2
     = (\lambda s. \mathbf{C}[[Z := 3]]((\lambda s. \mathbf{B}[[A = 0]]s \rightarrow \mathbf{C}[[\mathbf{diverge}]]s [] s)s))s_2
     = \mathbf{C}[[Z := 3]]((\lambda s. \mathbf{B}[[A = 0]]s \rightarrow \mathbf{C}[[\mathbf{diverge}]]s []s)s_2
     = C[[Z := 3]](B[[A = 0]]s_2 \rightarrow C[[diverge]]s_2 \mid s_2)
```



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```
• \mathbf{B}[[A=0]]s_2

= (\lambda s.\mathbf{E}[[A]]s equals \mathbf{E}[[0]]s)s_2 = \mathbf{E}[[A]]s_2 equals \mathbf{E}[[0]]s_2

= (access [[A]] s_2) equals zero

access [[A]] s_2

= s_2[[A]] = ([[[Z]] \mapsto one][[[A]] \mapsto two] newstore)[[A]]

= ([[A]] \mapsto two] newstore)[[A]] (why?)

= two
```

```
• Thus, \mathbf{B}[[A=0]]s_2 = \text{false}, implying that \mathbf{C}[[\mathbf{if}\ A=0\ \mathbf{then}\ \mathbf{diverge}]]s_2 = s_2. Now: \mathbf{C}[[Z:=3]]s_2 = [\ [[Z]] \mapsto three]s_2 let s' = [\ [[Z]] \mapsto three]s_2 in access [[Z]]s' = access\ [[Z]][\ [[Z]] \mapsto three]s_2 = ([\ [[Z]] \mapsto three]s_2)[[Z]] = three
```



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Languages with Context Block Structured Applicative Summary

```
• P[[Z := 1; if A = 0 then diverge; Z := 3.]](zero)
= let s' = C[[Z := 1; if A = 0 then diverge; Z := 3]]s_3 in access [[Z]] s'
where s_3 = [[A]] \mapsto zero] newstore
```

- C[[Z := 1; if A = 0 then diverge; Z := 3]]s<sub>3</sub>
   = C[[if A = 0 then diverge; Z := 3]]s<sub>4</sub>
   where s<sub>4</sub> = [ [[Z]] → one]s<sub>3</sub>
- $B[[A = 0]]s_4 \rightarrow C[[diverge]]s_4 [] s_4$ =  $true \rightarrow C[[diverge]]s_4 [] s_4$ =  $C[[diverge]]s_4$ =  $(\underline{\lambda}s.\bot)s_4$ =  $|\bot$
- $\mathbf{P} = let \ s' = \bot \ in \ access \ [[Z]] \ s' = \bot$



## Example Language with Assignment: Equivalence of Stores

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Prove that:

$$\mathbf{C}[[X := 0; Y := X + 1]]s = \mathbf{C}[[Y := 1; X := 0]]s$$

That is, these programs are equivalent.



## Example Language with Assignment

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Languages with Context Block Structured Applicative Summary Prove that:

$$C[[X := 0; Y := X + 1]]s = C[[Y := 1; X := 0]]s$$

That is, these programs are equivalent.

- C[[X := 0; Y := X + 1]]s= C[[Y := X + 1]](C[[X := 0]]s)=  $C[[Y := X + 1]]([[[X]] \mapsto zero]s)$ =  $update[[Y]] (E[[X + 1]] ([[X]] \mapsto zero]s))([[[X]] \mapsto zero]s)$ =  $update[[Y]] one[[[X]] \mapsto zero]s$ =  $[[[Y]] \mapsto one][[[X]] \mapsto zero]s = s_1$
- C[[Y := 1; X := 0]]s= C[[X := 0]] (C[[Y := 1]]s)=  $C[[X := 0]] ([[Y]] \mapsto one]s)$ =  $C[[X]] \mapsto zero] [[Y]] \mapsto one]s = s_2$
- Are they the  $s_1$  and  $s_2$  the same store?



## Example Language with Assignment

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Languages with Context Block Structured Applicative Summary

```
• Are they the s_1 = [[[Y]] \mapsto one] [[[X]] \mapsto zero]s and s_2 = [[[X]] \mapsto zero] [[[Y]] \mapsto one]s the same store?
```

```
• The argument is [[X]]: then s_1[[X]] = ([[[Y]] \mapsto one][[[X]] \mapsto zero]s)[[X]] = ([[[X]] \mapsto zero]s)[[X]] = zero; and s_2[[X]] = ([[[X]] \mapsto zero][[[Y]] \mapsto one]s)[[X]] = zero
```

• The argument is [[Y]]: then  $s_1[[Y]] = ([[[Y]] \mapsto one][[[X]] \mapsto zero]s)[[Y]] = one$ ; and  $s_2[[Y]] = ([[[X]] \mapsto zero][[[Y]] \mapsto one]s)[[Y]] = ([[[Y]] \mapsto one]s)[[Y]] = one$ 

• The argument is some identifier [[/]] other than [[X]] or [[Y]]:  $s_1[[I]] = s[[I]] = s[[I]]$ 



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## **Programs Are Functions**



Programs Are Functions

Consider again the example:

[[Z := 1; if A = 0 then diverge; Z := 3]]

What is its meaning?

• It is a function:  $Nat \rightarrow Nat$ 

• Its meaning is:

 $\lambda n.n$  equals zero  $\rightarrow \bot$  [] three

Prove.



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Languages with Context Block Structured Applicative Consider again the example: [[Z := 1; if A = 0 then diverge; Z := 3]]. What is its meaning? It is a function:  $Nat \rightarrow Nat_{\perp}$ 

```
• P[[Z := 1; if A = 0 then diverge; Z := 3.]]
  =\lambda n. let s=update[A] n newstore in
    let s' = \mathbb{C}[[Z := 1; if A = 0 \text{ then diverge}; Z := 3]]s in access[[Z]] s'
  =\lambda n.let s = update [A] n newstore in
    let s' = (\lambda s.(\lambda s.C[[Z := 3]](C[[if A = 0 then diverge]]s))s)(C[[Z := 1]]s)
    in access[[Z]] s'
  =\lambda n.let s = update [A] n newstore in
    let s' = (\lambda s.(\lambda s.update [[Z]] three s)
     ((\lambda s.(access [A])s) equals zero \rightarrow (\lambda s.\bot)s[s)s))
      ((\lambda s.update [[Z]] one s)s) in access [[Z]]s'
  which can be restated as: \lambda n.let s = update [A] n newstore in
    let s' = (lets'_1 = update [Z]) one s in
      let s_2' = (access [A] s_1') equals zero \rightarrow (\lambda s. \bot) s_1' 1 [s_1']
      in update [[Z]] three s_2 in access [[Z]]s'
```



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```
• \lambda n.let \ s' = (let \ s'_1 = update[[Z]] \ one \ s_0 \ in

let \ s'_2 = (access \ [[A]] \ s'_1) \ equals \ zero \rightarrow (\underline{\lambda} s. \bot) s'_1 \ [] \ s'1 \ in \ update \ [[Z]] \ three \ s'_2)

in \ access \ [[Z]] \ s'
```

```
(access [[A]] s_1) equals zero \rightarrow \bot [] s_1 = n equals zero \rightarrow \bot [] s_1
```

The conditional can be simplified no further. We can make use of the following property; "for  $e_2 \in Store_{\perp}$  s.t.  $e_2 \neq \perp$ , let  $s = (e_1 \rightarrow \perp []e_2)$  in  $e_3$  equals  $e_1 \rightarrow \perp [][e_2/s]e_3$ "

```
let s_2' = (n \text{ equals zero } \rightarrow \bot [] s_1) \text{ in update } [[Z]] \text{ three } s_2' = n \text{ equals zero } \rightarrow \bot [] \text{ update } [[Z]] \text{ three } s_1
```

 $\lambda n.let \ s' = (n \ equals \ zero \rightarrow \bot \ [] \ update \ [[Z]] \ three \ s_1) \ in \ access \ [[Z]]s'$ 

 $\lambda n.n \ equals \ zero \rightarrow \bot \ [] \ access[[Z]] \ (update \ [[Z]] \ three \ s_1)$ 

 $\lambda$ n.n equals zero  $\rightarrow \bot$  [] three



## Interactive File Editor

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#### Interactive File Editor



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- The language is an interactive file editor
- A file is a list of records, where the domain of records is taken as primitive
- The file editor makes use of two levels of store
  - the primary store is a component holding the file being edited upon by the user (has a current record marker), and
  - o the secondary store is a system of text files indexed by their names
- The edit process:
  - Load a file (identified by name) from secondary store to primary store. This
    initializes the current record to the first record of the file. This is skipped for new
    files
  - Edit the file in the primary store (forward / rewind move current record marker forward or reverse, insert / delete record). Alternately, the editor may Create a new file and start editing
  - Save the file from primary store to secondary store



## Interactive File Editor: Abstract Syntax

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**Abstract Syntax:** 

• Consider the entities as:

 $P \in Program\_session$ 

 $S \in Command\_sequence$ 

 $C \in Command$ 

 $R \in Record$ 

 $B \in Boolean\_expr$ 

 $I \in Identifier$ 

 $P ::= \mathbf{edit} \ I \ \mathbf{cr} \ S$ 

 $S := C \operatorname{cr} S \mid \operatorname{quit}$ 

 $C ::= newfile \mid moveforward \mid moveback \mid insert R \mid delete$ 



## An Interactive File Editor: Openfile Representation

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Languages with Context Block Structured Applicative • The edited files are values from the *Openfile* domain

• An opened file  $r_1, r_2, \dots, r_{last}$  is represented by two lists of text records; the lists break the file open in the middle:

$$r_1 r_2 \dots r_{i-1} r_i r_{i+1} \dots r_{last-1} r_{last}$$



Current Record

$$r_{i-1}...r_2r_1$$
  $r_ir_{i+1}...r_{last}$ 

where  $r_i$  is the *current* record of the opened file

Note how the first list is written in the reverse order



### An Interactive File Editor: newfile

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Summary

• newfile represents a file with no records



 $newfile : Openfile \\ newfile = (nil, nil)$ 



## An Interactive File Editor: copyin

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• copyin takes a file from the file system and organizes it as:

 $r_1 r_2 \dots r_{last}$ 

where  $r_1$  is the *current* record of the opened file *copyin*: File  $\rightarrow$  Openfile

copyin : File 
$$\rightarrow$$
 Openfile copyin =  $\lambda f.(nil, f)$ 



#### An Interactive File Editor: forward

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Languages with Context Block Structured Applicative • The *forwards* operation makes the record *following* the current record the new current record. Pictorially, for:

$$r_1 r_2 \dots r_{i-1} r_i r_{i+1} \dots r_{last-1} r_{last}$$

$$Current Record$$
 $r_{i-1} \dots r_2 r_1$ 
 $r_i r_{i+1} \dots r_{last}$ 

a forwards move produces:

$$r_1 r_2 \dots r_{i-1} r_i r_{i+1} \dots r_{last-1} r_{last}$$

$$forward \uparrow$$

$$Current Record$$

$$r_i r_{i-1} \dots r_2 r_1$$

$$r_{i+1} \dots r_{last}$$

forwards : Openfile  $\rightarrow$  Openfile forwards =  $\lambda$ (front, back).null back  $\rightarrow$  (front, back) [] ((hd back) cons front, (tl back))



### An Interactive File Editor: backward

Interactive File Editor

• The backwards operation makes the record preceding the current record the new current record. Pictorially, for:

 $r_{i-1}r_{i-2}...r_2r_1$   $r_ir_{i+1}...r_{last}$ 

a backward move produces:

$$\underline{r_{i-2}...r_2r_1} \qquad \underline{r_{i-1}r_ir_{i+1}}.$$

backwards : Openfile → Openfile  $backwards = \lambda(front, back).null\ front \rightarrow (front, back)\ []\ (tl\ front, (hd\ front)\ cons\ back)$ 



### An Interactive File Editor: insert R

Interactive File Editor

• insert places a record R after the current record. Pictorially, for:

 $r_{i-1}...r_2r_1$   $r_ir_{i+1}...r_{last}$ 

an insertion of record R produces:

$$r_1 r_2 \dots r_{i-1} r_i R r_{i+1} \dots r_{last-1} r_{last}$$

Insert R

Current Record

 $r_i \dots r_2 r_1$ 
 $R r_{i+1} \dots r_{last}$ 

The newly inserted record becomes current

insert : Record  $\times$  Openfile  $\rightarrow$  Openfile  $insert = \lambda(r, (front, back)).null\ back \rightarrow (front, r\ cons\ back)$ [] ((hd back) cons front), r cons (tl back))



### An Interactive File Editor: delete

Interactive File Editor

• *delete* removes the *current record*. Pictorially, for:

 $r_{i-1}...r_2r_1$   $r_ir_{i+1}...r_{last}$ 

deletion produces:

The record following the deleted record becomes *current* delete : Openfile → Openfile  $delete = \lambda(front, back).(front, (null back \rightarrow back [] tl back))$ 



### An Interactive File Editor: Test Operations

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• Check if the first record in the file is current (at\_first\_record),

 $at\_first\_record : Openfile \rightarrow Tr$  $at\_first\_record = \lambda(front, back).null front$ 

• Check if the last record in the file is current (at\_last\_record)

 $at\_last\_record: Openfile o Tr$  $at\_last\_record = \lambda(front, back).null\ back o true\ []\ (null\ (tl\ back) o true\ []\ false)$ 

• Check if the file is empty (isempty)



isempty : Openfile  $\rightarrow$  Tr



### An Interactive File Editor: copyout

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• An open file  $r_1, r_2, \dots, r_{last}$  in the *Openfile* domain:

 $r_{i-1}...r_2r_1$   $r_ir_{i+1}...r_{last}$ 

needs to be written back to File System. *copyout* is the operation for it which should convert it to:

 $r_1 r_2 \dots r_{last}$ 

and then write back:

```
copyout : Openfile \rightarrow File

copyout = \lambda p. "appends fst(p) to snd(p) – defined later" // Recursive

copyout = \lambda(front, back).null\ front \rightarrow back\ []\ copyout((tl\ front),\ ((hd\ front)\ cons\ back))
```



### Interactive File Editor: Semantic Algebra

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Truth Values
 Domain: t ∈ Tr
 Operations:

true, false:  $Tr = \mathcal{B}$ and:  $Tr \times Tr \rightarrow Tr$ 

• *Identifiers*: Domain:  $i \in Id = Identifier$ 

• Text records: Domain:  $r \in Record$ 

• Text file: Domain:  $f \in File = Record^*$ 

• File System

Domain:  $s \in File\_system = Id \rightarrow File$ 

Operations:

 $access: Id \times File\_system \rightarrow File$ 

 $access = \lambda(i, s).s(i)$ 

update :  $Id \times File \times File\_system \rightarrow File\_system$  $update = \lambda(i, f, s).[i \mapsto f]s$ 



### Interactive File Editor: Semantic Algebra

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```
    Open file

   Domain: p \in Openfile = Record^* \times Record^*
   Operations:
    newfile: Openfile
     newfile = (nil, nil)
    copvin : File \rightarrow Openfile
     copyin = \lambda f.(nil, f)
    copyout : Openfile \rightarrow File
     copvout = \lambda p. "appends fst(p) to snd(p) – defined later" // Recursive
     copyout = \lambda(front, back).null\ front \rightarrow back\ []\ copyout((tl\ front),\ ((hd\ front)\ cons\ back))
    forwards : Openfile → Openfile
     forwards = \lambda(front, back).null back \rightarrow (front, back) [] ((hd back) cons front, (tl back))
    backwards: Openfile \rightarrow Openfile
     backwards = \lambda(front, back).null\ front \rightarrow (front, back)\ []\ (tl\ front, (hd\ front)\ cons\ back)
    insert : Record \times Openfile \rightarrow Openfile
     insert = \lambda(r, (front, back)).null\ back \rightarrow (front, r\ cons\ back)
        [] ((hd back) cons front), r cons (tl back))
    delete: Openfile \rightarrow Openfile
     delete = \lambda(front, back).(front, (null back \rightarrow back [] tl back))
```



### Interactive File Editor: Semantic Algebra

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anguages with Context Block Structured Applicative Gummary • Open file (Contd.)

```
Operations: at\_first\_record : Openfile \rightarrow Tr at\_first\_record : A(front, back).null front at\_last\_record : Openfile \rightarrow Tr at\_last\_record = \lambda(front, back).null back \rightarrow true [] (null (tl back) \rightarrow true [] false) isempty : Openfile \rightarrow Tr isempty = \lambda(front, back).(null front) and (null back)
```

Character String

Domain: String =the strings formed from the elements of  $\mathcal C$  (including an  $\mathit{error}$  string) Operations:

A, B, C, ..., Z : String empty : String error : String

 $concat: String \times String \rightarrow String$ 

 $length: String \rightarrow Nat$ 

 $\textit{substr}: \textit{String} \times \textit{Nat} \times \textit{Nat} \rightarrow \textit{String}$ 

Output terminal log: Domain: I ∈ Log = String\*



### Interactive File Editor: Valuation Functions

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#### **Valuation Functions:**

- P: Program\_session → File\_system → (Log × File\_system)
   P[[edit / cr S]] =?
- S : Command\_sequence → Openfile → (Log × Openfile)
   S[[C cr S]] =?
   S[[quit]] =?
- C : Command → Openfile → (String × Openfile)
   C[[newfile]] =?
   C[[moveforward]] =?
   C[[moveback]] =?
   C[[insert R]] =?
   C[[delete]] =?



### Interactive File Editor: Valuation Functions

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#### **Valuation Functions:**

```
• P: Program\_session \rightarrow File\_system \rightarrow (Log \times File\_system)
• P[[edit | cr | S]]

= \lambda s.let p = copyin(access([[I]], s)) in
("edit | cons | fst(S[[S]]p), update([[I]], copyout(snd(S[[S]]p)), s))
```

• **S** :  $Command\_sequence \rightarrow Openfile \rightarrow (Log \times Openfile)$  **S**[[C **cr** S]]  $= \lambda p.let (l', p') = \mathbf{C}[[C]]p in$   $((l'cons\ fst(\mathbf{S}[[S]]p')), snd(\mathbf{S}[[S]]p'))$  **S**[[**quit**]]  $= \lambda p.("auit"\ cons\ nil, p)$ 



### Interactive File Editor

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- The S function collects the log messages into a list
- S[[quit]] builds the very end of this list
- The equation for S[[C cr S]] deserves a bit of study. It says to:
  - Evaluate C[[C]]p to obtain the next log entry I' plus the updated open file p'
  - $\circ$  Cons I' to the log list and pass p' onto S[[S]]
  - $\circ$  Evaluate S[[S]]p' to obtain the meaning of the remainder of the program, which is the rest of the log output plus the final version of the updated open file



### Interactive File Editor: Valuation Functions

```
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```

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Summary

```
• C : Command \rightarrow Openfile \rightarrow (String \times Openfile)
```

```
C[[newfile]] = \lambda p.("newfile", newfile)
```

### **C**[[moveforward]]

```
= \lambda p.let \ (k',p') = isempty(p) \rightarrow ("error: file is empty",p) \\ [] \ (at\_last\_record(p) \rightarrow ("error: at back already",p) [] \ ("",forwards(p))) \\ in \ ("moveforward" concat \ k',p'))
```

#### C[[moveback]]

```
= \lambda p.let \ (k',p') = isempty(p) \rightarrow ("error: file is empty",p) \\ [] \ (at\_first\_record(p) \rightarrow ("error: at front already",p)) [] \ ("",backwards(p)) \\ in \ ("moveback" concat \ k',p')
```

```
C[[insert R]] = \lambda p.("insert R", insert(R[[R]], p))
```

### C[[delete]]

 $=\lambda p.let\ (k',p')=isempty(p) \rightarrow ("error: file\ is\ empty",p)\ []\ ("",delete(p))$ in ("delete" concat k',p')



# Interactive File Editor: Example Program Workout 1

Interactive File Editor

 C[[delete]](newfile) [] ("", delete(newfile))

```
= let (k', p') = isempty(newfile) \rightarrow ("error : file is empty", newfile)
in ("delete" concat k', p')
```

= let(k', p') = ("error: file is empty", newfile)

in ("delete" concat k', p')

= ("delete" concat "error : file is empty", newfile)

= (" delete error : file is empty", newfile)



# Interactive File Editor: Example Program Workout 2

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Let [A] be the name of a nonempty file in the file system  $s_0$ 

- P[[edit A cr moveback cr delete cr quit]]s<sub>0</sub>
  - = ("edit A" cons fst( $S[[moveback cr delete cr quit]]p_0$ ), update([[A]], copyout(snd( $S[[moveback cr delete cr quit]]p_0$ ),  $s_0$ )) where  $p_0 = copyin(access([[A]], s_0)$ )
  - = ("edit A" cons "moveback error: at front already" cons  $fst(S[[delete\ cr\ quit]]p_0))$ ,  $update([[A]], copyout(snd(S[[delete\ cr\ quit]]p_0), s_0)))$



# Interactive File Editor: Example Program Workout 2

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Languages with Context Block Structured Applicative Let [A] be the name of a nonempty file in the file system  $s_0$ 

- P[[edit A cr moveback cr delete cr quit]]s<sub>0</sub>
  - = ("edit A" cons fst( $S[[moveback cr delete cr quit]]p_0$ ),  $update([[A]], copyout(snd(<math>S[[moveback cr delete cr quit]]p_0$ ),  $s_0$ )) where  $p_0 = copyin(access([[A]], s_0)$ )
  - = (" edit A" cons " moveback error : at front already" cons  $fst(S[[delete\ cr\ quit]]p_0))$ ,  $update([[A]], copyout(snd(S[[delete\ cr\ quit]]p_0))))$

**S**[[delete cr quit]] $p_0$  simplifies to a pair ("delete quit",  $p_1$ ), for  $p_1 = delete(p_0)$ , and the final result is:

("edit A moveback error: at front already delete quit,"  $update([[A]], copyout(p_1), s_0)$ )



# Dynamically Typed Language

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# **Dynamically Typed Language**



# Dynamically Typed Language with IO

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- An extension of the Language with assignment
- Languages like Python, SNOBOL allow variables to take on values from different data types during the course of evaluation
- This provides flexibility to the user but requires that type checking be performed at run-time
- The semantics of the language gives us insight into the type checking
- We use:
  - $\circ$  Storable\_value = Tr + Nat
  - $\circ$  Store = Id  $\rightarrow$  Storable\_value
- Since storable values are used in arithmetic and logical expressions, type errors are possible, as in an attempt to add a truth value to a number



### Dynamically Typed Language with IO: Abstract Syntax

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### **Abstract Syntax:**

• Consider the entities as:

 $P \in Program\_session$ 

 $C \in Command$ 

 $E \in Expression$ 

*N* ∈ *Numeral* 

 $I \in Id$ 

P ::= C.

 $C ::= C_1; \ C_2 \mid I := E \mid$ 

if E then  $C_1$  else  $C_2 \mid \text{read } I \mid \text{write } E \mid \text{diverge}$ 

 $E ::= E_1 + E_2 \mid E_1 = E_2 \mid \neg E \mid (E) \mid I \mid N \mid true$ 



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### **Semantic Algebras:**

Truth values

Domain:  $t \in Tr = B$ 

Operations:

true, false: Trnot:  $Tr \rightarrow Tr$ 

• Natural Numbers

Domain:  $n \in Nat = \mathcal{N}$ 

Operations:

zero, one, ... : Nat

 $plus : Nat \times Nat \rightarrow Nat$  $equals : Nat \times Nat \rightarrow Tr$ 

Identifiers

Domain:  $i \in Id = Identifier$ 



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### Semantic Algebras:

• Character String

Domain: String =the strings formed from the elements of  $\mathcal{C}$  (including an error string)

Operations:

A, B, C, ..., Z: String

empty : String
error : String

 $concat: String \times String \rightarrow String$ 

 $\textit{length}: \textit{String} \rightarrow \textit{Nat}$ 

 $substr: String \times Nat \times Nat \rightarrow String$ 

Values that may be stored

Domain:  $v \in Storable\_value = Tr + Nat$ 



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```
• Values that expressions may denote Domain: x \in Expressible\_value = Storable\_value + Errvalue
```

where Errvalue = Unit Operations:

 $check\_expr: (Store \rightarrow Expressible\_value) \times (Store \rightarrow Expressible\_v$ 

 $(Storable\_value \rightarrow Store \rightarrow Expressible\_value) \rightarrow (Store \rightarrow Expressible\_value)$ 

 $f_1$  check\_expr  $f_2 = \lambda s.$ let  $z = (f_1 \ s)$  in cases z of is S to rable value  $(v) \rightarrow (f_2 \ v \ s)$  [] is F revalue (v)

 $\textit{isStorable\_value}(\textit{v}) \rightarrow (\textit{f}_2 \ \textit{v} \ \textit{s}) \ [] \ \textit{isErrvalue}() \rightarrow \textit{inErrvalue}() \ \textit{end}$ 

#### Note:

- o check\_expr performs error trapping at the expression level when two expressions are used to build a bigger expression with an operator. For example, consider:  $E_1 + E_2$
- $f_1$  is the valuation function  $[[E_1]]$  of  $E_1$  that takes the store s to produce  $v \in Storable\_value$  (or an Errvalue in which case we cannot proceed)
- o If v is not a type error,  $f_2$ , the valuation function  $[[E_2]]$  of  $E_2$ , takes the store s to produce  $v' \in Storable\_value$  (or an Errvalue)
- $\circ$  Finally, the operator (*plus*) is applied onto v and v' (if there is not type error) to produce the final result



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```
    Input buffer
        Domain: i ∈ Input = Expressible_value*
        Operations:
        get_value : Input → (Expressible_value × Input)
        get_value = λi.null i → (inErrvalue(), i) [] (hd i, tl i)
```

• Output buffer Domain:  $o \in Output = (Storable\_value + String)^*$  Operations: empty: Output empty = nil put\_value: Storable\_value  $\times$  Output  $\rightarrow$  Output put\_value =  $\lambda(v, o).inStorable\_value(v)$  cons o put\_message:  $String \times Output \rightarrow Output$  put\_message =  $\lambda(t, o).inString(t)$  cons o



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Store

 $\mathsf{Domain:}\ s \in \mathit{Store} = \mathit{Id} \rightarrow \mathit{Storable\_value}$ 

Operations:

newstore : Store

 $access: Id \rightarrow Store \rightarrow Storable\_value$ 

 $access = \lambda(i, s).s(i)$ 

 $\textit{update}: \textit{Id} \rightarrow \textit{Storable\_value} \rightarrow \textit{Store} \rightarrow \textit{Store}$ 

 $update = \lambda(i, v, s).[i \mapsto v]s$ 

Program State

Domain:  $a \in State = Store \times Input \times Output$ 



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```
    Post program state

   Domain: z \in Post \ state = OK + Err
   where OK = State and Frr = State
   Operations:
   check\_result: (Store \rightarrow Expressible\_value) \times (Storable\_value \rightarrow State \rightarrow Post\_state_{\perp})
         \rightarrow (State \rightarrow Post_state \mid)
   f check_result g = \lambda(s, i, o).let z = (f s) in cases z of
         isStorable\_value(v) \rightarrow (g \ v \ (s, i, o))
          [] is Errvalue() \rightarrow
          inErr(s, i, put_message("type error", o)) end
   check\_cmd: (State \rightarrow Post\_state_{\perp}) \times
       (State \rightarrow Post\_state_{\perp}) \rightarrow (State \rightarrow Post\_state_{\perp})
      h_1 check_cmd h_2 = \lambda a.let z = (h_1 \ a) in cases z of
         isOK(s,i,o) \rightarrow h_2(s,i,o)
         [] is Err(s, i, o) \rightarrow z end
```



# Dynamically Typed Language with IO

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- Program state (*State*) is a triple of store and input and output buffers
- The Post\_state domain is used to signal when an evaluation is completed successfully and when a type error occurs
- The tag attached to the state is utilized by the *check\_cmd* operation

The expression ( $C[[C_1]]$  check\_cmd  $C[[C_2]]$ ) denotes the sequencing operation for the language and does the following:

- [1] It gives the current state a to  $C[[C_1]]$ , producing a  $Post\_state\ z = C[[C_1]]a$
- [2] If z is a proper state a', and then, if the state component is OK, it produces  $C[[C_2]]a'$
- [3] If z is erroneous,  $C[[C_2]]$  is ignored (it is branched over), and z is the result

*check\_result*, sequences an expression with a command:

- [1] For example, for an assignment [[I := E]], [[E]]'s value must be determined before a store update can occur
- [2] If Since [[E]]'s evaluation may cause a type error, the error must be detected before the update is attempted
- [3] Operation *check\_result* performs this action

check\_expr performs error trapping at the expression level



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#### **Valuation Functions:**

• **P** :  $Program \rightarrow Store \rightarrow Input \rightarrow Post\_state_{\perp}$ **P**[[C.]] =  $\lambda s.\lambda i.$ **C**[[C]] (s, i, empty)

• **C** :  $Command \rightarrow State \rightarrow Post\_state_{\perp}$  $\mathbf{C}[[C_1; C_2]] = \mathbf{C}[[C_1]] \ check\_cmd \ \mathbf{C}[[C_2]]$ 

```
 \begin{array}{l} \textit{check\_cmd}: (\textit{State} \rightarrow \textit{Post\_state}_\bot) \times \\ (\textit{State} \rightarrow \textit{Post\_state}_\bot) \rightarrow (\textit{State} \rightarrow \textit{Post\_state}_\bot) \\ \textit{h}_1 \ \textit{check\_cmd} \ \textit{h}_2 = \lambda \textit{a.let} \ \textit{z} = (\textit{h}_1 \ \textit{a}) \ \textit{in cases} \ \textit{z} \ \textit{of} \\ \textit{isOK}(s,i,o) \rightarrow \textit{h}_2 \ (s,i,o) \\ \boxed{[} \ \textit{isErr}(s,i,o) \rightarrow \textit{z} \ \textit{end} \end{array}
```



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```
• \mathbf{C}[[I := E]] = \mathbf{E}[[E]] check_result (\lambda v.\lambda(s,i,o).inOK((update[[I]]\ v\ s),i,o))

\mathbf{C}[[\mathbf{if}\ E\ \mathbf{then}\ C_1\ \mathbf{else}\ C_2]] = \mathbf{E}[[E]] check_result

(\lambda v.\lambda(s,i,o).cases\ v\ of\ isTr(t) \to (t \to \mathbf{C}[[C_1]]\ []\ \mathbf{C}[[C_2]])(s,i,o)

[]\ isNat(n) \to inErr(s,i,put\_message("bad\ test",o))\ end)

\mathbf{C}[[\mathbf{read}\ I]] = \lambda(s,i,o).let\ (x,i') = get\_value(i)\ in

cases\ x\ of\ isStorable\_value(v) \to inOK((update[[I]]\ v\ s),i',o)

[]\ isErrvalue() \to inErr(s,i',put\_message("bad\ input",o))\ end

\mathbf{C}[[\mathbf{write}\ E]] = \mathbf{E}[[E]]\ check\_result\ (\lambda v.\lambda(s,i,o).inOK(s,i,put\_value(v,o)))

\mathbf{C}[[\mathbf{diverge}]] = \lambda a.\bot
```

```
 \begin{array}{l} \textit{check\_result} : (\textit{Store} \rightarrow \textit{Expressible\_value}) \times (\textit{Storable\_value} \rightarrow \textit{State} \rightarrow \textit{Post\_state}_\bot) \\ \rightarrow (\textit{State} \rightarrow \textit{Post\_state}_\bot) \\ \textit{f check\_result} \ g = \lambda(s,i,o).let \ z = (f \ s) \ \textit{in cases} \ z \ \textit{of} \\ \textit{isStorable\_value}(v) \rightarrow (g \ v \ (s,i,o)) \ [] \ \textit{isErrvalue}() \rightarrow \\ \textit{inErr}(s,i,put\_message}("type \ error",o)) \ \textit{end} \\ \end{array}
```



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```
• \mathbf{E}: Expression \rightarrow Store \rightarrow Expressible\_value
\mathbf{E}[[E_1 + E_2]] = \mathbf{E}[[E_1]] \ check\_expr
(\lambda v. \ cases \ v \ of
isTr(t) \rightarrow \lambda s. inErrvalue()
[] \ isNat(n) \rightarrow \mathbf{E}[[E_2]] \ check\_expr
(\lambda v'.\lambda s. \ cases \ v' \ of
isTr(t') \rightarrow inErrvalue()
[] \ isNat(n') \rightarrow inStorable\_value(inNat(n \ plus \ n')) \ end)
end)
```

```
check\_expr: (Store \rightarrow Expressible\_value) \times \\ (Storable\_value \rightarrow Store \rightarrow Expressible\_value) \rightarrow (Store \rightarrow Expressible\_value) \\ f_1 check\_expr f_2 = \lambda s.let z = (f_1 s) in cases z of \\ isStorable\_value(v) \rightarrow (f_2 v s) [] isErrvalue() \rightarrow inErrvalue() \\ end
```



```
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```

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```
    E[[E1 = E2]] = similar to above equation
    E[[¬E]] = E[[E]]check_expr
        (\lambda v.\lambda s. cases v of isTr(t) → inStorable_value(inTr(not t)) [] isNat(n) → inErrvalue() end)
    E[[(E)]] = E[[E]]
    E[[I]] = \lambda s.inStorable_value(access [[I]] s)
    E[[N]] = \lambda s.inStorable_value(inNat(N[[N]]))
    E[[true]] = \lambda s.inStorable_value(inTr(true))
    N : Numeral → Nat(omitted)
```

```
 \begin{array}{l} \textit{check\_expr}: (\textit{Store} \rightarrow \textit{Expressible\_value}) \times \\ (\textit{Storable\_value} \rightarrow \textit{Store} \rightarrow \textit{Expressible\_value}) \rightarrow (\textit{Store} \rightarrow \textit{Expressible\_value}) \\ f_1 \ \textit{check\_expr} \ f_2 = \lambda s.let \ z = (f_1 \ s) \ \textit{in cases} \ z \ \textit{of} \\ \ \textit{isStorable\_value}(v) \rightarrow (f_2 \ v \ s) \ [] \ \textit{isErrvalue}() \rightarrow \textit{inErrvalue}() \\ \ \textit{end} \end{array}
```



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Languages wit Context Block Structured Applicative Summary

### Compute the semantics (post-state) for the following:

```
P[[read X; X := X + 1; write X.]](\(\lambda i. zero, (3), ())\)
  = C[[read X; X := X + 1; write X]] (\lambda i. zero, (3), ())
  = (C[[read X]] check\_cmd C[[X := X + 1; write X]]) (\lambda i. zero, (3), ())
  = (\lambda a.let z = (C[[read X; ]] a) in cases z of
     isOK(s, i, o) \rightarrow \mathbb{C}[[X := X + 1; write X]] (s, i, o)
     [] isErr(s, i, o) \rightarrow z \text{ end} (\lambda i, zero. (3), ())
  = \mathbb{C}[[X := X + 1: write X]] inOK((\lambda i.i equals X \to three [] zero, (), ()))
  = (C[[X := X + 1]] check\_cmd C[[write X]]) inOK((\lambda i.i equals X 	o three [] zero, (), ()))
  = (\lambda a.let z = (C[[X := X + 1]] a) in cases z of
     isOK(s, i, o) \rightarrow C[[write X]] (s, i, o)
     [] is Err(s, i, o) \rightarrow z end) in OK((\lambda i.i \text{ equals } X \rightarrow three \ [] \text{ zero}, (), ()))
  = C[[write X]] inOK((\lambda i.i equals X \rightarrow four [] zero,(),()))
  = inOK((\lambda i.i equals X \rightarrow four [] zero), (), (4))
```



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```
 \begin{split} \textbf{C}[[X := X+1]] & \text{ inOK}(\lambda i.i \text{ equals } X \rightarrow \text{three } [] \text{ zero}, (), ())) \\ &= \textbf{E}[[X+1]] & \text{ check\_result } (\lambda v.inOK((update[[X]] \text{ } v \text{ inOK}((\lambda i.i \text{ equals } X \rightarrow \text{three } [] \text{ zero})), (), ()))) \\ &= \text{let } z = (\textbf{E}[[X+1]] \text{ } s_1) \text{ in cases } z \text{ of } \text{ isStorable\_value}(v) \rightarrow (g \text{ } v \text{ } (s_1, (), ())) \\ &= [\text{ isErrvalue}() \rightarrow \text{inErr}(s_1, (), \text{put\_message}("type \text{ error"}, ())) \text{ end} \\ &\text{where } s_1 = (\lambda i.i \text{ equals } X \rightarrow \text{three } [] \text{ zero}), (), ()) \text{ and} \\ &= \lambda v.inOK((update[[X]] \text{ } v \text{ } (\lambda i.i \text{ equals } X \rightarrow \text{ three } [] \text{ zero})), (), ()) \\ &= g \text{ inNat}(\text{four}) \text{ } (s_1, (), ()) \\ &= inOK((update[[X]] \text{ inNat}(\text{four}) \text{ } (\lambda i.i \text{ equals } X \rightarrow \text{ three } [] \text{ zero})), (), ()) \\ &= inOK(\lambda i.i \text{ equals } X \rightarrow \text{ four } [] \text{ zero}), (), ()) \end{aligned}
```



```
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```

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```
\begin{aligned} \mathbf{E}[[X+1]] & s_1 = \mathbf{E}[[X+1]] \ inOK((\lambda i.i \ equals \ X \rightarrow three \ [] \ zero, (), ())) \\ &= \mathbf{E}[[X]] \ check\_expr \\ & (\lambda v. \ cases \ v \ of \ isTr(t) \rightarrow \lambda s.inErrvalue() \\ & [] \ isNat(n) \rightarrow \mathbf{E}[[1]] \ check\_expr \\ & (\lambda v'.\lambda s. \ cases \ v' \ of \ isTr(t') \rightarrow inErrvalue() \\ & [] \ isNat(n') \rightarrow inStorable\_value(inNat(n \ plus \ n')) \ end) \\ & end) \ inOK((\lambda i.i \ equals \ X \rightarrow three \ [] \ zero, (), ())) \\ &= inStorable\_value(inNat(three \ plus \ one)) = inStorable\_value(inNat(four)) \end{aligned}
\mathbf{C}[[\mathbf{write} \ X]] = \mathbf{E}[[X]] \ check\_result \ (\lambda v.\lambda(s,i,o).inOK(s,i,put\_value(v,o))) \\ &= inOK((\lambda i.i \ equals \ X \rightarrow four \ [] \ zero), (), (4)) \end{aligned}
```



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Compute the semantics (post-state) for the following:

- $P[[read \ X; X := X + 1; write \ X.]](\lambda i. \ zero, \ (3), \ ())$
- $P[[read \ X; X := X + 1; write \ X.]](\lambda i. zero, (), ())$
- P[[read X; read Y;
   if (X = Y) then M := true else M := ¬true; write M.]] (λi. zero, (3 3), ())
- P[[read X; read Y;
   if (X = Y) then M := true else M := ¬true; write M.]] (λi. zero, (3 4), ())
- P[[read X; read Y;
   if (X = Y) then M := true else M := ¬true; write M.]] (λi. zero, (3), ())
- P[[read X; read Y; if (X = Y) then M := X = Y else  $M := \neg(X = Y)$ ; write M.]]  $(\lambda i. zero, (3 4), ())$
- $P[[if (X = Y) then M := true else M := \neg true; write M.]] (\lambda i. two, (), ())$
- $P[[read \ X; read \ Y; X := X + Y; write \ X.]] (\lambda i. zero, (3 false), ())$



# Dynamically Typed Language with IO: Example Programs with denotations

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### **Denotations (post-state) for the programs:**

- P[[read X; X := X + 1; write X.]]( $\lambda i.$  zero, (3), ()) =  $inOK((\lambda i.i.$  equals  $X \rightarrow four$  [] zero, (), (4)))
- P[[read X; X := X + 1; write X.]](\(\lambda i. zero, \((), \(()) = inErr((\lambda i. zero, \((), \((''bad input''))))\))\)
- P[[read X; read Y; if (X = Y) then M := true else  $M := \neg \text{true}$ ; write M.] ( $\lambda i.$  zero, (3 3), ()) =  $inOK((\lambda i.i \text{ equals } X \to \text{three} [] \text{ i equals } Y \to \text{three} [] \text{ i equals } M \to \text{true} [] \text{ zero, (), (true))})$
- P[[read X; read Y; if (X = Y) then M := true else M := ¬true; write M.]] (λi. zero, (3 4), ()) = inOK((λi.i equals X → three [] i equals Y → four [] i equals M → false [] zero, (), (false)))
- P[[read X; read Y; if (X = Y) then M := true else  $M := \neg \text{true}$ ; write M.]]  $(\lambda i. zero, (3), ()) = inErr((\lambda i.i) equals <math>X \to three$  [] zero, (), ("bad input"))
- P[[read X; read Y;
   if (X = Y) then M := X = Y else M := ¬(X = Y); write M.]] (λi. zero, (3 4), ()) = inOK((λi.i equals X → three [] i equals Y → four [] i equals M → true [] zero, (), (true)))
- P[[if (X = Y) then M := true else M := ¬true; write M.]] (λi. two, (), ()) = inOK((λi.i equals M → true [] two, (), (true)))
- P[[read X; read Y; X := X + Y; write X.]] ( $\lambda i$ . zero, (3 false), ()) = inErr(( $\lambda i$ .i equals X  $\rightarrow$  three [] i equals Y  $\rightarrow$  false [] zero, (), ("type error")))



### Recursive Definitions

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Summar

### **Recursive Definitions**



## Recursively Defined Functions

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• The *copyout* function of File Editor, which concatenates two lists, could not be given. We can specify *copyout* using an iterative or recursive specification, but at this point neither is allowed in the function notation.

```
copyout : Openfile \rightarrow File

copyout = \lambda p. "appends fst(p) to snd(p)" // Recursive

copyout = \lambda (front, back).null\ front \rightarrow back

[] copyout((tl\ front),\ ((hd\ front)\ cons\ back))
```



## Recursively Defined Functions

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• A similar situation arises with the semantics of a Pascal-like while-loop:

B : Boolean\_expression

C: Command

 $C ::= \cdots \mid$  while B do  $C \mid \cdots \mid$ 

Here is a recursive definition of its semantics: for

**B** :  $Boolean\_expression \rightarrow Store \rightarrow Tr$ , and **C** :  $Command \rightarrow Store_{\perp} \rightarrow Store_{\perp}$  :

C[[while 
$$B$$
 do  $C$ ]] =  $\underline{\lambda}s$ .B[[ $B$ ]] $s \rightarrow$   
C[[while  $B$  do  $C$ ]](C[[ $C$ ]] $s$ ) []  $s$ 



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Languages with Context Block Structured Applicative • Unfortunately, the clause violates the rule that the meaning of a syntax phrase may be defined only in terms of the meanings of its proper sub-parts

• We avoid this problem by stating:

$$\mathbf{C}[[\mathbf{while}\ B\ \mathbf{do}\ C]] = w$$

where  $w: Store_{\perp} \rightarrow Store_{\perp}$  is

$$w = \underline{\lambda} s. \mathbf{B}[[B]] s \to w(\mathbf{C}[[C]] s) [] s$$

 But the recursion remains, for the new version exchanges the recursion in the syntax for recursion in the function notation



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A recursive definition may not uniquely define a function. Consider

$$q(x) = x$$
 equals zero  $\rightarrow$  one []  $q(x$  plus one)

which apparently is:  $\mathcal{N} \to \mathcal{N}_{\perp}$ . The following functions all satisfy q's definition in the sense that they have exactly the behavior required by the equation:

- $f_1(x) = one$ , if x = zero= 1, otherwise, OR
  - $f_1(x) = \lambda x. (x \text{ equals zero} \rightarrow \text{one } [] \perp) = \{(\text{zero}, \text{ one})\}, (\text{one}, \perp), (\text{two}, \perp), \cdots\}$
- $f_2(x) = one$ , if x = zero= two, otherwise. OR

$$f_2(x) = \lambda x.(x \text{ equals zero} \rightarrow \text{ one } [] \text{ two}) = \{(\text{zero, one}), (\text{one, two}), (\text{two, two}), \cdots\}$$

- $f_3(x) = \lambda x.(one) = \{(zero, one), (one, one), (two, one), \dots \}$
- $g_k(x) = \{(zero, one), (one, k), (two, k), \dots\}, k \in Nat$
- and there are infinitely many others



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Languages with Context Block Structured Applicative Given

$$q(x) = x$$
 equals zero  $\rightarrow$  one []  $q(x$  plus one)

Prove that  $\forall n \in Nat$ 

- [1] n equals  $zero \rightarrow one$  []  $f_1(n \text{ plus one}) = f_1(n) = q(n)$  where  $f_1(x) = \lambda x.(x \text{ equals } zero \rightarrow one$  []  $\bot$ )
- [2]  $n \text{ equals zero} \rightarrow one [] f_2(n \text{ plus one}) = f_2(n) = q(n)$ where  $f_2(x) = \lambda x.(x \text{ equals zero} \rightarrow one [] \text{ two})$
- [3]  $n \text{ equals } zero \rightarrow one [] f_3(n \text{ plus } one) = f_3(n) = q(n)$ where  $f_3(x) = \lambda x.(one)$
- [4]  $n \text{ equals zero} \rightarrow one [] g_k(n \text{ plus one}) = g_k(n) = q(n)$ where  $g_k(x) = \lambda x.(x \text{ equals zero} \rightarrow one [] k)$  and  $k \in Nat$



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```
[1] n equals zero \rightarrow one [] f_1(n) plus one)
             = n equals zero \rightarrow one [] (\lambda x.(x equals zero <math>\rightarrow one [] \bot))(n plus one)
             = n equals zero \rightarrow one [] ((n plus one) equals zero \rightarrow one [] \bot)
             = n equals zero \rightarrow one \llbracket \ \bot
             = f_1(n) = \lambda x.(x \text{ equals zero} \rightarrow \text{one } [] \perp)
[2] n = \text{equals zero} \rightarrow \text{one} [] f_0(n = \text{plus one})
             = n \text{ equals zero} \rightarrow \text{one } [] (\lambda x.(x \text{ equals zero} \rightarrow \text{one } [] \text{ two}))(n \text{ plus one})
             = n equals zero \rightarrow one [] ((n plus one) equals zero \rightarrow one [] two)
             = n \text{ equals zero} \rightarrow one \Pi \text{ two}
             = f_2(n) = \lambda x.(x \text{ equals zero} \rightarrow \text{one } [] \text{ two})
    n equals zero \rightarrow one [] f_3(n \text{ plus one})
             = n equals zero \rightarrow one [(\lambda x.(one))(n plus one)]
             = n equals zero \rightarrow one \Pi one
             = one
             = f_3(n) = \lambda x.(one)
```



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Languages with Context Block Structured Applicative • A large number of functions satisfy the recursive definition of q:

```
q(x) = x equals zero \rightarrow one [] q(x plus one)
```

- One choice is the function that maps *zero* to *one* and all other arguments to  $\bot$ . We write this function's graph as  $\{(zero, one)\}$  (rather than  $\{(zero, one), (one, \bot), (two, \bot), \cdots\}$ , treating the  $(n, \bot)$  pairs as *ghost members*)
- This choice is a natural one for programming, for it corresponds to what happens when the definition is run as a routine on a machine.

```
// Natural Operational Semantics in C
// q(n) = n equals zero -> one [] q(n plus one)
unsigned int q(unsigned int n) {
   if (n == 0) return 1;
   else return q(n + 1); // Never terminates -- bottom
}
```



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Languages with Context Block Structured Applicative • But the graph {(zero, one), (one, four), (two, four), (three, four), ...} also denotes a function that also has the behavior specified by q: zero maps to one and all other arguments map to the same answer as their successors

```
// Unnatural Operational Semantics in C
// q(n) = n equals zero -> one [] four
unsigned int q(unsigned int x) {
   if (x == 0) return 1;
   else return 4;
}
```

So we have multiple choices. Not all of them may be operationally acceptable.

- In general, any graph  $\{(zero, one), (one, k), (two, k), \dots\}$ , for some  $k \in Nat_{\perp}$ , represents a function that satisfies the specification.
- For a programmer, the last graph is an unnatural choice for the meaning of *q*, but a mathematician might like a function with the largest possible graph instead, the claim being that a *fuller* function gives more insight



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anguages with Context Block Structured Applicative • As a recursive specification may not define a unique function, so which one should be selected as the meaning of the specification?

- Choose the one that suits operational intuitions
- Theory of *least fixed point semantics* establishes the meaning of recursive specifications. The theory:
  - [1] Guarantees that the specification has at least one function satisfying it.
  - [2] Provides a means for choosing a *best* function out of the set of all functions satisfying the specification.
  - [3] Ensures that the function selected has a graph that *corresponds to the operational treatment* of recursion:

The function maps an argument a to a defined answer b iff the operational evaluation of the specification with the representation of argument a produces the representation of b in a **finite number of recursive invocations** 



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Consider:  $fac: Nat \rightarrow Nat_{\perp}$ 

```
fac(n) = n equals zero \rightarrow one [] n times (fac(n \text{ minus one})) = {(zero, one), (one, one), (two, two), (three, six), \cdots, (i, i!), \cdots}
```



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#### Finite Unfolding:

- [1] Zero unfolding ( $fac_0$ ): no argument  $n \in Nat$  can produce an answer, for no form fac(n) can simplify to an answer without the initial unfolding. Hence  $graph(fac_0) = \{ \}$
- [2] One unfolding ( $fac_1$ ): This allows fac to be replaced by its body only once. Thus,  $fac(zero) \Rightarrow zero \ equals \ zero \rightarrow one \ [] \cdots = one$ , but all other nonzero arguments require further unfoldings to simplify to answers. Hence  $graph(fac_1) = \{(zero, one)\}$
- [3] Two unfolding's (fac<sub>2</sub>): Since only one unfolding is needed for mapping argument zero to one, (zero, one) appears in the graph. The extra unfolding allows argument one to evaluate to one, for

```
fac(one) \Rightarrow one \ equals \ zero \rightarrow one \ [] \ one \ times \ (fac(one \ minus \ one)) = one \ times \ fac(zero) \Rightarrow one \ times \ (zero \ equals \ zero \rightarrow one \ [] \ \cdots) = one \ times \ one = one. All other arguments require further unfoldings and do not produce answers at this stage. Hence graph(fac_2) = \{(zero, one), (one, one)\}
```

[4] (i+1) unfolding's  $(fac_{i+1})$ , for  $i \ge 0$ : All arguments with values of i or less will simplify to answers i!, giving

$$graph(fac_{i+1}) = \{(zero, one), (one, one), (two, two), (three, six), \dots, (i, i!)\}.$$



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# Unfolding of fac by Simulation

```
// Project: PoPL 2019. fac_unfold.cpp, \perp shown as -1
fac = \lambda n.n \text{ equals zero} \rightarrow one [] n \text{ times } (fac(n \text{ minus one}))
COMPUTING LFP of fac(n) =
n equals zero -> one[] n times (fac(n minus one))
fac(0) = 1 in 1 unfolds
fac(1) = 1 in 2 unfolds
fac(2) = 2 in 3 unfolds
fac(3) = 6 in 4 unfolds
fac(4) = 24 in 5 unfolds
fac(5) = 120 in 6 unfolds
fac(6) = 720 \text{ in } 7 \text{ unfolds}
fac(7) = 5040 in 8 unfolds
fac(8) = 40320 \text{ in } 9 \text{ unfolds}
fac(9) = 362880 in 10 unfolds
```

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## Unfolding of fac by Simulation

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```
// Project: PoPL 2019. fac_unfold.cpp, \perp shown as -1
// fac(n) = n equals zero -> one[] n times (fac(n minus one))
#include <iostream>
using namespace std:
static unsigned int facCount = 0, maxUnfoldingLevel;
unsigned int fac(unsigned int x) { ++facCount:
    if (x == 0) return 1:
    else if (facCount == maxUnfoldingLevel) throw 1;
         else return x * fac(x - 1):
int fac unfold(unsigned int maxUnfoldingLevel = 100, unsigned int maxParam = 10) {
    bool bottom = false; unsigned int result; ::maxUnfoldingLevel = maxUnfoldingLevel;
    cout<<"COMPUTING LFP of fac(n) = n equals zero -> one [] n times (fac(n minus one))\n";
    for (unsigned int n = 0: n < maxParam: ++n) {
        try { bottom = false; facCount = 0; result = fac(n); }
        catch (int) { bottom = true: }
        cout << "fac(" << n << ") = "
             << (int)((bottom) ? -1 : result) << " in " << facCount << " unfolds" << endl:
    cout << endl << endl:
    return 0:
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```



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Prove:  $\bigcup_{i=0}^{\infty} graph(fac_i) = graph(factorial)$ 



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Summary

Prove:  $\bigcup_{i=0}^{\infty} graph(fac_i) = graph(factorial)$ 

Forward direction:

- We get:  $\forall i \geq 0$ ,  $graph(fac_i) \subseteq graph(fac_{i+1})$
- Clearly,  $\forall i \geq 0$ ,  $graph(fac_i) \subseteq graph(factorial)$
- Hence,

$$\cup_{i=0}^{\infty} graph(fac_i) \subseteq graph(factorial)$$

#### Backward direction:

• If some pair (a, b) is in graph(factorial), then there must be some finite i > 0 such that (a, b) is in  $graph(fac_i)$  also. Thus:

$$graph(factorial) \subseteq \cup_{i=0}^{\infty} graph(fac_i)$$

Hence,

$$\bigcup_{i=0}^{\infty} graph(fac_i) = graph(factorial)$$



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The fundamental principle of least fixed point semantics:

- The meaning of any recursively defined function is exactly the union of the meanings of its finite sub-functions
- It is easy to produce a non-recursive representation of each sub-function

For example: Define each  $fac_i : Nat \rightarrow Nat_{\perp}$ , for  $i \geq 0$ , as:

- $fac_0 = \lambda n. \perp$
- $fac_{i+1} = \lambda n.n$  equals  $zero \rightarrow one$  []  $n \text{ times } fac_i(n \text{ minus } one), \text{ for all } i \geq 0$

The graph of each  $fac_i$  is the one produced at stage i of the fac unfolding



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This has two advantages:

- [1] Each  $fac_i$  is a non-recursive definition, which suggests that a recursive specification can be understood in terms of a family of non-recursive ones; and
- [2] A format common to all the faci's can be extracted. Let:

```
F = \lambda f.\lambda n.n equals zero \rightarrow one []

n times f(n \text{ minus one})

= \lambda f.\lambda n.n equals zero \rightarrow one []

let \ n' = f(n \text{ minus one}) in n times n'
```

Each 
$$fac_{i+1} = F(fac_i), \forall i \geq 0$$



#### Recursive Functions Definitions: factorial

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Languages witl Context Block Structured Applicative • The non-recursive  $F:(Nat \to Nat_{\perp}) \to (Nat \to Nat_{\perp})$  is called a *functional*, because it takes a function as an argument and produces one as a result. Thus:

$$graph(factorial) = \bigcup_{i=0}^{\infty} graph(F^{i}(\Phi))$$

where  $F^i = F \circ F \circ \cdots \circ F$ , i times, and  $\Phi = (\lambda n. \perp)$ 

- Also, graph(F(factorial)) = graph(factorial), which implies F(factorial) = factorial, by the extensionality principle
- The *factorial* function is a fixed point of *F*, as the answer *F* produces from argument factorial is exactly factorial again

$$factorial = fix F$$



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Summary

Consider:

 $q: \mathsf{Nat} \to \mathsf{Nat}_\perp$ , q(x) = x equals  $\mathsf{zero} \to \mathsf{one} \ [] \ q(x \ \mathsf{plus} \ \mathsf{one})$ 

Then,  $Q:(\mathit{Nat} o \mathit{Nat}_\perp) o (\mathit{Nat} o \mathit{Nat}_\perp)$ 

 $Q = \lambda g.\lambda n.n$  equals zero  $\rightarrow$  one [] g(n plus one)

Compute the fixed point of Q



## Recursive Functions Definitions: *q* Function

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Summary

```
Consider: q: \mathcal{N} \to \mathcal{N}_{\perp}, q(x) = x equals zero \to one [] q(x plus one)
```

Then,  $Q:(Nat \rightarrow Nat_{\perp}) \rightarrow (Nat \rightarrow Nat_{\perp})$  $Q = \lambda g. \lambda n.n \ equals \ zero \rightarrow one \ [] \ g(n \ plus \ one)$ 

We get:

$$Q^{0}(\Phi) = (\lambda n. \perp)$$
, where  $\Phi = (\lambda n. \perp)$  graph $(Q^{0}(\Phi)) = \{ \}$ 

$$Q^1(\Phi) = Q(Q^0(\Phi)) = \lambda n.n$$
 equals zero  $\rightarrow$  one  $[](\lambda n.\perp)(n \text{ plus one}) = \lambda n.n$  equals zero  $\rightarrow$  one  $[]\perp$  graph( $Q^1(\Phi)$ ) = {(zero, one)}

$$Q^2(\Phi) = Q(Q^1(\Phi)) = \lambda n.n$$
 equals zero  $\rightarrow$  one [] ((n plus one) equals zero  $\rightarrow$  one []  $\perp$ ) =  $\lambda n.n$  equals zero  $\rightarrow$  one []  $\perp$  =  $Q^1(\Phi)$ 

$$graph(Q^2(\Phi)) = \{(zero, one)\}$$

Hence,  $\forall i \geq 1, graph(Q^i(\Phi)) = \{(zero, one)\}$ . It follows that:

$$\bigcup_{i=0}^{\infty} graph(Q^{i}(\Phi)) = \{(zero, one)\}$$
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## Recursive Functions Definitions: *q* Function

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Languages with Context Block Structured Applicative Let *qlimit* denote the function that has this graph. It is easy to show that Q(qlimit) = qlimit, that is, *qlimit* is a fixed point of Q. Or, *qlimit* = fix Q. Unlike the specification fac, q has many possible solutions. Recall that each one must have a graph of the form  $\{(zero, one), (one, k), \cdots, (i, k), \cdots\}$  for some  $k \in Nat_{\perp}$ .

Let *qk* be one of these solutions. We can show that:

- [1] qk is a fixed point of Q, that is, Q(qk) = qk
- [2]  $graph(qlimit) \subseteq graph(qk)$
- Fact 1 says that the act of satisfying a specification is formalized by the fixed point property – only fixed points of the associated functional are possible meanings of the specification
- Fact 2 states that the solution obtained using the stages of unfolding method is the smallest of all the possible solutions

So, we call it the *least fixed point* of the *functional* 

Try to prove Fact 1 and Fact 2 above

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## Unfolding of q by Simulation

```
// Project: PoPL 2019. g_unfold.cpp. \perp shown as -1
             q = \lambda x.x equals zero \rightarrow one [] q(x) plus one
             COMPUTING LFP of q(n) =
             n equals zero -> one [] q(n plus one)
             q(0) = 1 in 1 unfolds
             q(1) = -1 in 100 unfolds
            q(2) = -1 in 100 unfolds
             q(3) = -1 in 100 unfolds
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             q(4) = -1 in 100 unfolds
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            q(5) = -1 in 100 unfolds
            q(6) = -1 in 100 unfolds
            q(7) = -1 in 100 unfolds
             q(8) = -1 in 100 unfolds
             q(9) = -1 in 100 unfolds
```

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## Unfolding of q by Simulation

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Definitions

```
// Project: PoPL 2019. q_unfold.cpp, \perp shown as -1
// q(n) = n equals zero \rightarrow one [] q(n plus one)
#include <iostream>
using namespace std;
static unsigned int gCount = 0, maxUnfoldingLevel;
unsigned int q(unsigned int x) { ++qCount;
    if (x == 0) return 1:
    else if (qCount == maxUnfoldingLevel) throw 1; else return q(x + 1);
int q_unfold(unsigned int maxUnfoldingLevel = 100, unsigned int maxParam = 10) {
    bool bottom = false; unsigned int result; ::maxUnfoldingLevel = maxUnfoldingLevel;
    cout << "COMPUTING LFP of q(n) = n equals zero -> one [] q(n plus one)" << endl;</pre>
    for (unsigned int n = 0: n < maxParam: ++n) {
        try { bottom = false; qCount = 0; result = q(n); }
        catch (int) { bottom = true: }
        cout << "q(" << n << ") = " << (int)((bottom) ? -1 : result)
             << " in " << qCount << " unfolds" << endl;
    cout << endl << endl:
    return 0:
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```



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Languages with Context Block Structured Applicative Let a recursive specification f = F(f) denote the least fixed point of functional F, that is, the function associated with  $\bigcup_{i=0}^{\infty} graph(F^i(\Phi))$ , as obtained by the stages of unfolding.

The three desired properties follow:

- A solution to the specification exists;
- The criterion of least-ness is used to select from the possible solutions; and,
- Since the method for constructing the function exactly follows the usual operational treatment of recursive definitions, the solution corresponds to the one determined computationally



## Recursive Functions Definitions: copyout

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Languages with Context Block Structured Applicative Summary

#### copyout function:

• The domains:

```
File = Record^* and Openfile = Record^* \times Record^*
```

- Function *copyout* converts an open file into a file by appending the two record lists
- A specification of copyout: Openfile  $\rightarrow$  File\_\(\pm\) is: copyout =  $\lambda(front, back).null\ front \rightarrow back\[]$  copyout((tl front),((hd front) cons back))
- Construct functional F such that copyout = (fix F)
- Prove that the function  $F^i(\bot)$  is capable of appending list pairs whose first component has length i-1 or less
- This implies that the *lub* of the  $F^i(\bot)$  functions, (fix F), is capable of concatenating all pairs of lists whose first component has finite length



## Recursive Functions Definitions: copyout

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#### copyout function:

- $copyout^0 = \lambda(front, back).\bot$
- $copyout^1 = \lambda(front, back).null\ front \rightarrow back\ []\ copyout^0((tl\ front), ((hd\ front)\ cons\ back))$ =  $\lambda(front, back).null\ front \rightarrow back\ []\ \bot$
- $copyout^2 = \lambda(front, back).null\ front \rightarrow back\ []\ copyout^1((tl\ front), ((hd\ front)\ cons\ back))$   $= \lambda(front, back).null\ front \rightarrow back\ []\ ((tl\ front), ((hd\ front)\ cons\ back))$  $= \lambda(front, back).null\ front \rightarrow back\ []\ (null\ (tl\ front) \rightarrow ((hd\ front)\ cons\ back)\ []\ \bot)$
- $copyout^{i+1} = \lambda(front, back).null \ front \rightarrow back \ [] \ copyout^i((tl \ front), ((hd \ front) \ cons \ back))$
- Functional  $F: (Openfile \rightarrow File_{\perp}) \rightarrow (Openfile \rightarrow File_{\perp}):$  $F = \lambda f.\lambda(front, back).null\ front \rightarrow back\ []\ f((tl\ front),((hd\ front)\ cons\ back))$
- copyout = fix F = F(copyout)



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Consider the specification for  $g: \mathit{Nat} \to \mathit{Nat}_{\perp}:$ 

 $g = \lambda n.n$  equals zero  $\rightarrow$  one [] (g(n minus one) plus g(n minus one)) minus one

What is g?

Hint: Construct F and compute the graphs of  $F^{i}(\bot)$ 



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Languages with Context Block Structured Applicative

```
Consider the specification for g: Nat \rightarrow Nat_{\perp}:
```

```
g = \lambda n.n equals zero \rightarrow one [] (g(n \text{ minus one}) plus g(n \text{ minus one})) minus one
```

 $F = \lambda f. \lambda n.n$  equals zero  $\rightarrow$  one [] (f(n minus one) plus f(n minus one)) minus one

```
Using \perp for (\lambda n. \perp)
```

```
\begin{split} & graph(F^0(\bot)) = \{\} \\ & graph(F^1(\bot)) = \{(zero, one)\} \\ & graph(F^2(\bot)) = \{(zero, one)\} \\ & graph(F^3(\bot)) = \{(zero, one), (one, one)\} \\ & graph(F^4(\bot)) = \{(zero, one), (one, one)\} \\ & graph(F^5(\bot)) = \{(zero, one), (one, one)\} \\ & graph(F^6(\bot)) = \{(zero, one), (one, one)\} \\ & graph(F^7(\bot)) = \{(zero, one), (one, one), (two, one)\} \\ \end{split}
```



```
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```

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Summary

```
graph(F^0(\bot)) = \{\}
graph(F^1(\perp)) = \{(zero, one)\}
graph(F^2(\perp)) = \{(zero, one)\}
graph(F^3(\bot)) = \{(zero, one), (one, one)\}
graph(F^4(\perp)) = \{(zero, one), (one, one)\}
graph(F^5(\perp)) = \{(zero, one), (one, one)\}
graph(F^6(\bot)) = \{(zero, one), (one, one)\}
graph(F^7(\bot)) = \{(zero, one), (one, one), (two, one)\}
graph(F^8(\bot)) = \{(zero, one), (one, one), (two, one)\}
graph(F^9(\bot)) = \{(zero, one), (one, one), (two, one)\}
graph(F^{10}(\perp)) = \{(zero, one), (one, one), (two, one)\}
graph(F^{11}(\bot)) = \{(zero, one), (one, one), (two, one)\}
graph(F^{12}(\bot)) = \{(zero, one), (one, one), (two, one)\}
graph(F^{13}(\bot)) = \{(zero, one), (one, one), (two, one)\}
graph(F^{14}(\bot)) = \{(zero, one), (one, one), (two, one)\}
graph(F^{15}(\bot)) = \{(zero, one), (one, one), (two, one), (three, one)\}
\forall i, i \geq 0, graph(F^i(\bot)) = \{(zero, one), (one, one), (two, one), \cdots, (i, one)\}
Hence: (fix F) = \lambda n.one
Prove: graph(F^{i}(\bot)) = \bigcup_{i=1}^{j} \{(k, one)\}, 2^{j+1} - 1 \le i \le 2^{j+2} - 2, i \ge 0
```



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 $F = \lambda f.\lambda n.n$  equals zero  $\rightarrow$  one [] (f(n minus one) plus f(n minus one)) minus one

#### Prove:

• Exponential number of unfoldings are required for this graph:

$$graph(F^{0}(\bot)) = \{ \}$$
  
 $graph(F^{i}(\bot)) = \bigcup_{k=0}^{j} \{(k, one)\}, \ 2^{j+1} - 1 \le i \le 2^{j+2} - 2, \ j \ge 0 \}$ 

•  $(fix F) = \lambda n.one$ 



Unfolding Examples

# Unfolding of g (Double) by Simulation

```
// Project: PoPL 2019. g_double_unfold.cpp, \perp shown as -1
g = \lambda n.n equals zero \rightarrow one [] (g(n minus one) plus g(n minus one)) minus one
COMPUTING LFP of g(n) = n equals zero -> one []
          (g(n minus one) plus g(n minus one)) minus one
g double(0) = 1 in 1 unfolds
g_double(1) = 1 in 3 unfolds
g_double(2) = 1 in 7 unfolds
g_double(3) = 1 in 15 unfolds
g_double(4) = 1 in 31 unfolds
g_double(5) = 1 in 63 unfolds
```

This is till 1000 unfolds. g\_double(9) gets 1 in 1023 unfolds

g\_double(6) = 1 in 127 unfolds
g\_double(7) = 1 in 255 unfolds
g\_double(8) = 1 in 511 unfolds
g\_double(9) = -1 in 1000 unfolds



## Unfolding of g (Double) by Simulation

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```
// Project: PoPL 2019. g_double_unfold.cpp, \perp shown as -1
// g(n) = n equals zero -> one [] (g(n minus one) plus g(n minus one)) minus one
#include <iostream>
using namespace std:
static unsigned int g_doubleCount = 0, maxUnfoldingLevel;
unsigned int g double(unsigned int x) { ++g doubleCount:
    if (g doubleCount == maxUnfoldingLevel) throw 1:
   if (x == 0) return 1:
    else try { return g_double(x - 1) + g_double(x - 1) - 1;} catch (int) { throw; }
int g_double_unfold(unsigned int maxUnfoldingLevel = 100, unsigned int maxParam = 10) {
    bool bottom = false: unsigned int result: ::maxUnfoldingLevel = maxUnfoldingLevel:
    cout << "COMPUTING LFP of g(n)":</pre>
    cout << " = n equals zero -> one [] (g(n minus one) plus g(n minus one)) minus one\n";
    for (unsigned int n = 0: n < maxParam: ++n) {
        try { bottom = false: g_doubleCount = 0: result = g_double(n): }
        catch (int) { bottom = true: }
        cout << "g double(" << n << ") = " << (int)((bottom) ? -1 : result)
             << " in " << g_doubleCount << " unfolds" << endl;</pre>
    cout << endl << endl:
   return 0;
```



## Recursive Functions Definitions: Simultaneous Definition

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Languages with Context Block Structured Applicative Consider the specifications  $f: Nat \rightarrow Nat_{\perp}$  and  $g: Nat \rightarrow Nat_{\perp}$ :

$$f = \lambda x.x$$
 equals zero  $\rightarrow$   $g(zero)$  []  $f(g(x minus one))$  plus two

$$g = \lambda y.y$$
 equals zero  $\rightarrow$  zero []  $y$  times  $f(y$  minus one)

Build a functional for function pairs as:

$$F: ((\mathit{Nat} \rightarrow \mathit{Nat}_\perp) \times (\mathit{Nat} \rightarrow \mathit{Nat}_\perp)) \rightarrow ((\mathit{Nat} \rightarrow \mathit{Nat}_\perp) \times (\mathit{Nat} \rightarrow \mathit{Nat}_\perp))$$

$$F = \lambda(f, g).(\lambda x.x \text{ equals zero} \rightarrow g(\text{zero}) [] f(g(x \text{ minus one})) plus two, \lambda y.y \text{ equals zero} \rightarrow \text{zero} [] y times f(y \text{ minus one}))$$

Find a pair of functions  $(\alpha, \beta)$  such that  $F(\alpha, \beta) = (\alpha, \beta)$ 



## Recursive Functions Definitions: Simultaneous Definition

```
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```

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Languages with Context Block Structured Applicative

```
Summary
```

```
Consider the specifications f: Nat \rightarrow Nat_{\perp} and g: Nat \rightarrow Nat_{\perp}: f = \lambda x.x equals zero \rightarrow g(zero) [] f(g(x minus one)) plus two g = \lambda y.y equals zero \rightarrow zero [] y times f(y minus one)
```

 $F = \lambda(f,g).(\lambda x.x \text{ equals zero} \rightarrow g(\text{zero}) \text{ [] } f(g(x \text{ minus one})) \text{ plus two}, \\ \lambda y.y \text{ equals zero} \rightarrow \text{zero} \text{ [] } y \text{ times } f(y \text{ minus one}))$ 

Using  $\perp$  for  $((\lambda n. \perp), (\lambda n. \perp))$ 

 $F^0(\perp) = (\{ \}, \{ \})$ 

```
F^{1}(\bot) = (\{\ \}, \{(zero, zero)\})

F^{2}(\bot) = (\{(zero, zero)\}, \{(zero, zero)\})
```

$$F^3(\perp) = (\{(zero, zero)\}, \{(zero, zero), (one, zero)\})$$

$$F^4(\perp) = (\{(\mathsf{zero}, \mathsf{zero}), (\mathsf{one}, \mathsf{two})\}, \{(\mathsf{zero}, \mathsf{zero}), (\mathsf{one}, \mathsf{zero})\})$$

$$F^5(\perp) = \{\{(zero, zero), (one, two)\}, \{(zero, zero), (one, zero), (two, four)\}\}$$

$$F^{6}(\bot) = (\{(\mathsf{zero}, \mathsf{zero}), (\mathsf{one}, \mathsf{two}), (\mathsf{two}, \mathsf{two})\}, \ \{(\mathsf{zero}, \mathsf{zero}), (\mathsf{one}, \mathsf{zero}), (\mathsf{two}, \mathsf{four})\})$$

$$F^{7}(\bot) = (\{(zero, zero), (one, two), (two, two)\}, \{(zero, zero), (one, zero), (two, four), (three, six)\})$$

$$\forall i, i > 7, F^i(\bot) = F^7(\bot)$$

$$f = fst(fix F), g = snd(fix F)$$
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# Unfolding of f & g (Simultaneous) by Simulation

```
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```

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Summary

```
// Project: PoPL 2019, f_g_unfold.cpp, ⊥ shown as −1
f = \lambda x.x equals zero \rightarrow g(zero) \prod f(g(x minus one)) plus two
g = \lambda v \cdot v equals zero \rightarrow zero \int v \text{ times } f(v \text{ minus one})
COMPUTING LFP of f g simul
f(x) = x \text{ equals zero->}g(zero) [] f(g(x minus one)) plus two
g(y) = y equals zero -> zero[] y times f(y minus one)
g(0) = 0 in 1 unfolds
g(1) = 0 in 3 unfolds
g(2) = 4 in 5 unfolds
g(3) = 6 in 7 unfolds
g(4) = -1 in 1001 unfolds
g(5) = -1 in 1001 unfolds
g(6) = -1 in 1001 unfolds
g(7) = -1 in 1001 unfolds
g(8) = -1 in 1001 unfolds
g(9) = -1 in 1001 unfolds
f(0) = 0 in 2 unfolds
f(1) = 2 in 4 unfolds
f(2) = 2 in 6 unfolds
f(3) = -1 in 1001 unfolds
f(4) = -1 in 1001 unfolds
f(5) = -1 in 1001 unfolds
f(6) = -1 in 1001 unfolds
f(7) = -1 in 1001 unfolds
f(8) = -1 \text{ in 1001 unfolds}
f(9) = -1 in 1001 unfolds
```



# Unfolding of f & g (Simultaneous) by Simulation

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Summary

```
// Project: PoPL 2019. f_g_unfold.cpp, \perp shown as -1
//f(x) = x \text{ equals zero } -> g(zero)[] f(g(x minus one)) plus two
//g(y) = y \text{ equals zero } -> zero[] y \text{ times } f(y \text{ minus one})
#include <iostream>
using namespace std:
static unsigned int fCount = 0, gCount = 0, maxUnfoldingLevel;
unsigned int g(unsigned int x);
//f(x) = x \text{ equals zero } -> g(zero)[] f(g(x \text{ minus one})) plus two
unsigned int f(unsigned int x) {
    ++fCount:
    if (fCount + gCount > maxUnfoldingLevel) throw 1:
    if (x == 0) \{ // \text{ return } g(0) :
        try { int t = g(0): return t: } catch (int) { throw: }
    else try { int t = g(x - 1); t = f(t); return t + 2; } catch (int) { throw; }
//g(y) = y \text{ equals zero } -> zero[] y \text{ times } f(y \text{ minus one})
unsigned int g(unsigned int x) { ++gCount;
    if (fCount + gCount > maxUnfoldingLevel) throw 2;
    if (x == 0) return 0;
    else try { int t = f(x - 1); return x * t; } catch (int) { throw; }
```



## Unfolding of f & g (Simultaneous) by Simulation

Unfolding Examples

```
return 0:
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```

```
// Project: PoPL 2019. f_g_unfold.cpp, \perp shown as -1
//f(x) = x \text{ equals zero } -> g(zero)[] f(g(x minus one)) plus two
//g(v) = v equals zero -> zero[] v times f(v minus one)
int f_g_unfold(unsigned int maxUnfoldingLevel = 100, unsigned int maxParam = 10) {
    bool bottom = false: unsigned int gResult. fResult: ::maxUnfoldingLevel = maxUnfoldingLevel:
    cout << "COMPUTING LFP of f_g_simul" << endl;</pre>
    cout << "f(x) = x equals zero->g(zero) [] f(g(x minus one)) plus two" << endl;
    cout << "g(y) = y equals zero -> zero[] y times f(y minus one)" << endl;</pre>
    for (unsigned int n = 0; n < maxParam; ++n) {
        try { bottom = false; fCount = gCount = 0; gResult = g(n); }
        catch (int) { bottom = true; }
        cout << "g(" << n << ") = " << (int)((bottom) ? -1 : gResult) << " in "
             << fCount + gCount << " unfolds" << endl:
    cout << endl:
    for (unsigned int n = 0: n < maxParam: ++n) {
        try { bottom = false: fCount = gCount = 0: fResult = f(n): }
        catch (int) { bottom = true; }
        cout << "f(" << n << ") = " << (int)((bottom) ? -1 : fResult) << " in "
             << fCount + gCount << " unfolds" << endl:
    cout << endl << endl:
                                                         Partha Pratim Das
```



#### Recursive Functions Definitions: Simultaneous Definition

Unfolding Examples

This is the solution given in the book. This is wrong.

```
Consider the specifications f: Nat \rightarrow Nat_{\perp} and g: Nat \rightarrow Nat_{\perp}:
f = \lambda x.x equals zero \rightarrow g(zero) [] f(g(x minus one)) plus two
g = \lambda v.v equals zero \rightarrow zero []v times f(v) minus one
F = \lambda(f, g).(\lambda x.x \text{ equals zero} \rightarrow g(\text{zero}) \mid f(g(x \text{ minus one})) \text{ plus two},
      \lambda y.y equals zero \rightarrow zero [] y times f(y \text{ minus one})
Using \perp for ((\lambda n, \perp), (\lambda n, \perp))
F^0(\perp) = (\{ \}, \{ \})
F^{1}(\bot) = (\{\}, \{(zero, zero)\})
F^{2}(\bot) = (\{(zero, zero)\}, \{(zero, zero)\})
F^3(\perp) = (\{(zero, zero), (one, two)\}, \{(zero, zero), (one, zero)\})
F^{4}(\bot) = \{\{(zero, zero), (one, two), (two, two)\}, \{(zero, zero), (one, zero), (two, four)\}\}
F^5(\perp) = (\{(zero, zero), (one, two), (two, two)\},\
             {(zero, zero), (one, zero), (two, four), (three, six)})
\forall i, i > 5, F^i(\bot) = F^5(\bot)
```



#### Recursive Functions Definitions: Simultaneous Definition

Unfolding Examples

• Any finite set of mutually recursive function definitions can be handled in this manner

• Thus, the least fixed point method is powerful enough to model the most general forms of computation, such as general recursive equation sets and flowcharts



#### Unfolding of odd-even by Simulation

```
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```

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Summary

```
// Project: PoPL 2019. odd_even_unfold.cpp. \perp shown as -1
oe = \lambda x.x equals zero \rightarrow one [] (x equals <math>one \rightarrow one [] (odd x \rightarrow oe(x plus one) [] oe(x div two)))
COMPUTING LFP of oe(x) =
x equals zero -> one [] (x equals one -> one [] (odd x -> oe(x plus one) [] oe(x div two)))
odd even(0) = 1 in 1 unfolds
odd even(1) = 1 in 1 unfolds
odd even(2) = 1 in 2 unfolds
odd even(3) = 1 in 4 unfolds
odd even(4) = 1 in 3 unfolds
odd even(5) = 1 in 6 unfolds
odd even(6) = 1 in 5 unfolds
odd_even(7) = 1 in 5 unfolds
odd_even(8) = 1 in 4 unfolds
odd even(9) = 1 in 8 unfolds
```

Hence,  $oe = \lambda x$ , one



#### Unfolding of odd-even by Simulation

Unfolding Examples

```
// Project: PoPL 2019. odd_even_unfold.cpp, \perp shown as -1
// oe(x) = x equals zero -> one [] (x equals one -> one [] (odd x -> oe(x plus one) [] oe(x div two)))
#include <iostream>
using namespace std;
static unsigned int odd_evenCount = 0, maxUnfoldingLevel;
unsigned int odd even(unsigned int x) { ++odd evenCount:
    if (odd_evenCount == maxUnfoldingLevel) throw 1;
    if (x == 0) return 1:
    else if (x == 1) return 1:
    else if (x \% 2) return odd even(x + 1):
    else return odd_even(x / 2);
int odd_even_unfold(unsigned int maxUnfoldingLevel = 100, unsigned int maxParam = 10) {
    bool bottom = false; unsigned int result; ::maxUnfoldingLevel = maxUnfoldingLevel;
    cout << "COMPUTING LFP of oe(x) = x equals zero -> one [] (x equals one -> one"
         << "[] (odd x -> oe(x plus one) [] oe(x div two)))" << endl:
    for (unsigned int n = 0; n < maxParam: ++n) {
        try { bottom = false: odd_evenCount = 0: result = odd_even(n): }
        catch (int) { bottom = true; }
        cout << "odd even(" << n << ") = " << (int)((bottom) ? -1 : result) << " in "
             << odd evenCount << " unfolds" << endl:
    cout << endl << endl:
   return 0:
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```



### Unfolding of odd-even (bottom) by Simulation

```
// Project: PoPL 2019. odd_even_bot_unfold.cpp. \perp shown as -1
               oe = \lambda x.x equals zero \rightarrow one [] (odd x \rightarrow oe(x plus one) <math>[] oe(x div two))
               COMPUTING LFP of oe(x) =
               x equals zero \rightarrow one [] (odd x \rightarrow oe(x plus one) [] oe(x div two))
               odd even bot(0) = 1 in 1 unfolds
               odd even bot(1) = -1 in 1000 unfolds
               odd even bot(2) = -1 in 1000 unfolds
               odd even bot(3) = -1 in 1000 unfolds
               odd even bot(4) = -1 in 1000 unfolds
               odd even bot(5) = -1 in 1000 unfolds
               odd even bot(6) = -1 in 1000 unfolds
               odd_even_bot(7) = -1 in 1000 unfolds
Unfolding Examples
               odd even bot(8) = -1 in 1000 unfolds
               odd even bot(9) = -1 in 1000 unfolds
               Hence, oe = \lambda x.x equals zero \rightarrow one [] \perp
```



#### Unfolding of odd-even (bottom) by Simulation

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```
// Project: PoPL 2019. odd_even_bot_unfold.cpp, \perp shown as -1
// oe(x) = x equals zero -> one [] (odd x -> oe(x plus one) [] oe(x div two))
#include <iostream>
using namespace std;
static unsigned int odd even botCount = 0. maxUnfoldingLevel:
unsigned int odd_even_bot(unsigned int x) {
    ++odd_even_botCount;
    if (odd even botCount == maxUnfoldingLevel) throw 1:
    if (x == 0) return 1:
    else if (x % 2) return odd_even_bot(x + 1); else return odd_even_bot(x / 2);
int odd_even_bot_unfold(unsigned int maxUnfoldingLevel = 100, unsigned int maxParam = 10) {
    bool bottom = false; unsigned int result; ::maxUnfoldingLevel = maxUnfoldingLevel;
    cout << "COMPUTING LFP of oe(x) = x equals zero -> one "
         << "[] (odd x -> oe(x plus one) [] oe(x div two))" << endl:
   for (unsigned int n = 0: n < maxParam: ++n) {
        try { bottom = false: odd even botCount = 0: result = odd even bot(n): }
        catch (int) { bottom = true: }
        cout << "odd even bot(" << n << ") = " << (int)((bottom) ? -1 : result) << " in "
             << odd even botCount << " unfolds" << endl:
    cout << endl << endl:
   return 0:
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                                                        Partha Pratim Das
```



#### Unfolding of Simple Simultaneous by Simulation

```
// Project: PoPL 2019. f_g_simple_unfold.cpp, \perp shown as -1
                 f = \lambda x.x equals zero \rightarrow g(zero) [] f(g(x)) plus two
                 g = \lambda v.v equals zero \rightarrow zero []v times f(v)
                 COMPUTING LFP of f g simple
                 f(x) = x \text{ equals zero->} g(zero)[] f(g(x)) plus two
                 g(y) = y \text{ equals zero } \rightarrow \text{zero } [] \text{ y times } f(y)
                 g s(0) = 0 in 1 unfolds
                 g_s(1) = -1 in 1001 unfolds
                 g_s(2) = -1 in 1001 unfolds
                 g s(3) = -1 in 1001 unfolds
                 g_s(4) = -1 in 1001 unfolds
                 g s(5) = -1 in 1001 unfolds
                 g_s(9) = -1 in 1001 unfolds
                 f s(0) = 0 in 2 unfolds
                 f_s(1) = -1 in 1001 unfolds
Unfolding Examples
                 f_s(2) = -1 in 1001 unfolds
                 f_s(3) = -1 in 1001 unfolds
                 f_s(4) = -1 in 1001 unfolds
                 f_s(5) = -1 in 1001 unfolds
                 f s(9) = -1 in 1001 unfolds
```



### Unfolding of Simple Simultaneous by Simulation

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```
// Project: PoPL 2019. f_g_simple_unfold.cpp, \perp shown as -1
//f(x) = x \text{ equals zero } \rightarrow g(zero) [] f(g(x)) plus two
//g(y) = y equals zero -> zero [] y times f(y)
#include <iostream>
using namespace std:
static unsigned int fCount = 0, gCount = 0, maxUnfoldingLevel;
unsigned int g_s(unsigned int x);
//f = x:x equals zero \rightarrow g(zero) [] f(g(x)) plus two
unsigned int f_s(unsigned int x) {
   ++fCount:
   if (fCount + gCount > maxUnfoldingLevel) throw 1:
    if (x == 0) \{ // \text{ return } g(0) :
        try { int t = g s(0): return t: } catch (int) { throw: }
    else try { int t = g_s(x); t = f_s(t); return t + 2; } catch (int) { throw; }
unsigned int g_s(unsigned int x) { ++gCount;
    if (fCount + gCount > maxUnfoldingLevel) throw 2;
   if (x == 0) return 0;
    else try { int t = f_s(x); return x * t; } catch (int) { throw; }
```



#### Unfolding of Simple Simultaneous by Simulation

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```
// Project: PoPL 2019. f_g_simple_unfold.cpp, \perp shown as -1
//f(x) = x \text{ equals zero } \rightarrow g(zero) [] f(g(x)) plus two
//g(y) = y equals zero -> zero [] y times f(y)
int f_g_simple_unfold(unsigned int maxUnfoldingLevel = 100, unsigned int maxParam = 10) {
    bool bottom = false; unsigned int gResult. fResult: ::maxUnfoldingLevel = maxUnfoldingLevel:
    cout << "COMPUTING LFP of f_g_simple" << endl;</pre>
    cout << "f(x) = x \text{ equals zero-} (zero)[] f(g(x)) plus two" << endl;
    cout << "g(y) = y equals zero -> zero [] y times f(y)" << endl;
    for (unsigned int n = 0; n < maxParam; ++n) {
        try { bottom = false; fCount = gCount = 0; gResult = g_s(n); } catch (int) { bottom = true; }
        cout << "g_s(" << n << ") = " << (int)((bottom) ? -1 : gResult) << " in "
             << fCount + gCount << " unfolds" << endl:
    cout << endl:
    for (unsigned int n = 0: n < maxParam: ++n) {
        try { bottom = false; fCount = gCount = 0; fResult = f_s(n); } catch (int) { bottom = true; }
        cout << "f s(" << n << ") = " << (int)((bottom) ? -1 : fResult) << " in "
             << fCount + gCount << " unfolds" << endl;
    cout << endl << endl;</pre>
    return 0;
```



Unfolding Examples

Specification of the semantics of while loop:

 $C[[\text{while } B \text{ do } C]] = \underline{\lambda} s.B[[B]]s \rightarrow C[[\text{while } B \text{ do } C]](C[[C]]s)[]s$ 

In terms of fix operations:

 $C[[\mathbf{while}\ B\ \mathbf{do}\ C]] = fix(\lambda f.\lambda s.\mathbf{B}[[B]]s \to f(\mathbf{C}[[C]]s)\ []\ s)$ 

The functional is  $Store_{\perp} \rightarrow Store_{\perp}$ , where  $Store = Id \rightarrow Nat$ 



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While Loop

Languages with Context Block Structured Applicative Summary • Let us unfold the loop  $\mathbf{C}[[\mathbf{while}\ A>0\ \mathbf{do}\ (A:=A-1;B:=B+1)]]$  and capture the transformation to the  $Store_{\perp}$  at every stage. The functional is:  $F=\lambda f.\underline{\lambda}s.test\ s\to f(adjust\ s)\ []\ s\ \text{where}\ test=\mathbf{B}[[A>0]]$  and  $adjust=\mathbf{C}[[A:=A-1;B:=B+1]]$ 

- To unfold the functional of the while loop, we need to compute on the store s
- Let us assume that initially the store is:  $s_0 = \lambda i.zero$  That is, all identifiers are initialized to 0
- Additionally, we may assume that before entry to the loop, the store may have been changed (for A, B, as well as other identifiers) to s<sub>loop\_start</sub>, where A and B may have any pair of Nat values that will impact the computation of F<sup>i</sup>
- Now only identifiers A and B are involved in the computation of F<sup>i</sup>. Hence, at some stage of the loop if A has value a and B has value b, the store is:
   s = λi.i equals A → a [] i equals B → b [] stoop start
- For the purpose of computation of  $F^i$ , we can represent this s as a pair (a, b) that actually stands for an infinite class of mappings for s as given by all possible mappings for  $s_{loop\_start}$
- We enumerate all such pairs (a, b) at every loop entry and loop exit during unfolding



 $\rightarrow_0$ 

 $\rightarrow$  1

 $\rightarrow 2$ 

 $\rightarrow$  3

Let us unfold the loop C[[while A > 0 do (A := A - 1; B := B + 1)]] and capture the transformation to the Store  $\bot$  at every stage. The functional is:  $F = \lambda f \cdot \lambda s \cdot test \ s \rightarrow f(adjust \ s) \ [] \ s$ , where test = B[[A > 0]] and  $adjust = \mathbf{C}[[A := A - 1; B := B + 1]]$ 

#### On loop Entry (A. B)

0,0	0,1	0,2	0,3	0,4
1,0	1,1	1,2	1,3	1,4
2,0	2,1	2,2	2,3	2,4
3,0	3,1	3,2	3,3	3,4
4,0	4,1	4,2	4,3	4,4
.,0	.,.	-,,	.,0	-,,.

Г	0,0	0,1	0,2	0,3	0,4
Г	1,0	1,1	1,2	1,3	1,4
Г	2,0	2,1	2,2	2,3	2,4
Г	3,0	3,1	3,2	3,3	3,4
	4,0	4,1	4,2	4,3	4,4

0,0	0,1	0,2	0,3	0,4	
1,0	1,1	1,2	1,3	1,4	
2,0	2,1	2,2	2,3	2,4	
3,0	3,1	3,2	3,3	3,4	
4,0	4,1	4,2	4,3	4,4	

0,0	0,1	0,2	0,3	0,4
1,0	1,1	1,2	1,3	1,4
2,0	2,1	2,2	2,3	2,4
3,0	3,1	3,2	3,3	3,4
4,0	4,1	4,2	4,3	4,4

#### On loop Exit (A. B)

(* 1, = )						
			Τ.			
				Τ.		
		1				

0,0	0,1	0,2	0,3	0,4
1	1	1	1	

0,0	0,1	0,2	0,3	0,4
0,1	0,2	0,3	0,4	0,5
			上	
上		上	上	

0,0	0,1	0,2	0,3	0,4
0,1	0,2	0,3	0,4	0,5
0,2	0,3	0,4	0,5	0,6



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```
Consider: C[[\text{while } A > 0 \text{ do } (A := A - 1; B := B + 1)]]
Let test = B[[A > 0]] and adjust = C[[A := A - 1; B := B + 1]]
```

```
The functional is: F = \lambda f \cdot \underline{\lambda} s \cdot test \ s \rightarrow f(adjust \ s) [] s
```

```
\begin{split} & \operatorname{graph}(F^0(\bot)) = \{\} \\ & \operatorname{graph}(F^1(\bot)) = \{ \\ & (\{([[A]], \operatorname{zero}), ([[B]], \operatorname{zero}), \cdots\}, \{([[A]], \operatorname{zero}), ([[B]], \operatorname{zero}), \cdots\}), \cdots, \\ & (\{([[A]], \operatorname{zero}), ([[B]], \operatorname{four}), \cdots\}, \{([[A]], \operatorname{zero}), ([[B]], \operatorname{four}), \cdots\}), \cdots \} \end{split}
```

Since the result is a member of  $Store_{\perp} \to Store_{\perp}$ ,  $graph(F^1(\perp))$  contains pairs of function graphs. Each pair shows a store prior to its  $loop\ entry$  and the store after  $loop\ exit$ . The members shown in the graph at this step are those stores whose [[A]] value equals zero. Thus, those stores that already map [[A]] to zero fail the test upon loop entry and exit immediately. The store is left unchanged. Those stores that require loop processing are mapped to  $\perp$ .

```
\begin{split} & \textit{graph}(F^2(\bot)) = \{ \\ & \{ ([[A]], \textit{zero}), ([[B]], \textit{zero}), \cdots \}, \{ ([[A]], \textit{zero}), ([[B]], \textit{zero}), \cdots \}, \\ & \{ ([[A]], \textit{zero}), ([[B]], \textit{four}), \cdots \}, \{ ([[A]], \textit{zero}), ([[B]], \textit{four}), \cdots \}, \\ & \{ ([[A]], \textit{one}), ([[B]], \textit{zero}), \cdots \}, \{ ([[A]], \textit{zero}), ([[B]], \textit{one}), \cdots \}, \\ & \{ ([[A]], \textit{one}), ([[B]], \textit{four}), \cdots \}, \{ ([[A]], \textit{zero}), ([[B]], \textit{five}), \cdots \}, \cdots \} \\ & Principles of Programming Languages \\ & Parthe Partim Das \\ \end{split}
```



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```
 \begin{split} & \textit{graph}(F^2(\bot)) = \{ \\ & (\{([[A]], \textit{zero}), ([[B]], \textit{zero}), \cdots\}, \{([[A]], \textit{zero}), ([[B]], \textit{zero}), \cdots\}), \cdots, \\ & (\{([[A]], \textit{zero}), ([[B]], \textit{four}), \cdots\}, \{([[A]], \textit{zero}), ([[B]], \textit{four}), \cdots\}), \cdots, \\ & (\{([[A]], \textit{one}), ([[B]], \textit{zero}), \cdots\}, \{([[A]], \textit{zero}), ([[B]], \textit{one}), \cdots\}), \cdots, \\ & (\{([[A]], \textit{one}), ([[B]], \textit{four}), \cdots\}, \{([[A]], \textit{zero}), ([[B]], \textit{five}), \cdots\}), \cdots \} \end{split}
```

Those input stores that require one or fewer iterations to process appear in the graph. For example, the fourth illustrated pair denotes a store that has [[A]] set to one and [[B]] set to four upon loop entry. Only one iteration is needed to reduce [[A]] down to zero, the condition for loop exit. In the process [[B]] is incremented to five:

```
\begin{split} & graph(F^3(\bot)) = \{ \\ & (\{([[A]], zero), (([[B]], zero), \cdots\}, \{(([[A]], zero), (([[B]], zero), \cdots\}), \cdots, \\ & (\{([[A]], zero), (([[B]], four), \cdots\}, \{(([[A]], zero), (([[B]], four), \cdots\}), \cdots, \\ & (\{([[A]], one), (([[B]], zero), \cdots\}, \{(([[A]], zero), (([[B]], five), \cdots\}), \cdots, \\ & (\{([[A]], two), (([[B]], zero), \cdots\}, \{(([[A]], zero), (([[B]], two), \cdots\}), \cdots, \\ & (\{([[A]], two), (([[B]], four), \cdots\}, \{(([[A]], zero), (([[B]], six), \cdots\}), \cdots\} \end{split}
```



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```
\begin{split} & graph(F^3(\bot)) = \{ \\ & (\{([[A]], zero), ([[B]], zero), \cdots\}, \{([[A]], zero), ([[B]], zero), \cdots\}), \cdots, \\ & (\{([[A]], zero), ([[B]], four), \cdots\}, \{([[A]], zero), ([[B]], four), \cdots\}), \cdots, \\ & (\{([[A]], one), ([[B]], zero), \cdots\}, \{([[A]], zero), ([[B]], one), \cdots\}), \cdots, \\ & (\{([[A]], two), ([[B]], zero), \cdots\}, \{([[A]], zero), ([[B]], two), \cdots\}), \cdots, \\ & (\{([[A]], two), ([[B]], four), \cdots\}, \{([[A]], zero), ([[B]], six), \cdots\}), \cdots \} \end{split}
```

All stores that require two iterations or less for processing are included in the graph. The  $graph(F^{i+1}(\bot))$  contains those pairs whose input stores finish processing in i iterations or less. The least fixed point of the functional contains mappings for those stores that conclude their loop processing in a finite number of iterations.



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The while-loop's semantics makes a good example for restating the important principle of least fixed point semantics:

The meaning of a recursive specification is totally determined by the meanings of its finite subfunctions. Each subfunction can be represented non-recursively in the function notation.

In this case:

The family of expressions makes apparent that iteration is an unwinding of a loop body; this corresponds to the operational view



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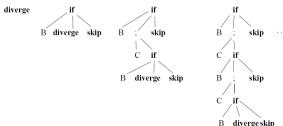
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Can we restate this idea even more directly? Recall that  $C[[diverge]] = \lambda s. \perp$ . Substituting the commands into the set just constructed gives us:

```
C[[while B do C]] = \sqcup {C[[diverge]],
C[[if B then diverge else skip]],
C[[if B then (C; if B then diverge else skip) else skip]],
C[[if B then (C; if B then (C; if B then diverge else skip) else skip) else skip]], \cdots}
```

A family of finite non-iterative programs represents the loop. It is easier to see what is happening by drawing the abstract syntax trees:



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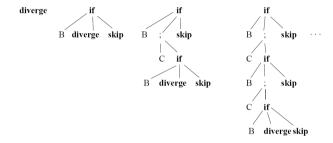
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At each stage, the finite tree becomes larger and better defined. The obvious thing to do is to place a partial ordering upon the trees: for all commands C, **diverge**  $\subseteq$  C, and for commands  $C_1$  and  $C_2$ ,  $C_1 \subseteq C_2$  iff  $C_1$  and  $C_2$  are the same command type (have the same root node) and all subtrees in  $C_1$  are less defined than the corresponding trees in  $C_2$ . This makes families of trees like the one above into chains. What is the lub of such a chain? It is the infinite tree corresponding to:

if B then (C; if B then (C; if B then (C;  $\cdots$ ) else skip) else skip) else skip



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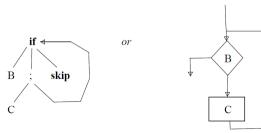
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Languages with Context Block Structured Applicative Draw this tree, and define L = if B then (C; L) else skip.

The while-loop example has led researchers to study languages that contain infinite programs that are represented by recursive definitions, such as *L*. The goal of such studies is to determine the semantics of recursive and iterative constructs by studying their circularity at the syntax level. The fundamental discovery of this research is that, whether the recursion is handled at the syntax level or at the semantics level, the result is the same:

$$C[[while B do C]] = C[[L]]$$

Finally, the infinite tree L is abbreviated:





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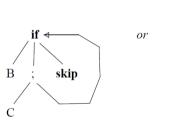
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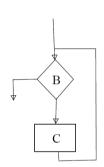
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Summary





Every flowchart loop can be read as an abbreviation for an infinite program. This brings us back to representations of functions again, for the use of finite loops to represent infinite flowcharts parallels the use of finite function expressions to denote infinite objects – functions. The central issue of computability theory might be stated as the search for finite representations of infinite objects.



## Languages with Context

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#### Language with Contexts

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• Languages rely on notions of context which influences the meanings of phrases - attributes meanings to identifiers

Programming language contexts can have different notions

#### Store as Context

Store establishes the context for a phrase – but it does suggest that the context within the block is constantly changing which is counter-intuitive. Surely the declarations of the identifiers X and Y establish the context of the block, and the commands within the block operate within that context.

#### begin

end

```
integer X; integer Y;
Y:=0; // X = bot, Y = 0
X:=Y; // X = 0, Y = 0
Y:=1; // X = 0, Y = 1
X:=Y+1 // X = 2, Y = 1
```

#### **Block as Context**

The meaning of an identifier is not just its storeable value. There are two definitions of X – outer (inner) is an integer (real) object. Any ambiguity in using X is handled by the scope rules. These are actually computer storage locations, and the primary meaning of an identifier is the location bound to it.



## Language with Contexts: Environment

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The context we choose to use is

- the set of identifier and storage location pairs (typically referred to as binding) that are
- accessible at a textual position

Each position in the program

- resides within a unique context, and
- the context can be determined without running the program



## Language with Contexts: Environment

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In denotational semantics, the context of a phrase is modeled by a value called an **environment**. Environments possess several distinctive properties:

- [1] An environment establishes a context for a syntactic phrase, resolving any ambiguities concerning the meaning of identifiers.
- [2] There are as many environment values as there are distinct contexts in a program. Multiple environments may be maintained during program evaluation.
- [3] An environment is (usually) a static object. A phrase uses the same environment each time it is evaluated with the store.



## Language with Contexts: Environment & Store

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- An environment argument was not needed for the languages so far, because the programs in the languages used exactly one environment
- The single *Environment* was *pasted onto* the *Store*, giving a map from *Identifiers* to *Storable Values*
- Now, that simple model is split apart into two separate components:
  - the Environment and
  - the *Store*)
- Identifiers map to Locations (in Environment) and Locations map to Storeable Values (in Store)



# Language with Contexts: Symbol Table

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- The primary real-life example of an environment is a compiler's symbol table used to translate a source program into compiled code
- The symbol table contains an entry for each identifier in the program, listing:
  - o the identifier's data type,
  - o its mode of usage (variable, constant, parameter, . . .), and
  - o its relative location in the run-time computer store
- Since a block-structured language allows multiple uses of the same identifier, the symbol table is responsible for resolving naming conflicts.



# Language with Contexts: Symbol Table

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- The schemes for implementation are many:
  - one is to keep a different symbol table for each block of the program (the portions in common between blocks may be shared);
  - another is to build the table as a single stack, which is incremented and decremented upon respective entry and exit for a block.
- Symbol tables may be
  - o compile-time objects, as in ALGOL68, standard Pascal, C, C++, or
  - o run-time objects, as in SNOBOL4, LISP or
  - o used in both phases, as in ALGOL60, Java, Python



# Language with Contexts: Static & Dynamic Semantics

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- Those portions of a semantics definition that use an environment to resolve context questions are sometimes called the Static Semantics
  - The term traditionally describes compile-time actions such as type-checking, scope resolution, and storage calculation
- Static semantics may be contrasted with the *real* production of meaning, which takes the name **Dynamic Semantics** 
  - Code generation and execution comprise the implementation-oriented version of dynamic semantics
- In general, the separation of static from dynamic semantics is rarely clear cut, and will be skipped here



### Language with Contexts: Commands

Languages with Context

Environments are used as arguments by the valuation functions. The meaning of a command is now determined by the function:

 $C: Command \rightarrow Environment \rightarrow Store \rightarrow Store$ 

instead of the earlier:

 $C: Command \rightarrow Store \rightarrow Store$ 

- The meaning of a command as a  $Store \rightarrow Store$  function is determined once an environment establishes the context for the command
- An environment belongs to the domain:

 $Environment = Identifier \rightarrow Denotable_value$ 

- The Denotable\_value domain contains all the values that identifiers may represent.
- This domain varies widely from language to language and its structure largely determines the character of the language



# Language with Contexts: Block-structured and Applicative languages

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- We study language features whose semantics are understood in terms of environments
- These features include:
  - declarations,
  - block structure,
  - scoping mechanisms,
  - o recursive bindings, and
  - compound data structures
- The concepts are covered within the framework of two languages:
  - o an imperative block-structured language and
  - o an applicative language



### Languages with Context: Block Structured Languages

Block Structured

**Languages with Context: Block Structured Languages** 



#### Block Structured Language: Abstract Syntax

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#### **Abstract Syntax:**

•  $P \in Program$ 

 $K \in Block$ 

 $D \in Declaration$ 

 $C \in Command$ 

 $E \in Expression$ 

 $B \in Boolean\_expr$ 

 $I \in Identifier$ 

 $N \in Numeral$ 

P ::= K.

K ::= begin D; C end

 $D ::= D_1$ ;  $D_2 \mid \mathbf{const} \mid I = N \mid \mathbf{var} \mid I$ 

 $C ::= C_1; \ C_2 \mid I := E \mid$  while  $B \$ do  $C \mid K$ 

 $E ::= E_1 + E_2 \mid I \mid N$ 

 $B ::= E_1 = E_2 \mid \neg B$ 



#### Block Structured Language: Semantic Algebras

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Summary

#### **Semantic Algebras:**

• Truth values

Domain:  $t \in Tr = B$ 

Operations:

true, false: Tr not: Tr o Tr

Natural Numbers

Domain:  $n \in Nat = \mathcal{N}$ 

Operations:

zero, one, ...: Nat

 $plus : Nat \times Nat \rightarrow Nat$  $equals : Nat \times Nat \rightarrow Tr$ 

• Identifiers

Domain:  $i \in Id = Identifier$ 



### Block Structured Language: Semantic Algebras

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• Expressible value

Domain:  $x \in Expressible\_value = Nat + Errvalue$ where  $Expressible\_value = Unit$ 

- Expressible value errors occur when an expressible value is inappropriately used
- For example, a truth value is added to a natural number expression



#### Block Structured Language: Semantic Algebras

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Storage Location

Domain:  $I \in Location$ 

Operations:

first\_locn : Location

 $next\_locn : Location \rightarrow Location$ 

equal\_locn : Location  $\rightarrow$  Location  $\rightarrow$  Tr lessthan\_locn : Location  $\rightarrow$  Tr

- o first\_locn is a constant, marking the first usable location in a store
- next\_locn maps a location to its immediate successor in a store
- o equal\_locn checks for equality of two values, and
- lessthan\_locn compares two locations and returns a truth value based on the locations' relative values



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Denotable values

Domain:  $d \in Denotable\_value = Location + Nat + Errvalue$ where Errvalue = Unit

- Of the three components of the *Denotable\_value* domain:
  - ▶ Location holds the denotations of variable identifiers,
  - ▶ Nat holds the meanings of constant identifiers, and
  - ▶ Errvalue holds the meaning for undeclared identifiers
- Since the Denotable\_value domain contains both natural numbers and locations, denotable value errors may occur in a program; for example, an identifier with a number denotation might be used where an identifier with a location denotation is required
- o An identifier with an erroneous denotable value always induces an error



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Languages with Context Block Structured Applicative  Environment: a map to denotable values and the maximum store location Domain: e ∈ Environment = (Id → Denotable\_value) × Location Operations:

```
emptyenv : Location \rightarrow Environment emptyenv = \lambda l.((\lambda l.inErrvalue()), l) accessenv : ld \rightarrow Environment \rightarrow Denotable_value accessenv = \lambda i.\lambda(map, l).map(i) updateenv : ld \rightarrow Denotable_value \rightarrow Environment \rightarrow Environment updateenv = \lambda i.\lambda d.\lambda(map, l).([i \mapsto d]map, l) reserve_locn : Environment \rightarrow (Location \times Environment) reserve_locn = \lambda(map, l).(l, (map, next_locn(l)))
```



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- An environment is a pair
  - The first component is the function that maps identifiers to their denotable values
  - The second component is a location value, which marks the extent of the store reserved for declared variables
- The environment takes the responsibility for assigning locations to variables. This is done by the *reserve\_locn* operation, which returns the next usable location
- Although it is not made clear by the algebra, the structure of the language will cause the locations to be used in a stack-like fashion
- The *emptyenv* must be given the location marking the beginning of usable space in the store so that it can build the initial environment



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Storable values

Domain:  $v \in Storable\_value = Nat$ 

Store

Domain:  $s \in Store = Location \rightarrow Storable\_value$ 

Operations:

 $access: Location \rightarrow Store \rightarrow Storable\_value$ 

 $access = \lambda(I, s).s(I)$ 

 $update: Location \rightarrow Storable\_value \rightarrow Store \rightarrow Store$ 

 $update = \lambda(I, v, s).[I \mapsto v]s$ 

- The store is a map from storage locations to storable values, and the operations are the obvious ones
- Errors during evaluation are possible, so the store will be labeled with the status of the evaluation
- The check operation uses the tags to determine if evaluation should continue



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```
• Run-time store, labeled with status of computation
   Domain: p \in Poststore = OK + Err
   where OK = Frr = Store
   Operations:
   return : Store \rightarrow Poststore
     return = \lambda s.inOK(s)
   signalerr: Store \rightarrow Poststore
     signalerr = \lambda s.inErr(s)
   check: (Store \rightarrow Poststore_{\perp}) \rightarrow
             (Poststore_{\perp} \rightarrow Poststore_{\perp})
      check f = \lambda p. cases p of
         isOK(s) \rightarrow (f \ s) \ [] \ isErr(s) \rightarrow p \ end
```



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#### **Valuation Functions:**

• **P**: Program $\rightarrow$  Location  $\rightarrow$  Store  $\rightarrow$  Poststore $_{\perp}$ 

$$P[[K.]] = \lambda I.K[[K]]$$
 (emptyenv I)

- The **P** valuation function requires a store and a location value, the latter marking the beginning of the store's free space
- **K**: Block $\rightarrow$  *Environment*  $\rightarrow$  *Store*  $\rightarrow$  *Poststore* $_{\perp}$

$$K[[\mathbf{begin}\ D; C\ \mathbf{end}]] = \lambda e.\mathbf{C}[[C]](\mathbf{D}[[D]]e)$$

• The **K** function establishes the context for a block



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#### **Valuation Functions:**

• **D**: Declaration→ *Environment* → *Environment* 

$$\mathbf{D}[[D_1;D_2]] = \mathbf{D}[[D_2]] \circ \mathbf{D}[[D_1]]$$

- The D function augments an environment
- The composition of declarations parallels the composition of commands

$$\mathbf{D}[\mathbf{const}\ I = N]] = updateenv\ [[I]]\ inNat(\mathbf{N}[[N]])\ e$$

 A constant identifier declaration causes an environment update, where the identifier is mapped to its numeral value in the environment



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#### **Valuation Functions:**

• **D**: Declaration → *Environment* → *Environment* 

$$\begin{aligned} \mathbf{D}[\mathbf{var} \ I]] &= \lambda e.let(I', e') = \\ & (\mathit{reserve\_locn} \ e) \ \mathit{in} \ (\mathit{updateenv} \ [[I]] \ \mathit{inLocation}(I') \ e') \end{aligned}$$

- The denotation of a variable declaration is more involved: a new location is reserved for the variable
- This location, I', plus the current environment, e', are used to create the environment in which the variable [[I]] binds to inLocation(I')
- What happens on duplicate declaration of the same identifier in the same block?



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#### **Valuation Functions:**

• **C**: Command  $\rightarrow$  *Environment*  $\rightarrow$  *Store*  $\rightarrow$  *Poststore*<sub> $\perp$ </sub>

$$\mathbf{C}[[C_1; C_2]] = \lambda e.(check(\mathbf{C}[[C_2]]e)) \circ (\mathbf{C}[[C_1]]e)$$

- O First, consider the *check* operation. If command  $C[[C_1]]$  e maps a store into an erroneous *Poststore*, then *check* traps the error and prevents  $C[[C_2]]$  e from altering the store
- O Note that the commands  $[[C_1]]$  and  $[[C_2]]$  are both evaluated in the context represented by e. This is important, for  $[[C_1]]$  could be a block with local declarations that would need its own local environment to process its commands while  $\mathbf{C}[[C_2]]$  retains its own copy of e. (Of course, whatever alterations  $\mathbf{C}[[C_1]]e$  makes upon the store are passed to  $\mathbf{C}[[C_2]]e$ .)
- O This language feature is called **static scoping**. The context for a phrase in a statically scoped language is determined solely by the textual position of the phrase and any identifier declared within a block may be referenced only by the commands within that block
- O **Dynamically scoped** languages, whose contexts are not totally determined by textual position, will be discussed later.



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#### **Valuation Functions:**

• **C**: Command  $\rightarrow$  *Environment*  $\rightarrow$  *Store*  $\rightarrow$  *Poststore* $_{\perp}$ 

```
 \begin{aligned} \mathbf{C}[[I := E]] &= \lambda e. \lambda s. cases \; (accessenv \; [[I]] \; e) \; of \\ & is Location(I) \rightarrow (cases(\mathbf{E}[[E]] e \; s) \; of \\ & is Nat(n) \rightarrow (return(update \; I \; n \; s)) \\ & [] \; is Err Value() \rightarrow (signalerr \; s) \; end) \\ & [] \; is Nat(n) \rightarrow (signalerr \; s) \\ & [] \; is Err Value() \rightarrow (signalerr \; s) \; end \end{aligned}
```

Note that, if identifier I has not been declared in this environment, then accessenv
will return a Errvalue as the Denotational\_value. On this, a signalerr is rightly done
putting the store s as Err



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#### **Valuation Functions:**

• **C**: Command  $\rightarrow$  *Environment*  $\rightarrow$  *Store*  $\rightarrow$  *Poststore* $_{\perp}$ 

**C**[[while 
$$B$$
 do  $C$ ]] =  $\lambda e.fix(\lambda f.\lambda s. cases (B[[B]]e s) of is Tr(t)  $\rightarrow$  ( $t \rightarrow$  (check  $f$ )  $\circ$  (C[[C]]e) [] return)(s) [] is ErrValue( $I$ )  $\rightarrow$  (signaler  $f$ ) end)$ 

$$\mathbf{C}[[K]] = \mathbf{K}[[K]]$$



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#### **Valuation Functions:**

• **E**: Expression→ Environment → Store → Expressible\_value

$$\begin{aligned} \mathbf{E}[[E_1 + E_2]] &= \lambda e.\lambda s. cases \ (\mathbf{E}[[E_1]]e \ s) \ of \\ &[] \ isNat(n_1) \rightarrow (cases \ (\mathbf{E}[[E_2]]e \ s) \ of \\ &isNat(n_2) \rightarrow inNat(n_1 \ plus \ n_2) \\ &[] \ isErrvalue() \rightarrow inErrvalue() \ end \end{aligned}$$

$$\begin{aligned} \mathbf{E}[[I]] &= \lambda e. \lambda s. cases \; (accessenv \; [[I]] \; e) \; of \\ & is Location(I) \rightarrow in Nat(access \; I \; s) \\ & [] \; is Nat(n) \rightarrow in Nat(n) \\ & [] \; is Err Value() \rightarrow in Err value() \; end \end{aligned}$$

$$\mathbf{E}[[N]] = \lambda e.\lambda s.inNat(\mathbf{N}[[N]])$$



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#### **Valuation Functions:**

• **B** :  $Boolean\_expr \rightarrow Environment \rightarrow Store \rightarrow (Tr + Errvalue)$ 

$$\begin{aligned} \mathbf{B}[[E_1 = E_2]] &= \lambda e. \lambda s. cases \ (\mathbf{E}[[E_1]]e \ s) \ of \\ &[] \ isNat(n_1) \rightarrow (cases \ (\mathbf{E}[[E_2]]e \ s) \ of \\ &isNat(n_2) \rightarrow inTr(n_1 \ equals \ n_2) \\ &[] \ isErrvalue() \rightarrow inErrvalue() \ end) \\ &[] \ isErrvalue() \rightarrow inErrvalue() \ end \end{aligned}$$

$$\mathbf{B}[[\neg B]] = \lambda e.\lambda s.cases \ (\mathbf{B}[[B]]e \ s) \ of \ [] \ is Tr(t) \rightarrow in Tr(not \ t) \ [] \ is Errvalue() \rightarrow in Errvalue() \ end$$

• **N** : Numeral  $\rightarrow$  Nat (omitted)



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Perform the valuation for:  $P[[begin D_0; D_1; C_0 end]]$  where

```
\begin{array}{rclcrcl} D_0 & = & {\rm const} \ A = 1 \\ D_1 & = & {\rm var} \ X \\ C_0 & = & C1; \ C2; \ C3 \\ C_1 & = & X := A + 2 \\ C_2 & = & {\rm begin} \ {\rm var} \ A; \ C4 \ {\rm end} \\ C_3 & = & X := A \\ C_4 & = & {\rm while} \ X = 0 \ {\rm do} \ A := X \end{array}
```

```
begin
   const A = 1;
   var X;
   X := A + 2;
   begin
      var A;
      while X = 0 do A := X
   end
   X := A
end
```



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```
P[[begin D_0: D_1: C_0 end]] =
\lambda I.K[[\mathbf{begin}\ D_0;\ D_1;\ C_0\ \mathbf{end}]](emptyenv\ I) =
    where e_0 = emptvenv I
\mathbf{C}[[C_0]](\mathbf{D}[[D_0; D_1]]e_0) =
 D[[D_0: D_1]]e_0 = D[[D_1]](D[[const A = 1]]e_0)
   D[[D_0]] = D[[const A = 1]]e_0 = (updateenv [[A]] inNat(one) e_0) = e_1
      where e_1 = [A \mapsto inNat(one)]
   \mathbf{D}[[D_1]] = \mathbf{D}[[\mathsf{var}\ X]]e_1 = (\mathit{updateenv}\ [[X]]\ \mathit{inLocation}(I)\ e_2) = e_3
      where let(l', e') = (reserve\_locn e_1) in e_2 = (l, (map, (next\_locn l)))
           e_2 = [I.inErrvalue(), A \mapsto inNat(one)],
            e_3 = [X \mapsto inLocation(I), A \mapsto inNat(one)]
```



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```
(check(C[[C_2: C_3]]e_3)) \circ (C[[C_1]]e_3) =
(check(C[[C_2; C_3]]e_3)) \circ (C[[X := A + 2]]e_3) =
 C[[X := A + 2]] = \lambda s. cases (accessenv [[X]] e_3) of isLocation(I) <math>\rightarrow
       (cases(\mathbf{E}[[A+2]]e_3 s) \text{ of } isNat(n) \rightarrow (return(update | l n s)) \dots end) \dots end =
       inOK([I \mapsto three]s), where e_3 = [X \mapsto inLocation(I), A \mapsto inNat(one)]
   E[[A+2]]e_3 = \lambda s. cases (E[[A]]e_3 s) of [] isNat(n_1) \rightarrow (cases) (E[[2]]e_3 s) of
       isNat(n_2) \rightarrow inNat(n_1 \ plus \ n_2) \dots end) \dots end =
       inNat(one plus two) = inNat(three)
     E[[A]]e_3 = \lambda s.cases (accessenv [[A]]e_3) of isLocation(I) \rightarrow
       inNat(access \ l \ s) \ ] isNat(n) \rightarrow inNat(n) ...end = inNat(one)
     E[[2]]e_3 = inNat(N[[2]]) = inNat(two)
```



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```
(check(\mathbf{C}[[C_2: C_3]]e_3)) =
(check(\mathbf{C}[[C_3]]e_3)) \circ (\mathbf{C}[[\mathbf{while}\ X = 0\ \mathbf{do}\ A := X]]e_3) =
 C[[while X = 0 do A := X]]e_3) = C[[C_4]](D[[var A]]e_3) =
 C[[while X = 0 do A := X]]e_5 =
    fix(\lambda f. \lambda s. cases (B[[X = 0]]e_5 s) of ...end
     ((access I s) equals zero \rightarrow (check f) \circ (\mathbb{C}[[A := X]]e_5) [] return) s
     \lambda s, return(update(next locn I) (access I s) s)
     B[[X = 0]]e_5 s = inTr((access | s) equals zero) = false
   D[[var A]]e_3 = (updateenv [[A]] inLocation(I) e_4) = e_5
      where let(I', e') = (reserve\_locn e_3) in e_4 = (I, (map, (next\_locn I)))
           e_4 = [X \mapsto inLocation(I), A \mapsto inNat(one), l_{inner}.inErrvalue()],
           e_5 = [X \mapsto inLocation(I), A \mapsto inNat(one), A_{inner} \mapsto inLocation(I_{inner})]
 C[[C_3]]e_3 = C[[X := A]]e_3
   \lambda s. \ return(update \ l \ one \ s) = inOK([l \mapsto one]s)
```



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Summary

Code blocks annotated with environment and store

```
begin
// e0 (empty), s0 (empty)
    const. A = 1:
    // e1 (A -> one). s0 (empty)
    var X:
    // e2, e3 (A -> one, X -> loc(X)). s0 (empty)
    X := A + 2:
    // e3 (A -> one, X -> loc(X)). s1 (loc(X) -> three)
    begin
    // e3 (A -> one, X -> loc(X)), s1 (loc(X) -> three)
        var A:
       // e4. e5 (A -> one, X -> loc(X), Ain -> loc(Ain)), s1 (loc(X) -> three)
        while Y = 0 do A := Y
       // e5 (A -> one, X -> loc(X), Ain -> loc(Ain)), s1 (loc(X) -> three)
    end
    // e3 (A -> one, X -> loc(X)), s1 (loc(X) -> three)
    X := A
    // e3 (A -> one, X -> loc(X)), s2 (loc(X) -> one)
end
// e0 (empty), s0 (empty)
```



# Block Structured Language: Stack-Managed Storage

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- The store of a **block-structured language** is used in a **stack-like fashion**:
  - o Locations are bound to identifiers sequentially using next\_locn, and
  - A location bound to an identifier in a local block is freed for re-use when the block is exited
  - $\circ~$  The re-use of locations happens automatically due to the equation for  $\boldsymbol{C}[[\mathit{C}_1;~\mathit{C}_2]]$
  - o Any locations bound to identifiers in  $[[C_1]]$  are reserved by the environment built from e for  $\mathbf{C}[[C_1]]$ , but  $\mathbf{C}[[C_2]]$  re-uses the original e (and its original location marker), effectively deallocating the locations.



# Block Structured Language: Stack-Managed Storage

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- Stack-based storage is a significant characteristic of block-structured programming languages, and
- The Store Algebra deserves to possess mechanisms for stack-based allocation and deallocation
- Next we start to move the storage calculation mechanism over to the store algebra



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• Stack-based store Domain:  $s \in Store = (Location \rightarrow Storable\_value) \times Location$ 

The new store domain uses the

 $Location \rightarrow Storable\_value$ 

component as the data space of the stack, and

- the Location component indicates the amount of storage in use: it is the
  - stack top marker



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Domain:  $s \in Store = (Location \rightarrow Storable\_value) \times Location$ Operations:

```
access: Location \rightarrow Store \rightarrow (Storable\_value + Errvalue)
access = \lambda(I, s). \ s(I)
```

```
update : Location \rightarrow Storable\_value \rightarrow Store \rightarrow Poststore

update = \lambda I. \ \lambda v. \ \lambda (map, top). \ I \ less than\_locn \ top \rightarrow

inOK([I \mapsto v]map, top) \ [] \ inErr(map, tops)
```

 Operations access and update verify that any reference to a storage location is a valid one, occurring at an active location beneath the stack top

Stack-based store



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Languages with Context Block Structured Applicative • Stack-based store Domain:  $s \in Store = (Location \rightarrow Storable\_value) \times Location$  Operations:

```
mark\_locn: Store \rightarrow Location \\ mark\_locn = \lambda(map, top).top \\ allocate\_locn: Store \rightarrow Location \times Poststore \\ allocate\_locn = \\ \lambda(map, top).(top, inOK(map, next\_locn(top)))
```

 The purposes of mark\_locn and allocate\_locn should be clear; the latter is the run-time version of the environment's reserve\_locn operation



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Applicative  Stack-based store Operations:

```
deallocate\_locns : Location \rightarrow Store \rightarrow Poststore \ deallocate\_locns = \lambda l.\lambda(map, top). \ (l \ less than\_locn \ top) \ or \ (l \ equal\_locn \ top) \rightarrow \ inOK(map, l) \ [] \ inErr(map, top)
```

- o The  $deallocate\_locns$  operation releases stack storage from the stack top to the value indicated by its argument. Freed from storage management, the environment domain takes the form  $Environment = Id \rightarrow Denotable\_value$
- o The operations are adjusted accordingly, and the operation reserve\_locn is dropped
- If the environment leaves the task of storage calculation to the store operations, then processing of declarations requires the store as well as the environment



# Block Structured Language: Stack-Managed Storage: Valuation Functions

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The functionality of the valuation function for declarations becomes:

• **D**: Declaration  $\rightarrow$  Environment  $\rightarrow$  Store  $\rightarrow$  (Environment  $\times$  Poststore)

$$\begin{aligned} \mathbf{D}[\mathbf{var}\ I]] &= \lambda e.\lambda s.let(I,p) = (allocate\_locns) \\ ∈\ ((updateenv\ [[I]]\ inLocation(I)\ e),\ p) \end{aligned}$$

$$\mathbf{D}[[D_1; D_2]] == \lambda e.\lambda s.let(e', p) = (\mathbf{D}[[D_1]]e \ s) \ in \ (check \ \mathbf{D}[[D_2]]e')(p)$$

$$\begin{array}{l} \textit{check}: \; (\textit{Store} \rightarrow (\textit{Environment} \times \textit{Poststore})) \rightarrow \\ (\textit{Poststore} \rightarrow (\textit{Environment} \times \textit{Poststore})) \end{array}$$

Earlier it was:

**D**: Declaration→ Environment → Environment

$$\begin{aligned} \mathbf{D}[\mathbf{var} \ I]] &= \lambda e.let(I', e') = \\ & (\textit{reserve\_locn} \ e) \ \textit{in} \ (\textit{updateenv} \ [[I]] \ \textit{inLocation}(I') \ e') \end{aligned}$$

- This version of declaration processing makes the environment into a run-time object, for the binding of location values to identifiers cannot be completed without the run-time store
- Contrast this with the arrangement in the last model, where location binding is computed by the environment operation reserve\_locn, which produced a result relative
  to an arbitrary base address
- A solution for freeing the environment from dependence upon allocate. Jocn is to provide it information about storage management strategies, so that the necessary address calculations can be performed independently of the value of the run-time store



# Block Structured Language: Stack-Managed Storage: Valuation Functions

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• **K**: Block $\rightarrow$  Environment  $\rightarrow$  Store  $\rightarrow$  Poststore $_{\perp}$ 

The K function manages the storage for the block:

```
 \begin{split} & \textbf{K}[[\textbf{begin } D; C \ \textbf{end}]] = \lambda e. \ \lambda s. \ \textit{let } l = \textit{mark\_locn } s \ \textit{in} \\ & \textit{let } (e', p) = \textbf{D}[[D]]e \ s \ \textit{in} \\ & \textit{let } p' = (\textit{check}(\textbf{c}[[C]]e'))(p) \ \textit{in } (\textit{check}(\textit{deallocate\_locns } l))(p') \end{split}
```

Earlier, it was:

 $\textbf{K} \colon \mathsf{Block} \!\! \to \mathit{Environment} \, \to \mathit{Store} \, \to \mathit{Poststore}_{\bot}$ 

```
\mathsf{K}[[\mathsf{begin}\ D; C\ \mathsf{end}]] = \lambda e. \mathsf{C}[[C]](\mathsf{D}[[D]]e)
```

 The deallocate\_locns operation frees storage down to the level held by the store prior to block entry, which is (mark\_locn s)



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• The notion of context can be even more subtle than we first imagined. Consider the Pascal assignment statement

$$X := X+1$$

- The meaning of X on the right-hand side of the assignment is decidedly different from X's meaning on the left-hand side. Specifically,
  - o the left-hand side value is a location value, while
  - o the right-hand side value is the storable value associated with that location.
  - Apparently the context problem for identifiers is found even at the primitive command level



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- One way out of this problem would be to introduce two environment arguments for the semantic function for commands:
  - o a left-hand side one and
  - o a right-hand side one

This arrangement is hardly natural; commands are the *sentences* of a program, and sentences normally operate in a *single context* 



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- Another option is to say that any variable identifier actually denotes a pair of values:
  - o a location value, or,
    - □ identifier's L-value which is kept in the
    - ▷ environment and
  - o a storable value, or,

    - > store



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We introduce a valuation function

$$\textbf{I}: \textit{Id} \rightarrow \textit{Environment} \rightarrow \textit{Store} \rightarrow (\textit{Location} \times \textit{Storable\_value})$$

. In practice, the  ${\bf I}$  function is split into two semantic functions

$$L: Id \rightarrow Environment \rightarrow Location$$

and

$$\textbf{R}: \textit{Id} \rightarrow \textit{Environment} \rightarrow \textit{Store} \rightarrow \textit{Storable\_value}$$

such that:

- $\circ$  L[[I]] = accessenv [[I]]
- $\circ$  R[[I]] = access  $\circ$  accessenv [[I]]
- We restate the semantic equations using variables as:

$$C[[I := E]] = \lambda e. \ \lambda s. \ return(update(L[[I]]e)(E[[E]]e \ s) \ s)$$
  
 $E[[I]] = R[[I]]$ 



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- The definitions are a bit simplistic because they assume that all identifiers are variables.
  - Constant identifiers can be integrated into the scheme
  - $\circ$  a declaration such as [[const A = N]] suggests L[[A]]e = inErrvalue()
  - O What should  $(R[[A]]e^{-s})$  be?
- Yet another view to take is that the R-value of a variable identifier is a function of its Lvalue
- The *true meaning* of a variable is its *Lvalue*, and a *coercion* occurs when a variable is used on the right-hand side of an assignment
- This coercion is called dereferencing



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We formalize this view as:

```
 \begin{split} \mathbf{J} : Id &\rightarrow Environment \rightarrow Denotable\_value \\ \mathbf{J}[[I]] &= \lambda e. \; (accessenv \; [[I]] \; e) \\ \mathbf{C}[[I := E]] &= \lambda e. \; \lambda s. \; return(update(\mathbf{J}[[I]]e)(\mathbf{E}[[E]]e \; s) \; s) \\ \mathbf{E}[[I]] &= \lambda e. \; \lambda s. \; dereference(\mathbf{J}[[I]]e) \; s \end{split}
```

where

```
dereference: Location \rightarrow Store \rightarrow Storable\_value
dereference = access
```



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• An identifier's meaning is just its denotable value

• Those identifiers with locations as their meanings (the variables) are dereferenced when an expressible value is needed.

 The implicit use of dereferencing is so common in general purpose programming languages that we take it for granted, despite the somewhat unorthodox appearance of commands such as

$$X = X + 1$$

in FORTRAN



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• Systems-oriented programming languages such as BCPL, Bliss, and C use an explicit dereferencing operator

 For example, in BCPL expressible values include locations, and the appropriate semantic equations are:

$$\mathbf{E}[[I]] = \lambda e. \ \lambda s. \ inLocation(\mathbf{J}[[I]]e)$$
  
 $\mathbf{E}[[@E]] = \lambda e. \ \lambda s. \ cases \ (\mathbf{E}[[E]]e \ s) \ of$   
 $isLocation(I) \rightarrow (dereference \ I \ s)$   
 $[]...end$ 

- The @ symbol is the dereferencing operator
- o The meaning of

$$X := X + 1$$

in BCPL is decidedly different from that of

$$X := @X+1$$



# Languages with Context: Applicative Languages

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Summar

#### **Languages with Context: Applicative Languages**



# Applicative Language

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- An applicative language contains no variables
- All identifiers are constants and can be given attributes but once, at their point of definition
- Without variables, mechanisms such as assignment are superfluous and are dropped
- Arithmetic is an applicative language
- Another example is the minimal subset of LISP known as pure LISP
- The function notation that we use to define denotational definitions can also be termed an applicative language
- Since an applicative language has no variables, its semantics can be specified without a Store domain
- The environment holds the attributes associated with the identifiers



# Applicative Language

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- It is similar to pure LISP a list processing language
- A program in the language is just an expression
- An expression can be
  - a LET definition;
  - o a LAMBDA form;
    - ▷ representing a function routine with parameter I
  - a function application;
  - a list expression using CONS, HEAD, TAIL, or NIL;
  - an identifier; or
  - o an atomic symbol



## Applicative Language: Abstract Syntax

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#### **Abstract Syntax:**

E ∈ Expression
 A ∈ Atomic\_symbol
 I ∈ Identifier

```
E ::= LET \mid I = E_1 \mid IN \mid E_2 \mid
LAMBDA \mid I \mid E \mid
E_1 \mid E_2 \mid
E_1 \mid CONS \mid E_2 \mid HEAD \mid E \mid TAIL \mid E \mid NIL \mid
\mid I \mid
A \mid (E)
```

**Note**: (let  $x = e_1$  in  $e_2$ ) for  $(\lambda x. e_2)e_1$ 



## Applicative Language: Semantic Algebras

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### Semantic Algebras:

• Atomic answer values

Domain:  $a \in Atom$ 

Operations: (Omitted)

o Atom is a primitive answer domain and its internal structure will not be considered

Identifiers

Domain:  $i \in Id = Identifier$ 

Operations: (Usual)



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#### Semantic Algebras:

• Denotable values, functions, and lists

Domain:  $d \in Denotable\_value = (Function + List + Atom + Error)_{\perp}$   $f \in Function = Denotable\_value \rightarrow Denotable\_value$   $t \in List = Denotable\_value^*$ 

Error = Unit

- The language also contains a domain of functions, which map denotable values to denotable values; a denotable value can be a function, a list, or an atom
- For the first time, we encounter a semantic domain defined in terms of itself. By substitution, we see that:

```
Denotable\_value = ((Denotable\_value 	o Denotable\_value) + Denotable\_value^* + Atom + Error)_{\perp}
```



### Applicative Language: Semantic Algebras

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#### Semantic Algebras:

• Expressible value

Domain:  $x \in Expressible\_value = Denotable\_value$ 

Environment

Domain:  $e \in Environment = Id \rightarrow Denotable\_value$ 

Operations:

 $accessenv: Id \rightarrow Environment \rightarrow Denotable\_value$ 

 $accessenv = \lambda i.\lambda e. \ e(i)$ 

 $updateenv: Id \rightarrow Denotable\_value \rightarrow$ 

 $Environment \rightarrow Environment$ 

 $updateenv = \lambda i.\lambda d.\lambda e. \ [i \mapsto d]e$ 



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Summary

#### Valuation Functions:

E: Expression→ Environment → Expressible\_value

$$\mathbf{E}[[LET \ I = E_1 \ IN \ E_2]] = \lambda e. \ \mathbf{E}[[E_2]](updateenv \ [[I]] \ (\mathbf{E}[[E_1]]e) \ e)$$

**Note**: (let  $x = e_1$  in  $e_2$ ) for  $(\lambda x. e_2)e_1$ 

- O E determines the meaning of an expression, a denotable value, with the aid of an environment
- O An atom, list, or even a function can be a legal answer
- O The LET expression provides a definition mechanism for augmenting the environment
- Static scoping is used



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#### Valuation Functions:

E: Expression→ Environment → Expressible\_value

```
\mathbf{E}[[LAMBDA\ (I)\ E]] = \\ \lambda e.\ inFunction(\lambda d.\ \mathbf{E}[[E]](updateenv\ [[I]]\ d\ e))
```

```
\begin{split} \mathbf{E}[[E_1 \ E_2]] &= \lambda e. \ let \ x = (\mathbf{E}[[E_1]]e) \ in \ cases \ x \ of \\ isFunction(f) &\rightarrow f(\mathbf{E}[[E_2]]e) \\ ] \ isList(t) &\rightarrow inError() \\ ] \ isAtom(a) &\rightarrow inError() \\ [] \ isError() &\rightarrow inError() \ end \end{split}
```

- Punctions are created by the LAMBDA construction
- O A function body is evaluated in the context that is active at the point of function definition, augmented by the binding of an actual parameter to the binding identifier
- O This definition is also statically scoped



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#### Valuation Functions:

E: Expression→ Environment → Expressible\_value

```
E[[E_1 \ CONS \ E_2]] = \lambda e. let x = (E[[E_2]]e) in cases x of
   isFunction(f) \rightarrow inError()
   [] isList(t) \rightarrow inList(\mathbf{E}[[E_1]]e \ cons \ t)
   [] isAtom(a) \rightarrow inError()
[] isError() \rightarrow inError() end
E[[HEAD\ E]] = \lambda e.\ let\ x = (E[[E]]e) in cases x of
   isFunction(f) \rightarrow inError()
   [] isList(t) \rightarrow (null\ t \rightarrow inError()\ []\ (hd\ t))
   [] isAtom(a) \rightarrow inError()
   [] is Error() \rightarrow in Error() end
E[[TAIL\ E]] = \lambda. let x = (E[[E]]e) in cases x of
   isFunction(f) \rightarrow inError()
   [] isList(t) \rightarrow (null t \rightarrow inError() [] inList(tl t))
   ||isAtom(a) \rightarrow inError()||
   isError() → inError() end
E[[NIL]] = \lambda e. inList(nil)
```



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Summar

#### Valuation Functions:

E: Expression→ Environment → Expressible\_value

E[[I]] = accessenv [[I]]

 $\mathsf{E}[[A]] = \lambda e. \ \mathit{inAtom}(\mathsf{A}[[A]])$ 

 $\mathbf{E}[[(E)]] = \mathbf{E}[[E]]$ 

• **A**:Atomic-symbol  $\rightarrow$  *Atom* 



## Applicative Language: Scoping Rule

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#### **Static Scoping**

- The applicative language uses static scoping; that is, the context of a phrase is determined by its physical position in the program
  - Consider (let  $a_0$  and  $a_1$  be atomic symbols):

Note: (let  $x=e_1$  in  $e_2$ ) for  $(\lambda x. e_2)e_1$ 

• The occurrence of the first F in the body of the function bound to the second F refers to the atom  $a_0$  – the function is not recursive. The meaning of the entire expression is the same as

which equals

$$(a_0 \ CONS \ (a_1 \ CONS \ NIL)) = (a_0 \ a_1)$$



## Applicative Language: Scoping Rule

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#### **Dynamic Scoping**

- An alternative to static scoping is dynamic scoping, where the context of a phrase is determined by the place(s) in the program where the phrase's value is required
- The most general form of dynamic scoping is macro definition and invocation. A definition LET I = E binds identifier
   I to the text E; E is not assigned a context until its value is needed
- When I's value is required, the context where I appears is used to acquire the text that is bound to it
- I is replaced by the text, and the text is evaluated in the existing context
- The version of dynamic scoping found in LISP limits dynamic scoping just to LAMBDA forms
- The semantics of [[LAMBDA (I) E]] shows that the construct is evaluated within the context of its application to an argument (and not within the context of its definition)



## Applicative Language: Scoping Rules

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#### Semantic Algebras:

Function

Domain:  $f \in Function = Environment \rightarrow Denotable\_value \rightarrow Denotable\_value$ 

#### **Valuation Functions:**

E: Expression→ Environment → Expressible\_value

$$\mathbf{E}[[LAMBDA\ (I)\ E]] = \lambda e.\ inFunction(\lambda e'.\ \lambda d.\ \mathbf{E}[[E]](updateenv\ [[I]]\ d\ e'))$$

$$\mathbf{E}[[E_1 \ E_2]] = \lambda e. \ let \ x = (\mathbf{E}[[E_1]]e) \ in \ cases \ x \ of \ isFunction(f) \rightarrow (f \ e \ (\mathbf{E}[[E_2]]e)) \ [] \ isList(t) \rightarrow inError() \ [] \ isAtom(a) \rightarrow inError() \ end$$



## Principles of Programming Languages: Summary

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λ-Calculus: Syntax

• λ-Calculus: Semantics

•  $\lambda$ -Calculus: Typed

ullet Programming Languages with  $\lambda$ 

o Functional: Haskell, Scheme, Lisp, ML

 $\circ$  Multi-Paradigm:  $\lambda$  in C++

Type Systems

• Denotational Semantics

Definition

o Relationship with Operational and Axiomatic Semantics

Semantics of Imperative Languages



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b) Prerequisites

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Module 03

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2 Module 02:  $\lambda$ -Calculus: Syntax

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b) Functions

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C)  $\lambda$ -Calculus

 $\bullet \ \ \mathsf{Concept} \ \mathsf{of} \ \lambda$ 

d) Syntax

•  $\lambda$ -expressions

\* Notation

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\* Simple

\* Composition

\* Boolean

\* Numerals

\* Recursion

\* Curried Functions

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[3] Module 03:  $\lambda$ -Calculus: Semantics

a) Semantics

- Free and Bound Variables
- Substitution
- Reduction
- \*  $\alpha$ -Reduction
- \*  $\beta$ -Reduction
- \*  $\eta$ -Reduction
- \*  $\delta$ -Reduction
- Order of Evaluation
- \* Normal and Applicative Order



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[4] Module 04: Typed  $\lambda$ -Calculus

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Type Expression

Pre-Expression & Expression

Type-checking Rules

\* Example

\* Practice Problems

b)  $\Lambda_{rr}^{\rightarrow}$ 

Types

\* Tuple Type

\* Record Type

\* Sum Type

\* Reference Type

\* Array Type

Type Expression

Pre-Expression

Type-checking Rules

\* Derived Rules



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[5] Module 05:  $\lambda$  in C++

a) Functors

Callable Entities

Function Pointers

\* Replace Switch / IF Statements

\* Late Binding

\* Virtual Function

\* Callback

\* Issues

Basic Functors

\* Elementary Example

\* Examples from STL

b)  $\lambda$  in C++

•  $\lambda$  Expression

Closure Object

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\* Factorial

\* Fibonacci

\* Pipeline

Curry Function

C) More on  $\lambda$  in C++



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a) Type Systems

Type & Type Error

Type & TypeType Safety

Type Checking

Type Inference

b) Type Inference

• add x = 2 + x

• apply (f, x) = f x

Inference Algorithm

\* Unification

Examples

• sum

length

append

Homework

d) Type Deduction in C++

Polymorphism

• \* Ad-hoc

\* Parametric

\* Subtype

● C++11,...



Module M09

Partha Prat Das

Imperative Languages

Language Assignmen

Programs Are Functions

Interactive File Editor

Dynamically Typed Language

Definitions
copyout
Unfolding Examples

Languages with Context

Block Structure Applicative

Summary

[7] Module 07: Denotational Semantics

- a) Semantic Styles
- b) Syntax
- C) Semantic Domains
  - · Set, Functions, and Domains
  - \* Product
  - \* Sum
  - Rat
- d) Semantic Algebras
  - Nat. Tr
  - String
  - Unit
  - Product Dom
  - Sum Dom
  - Sum DomLists
  - Function
  - Arrays
  - Lifted Domains
  - Recursive Fn
- e) Denotational Definitions
  - Binary
  - Calculator



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Languages wi Context Block Structure

Summary

# Principles of Programming Languages: Modules

- 8 Module 08: Denotational Semantics of Imperative Languages
  - a) Imperative Languages
  - b) Language + Assignment
  - c) Programs Are Functions
  - d) Interactive File Editor
  - e) Dynamically Typed Language
  - f) Recursive Definitions
  - g) Language with Contexts
    - Block Structured Language
    - Applicative Language



Module M09

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Programs Ar Functions

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copyout

Unfolding Example

While Loop

Languages wit

Block Structure

Summary

8 Module 09:  $\lambda$  Calculus – Languages

- a) Overview of Functional Programming
- b) Haskell
- C) Scheme
- d) Lisp