

<u>Course</u> > <u>Policy Gradient and</u>... > <u>Knowledge Checks</u> > Knowledge Checks

## **Knowledge Checks**

## Question 1

1/1 point (graded) Which two of the following are advantages of policy gradient methods over value-function based methods??
Policy gradient methods are scalable to problems with high dimensions or continuous state spaces.
☑ Policy gradient methods can learn stochastic policies.
$\square$ Policy gradient methods converge to the global optimum policy.
$\square$ Policy gradient methods are more sample efficient.
<b>✓</b>
Submit You have used 1 of 2 attempts
✓ Correct (1/1 point)
Question 2
1/1 point (graded) Which reinforcement learning methods does Actor-Critic algorithms combine??
Policy gradient algorithms as critics and policy iteration algorithms as actors.

<ul> <li>Policy gradient algorithms as actors and policy iteration algorithms as critics.</li> </ul>
O Discounted returns as actors and policy interaction algorithms as critics.
<ul> <li>Policy gradient algorithms as actors and expected value functions as critics.</li> </ul>
Submit You have used 1 of 2 attempts
✓ Correct (1/1 point)
Question 3
1/1 point (graded) Intuitively, the likelihood ratio method has which two of the following policies?
☐ Following the gradient decreases the likelihood of following trajectories with high variance.
☐ Following the gradient increases the likelihood of finding trajectories with high reward.
☐ Following the gradient decreases the likelihood of following trajectories with high bias.
☑ Following the gradient decreases the likelihood of finding trajectories with low or negative reward.
✓
Submit You have used 1 of 2 attempts
✓ Correct (1/1 point)

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1/1 point (graded)

Which of the following are properties of the Reinforce algorithm?
$\bigcirc$ Uses a policy $\pi\left(s_{t} ight)$ during an episode to collect information on states, actions and rewards.
O Computes the return for each episode using the rewards collected.
O Updates the model parameters in the director of the policy gradient.
● All of the above. ✔
Submit You have used 1 of 2 attempts
✓ Correct (1/1 point)
Question 5
1/1 point (graded) Which two of the following are methods to reduce the variance of the REINFORCE algorithm?
☐ Use the minimum variance policy gradient to minimize variance of the return.
☑ Discount returns to encourage trajectories with good actions and discourage trajectories with bad actions.
☐ Using the discounted expected returns given the policy as a baseline discourages trajectories with return below the baseline.

☐ Using the expected returns given the policy as a baseline discourages trajectories with return away from the baseline.
Submit You have used 1 of 2 attempts
✓ Correct (1/1 point)
Question 6  1/1 point (graded)  Which of the following is a correct definition of the advantage function?
The difference between the gradient of the log likelihood and the state value function.
The difference between the Q-value and the gradient of the log likelihood.
● The difference between the Q-value and the state value function. ✔
O The difference between the Q-value and the discounted return.
Submit You have used 2 of 2 attempts
✓ Correct (1/1 point)
Ouestion 7

1/1 point (graded)

Which two of the following are the following are advantages of using an N-step Q-value function in an actor-critic algorithm?

☐ The N-step Q-value function leads to solutions which maximize the advantage function.
☐ The N-step Q-value function bootstraps and does not need to sample to the end of an episode to compute an estimate of Q.
☐ The N-step Q-value function trades off bias for lower variance.
☐ The N-step Q-value function trades off variance for lower bias.
Submit You have used 1 of 2 attempts
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✓ Correct (1/1 point)
Question 8
1/1 point (graded) Which two of the following are advantages of the Asynchronous Advantage Actor-Critic (A3C) algorithm when compared to other actor-critic methods?
☐ Shares parameters between the actor and critic networks to improve data efficiency or speed of training.
☐ Eliminates shared parameters between actor and critic networks to improve data efficiency or speed of training.
☐ Trains multiple policies on copies of the environment simultaneously improving convergence.
☐ Trains a single policy by acting on and collecting experience from parallel environments simultaneously to improve scalability.
<b>✓</b>
Submit You have used 1 of 2 attempts

✓ Correct (1/1 point)

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