

Topic 16: Graphical Network Inference

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Key points:

Disclaimer: The note is built on Prof. [Jinchi Lv](#)'s lectures of the course at USC, DSO 607, High-Dimensional Statistics and Big Data Problems.

16.1 Motivation

Consider a classic question: For n observations of dimension p , how can we capture the statistical relationships between the variables of interest? Consider the example of the multivariate Gaussian distribution:

Example 16.1.1: Multivariate Gaussian Distribution

Suppose we have n observations of dimension p , $\mathbf{x} \sim \mathcal{N}(\boldsymbol{\mu}, \boldsymbol{\Sigma})$. let \mathbf{S} be the empirical covariance matrix. Then the probability density

$$f(\mathbf{x}) = \frac{1}{(2\pi)^{p/2} \det(\boldsymbol{\Sigma})^{1/2}} \exp \left\{ -\frac{1}{2} (\mathbf{x} - \boldsymbol{\mu})' \boldsymbol{\Sigma}^{-1} (\mathbf{x} - \boldsymbol{\mu}) \right\}$$

define the **inverse covariance matrix** or **precision matrix** as $\boldsymbol{\Omega} = \boldsymbol{\Sigma}^{-1}$, then we have

$$f_{\boldsymbol{\mu}, \boldsymbol{\Omega}} = \exp \left\{ \boldsymbol{\mu}' \boldsymbol{\Omega} \mathbf{x} - \left\langle \boldsymbol{\Omega}, \frac{1}{2} \mathbf{x} \mathbf{x}' \right\rangle - \frac{p}{2} \log(2\pi) + \frac{1}{2} \log \det(\boldsymbol{\Omega}) - \frac{1}{2} \boldsymbol{\mu}' \boldsymbol{\Omega} \boldsymbol{\mu} \right\}$$

where $\langle \mathbf{A}, \mathbf{B} \rangle = \text{tr}(\mathbf{A}\mathbf{B})$.

In this example, we know that **every** multivariate Gaussian distribution can be represented by a pairwise **Gaussian Markov Random Field (GMRF)**, which an **undirected graph** $G = (V, E)$

- representing the collection of variables \mathbf{x} by a vertex set $\mathcal{V} = \{1, \dots, p\}$
- encoding correlations between variables by a set of edges $\mathcal{E} = \{(i, j) \in \mathcal{V} \mid i \neq j, \Omega_{ij} \neq 0\}$

For simplicity, we normalize $\boldsymbol{\mu} = \mathbf{0}$. If we draw n i.i.d. samples $\mathbf{x}_1, \dots, \mathbf{x}_n \sim \mathcal{N}(\mathbf{0}, \boldsymbol{\Sigma})$, then the log-likelihood is

$$\begin{aligned} \mathcal{L}(\boldsymbol{\Omega}) &= \frac{1}{n} \sum_{i=1}^n \log f(\mathbf{x}_i) = \frac{1}{2} \log \det(\boldsymbol{\Omega}) - \frac{1}{2n} \sum_{i=1}^n \mathbf{x}_i' \boldsymbol{\Omega} \mathbf{x}_i \\ &= \frac{1}{2} \log \det(\boldsymbol{\Omega}) - \frac{1}{2} \left\langle \boldsymbol{\Omega}, \frac{1}{n} \sum_{i=1}^n \mathbf{x}_i \mathbf{x}_i' \right\rangle \end{aligned}$$

What's the goal? We want to estimate a **sparse** graph structure given $n \ll p$ i.i.d. observations. But what does sparsity means in this context? A sparse graph is **equivalent** to a sparse precision matrix: the precision

matrix should have many 0s.

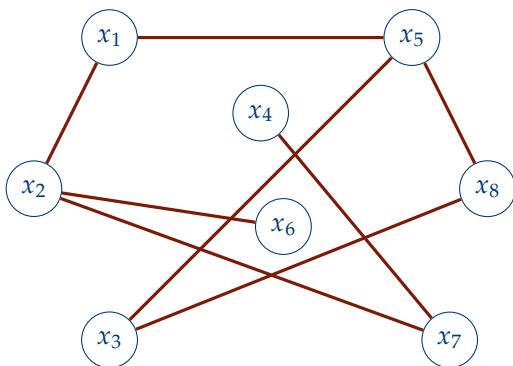
Sparse precision matrix for the Gaussian vector mentioned above $\mathbf{x} \sim \mathcal{N}(\mathbf{0}, \Sigma)$, we have $\forall u, v$

$$x_u \perp x_v \mid \mathbf{x}_{V \setminus \{u, v\}} \Leftrightarrow \Omega_{u, v} = 0$$

that is, sparsity of the precision matrix is equivalent to **conditional independence**¹. Consider a graph, where x_1 and x_4 are only connected through other nodes, that is x_1 and x_4 are conditional independent, then we can have the precision matrix be something like:

$$\Theta = \begin{bmatrix} * & * & 0 & 0 & * & 0 & 0 & 0 \\ * & * & 0 & 0 & 0 & * & * & 0 \\ 0 & 0 & * & 0 & * & 0 & 0 & * \\ 0 & 0 & 0 & * & 0 & 0 & * & 0 \\ * & 0 & * & 0 & * & 0 & 0 & * \\ 0 & * & 0 & 0 & 0 & * & 0 & 0 \\ 0 & * & 0 & * & 0 & 0 & * & 0 \\ 0 & 0 & * & 0 & * & 0 & 0 & * \end{bmatrix}$$

where 0 captures precisely the conditional independence.



x_1 and x_4 are connected



x_1 and x_4 are NOT connected, conditionally

Intuitively, a sparse graph is much simpler, which is why conditional independence is desired. So how to achieve sparsity? We can again use a L-1 regularization when maximizing the log-likelihood $\mathcal{L}(\Omega)$. Denote the sample covariance matrix as $\mathbf{S} = \frac{1}{n} \sum_{i=1}^n \mathbf{x}_i \mathbf{x}_i'$, then the problem becomes the so-called **Graphical Lasso**

$$\max_{\Omega \geq 0} \log \det(\Omega) - \text{tr}(\mathbf{S}\Omega) - \rho \|\Omega\|_1$$

which is equivalent to

$$\min_{\Omega \geq 0} -\log \det(\Omega) + \text{tr}(\mathbf{S}\Omega) + \rho \|\Omega\|_1$$

16.2 Graphical Lasso

The graphical lasso method is developed by (Friedman et al., 2008). For the optimization problem

$$\min_{\Omega \geq 0} -\log \det(\Omega) + \text{tr}(\mathbf{S}\Omega) + \rho \|\Omega\|_1 \quad (16.1)$$

¹Meanwhile, for independence: $\Sigma_{u, v} = 0 \Leftrightarrow x_u \perp x_v$

The first-order optimality condition gives

$$\mathbf{0} \in \mathbf{\Omega}^{-1} - \mathbf{S} - \lambda \mathbf{\Gamma}$$

where $\mathbf{\Gamma}$ is a matrix of component-wise signs of $\mathbf{\Omega}$

$$\mathbf{\Gamma} = \partial \|\mathbf{\Omega}\|_1 \Rightarrow \gamma_{jk} \begin{cases} = \text{sign}(\omega_{jk}), & \omega_{jk} \neq 0 \\ \in [-1, 1], & \omega_{jk} = 0 \end{cases}$$

since in a graph, we always have that, following the global stationarity conditions, $\omega_{jj} > 0$, which implies that

$$w_{ii} = s_{ii} + \lambda \quad i = 1, \dots, p \quad (16.2)$$

where we denote a working version of $\mathbf{\Omega}^{-1}$ as \mathbf{W} .

The idea is to repeatedly cycle through all columns-rows and in each step optimize only a single column-row. Consider the following partition where all matrices are partitioned into one column/row versus the rest

$$\mathbf{\Omega} = \begin{pmatrix} \mathbf{\Omega}_{11} & \boldsymbol{\omega}_{12} \\ \boldsymbol{\omega}'_{12} & \omega_{22} \end{pmatrix} \quad \mathbf{S} = \begin{pmatrix} \mathbf{s}_{11} & \mathbf{s}_{12} \\ \mathbf{s}'_{12} & s_{22} \end{pmatrix} \quad \mathbf{W} = \begin{pmatrix} \mathbf{W}_{11} & \mathbf{w}_{12} \\ \mathbf{w}'_{12} & w_{22} \end{pmatrix} \quad \mathbf{\Gamma} = \begin{pmatrix} \mathbf{\Gamma}_{11} & \boldsymbol{\gamma}_{12} \\ \boldsymbol{\gamma}'_{12} & \gamma_{22} \end{pmatrix}$$

apply this partition to the optimality condition, get

$$\mathbf{\Omega}^{-1} = \mathbf{S} - \lambda \mathbf{\Gamma}$$

$$\begin{pmatrix} \mathbf{W}_{11} & \mathbf{w}_{12} \\ \mathbf{w}'_{12} & w_{22} \end{pmatrix} = \begin{pmatrix} \mathbf{s}_{11} & \mathbf{s}_{12} \\ \mathbf{s}'_{12} & s_{22} \end{pmatrix} + \lambda \begin{pmatrix} \mathbf{\Gamma}_{11} & \boldsymbol{\gamma}_{12} \\ \boldsymbol{\gamma}'_{12} & \gamma_{22} \end{pmatrix}$$

where $\mathbf{\Omega}_{11}$ is $(p-1) \times (p-1)$, $\boldsymbol{\omega}_{12}$ is $(p-1) \times 1$, ω_{22} is a scalar.

Consider a **blockwise** step: suppose we fix all but the last row/column, then using properties of inverses of block-partitioned matrices, we have

$$\begin{pmatrix} \mathbf{W}_{11} & \mathbf{w}_{12} \\ \mathbf{w}'_{12} & w_{22} \end{pmatrix} = \begin{pmatrix} \left(\mathbf{\Omega}_{11} - \frac{\boldsymbol{\omega}_{12} \boldsymbol{\omega}'_{12}}{\omega_{22}} \right)^{-1} & -\mathbf{W}_{11} \frac{\boldsymbol{\omega}_{12}}{\omega_{22}} \\ \frac{1}{\omega_{22}} - \frac{\boldsymbol{\omega}'_{12} \mathbf{W}_{11} \boldsymbol{\omega}_{12}}{\omega_{22}^2} & \end{pmatrix}$$

$$= \begin{pmatrix} \mathbf{\Omega}_{11}^{-1} + \frac{\mathbf{\Omega}_{11}^{-1} \boldsymbol{\omega}_{12} \boldsymbol{\omega}'_{12} \mathbf{\Omega}_{11}^{-1}}{\omega_{22} - \boldsymbol{\omega}'_{12} \mathbf{\Omega}_{11}^{-1} \boldsymbol{\omega}_{12}} & -\frac{\mathbf{\Omega}_{11}^{-1} \boldsymbol{\omega}_{12}}{\omega_{22} - \boldsymbol{\omega}'_{12} \mathbf{\Omega}_{11}^{-1} \boldsymbol{\omega}_{12}} \\ \frac{1}{\omega_{22} - \boldsymbol{\omega}'_{12} \mathbf{\Omega}_{11}^{-1} \boldsymbol{\omega}_{12}} & \end{pmatrix}$$

then, by the partitioned optimality condition, we have²:

$$\mathbf{0} = -\mathbf{w}_{12} + \mathbf{s}_{12} + \lambda \boldsymbol{\gamma}_{12} = \mathbf{W}_{11} \frac{\boldsymbol{\omega}_{12}}{\omega_{22}} + \mathbf{s}_{12} + \lambda \boldsymbol{\gamma}_{12} \quad (16.3)$$

$$\mathbf{0} = \frac{\mathbf{\Omega}_{11}^{-1} \boldsymbol{\omega}_{12}}{\omega_{22} - \boldsymbol{\omega}'_{12} \mathbf{\Omega}_{11}^{-1} \boldsymbol{\omega}_{12}} + \mathbf{s}_{12} + \lambda \boldsymbol{\gamma}_{12} = w_{22} \mathbf{\Omega}_{11}^{-1} \boldsymbol{\omega}_{12} + \mathbf{s}_{12} + \lambda \boldsymbol{\gamma}_{12} \quad (16.4)$$

The graphic Lasso algorithm then solves Eq.16.3 for $\boldsymbol{\beta} = \boldsymbol{\omega}_{12}/\omega_{12}$, that is

$$\mathbf{W}_{11} \boldsymbol{\beta} + \mathbf{s}_{12} + \lambda \boldsymbol{\gamma}_{12} = \mathbf{0}$$

²For Eq.16.4, by Eq.16.2, we know that $w_{22} = s_{22} + \lambda$, which is fixed.

where $\gamma_{12} \in \text{sign}(\beta)$ since $\omega_{22} > 0$, which is essentially solving:

$$\min_{\beta \in \mathbb{R}^{p-1}} \left\{ \frac{1}{2} \beta' \mathbf{W}_{11} \beta + \beta' \mathbf{s}_{12} + \lambda \|\beta\|_1 \right\}$$

and $\mathbf{W}_{11} > 0$ is assumed to be fixed.

This problem is analogous to a lasso regression problem of **the last variable on the rest**, but the cross-product matrix \mathbf{S}_{11} is replaced by its **current estimation** \mathbf{W}_{11} . It is relatively easier to solve using elementwise coordinate descent, then

$$\mathbf{w}_{12} = -\mathbf{W}_{11} \frac{\omega_{12}}{\omega_{22}} \quad \Rightarrow \quad \hat{\mathbf{w}}_{12} = -\mathbf{W}_{11} \hat{\beta} \quad \text{Step 1}$$

$$w_{22} = \frac{1}{\omega_{22}} - \frac{\omega'_{12} \mathbf{W}_{11} \omega_{12}}{\omega_{22}^2} \quad \Rightarrow \quad \frac{1}{\hat{\omega}_{22}} = w_{22} - \hat{\beta}' \hat{\mathbf{w}}_{12} \quad \text{Step 2}$$

$$\omega_{12} = -\mathbf{W}_{11}^{-1} \mathbf{w}_{12} \omega_{22} \quad \Rightarrow \quad \hat{\omega}_{12} = -\mathbf{W}_{11}^{-1} \hat{\mathbf{w}}_{12} \hat{\omega}_{22} \quad \text{Step 3}$$

notice that after solving for β and updating \mathbf{w}_{12} in Step 1, the graphic Lasso procedure can move onto the next block, that is, only Step 1 is used in the loop, Step 2 and 3 can be done at the end. The algorithm can be summarized as:

Algorithm 16.2.1: Graphical Lasso algorithm

- 1 Initialize $\mathbf{W} = \mathbf{S} + \lambda \mathbf{I}$
- Cycle around the columns repeatedly, performing the following steps till convergence:
 - a rearrange the rows/columns so that the target column is **the last** (implicitly)
 - b solve the lasso problem, starting the solution from the previous round for this column
 - c update the row/column (*off-diagonal*) of the covariance using $\hat{\mathbf{w}}_{12}$
 - d save $\hat{\beta}$ for this column in the matrix \mathbf{B}
- 3 after convergence, for every row/column, compute the diagonal entries $\hat{\omega}_{jj}$, and covert the \mathbf{B} matrix to $\hat{\Omega}$

16.3 What Is GLasso Solving?

Again, consider the optimization problem

$$\min_{\Omega \geq 0} -\log \det(\Omega) + \text{tr}(\mathbf{S}\Omega) + \rho \|\Omega\|_1$$

and its stationarity condition

$$\mathbf{0} = \Omega^{-1} - \mathbf{S} - \lambda \Gamma$$

rewrite the stationarity condition

$$\mathbf{0} = \Omega^{-1} - \mathbf{S} - \lambda \Gamma = \Omega - (\mathbf{S} + \lambda \Gamma)^{-1}$$

since $\Gamma = \text{sign}(\Omega)$, write $\tilde{\Gamma} = \lambda \Gamma$, we have $\|\tilde{\Gamma}\|_\infty \leq \lambda$. Denote the element-wise absolute value matrix of Ω as $\text{abs}(\Omega)$, then let $\tilde{\Gamma} = \lambda \Gamma$, $\mathbf{P} = \text{abs}(\Omega)$, we have

$$\begin{aligned} \mathbf{0} &= \Omega - (\mathbf{S} + \lambda \Gamma)^{-1} \\ &= \mathbf{P} \circ \text{sign}(\tilde{\Gamma}) - (\mathbf{S} + \tilde{\Gamma})^{-1} \end{aligned}$$

and mechanically, we also have

$$\begin{aligned} \mathbf{P} \circ (\text{abs}(\tilde{\Gamma}) - \lambda \mathbf{1}_p \mathbf{1}_p') &= \mathbf{0} \\ \|\tilde{\Gamma}\|_{\infty} &\leq \lambda \end{aligned}$$

together, these are just the KKT optimality condition for the following box-constrained SDP

$$\max_{\tilde{\Gamma}: \|\tilde{\Gamma}\|_{\infty} \leq \lambda} g(\tilde{\Gamma}) := \log \det(\mathbf{S} + \tilde{\Gamma}) + p \quad (16.5)$$

with the transformation $\mathbf{S} + \tilde{\Gamma} = \mathbf{\Omega}^{-1}$. Essentially, this is the dual problem of the initial optimization problem, both of them are solved by the GLasso algorithm.

Issues of GLasso method :

- the non-monotonic behavior of GLasso in minimizing $f(\mathbf{\Omega})$
 - θ_{12} is entangled in \mathbf{W}_{11} , which is **incorrectly** treated as a constant
 - after updating θ_{12} , the entire (working) covariance matrix \mathbf{W} changes, but GLasso algorithm only updates \mathbf{w}_{12} and \mathbf{w}_{12}'
- high dimensionality problems
 - not computationally efficient when p is ultra-large
 - $\mathbf{\Sigma}^{-1}$ doesn't exist when $p > n$
 - method is not scalable

Next, we address these issues by introducing some modifications.

16.4 Graphical Lasso: Modifications

16.4.1 Primal GLasso

Consider the optimality condition in Eq.16.4:

$$0 = \frac{\mathbf{\Omega}_{11}^{-1} \omega_{12}}{\omega_{22} - \omega_{12}' \mathbf{\Omega}_{11}^{-1} \omega_{12}} + \mathbf{s}_{12} + \lambda \gamma_{12} = w_{22} \mathbf{\Omega}_{11}^{-1} \omega_{12} + \mathbf{s}_{12} + \lambda \gamma_{12}$$

Here, the dependence of the covariance submatrix \mathbf{W}_{11} on $\mathbf{\Omega}_{12}$ is **explicit**. Let $\alpha = \omega_{12} w_{22}$ with fixed $w_{22} \geq 0^3$, then this optimality condition is essentially solving

$$\min_{\alpha \in \mathbb{R}^{p-1}} \left\{ \frac{1}{2} \alpha' \mathbf{\Omega}_{11}^{-1} \alpha + \alpha' \mathbf{s}_{12} + \lambda \|\alpha\|_1 \right\}$$

the minimizer of this problem $\hat{\alpha}$ can then be used to derive the estimation for ω_{12} :

$$\hat{\omega}_{12} = \frac{\hat{\alpha}}{w_{22}}$$

, then we can update w_{22} as before via

$$\hat{w}_{22} = \frac{1}{w_{22}} + \hat{\omega}_{12}' \mathbf{\Theta}_{11}^{-1} \hat{\omega}_{12}$$

³ $w_{22} = 1/(\omega_{22} - \omega_{12}' \mathbf{\Omega}_{11}^{-1} \omega_{12})$

with $w_{22} = s_{22} + \lambda$. Another problem is how to obtain Ω_{11}^{-1} : as the iterations proceed, maintain $\mathbf{W} = \Omega^{-1}$, and Ω_{11}^{-1} can be derived from

$$\Omega_{11}^{-1} = \mathbf{W}_{11} - \frac{\mathbf{w}_{12}\mathbf{w}_{12}'}{w_{22}}$$

once ω_{12} is updated, the **entire** working covariance matrix \mathbf{W} is updated using Ω_{11}^{-1} . This procedure, the so-called primal graphical lasso, can be represented in the following algorithm:

Algorithm 16.4.1: P-Glasso Algorithm

- 1 Initialize $\mathbf{W} = \text{diag}(\mathbf{S}) + \lambda \mathbf{I}$ and $\Omega = \mathbf{W}^{-1}$
- 2 Cycle around the columns repeatedly, performing the following steps till convergence:
 - a rearrange the rows/columns so that the target column is the last (implicitly)
 - b compute Ω_{11}^{-1} using $\Omega_{11}^{-1} = \mathbf{W}_{11} - \frac{\mathbf{w}_{12}\mathbf{w}_{12}'}{w_{22}}$
 - c solve $\min_{\alpha \in \mathbb{R}^{p-1}} \left\{ \frac{1}{2} \alpha' \Omega_{11}^{-1} \alpha + \alpha' \mathbf{s}_{12} + \lambda \|\alpha\|_1 \right\}$ for α , using as warm starts the solution from the previous round of row/column updates. Then update $\hat{\omega}_{12} = \hat{\alpha}/w_{22}$ and $\hat{\omega}_{22}$
 - d update Ω and \mathbf{W} , ensuring that $\Omega \mathbf{W} = \mathbf{I}_p$
- 3 output the solution: precision matrix Ω and its exact inverse, covariance matrix \mathbf{W}

16.4.2 Innovated Scalable Efficient Estimation

Now, we try to tackle the high-dimensionality issues: Σ^{-1} does **not** exist when $p > n$. Again,

$$\mathbf{x} \sim \mathcal{N}(\mathbf{0}, \Sigma)$$

consider a linear transformation where $\tilde{\mathbf{x}} = \Omega \mathbf{x}$ (Ω is still the precision matrix Σ^{-1}), and

$$\text{cov}(\tilde{\mathbf{x}}) = \Omega \text{cov}(\mathbf{x}) \Omega = \Omega \Sigma \Omega = \Omega$$

But Ω is unknown and to be estimated. To get around this, we **break** the long vector $\tilde{\mathbf{x}}$ into small sub-vectors and then estimate each one.

Notation for subsets $A, B \subset \{1, \dots, p\}$, let \mathbf{x}_A denote a sub-vector of \mathbf{x} formed by its components with indices in A , and the sub-(precision)-matrix is $\Omega_{A,B} = (\omega_{jk})_{j \in A, k \in B}$, $\Omega_A := \Omega_{A,A}$ for simplicity. Then define

$$\tilde{\mathbf{x}}_A = \Omega_A \boldsymbol{\eta}_A$$

where $\boldsymbol{\eta}_A = \mathbf{x}_A + \Omega_A^{-1} \Omega_{A,A^c} \mathbf{x}_{A^c}$, and $A^c := \{1, \dots, p\} \setminus A$. With this definition, we have the following proposition:

Proposition 16.4.2: Conditional Distribution of Sub-vectors

Conditional distribution $\mathbf{x}_A \mid \mathbf{x}_B \sim \mathcal{N}(\boldsymbol{\mu}_{A|B}, \Sigma_{A|B})$, where

$$\begin{aligned} \boldsymbol{\mu}_{A|B} &= \boldsymbol{\mu}_A + \Sigma_{A,B} \Sigma_B^{-1} (\mathbf{x}_B - \boldsymbol{\mu}_B) \\ \Sigma_{A|B} &= \Sigma_A - \Sigma_{A,B} \Sigma_B^{-1} \Sigma_{B,A} \end{aligned}$$

and when $\mathbf{x}_B = \mathbf{x}_{A^c}$, we have

$$\mathbf{x}_A \mid \mathbf{x}_{A^c} \sim \mathcal{N}(-\boldsymbol{\Omega}_A^{-1} \boldsymbol{\Omega}_{A,A^c} \mathbf{x}_{A^c}, \boldsymbol{\Omega}_A^{-1})$$

Prop.16.4.2 gives a multivariate linear regression model:

$$\mathbf{x}_A = \mathbf{C}'_A \mathbf{x}_{A^c} + \boldsymbol{\eta}_A$$

where $\mathbf{C}_A = -\boldsymbol{\Omega}_{A^c,A} \boldsymbol{\Omega}_A^{-1}$ is the coefficient matrix, and $\boldsymbol{\eta}_A$ is model errors with Gaussian distribution $\mathcal{N}(\mathbf{0}, \boldsymbol{\Omega}_A^{-1})$. Then we can have the following algorithm to solve this problem:

Algorithm 16.4.3: ISEE Algorithm

- 1 Let $(A_l)_{l=1}^L$ be a partition of index set $\{1, \dots, p\}$, s.t. $\bigcup_{l=1}^L A_l = \{1, \dots, p\}$
- 2 estimate $\boldsymbol{\eta}_{A_l}$ and then obtain estimated $\tilde{\mathbf{x}}_{A_l}$
- 3 stack all estimated sub-vectors $\tilde{\mathbf{x}}_{A_l}$ together to obtain $\tilde{\mathbf{x}}$

ISEE algorithm breaks large-scale precision estimation into **small-scale linear regression problems**, each of which is computationally efficient and effective.

Estimation for the $n \times p$ data matrix $\mathbf{X} = (\mathbf{x}_1, \dots, \mathbf{x}_n)'$, we construct the linear transformation

$$\tilde{\mathbf{X}} = (\tilde{\mathbf{x}}_1, \dots, \tilde{\mathbf{x}}_n) = \mathbf{X}\boldsymbol{\Omega}$$

then the multivariate linear regression model by matrix notation is

$$\mathbf{X}_A = \mathbf{X}_{A^c} \mathbf{C}_A + \mathbf{E}_A$$

and the corresponding sub-matrix $\tilde{\mathbf{X}}_A$ can be written as

$$\tilde{\mathbf{X}}_A = (\mathbf{X}\boldsymbol{\Omega})_A = \mathbf{X}_A \boldsymbol{\Omega}_A + \mathbf{X}_{A^c} \boldsymbol{\Omega}_{A^c,A} = (\mathbf{X}_A + \mathbf{X}_{A^c} \boldsymbol{\Omega}_{A^c,A} \boldsymbol{\Omega}_A^{-1}) \boldsymbol{\Omega}_A = \mathbf{E}_A \boldsymbol{\Omega}_A$$

Sparsity is achieved via scaled Lasso: for each node j in index set A ,

$$\mathbf{X}_j = \mathbf{A}^C \boldsymbol{\beta}_j + \mathbf{E}_j$$

where $\boldsymbol{\beta}_j$ is the column of \mathbf{C}_A corresponds to node j . The estimation is then done in the following steps:

- run the PLS

$$(\hat{\boldsymbol{\beta}}_j, \hat{\sigma}_j^{1/2}) = \arg \min_{\boldsymbol{\beta} \in \mathbf{R}^{p-|A|}, \sigma \geq 0} \left\{ \frac{\|\mathbf{X}_j - \mathbf{X}_{A^c} \boldsymbol{\beta}\|_2^2}{2n\sigma} + \frac{\sigma}{2} + \lambda \|\boldsymbol{\beta}_*\|_1 \right\}$$

where $\boldsymbol{\beta}_*$ is component-wise product of $\boldsymbol{\beta}$ and $(\frac{1}{\sqrt{n}} \|\mathbf{X}_k\|_2)_{k \in A^c}$, and the penalizing factor is $\lambda = C \left(\frac{2 \log p}{n} \right)$.

- after obtaining $\hat{\boldsymbol{\beta}}_j$, get the estimation of the (partitioned) precision matrix $\hat{\boldsymbol{\Omega}}_A$

$$\hat{\boldsymbol{\Omega}}_A = \left(\frac{1}{n} \hat{\mathbf{E}}'_A \hat{\mathbf{E}}_A \right)^{-1}$$

where $\hat{\mathbf{E}}_j = \mathbf{X}_j - \mathbf{X}_{A^c} \hat{\boldsymbol{\beta}}_j$, $\hat{\mathbf{E}}_A = (\hat{\mathbf{E}}_j)_{j \in A}$

- for the whole partition $(A_l)_{l=1}^L$, we have $\hat{\mathbf{X}} = (\hat{\mathbf{X}}_{A_l})_{1 \leq l \leq L}$ where $\hat{\mathbf{X}}_{A_l} = \hat{\mathbf{E}}_{A_l} \hat{\boldsymbol{\Omega}}_{A_l}$, then the initial estimation of the whole precision matrix is $\hat{\boldsymbol{\Omega}}_{ISEE,ini} = \frac{1}{n} \hat{\mathbf{X}}' \hat{\mathbf{X}}$
- next, introduce a threshold $\tau \geq 0$, define

$$\hat{\boldsymbol{\Omega}}_{ISEE,g} = T_\tau (\hat{\boldsymbol{\Omega}}_{ISEE,ini})$$

where $T_\tau(\mathbf{B}) = (b_{jk} \mathbf{1}_{|b_{jk}| \geq \tau})$ for matrix $\mathbf{B} = (b_{jk})$, then estimate the structure \mathbf{E} as $\hat{\mathbf{E}}_{ISEE} = \text{supp}(\hat{\boldsymbol{\Omega}}_{ISEE,g})$. One can then use the cross validation method to choose the optimal threshold:

- randomly split sample of n rows into 2 samples of n_1 and n_2 , repeat N_1 times. Denote $\hat{\boldsymbol{\Omega}}_{ISEE,ini}^{1,v}, \hat{\boldsymbol{\Omega}}_{ISEE,ini}^{2,v}$ the corresponding covariance matrices
- choose τ by minimizing

$$\mathcal{R}(\tau) = \frac{1}{N_1} \sum_{v=1}^{N_1} \left\| T_\tau \left(\hat{\boldsymbol{\Omega}}_{ISEE,ini}^{1,v} \right) - \hat{\boldsymbol{\Omega}}_{ISEE,ini}^{2,v} \right\|^2$$

16.5 Heterogeneous Graphical Networks

Next, we introduce heterogeneity into this problem: the samples are now drawn from k different subpopulations

$$\mathbf{X}^{(t)} = (\mathbf{X}_1^{(t)}, \dots, \mathbf{X}_p^{(t)}) \sim \mathcal{N} \left(\mathbf{0}, \left(\boldsymbol{\Omega}^{(t)} \right)^{-1} \right) \quad t = 1, \dots, k$$

Some simple observations on this problem are

- For each node $1 \leq j \leq p$ in graph $1 \leq t \leq k$

$$\mathbf{X}_j^{(t)} | \mathbf{X}_{-j}^{(t)} \sim \mathcal{N} \left(\mathbf{X}_{-j}^{(t)'} \mathbf{C}_j^{(t)}, \frac{1}{\omega_{j,j}^{(t)}} \right)$$

with $\mathbf{C}_j^{(t)} = -\frac{\boldsymbol{\Omega}_{-j,j}^{(t)}}{\omega_{j,j}^{(t)}}$ and $\boldsymbol{\Omega}^{(t)} = (\omega_{a,b}^{(t)})_{p \times p}$

- For each pair of nodes (a, b) ,

$$\text{Cov} \left(\epsilon_a^{(t)}, \epsilon_b^{(t)} \right) = \frac{\omega_{a,b}^{(t)}}{\omega_{a,a}^{(t)} \omega_{b,b}^{(t)}}$$

with $\epsilon_j^{(t)} = \mathbf{X}_j^{(t)} - \mathbf{X}_{-j}^{(t)'} \mathbf{C}_j^{(t)} \sim \mathcal{N} \left(\mathbf{0}, \frac{1}{\omega_{j,j}^{(t)}} \right)$ **independent** across t

- Under null hypothesis on joint link strength vector

$$H_{0,ab} : \omega_{a,b}^0 = \left(\omega_{a,b}^{(1)}, \dots, \omega_{a,b}^{(k)} \right)' = \mathbf{0}$$

distributions of $\mathbf{X}_j^{(t)} | \mathbf{X}_{-j}^{(t)}$ across t share **similar sparsity structure** on coefficient vectors $\mathbf{C}_j^{(t)}$

Based on these observations, we can turn the problem of multiple-network estimation into a problem of **high-dimensional multi-response linear regression with heterogeneity**.

Nodewise Heterogeneous Multi-Response Regression

For each node $1 \leq j \leq p$,

$$\begin{pmatrix} \mathbf{x}_j^{(1)} \\ \mathbf{x}_j^{(2)} \\ \vdots \\ \mathbf{x}_j^{(k)} \end{pmatrix} = \begin{pmatrix} \mathbf{x}_{-j}^{(1)} & & & \\ & \mathbf{x}_{-j}^{(2)} & & \\ & & \ddots & \\ & & & \mathbf{x}_{-j}^{(k)} \end{pmatrix} \begin{pmatrix} \mathbf{c}_j^{(1)} \\ \mathbf{c}_j^{(2)} \\ \vdots \\ \mathbf{c}_j^{(k)} \end{pmatrix} + \begin{pmatrix} \boldsymbol{\epsilon}_j^{(1)} \\ \boldsymbol{\epsilon}_j^{(2)} \\ \vdots \\ \boldsymbol{\epsilon}_j^{(k)} \end{pmatrix}$$

The noises are **Heterogeneous** since $\omega_{j,j}^{(t)}$ generally varies over $1 \leq t \leq k$. To tackle this problem with a tuning-free estimation procedure, follow this roadmap:

- construct estimators based on residuals from the heterogeneous multi-response regressions
- rely on 2 tests (chi-based and linear-functional-based) for common sparsity pattern with optimality
- develop the scaled iterative thresholding HGSL algorithm with provable convergence for the scalability of Tuning-free heterogeneous inference (THI)

References

Jerome Friedman, Trevor Hastie, and Robert Tibshirani. Sparse inverse covariance estimation with the graphical lasso. *Biostatistics*, 9(3):432–441, 2008.