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Topic 19: Community Detection

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Key points: .

Disclaimer: The note is built on Prof. Jinchi Lv's lectures of the course at USC, DSO 607, High-Dimensional Statistics and Big Data Problems.

19.1 Stochastic Block Model

Consider an undirected graph G, with nodes V and edges E. Let

- *n* be a positive integer: the number of **vertices**
- *k* be a positive integer: the number of **communities**
- $p = (p_1, \dots, p_k)$ be a probability vector on $\{1, \dots, k\} := [k]$: the **prior** on the k communities
- **W** be a $k \times k$ symmetric matrix with entries $W_{ij} \in [0,1]$: the matrix of **connectivity probabilities**

then we have

Definition 19.1.1: Stochastic Block Model

The pair (\mathbf{X}, G) is drawn under $SBM(n, p, \mathbf{W})$ if \mathbf{X} is an n dimensional random vector with i.i.d. components distributed under p, and G is an n-vertex simple graph where vertices i and j are connected with probability W_{X_i,X_j} , **independently** of other pairs of vertices. And the **community** sets can be defined by

$$\Omega_i = \Omega_i(\mathbf{X}) := \{v \in [n] : X_v = i\}, i \in [k]$$

Immediately, we can define the symmetry of SBM as:

Definition 19.1.2: Symmetric SBM

An SBM is called symmetric if

- p is uniform
- W takes the same value on the diagonal and the same value off the diagonal

 (\mathbf{X}, G) is drawn under SSBM(n, k, A, B) if $p = \{1/k\}^k$ and \mathbf{W} takes avolue A on the diagonal and B off the diagonal.

19.1.1 Recovery

The goal of community detection is to recover the labels X by observing G, up to some level of accuracy. First, define **agreement** as

Definition 19.1.3: Agreement of Communities

The agreement between two community vectors \mathbf{x} , $\mathbf{y} \in [k]^n$ is obtained by maximizing the common components between \mathbf{x} and any relabelling of \mathbf{y} , that is

$$A(\mathbf{x}, \mathbf{y}) = \max_{\pi \in S_k} \frac{1}{n} \sum_{i=1}^{n} \mathbf{1} \left[x_i = \pi(y_i) \right]$$

where S_k is the group of permutations on [k].

The **relabelling** permutation is used to handle symmetric communities such as in SSBM, as it is impossible to recover the actual labels in this case. But it's possible to recover the **partition**. There are 2 types of partition recovery we consider

Exact Recovery First, consider the case of **exact recovery**:

Definition 19.1.4: Exact Recovery

Let $(\mathbf{X}, G) \sim SBM(n, p, W)$, the exact recovery is solved if there exists an algorithm that takes G as an input and outpus $\hat{\mathbf{X}} = \hat{\mathbf{X}}(G)$ such that $\mathbb{P}\left\{A(\mathbf{X}, \hat{\mathbf{X}}) = 1\right\} = 1 - o_p(1)$

In the SSBM case, algorithms that guarantee

$$A(\mathbf{X}, \hat{\mathbf{X}}) \to \frac{1}{k}$$

would be trivial.

Weak Recovery On the other hand, we the case of **weak recovery** defined as

Definition 19.1.5: Weak Recovery

Weak recovery or detection is solved SSBM(n,k,A,B) if for $(\mathbf{X},G) \sim SSBM(n,k,A,B)$, then $\exists \epsilon > 0$ and an algorithm that takes G as an input and outputs $\hat{\mathbf{X}}$ such that

$$\mathbb{P}\left\{A(\mathbf{X}, \hat{\mathbf{X}}) \ge \frac{1}{k} + \epsilon\right\} = 1 - o(1)$$