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Topic 16: Graphical Network Inference

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Key points:

Disclaimer: The note is built on Prof. Jinchi Lv's lectures of the course at USC, DSO 607, High-Dimensional Statistics and Big Data Problems.

16.1 Motivation

Consider a classic question: For n observations of dimension p, how can we capture the statistical relationships between the variables of interest? Consider the example of the multivariate Gaussian distribution:

Example 16.1.1: Multivariate Gaussian Distribution

Suppose we have n observations of dimension p, $\mathbf{x} \sim \mathcal{N}(\mu, \Sigma)$. let \mathbf{S} be the empirical covariance matrix. Then the probability density

$$f(\mathbf{x}) = \frac{1}{(2\pi)^{p/2} \det(\mathbf{\Sigma})^{1/2}} \exp\left\{-\frac{1}{2}(\mathbf{x} - \boldsymbol{\mu})' \mathbf{\Sigma}^{-1} (\mathbf{x} - \boldsymbol{\mu})\right\}$$

define the **inverse covariance matrix** or **precision matrix** as $\Omega = \Sigma^{-1}$, then we have

$$f_{\mu,\Omega} = \exp\left\{\mu'\Omega x - \left\langle\Omega, \frac{1}{2}xx'\right\rangle - \frac{p}{2}\log(2\pi) + \frac{1}{2}\log\det(\Omega) - \frac{1}{2}\mu'\Omega\mu\right\}$$

where $\langle \mathbf{A}, \mathbf{B} \rangle = \operatorname{tr}(\mathbf{A}\mathbf{B})$.

In this example, we know that **every** multivariate Gaussian distribution can be represented by a pairwise **Gaussian Markov Random Field (GMRF)**, which an **undirected graph** G = (V, E)

- representing the collection of variables **x** by a vertex set $\mathcal{V} = \{1, \dots, p\}$
- encoding correlations between variables by a set of edges $\mathcal{E} = \{(i, j) \in \mathcal{V} \mid i = \neq j, \Omega_{ij} \neq 0\}$

For simplicity, we normalize $\mu = 0$. If we draw n i.i.d. samples $\mathbf{x}_1, \dots, \mathbf{x}_n \sim \mathcal{N}(\mathbf{0}, \Sigma)$, then the log-likelihood is

$$\mathcal{L}(\mathbf{\Omega}) = \frac{1}{n} \sum_{i=1}^{n} \log f(\mathbf{x}_i) = \frac{1}{2} \log \det(\mathbf{\Omega}) - \frac{1}{2n} \sum_{i=1}^{n} \mathbf{x}_1' \mathbf{\Theta} \mathbf{x}_i$$
$$= \frac{1}{2} \log \det(\mathbf{\Omega}) - \frac{1}{2} \left\langle \mathbf{\Omega}, \frac{1}{n} \sum_{i=1}^{n} \mathbf{x}_i' \mathbf{x}_i' \right\rangle$$

What's the goal? We want to estimate a **sparse** graph structure given $n \ll p$ i.i.d. observations. But what does sparsity means in this context? A sparse graph is **equivalent** to a sparse precision matrix: the precision

matrix should have many 0s.

Sparse precision matrix for the Gaussian vector mentioned above $\mathbf{x} \sim \mathcal{N}(\mathbf{0}, \mathbf{\Sigma})$, we have $\forall u, v$

$$x_u \perp x_v \mid \mathbf{x}_{V \setminus \{u,v\}} \Leftrightarrow \Omega_{u,v} = 0$$

that is, sparsity of the precision matrix is equivalent to **conditional independence**¹. Consider a graph, where x_1 and x_4 are only connected through other nodes, that is x_1 and x_4 are conditional independent, then we can have the precision matrix be something like:

$$\Theta = \begin{bmatrix} * & * & 0 & 0 & * & 0 & 0 & 0 \\ * & * & 0 & 0 & 0 & * & * & 0 \\ 0 & 0 & * & 0 & * & 0 & 0 & * \\ 0 & 0 & 0 & * & 0 & 0 & * & 0 \\ * & 0 & * & 0 & * & 0 & 0 & * \\ 0 & * & 0 & 0 & 0 & * & 0 & 0 \\ 0 & * & 0 & * & 0 & 0 & * & 0 \\ 0 & 0 & * & 0 & * & 0 & 0 & * \end{bmatrix}$$

where 0 captures precisely the conditional independence.



 x_1 and x_4 are connected



 x_1 and x_4 are NOT connected, conditionally

Intuitively, a sparse graph is much simpler, which is why conditional independence is desired. So how to achieve sparsity? We can again use a L-1 regularization when maximizing the log-likelihood $\mathcal{L}(\Omega)$. Denote the sample covariance matrix as $\mathbf{S} = \frac{1}{n} \sum_{i=1}^{n} \mathbf{x}_{i} \mathbf{x}'_{i}$, then the problem becomes the so-called **Graphical Lasso**

$$\max_{\boldsymbol{\Omega} \geq \mathbf{0}} \log \det(\boldsymbol{\Omega}) - \operatorname{tr}(\mathbf{S}\boldsymbol{\Omega}) - \rho \; \|\boldsymbol{\Omega}\|_1$$

which is equivalent to

$$\min_{\Omega \geq 0} - \log \det(\Omega) + \operatorname{tr}(\mathbf{S}\Omega) + \rho \ \|\Omega\|_1$$

16.2 Graphical Lasso

The graphical lasso method is developed by (Friedman et al., 2008). For the optimization problem

$$\min_{\Omega \ge 0} -\log \det(\Omega) + \operatorname{tr}(\mathbf{S}\Omega) + \rho \|\Omega\|_{1}$$
(16.1)

¹Meanwhile, for independence: $\Sigma_{u,v} = 0 \Leftrightarrow x_u \perp x_v$

The first-order optimality condition gives

$$\mathbf{0} \in \mathbf{\Omega}^{-1} - \mathbf{S} - \lambda \mathbf{\Gamma}$$

where Γ is a matrix of component-wise signs of Ω

$$\Gamma = \partial \|\mathbf{\Omega}\|_1 \Rightarrow \gamma_{jk} \begin{cases} = \operatorname{sign}(\omega_{jk}), & \omega_{jk} \neq 0 \\ \in [-1, 1], & \omega_{jk} = 0 \end{cases}$$

since in a graph, we always have that, following the global stationarity conditions, $\omega_{jj} > 0$, which implies that

$$w_{ii} = s_{ii} + \lambda \qquad \qquad i = 1, \cdots, p \tag{16.2}$$

where we denote a working version of Ω^{-1} as **W**.

The idea is to repeatedly cycle through all columns-rows and in each step optimize only a single column-row. Consider the following partition where all matrices are partitioned into one column/row versus the rest

$$\mathbf{\Omega} = \begin{pmatrix} \mathbf{\Omega}_{11} & \boldsymbol{\omega}_{12} \\ \boldsymbol{\omega}_{12}' & \boldsymbol{\omega}_{22} \end{pmatrix} \qquad \mathbf{S} = \begin{pmatrix} \mathbf{S}_{11} & \mathbf{S}_{12} \\ \mathbf{s}_{12}' & \boldsymbol{s}_{22} \end{pmatrix} \qquad \mathbf{W} = \begin{pmatrix} \mathbf{W}_{11} & \mathbf{w}_{12} \\ \mathbf{w}_{12}' & \boldsymbol{w}_{22} \end{pmatrix} \qquad \Gamma = \begin{pmatrix} \mathbf{\Gamma}_{11} & \boldsymbol{\gamma}_{12} \\ \boldsymbol{\gamma}_{12}' & \boldsymbol{\gamma}_{22} \end{pmatrix}$$

apply this partition to the optimality condition, get

$$\mathbf{\Omega}^{-1} = \mathbf{S} - \lambda \mathbf{\Gamma}$$

$$\begin{pmatrix} \mathbf{W}_{11} & \mathbf{w}_{12} \\ \mathbf{w}'_{12} & w_{22} \end{pmatrix} = \begin{pmatrix} \mathbf{S}_{11} & \mathbf{s}_{12} \\ \mathbf{s}'_{12} & s_{22} \end{pmatrix} + \lambda \begin{pmatrix} \mathbf{\Gamma}_{11} & \mathbf{\gamma}_{12} \\ \mathbf{\gamma}'_{12} & \mathbf{\gamma}_{22} \end{pmatrix}$$

where Ω_{11} is $(p-1) \times (p-1)$, ω_{12} is $(p-1) \times 1$, ω_{22} is a scalar.

Consider a **blockwise** step: suppose we fix all but the last row/column, then using properties of inverses of block-partitioned matrices, we have

$$\begin{pmatrix} \mathbf{W}_{11} & \mathbf{w}_{12} \\ \mathbf{w}'_{12} & w_{22} \end{pmatrix} = \begin{pmatrix} \left(\mathbf{\Omega}_{11} - \frac{\omega_{12}\omega'_{12}}{\omega_{22}} \right)^{-1} & -\mathbf{W}_{11} \frac{\omega_{12}}{\omega_{22}} \\ & \frac{1}{\omega_{22}} - \frac{\omega'_{12}\mathbf{W}_{11}\omega_{12}}{\omega_{22}^{2}} \end{pmatrix}$$

$$= \begin{pmatrix} \mathbf{\Omega}_{11}^{-1} + \frac{\mathbf{\Omega}_{11}^{-1}\omega_{12}\omega'_{12}\mathbf{\Omega}_{11}^{-1}}{\omega_{22} - \omega'_{12}\mathbf{\Omega}_{11}^{-1}\omega_{12}} & -\frac{\mathbf{\Omega}_{11}^{-1}\omega_{12}}{\omega_{22} - \omega'_{12}\mathbf{\Omega}_{11}^{-1}\omega_{12}} \\ & \frac{1}{\omega_{22} - \omega'_{12}\mathbf{\Omega}_{11}^{-1}\omega_{12}} \end{pmatrix}$$

then, by the partitioned optimality condition, we have²:

$$\mathbf{0} = -\mathbf{w}_{12} + \mathbf{s}_{12} + \lambda \gamma_{12} = \mathbf{W}_{11} \frac{\omega_{12}}{\omega_{22}} + \mathbf{s}_{12} + \lambda \gamma_{12}$$
 (16.3)

$$\mathbf{0} = \frac{\mathbf{\Omega}_{11}^{-1} \boldsymbol{\omega}_{12}}{\boldsymbol{\omega}_{22} - \boldsymbol{\omega}_{12}' \mathbf{\Omega}_{11}^{-1} \boldsymbol{\omega}_{12}} + \mathbf{s}_{12} + \lambda \boldsymbol{\gamma}_{12} = w_{22} \mathbf{\Omega}_{11}^{-1} \boldsymbol{\omega}_{12} + \mathbf{s}_{12} + \lambda \boldsymbol{\gamma}_{12}$$
(16.4)

The graphic Lasso algorithm them solves Eq.16.3 for $\beta = \omega_{12}/\omega_{12}$, that is

$$\mathbf{W}_{11}\boldsymbol{\beta} + \mathbf{s}_{12} + \lambda \gamma_{12} = \mathbf{0}$$

²For Eq.16.4, by Eq.16.2, we know that $w_{22} = s_{22} + \lambda$, which is fixed.

where $\gamma_{12} \in \text{sign}(\beta)$ since $\omega_{22} > 0$, which is essentially solving:

$$\min_{\boldsymbol{\beta} \in \mathbb{R}^{p-1}} \left\{ \frac{1}{2} \boldsymbol{\beta}' \mathbf{W}_{11} \boldsymbol{\beta} + \boldsymbol{\beta}' \mathbf{s}_{12} + \lambda \left\| \boldsymbol{\beta} \right\|_{1} \right\}$$

and $W_{11} > 0$ is assumed to be fixed.

This problem is analogous to a lasso regression problem of the **last variable** on **the rest**, but the cross-product matrix S_{11} is replaced by its <u>current estimation</u> W_{11} . It is relatively easier to solve using elementwise coordinate descent, then

$$\mathbf{w}_{12} = -\mathbf{W}_{11} \frac{\omega_{12}}{\omega_{22}} \qquad \Rightarrow \hat{\mathbf{w}}_{12} = -\mathbf{W}_{11} \hat{\boldsymbol{\beta}} \qquad \text{Step 1}$$

$$w_{22} = \frac{1}{\omega_{22}} - \frac{\omega'_{12} \mathbf{W}_{11} \omega_{12}}{\omega_{22}^2} \qquad \Rightarrow \frac{1}{\hat{\omega}_{22}} = w_{22} - \hat{\boldsymbol{\beta}}' \hat{\mathbf{w}}_{12} \qquad \text{Step 2}$$

$$\omega_{12} = -\mathbf{W}_{11}^{-1} \mathbf{w}_{12} \omega_{22} \qquad \Rightarrow \hat{\omega}_{12} = -\mathbf{W}_{11}^{-1} \hat{\mathbf{w}}_{12} \hat{\omega}_{22} \qquad \text{Step 3}$$

notice that after solving for β and updating \mathbf{w}_{12} in Step 1, the graphic Lasso procedure can move onto the next block, that is, only Step 1 is used in the loop, Step 2 and 3 can be done at the end. The algorithm can be summarized as:

Algorithm 16.2.1: Graphical Lasso algorithm

- 1 Initialize $\mathbf{W} = \mathbf{S} + \lambda \mathbf{I}$
- Cycle around the columns repeatedly, performing the following steps till convergence:
 - a rearrange the rows/columns so that the target column is the last (implicitly)
 - b solve the lasso problem, starting the solution from the previous round for this column
 - c update the row/column (off-diagonal) of the covariance using $\hat{\mathbf{w}}_{12}$
 - d save $\hat{\beta}$ for this column in the matrix **B**
- 3 after convergence, for every row/column, compute the diagonal entries $\hat{\omega}_{jj}$, and covert the **B** matrix to Ω

16.3 What Is GLasso Solving?

Again, consider the optimization problem

$$\min_{\boldsymbol{\Omega} \geq \mathbf{0}} - \log \det(\boldsymbol{\Omega}) + \operatorname{tr}(\mathbf{S}\boldsymbol{\Omega}) + \rho \; \|\boldsymbol{\Omega}\|_1$$

and its stationarity condition

$$\mathbf{0} = \mathbf{\Omega}^{-1} - \mathbf{S} - \lambda \mathbf{\Gamma}$$

rewrite the stationarity condition

$$\mathbf{0} = \mathbf{\Omega}^{-1} - \mathbf{S} - \lambda \mathbf{\Gamma} = \mathbf{\Omega} - (\mathbf{S} + \lambda \mathbf{\Gamma})^{-1}$$

since $\Gamma = \text{sign}(\Omega)$, write $\tilde{\Gamma} = \lambda \Gamma$, we have $\|\tilde{\Gamma}\|_{\infty} \le \lambda$. Denote the element-wise absolute value matrix of Ω as $\text{abs}(\Omega)$, then let $\tilde{\Gamma} = \lambda \Gamma$, $P = \text{abs}(\Omega)$, we have

$$\begin{aligned} \mathbf{0} &= \mathbf{\Omega} - \left(\mathbf{S} + \lambda \mathbf{\Gamma} \right)^{-1} \\ &= \mathbf{P} \circ \text{sign}(\tilde{\mathbf{\Gamma}}) - (\mathbf{S} + \tilde{\mathbf{\Gamma}})^{-1} \end{aligned}$$

and mechanically, we also have

$$\mathbf{P} \circ \left(\operatorname{abs}(\tilde{\mathbf{\Gamma}}) - \lambda \mathbf{1}_p \mathbf{1}'_p \right) = \mathbf{0}$$
$$\left\| \tilde{\mathbf{\Gamma}} \right\|_{\infty} \le \lambda$$

together, these are just hte KKT optimality condition for the following box-constrained SDP

$$\max_{\tilde{\Gamma}: \|\tilde{\Gamma}\|_{\infty} \le \lambda} g(\tilde{\Gamma}) := \log \det(\mathbf{S} + \tilde{\Gamma}) + p \tag{16.5}$$

with the transformation $S + \tilde{\Gamma} = \Omega^{-1}$. Essentially, this is the dual problem of the initial optimization problem, both of them are solved by the GLasso algorithm.

Issues of GLasso method:

- the non-monotonic behavior of Glasso in minimizing $f(\Omega)$
 - θ_{12} is entangled in W_{11} , which is *incorrectly* treated as a constant
 - after updating θ_{12} , the entire (working) covariance matrix **W** changes, but Glasso algorithm only updates \mathbf{w}_{12} and \mathbf{w}'_{12}
- · high dimesnionality problems
 - not computationally efficient when p is ultra-large
 - Σ^{-1} doesn't exist when p > n
 - method is not scalable

Next, we address these issues by introducing some modifications.

16.4 Graphical Lasso: Modifications

16.4.1 Primal GLasso

Consider the optimality condition in Eq.16.4:

$$\mathbf{0} = \frac{\mathbf{\Omega}_{11}^{-1} \boldsymbol{\omega}_{12}}{\boldsymbol{\omega}_{22} - \boldsymbol{\omega}_{12}' \mathbf{\Omega}_{11}^{-1} \boldsymbol{\omega}_{12}} + \mathbf{s}_{12} + \lambda \boldsymbol{\gamma}_{12} = w_{22} \mathbf{\Omega}_{11}^{-1} \boldsymbol{\omega}_{12} + \mathbf{s}_{12} + \lambda \boldsymbol{\gamma}_{12}$$

Here, the dependence of the covariance submatrix W_{11} on Ω_{12} is **explicit**. Let $\alpha = \omega_{12}w_{22}$ with fixed $w_{22} \ge 0^3$, then this optimality condition is essentially solving

$$\min_{\boldsymbol{\alpha} \in \mathbb{R}^{p-1}} \left\{ \frac{1}{2} \boldsymbol{\alpha}' \boldsymbol{\Omega}_{11}^{-1} \boldsymbol{\alpha} + \boldsymbol{\alpha}' \mathbf{s}_{12} + \lambda \|\boldsymbol{\alpha}\|_{1} \right\}$$

the minimizer of this problem \hat{a} can then be used to derive the estimation for ω_{12} :

$$\hat{\boldsymbol{\omega}}_{12} = \frac{\hat{\boldsymbol{\alpha}}}{w_{22}}$$

, then we can update ω_{22} as before via

$$\hat{\omega}_{22} = \frac{1}{w_{22}} + \hat{\omega}'_{12} \mathbf{\Theta}_{11}^{-1} \hat{\omega}_{12}$$

 $^{^{3}}w_{22} = 1/(\omega_{2}2 - \boldsymbol{\omega}_{12}'\boldsymbol{\Omega}_{11}^{-1}\boldsymbol{\omega}_{12})$

with $w_{22} = s_{22} + \lambda$. Another problem is how to obtain Ω_{11}^{-1} : as the iterations proceed, maintain $\mathbf{W} = \Omega^{-1}$, and Ω_{11}^{-1} can be derived from

$$\mathbf{\Omega}_{11}^{-1} = \mathbf{W}_{11} - \frac{\mathbf{w}_{12}\mathbf{w}_{12}'}{w_{22}}$$

once ω_{12} is updated, the *entire* working covariance matrix **W** is updated using Ω_{11}^{-1} . This procedure, the so-called primal graphical lasso, can be represented in the following algorithm:

Algorithm 16.4.1: P-GLasso Algorithm

- 1 Initialize $\mathbf{W} = \operatorname{diag}(\mathbf{S}) + \lambda \mathbf{I}$ and $\mathbf{\Omega} = \mathbf{W}^{-1}$
- 2 Cycle around the columns repeatedly, performing the following steps till convergence:
 - a rearrange the rows/columns so that the target column is the last (implicitly)
 - b compute Ω_{11}^{-1} using $\Omega_{11}^{-1} = \mathbf{W}_{11} \frac{\mathbf{w}_{12}\mathbf{w}_{12}'}{w_{22}}$
 - c solve $\min_{\boldsymbol{\alpha} \in \mathbb{R}^{p-1}} \left\{ \frac{1}{2} \boldsymbol{\alpha}' \boldsymbol{\Omega}_{11}^{-1} \boldsymbol{\alpha} + \boldsymbol{\alpha}' \mathbf{s}_{12} + \hat{\lambda} \|\boldsymbol{\alpha}\|_1 \right\}$ for $\boldsymbol{\alpha}$, using as warm starts the solution from the previous round of row/column updates. Then update $\hat{\omega}_{12} = \hat{\boldsymbol{\alpha}}/w_{22}$ and $\hat{\omega}_{22}$
 - d update Ω and W, ensuring that $\Omega W = I_p$
- 3 output the solution: precision matrix Ω and its exact inverse, covariance matrix W

16.4.2 Innovated Scalable Efficient Estimation

Now, we try to tackle the high-dimesnionality issues: Σ^{-1} does **not** exist when p > n. Again,

$$x \sim \mathcal{N}(0, \Sigma)$$

consider a linear transformation where $\tilde{x} = \Omega x$,

References

Jerome Friedman, Trevor Hastie, and Robert Tibshirani. Sparse inverse covariance estimation with the graphical lasso. *Biostatistics*, 9(3):432–441, 2008.