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## Topic 13: Non-convex Learning + Lasso

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**Key points**: Combining the best of the two, we can use **Lasso plus Concave** method, with Lasso screening and concave component selecting variables, achieving a coordinated intrinsic two-scale learning.

**Disclaimer**: The note is built on Prof. Jinchi Lv's lectures of the course at USC, DSO 607, High-Dimensional Statistics and Big Data Problems.

We are facing a tradeoff:

- **Convex** methods: have appealing <u>prediction power and oracle inequalities</u>, but challenging to provide tight false sign rate control
- Concave methods: have good <u>variable selection</u> properties, but challenging to establish <u>global</u> properties and risk properties

Here, we take advantage of the linearity of Lasso (convex *and* concave) and try to combine it with concave regularization to get the best of both.

## 13.1 Model Setup

Again, consider a linear regression model  $y = X\beta + \epsilon$ , where

- response vector  $(n \times 1)$ :  $\mathbf{y} = (y_1, \dots, y_n)'$
- design matrix  $(n \times p)$ :  $\mathbf{X} = (\mathbf{x}_1, \dots, \mathbf{x}_p)$ , with each column rescaled to have  $L_2$ -norm  $n^{1/2}$

here, we consider a scenario where

- $\beta_0 = (\beta_{0,1}, \dots, \beta_{0,p})'$  is *sparse* (with many 0 components)
- ultra-**high** dimensions:  $\log p = O(n^a)$ , for some 0 < a < 1

and consider the penalized least squares

$$\min_{\beta \in \mathbb{R}^p} \left\{ (2n)^{-1} \|\mathbf{y} - \mathbf{X}\boldsymbol{\beta}\|_2^2 + \lambda_0 \|\boldsymbol{\beta}\|_1 + \|p_{\lambda}(\boldsymbol{\beta})\|_1 \right\}$$
 (13.1)

where

- $\lambda_0 = c \left(\frac{\log p}{n}\right)^{1/2}$  for some c > 0
- $p_{\lambda}(\boldsymbol{\beta}) = p_{\lambda}(|\boldsymbol{\beta}|) = (p_{\lambda}(|\beta_1|), \dots, p_{\lambda}(|\beta_p|))'$ , with  $|\boldsymbol{\beta}| = (|\beta_1|, \dots, |\beta_p|)'$ ; the concave penalty  $p_{\lambda}(t)$  is defined on  $t \in [0, \infty)$ , indexed by  $\lambda \ge 0$ , increasing in **both** t and  $\lambda$ ,  $p_{\lambda}(0) = 0$

the 2 penalty components

- $L_1$ -component: minimum amount of regularization for removing noise in prediction
- concave component  $||p_{\lambda}(\beta)||_1$ : adapt model sparsity for *variable selection*

Under this set up, we can derive the hard-thresholding property as

## **Proposition 13.1.1: Hard-Thresholding Property**

Assume the  $p_{\lambda}(t)$ ,  $t \ge 0$ , is **increasing and concave** with

- $p_{\lambda}(t) \ge p_{H,\lambda}(t) = \frac{1}{2} \left[ \lambda^2 (\lambda t)_+^2 \right]$  on  $[0, \lambda]$
- $p'_{\lambda}((1-c_1)\lambda) \le c_1\lambda$  for some  $c_1 \in [0,1)$
- $-p_{\lambda}''(t)$  decreasing on  $[0, (1-c_1)\lambda]$

then any <u>local minimizer</u> of 13.1 that is also a <u>global minimizer</u> in each coordinate has the **hard-thresholding** feature that each component is either 0 or of magnitude **larger** than  $(1 - c_1)\lambda$ 

Such property is shared by a wide class of concave penalties, including hard-thresholding penalty  $p_{H,\lambda}(t)$  with  $c_1 = 0$ ,  $L_0$ —penalty, and SICA (with suitable  $c_1$ ).

**How to** <u>understand</u> **this proposition?** Let  $\hat{\beta} = (\hat{\beta}_1, \dots, \hat{\beta}_p)'$ , then **each**  $\hat{\beta}_j$  is the glocal minimizer of the corresponding univariate penalized least-square problem along the j-th coordinate. These univariate problems share a common form with (generally) different scalars z

$$\hat{\beta}(z) = \arg\min_{\beta \in \mathbb{R}} \left\{ \frac{1}{2} (z - \beta)^2 + \lambda_0 |\beta| + p_{H,\lambda}(|\beta|) \right\}$$

after we rescale all covariates to have  $L_2$ -norm  $n^{1/2}$ . The solution to these univariate problems are

$$\hat{\beta}(z) = \operatorname{sgn}(z)(|z| - \lambda_0) \cdot \mathbf{1}_{|z| > \lambda + \lambda_0}$$

these solutions have the same feature as the hard-thresholded estimator: each component is either 0 or of magnitude larger than  $\lambda$ . This provides a better distinction between insignificant and significant covariates then soft-thresholding by  $L_1$  penalty.

With the hard-thresholding property of Prop. 13.1.1, we can prove a basic constraint for the global optimum  $\hat{\beta}$  on an event with significant probability (Fan and Lv, 2014)

$$\|\boldsymbol{\delta}_2\|_1 \le 7\|\boldsymbol{\delta}_1\|_1$$

where  $\delta = \hat{\beta} - \beta_0 = (\delta_1', \delta_2')'$ , with  $\delta_1 \in \mathbb{R}^s$ . Where does this constraint come from? For the penalized least square quesion 13.1

$$(2n)^{-1} \|\mathbf{y} - \mathbf{X}\boldsymbol{\beta}\|_2^2 + \lambda_0 \|\boldsymbol{\beta}\|_1 + \|p_{\lambda}(\boldsymbol{\beta})\|_1$$

the global minimizer  $\hat{\beta}$  leads to

$$(2n)^{-1} \|\mathbf{y} - \mathbf{X}\boldsymbol{\beta}\|_{2}^{2} + \lambda_{0} \|\boldsymbol{\beta}\|_{1} + \|p_{\lambda}(\boldsymbol{\beta})\|_{1}$$

## References

Yingying Fan and Jinchi Lv. Asymptotic properties for combined 11 and concave regularization. *Biometrika*, 101(1):57–70, 2014.