

LEC 23: Dirac Delta, Impulse Response

input is unit impulse

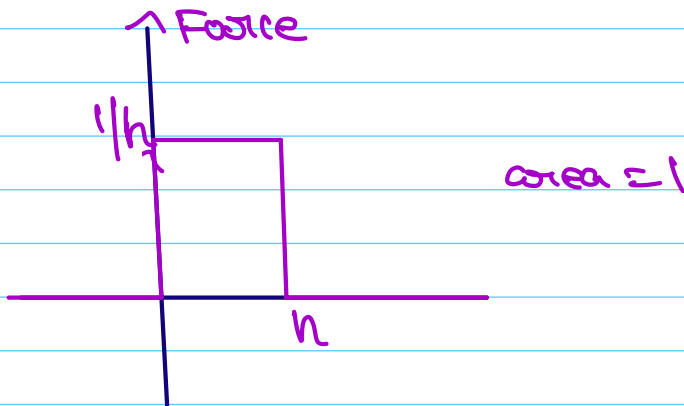
$$f(t) = \text{force}$$

$$\text{Impulse of } f(t) = \int_a^b f(t) dt$$

over $[a, b]$

* if $f(t)$ is constant F

$$\text{Impulse over time} = F \cdot (b-a)$$



Since Impulse is area under the curve,
if we want unit Impulse

Ex:

$$y'' + y = \frac{1}{h} u_{0h}(t)$$

what's the $\mathcal{L}\left(\frac{1}{h} u_{0h}(t)\right)$

$$\Rightarrow \frac{1}{h} \mathcal{L}(u(t) - u_h(t))$$

$$\Rightarrow \frac{1}{h} \mathcal{L}(u(t) - u(t-h))$$

$$\Rightarrow \frac{1}{h} \left(\frac{1}{s} - \frac{e^{-hs}}{s} \right)$$

$$\Rightarrow \mathcal{L}\left(\frac{1}{h} u_{0h}(t)\right) = \frac{1 - e^{-hs}}{hs}$$

$$\lim_{h \rightarrow 0} \mathcal{L}\left(\frac{1}{h} u_{0h}(t)\right) = \lim_{h \rightarrow 0} \frac{1 - e^{-hs}}{hs}$$

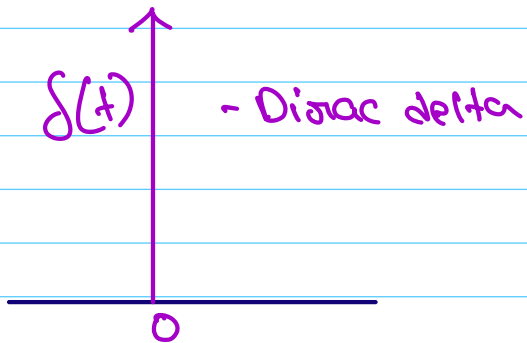
$$= \lim_{u \rightarrow 0} \frac{1 - e^{-u}}{u}$$

$$= \lim_{u \rightarrow 0} \frac{e^{-u}}{1} = 1$$

$$\frac{1}{h} \text{Mon}(t) \rightsquigarrow \frac{1 - e^{hs}}{hs}$$

$$\downarrow h \rightarrow 0$$

$$\downarrow h \rightarrow 0$$



$$\rightsquigarrow \mathcal{L}(\delta(t)) = 1$$

$$\delta(t) \rightsquigarrow 1$$

$$\int_{-\infty}^{\infty} \delta(t) dt = 1$$

$$* \quad u(t)f(t) * \delta(t) \rightsquigarrow \mathcal{L} \quad F(s) F(\delta(t))$$

$$\Updownarrow$$

$$u(t)f(t) \xleftarrow{\mathcal{L}^{-1}} = F(s)$$

$\Rightarrow \delta(t)$ for the convolution operator
is acting like an identity.

$$u'(t) = \delta(t)$$

Example:

$$y'' + y = A \delta(t - \frac{\pi}{2}) \quad y(0) = 1 \quad y'(0) = 0$$

Spring is kicked with an impulse A

at time $t = \frac{\pi}{2}$

* Kick it means deliver that over an extremely short time interval, but in such a way kicked it sufficiently hard that the total impulse was A

$$y'' + y = A \delta(t - \frac{\pi}{2})$$

$$\mathcal{L}(y'' + y) = \mathcal{L}(A \delta(t - \frac{\pi}{2}))$$

$$s^2 y(s) - s y(0) - y'(0) + y(s)$$

$$= A e^{-\frac{\pi s}{2}}$$

$$(s^2 + 1) y(s) - s = A e^{-\frac{\pi s}{2}}$$

$$y(s) = \frac{s}{s^2 + 1} + \frac{A}{s^2 + 1} e^{-\frac{\pi s}{2}}$$

$$\mathcal{L}^{-1}(y(s)) = \mathcal{L}^{-1}\left(\frac{s}{s^2 + 1} + \frac{A}{s^2 + 1} e^{-\frac{\pi s}{2}}\right)$$

$$= u(t) \cos t + A u(t - \frac{\pi}{2}) \sin(t - \frac{\pi}{2})$$

$$y(t) = \begin{cases} \cos t & 0 \leq t \leq \frac{\pi}{2} \\ (1-A) \cos t & \text{o.w.} \end{cases}$$

Eqn :

$$y'' + ay' + by = f(t)$$

↑
system

↑
input

$$y(0) = 0$$
$$y'(0) = 0$$

$$\mathcal{L}(y'' + ay' + by) = \mathcal{L}(f(t))$$

$$(s^2 + as + b)Y(s) = F(s)$$

$$Y(s) = F(s) \cdot \frac{1}{s^2 + as + b}$$

$$\frac{1}{s^2 + as + b}$$

→ It only depends on

Damping constant, spring constant

(Depends only on system,

Not on what input going into it)

= Transfer function = $W(s)$ or $H(s)$

$$\mathcal{L}^{-1}(W(s)) = w(t)$$

= weight function
of the system.

$$\Rightarrow y(t) = \int_0^t f(u) \omega(t-u) du$$

in other words the solution to differential eqⁿ is presented as definite integral.

what is $\omega(t)$? really.

$$y'' + ay' + by = \delta(t)$$

$$y(0) = y'(0) = 0$$



kicking the system with unit impulse at $t=0$, unit impulse.

$$\mathcal{L}(y'' + ay' + by) = \mathcal{L}(\delta(t))$$

$$\Rightarrow Y(s) (s^2 + as + b) = 1$$

$$\Rightarrow Y(s) = \frac{1}{s^2 + as + b}$$

$y(t) \rightsquigarrow$ weight function